#### **Pimpri Chinchwad Education Trust's**

#### PIMPRI CHINCHWAD COLLEGE OF ENGINEERING

#### SECTOR NO. 26, PRADHIKARAN, NIGDI, PUNE 411044

An Autonomous Institute Approved by AICTE and Affiliated to SPPU, Pune

## **DEPARTMENT OF MECHANICAL ENGINEERING**



## Curriculum Structure and Syllabus of

M. Tech. Mechanical Design Engineering (Approved by BoS Mechanical Engineering) (Course 2020)



## **Effective from Academic Year 2023-24**

(Updated with minor changes)

#### **Institute Vision**

To be one of the top 100 Engineering Institutes of India in coming five years by offering exemplarily Ethical, Sustainable and Value Added Quality Education through a matching ecosystem for building successful careers.

#### **Institute Mission**

- 1. Serving the needs of the society at large through establishment of a state-of-art Engineering Institute.
- 2. Imparting right Attitude, Skills, Knowledge for self-sustenance through Quality Education.
- 3. Creating globally Competent and Sensible Engineers, Researchers and Entrepreneurs with an ability to think and act independently in demanding situations.

#### **Quality Policy**

We at PCCOE are committed to impart Value Added Quality Education to satisfy the applicable requirements, needs and expectations of the Students and Stakeholders. We shall strive for academic excellence, professional competence and social commitment in fine blend with innovation and research. We shall achieve this by establishing and strengthening state-ofthe-art Engineering and Management Institute through continual improvement in effective implementation of Quality Management System.



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#### **ABBREVIATION**

Abbreviations	Course Full Name
PCC	Programme Core Course
PEC	Professional Elective Course
OEC#	Open Elective Course
PROJ	Project, Mini / Minor Projects, Integrated Projects
SEM	Seminar
INTR	Internship
LS	Life Skill
AUDIT*	Audit Course
МО	Massive Open Online Courses

Note: \* Indicates that these courses are at institute level

# The Course offered by other departments

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# Curriculum Structure

## CURRICULUM STRUCTURE STRUCTURE FOR 1<sup>ST</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – I

M.Tech. Str	ucture	Semester-I	Tea	ching	g Sch	eme	Exam	ination S	Scheme			
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ЕТЕ	TW	OR	Total
MMD1401	PCC	Research Methodology & IPR	3	-	3	3	20	30	50	-	-	100
MMD1402	PCC	Stress Analysis	3	-	3	3	20	30	50	-	-	100
MMD1403	PCC	Finite Element Method	3	-	3	3	20	30	50	-	-	100
MMD1404	PCC	Professional core Lab-I (SA, FEM)	-	2	2	1	-	-	-	50	50	100
MMD1405	PCC	Skill Development Lab - I (Software Skills)	-	2	2	1	-	-	-	50	-	50
MMD1501	PEC	Professional Elective-I	3	-	3	3	20	30	50	-	-	100
MMD1502	PEC	Professional Elective-II	3	-	3	3	20	30	50	-	-	100
MMD1503	PEC	Professional Elective Lab-I ( PE I , PE II)	-	2	2	1	-	-	-	50	50	100
**	OEC	Open Elective-I	2	-	2	2	20	-	30	-	-	50
M_1961	Audit	Audit course – I	1	-	1	-	-	-	-	-	-	-
		Total	18	6	24	20	120	150	280	150	100	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam \*\* Course code of the selected open elective by student

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## STRUCTURE FOR 1<sup>ST</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – II

M.Tech. Str	ucture	Semester -II	Tea	ching	s Sch	eme	Examin	nation So	cheme			
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ЕТЕ	TW	OR	Total
MMD2406	PCC	Optimization Techniques in Design	3	-	3	3	20	30	50	-	-	100
MMD2407	PCC	Advanced Vibrations and Acoustics	3	-	3	3	20	30	50	-	-	100
MMD2408	PCC	Professional core Lab- II (OT, AVA)	-	2	2	1	140	-	-	50	50	100
MMD2504	PEC	Professional Elective- III	3	-	3	3	20	30	50	-	-	100
MMD2505	PEC	Professional Elective- IV	3	-	3	3	20	30	50	-	-	100
MMD2506	PEC	Professional Elective Lab-II (EL III, EL IV)	-	2	2	1	-	-	-	50	50	100
MMD2701	PROJ	Integrated Mini-Project	-	6	6	3	-	50	-	-	50	100
**	OEC	Open Elective –II	2	-	2	2	20	-	30	-	-	50
M_2101	HSMC	Skill Development Lab – II (Written & Oral Communication)	-	2	2	1	-	-	-	50	-	50
M_2962	Audit	Audit course – II	1	-	1	-	-	-	-	-	-	-
		Total	15	12	27	20	100	170	230	150	150	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam \*\* Course code of the selected open elective by student

## STRUCTURE FOR II<sup>ND</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-III

M. Tech. S	Structure	Semester – III	ſ	TEACI	HING	SCHE	ME	EXAM	INATIO	N SCH	EME	
Course Code	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ЕТЕ	TW	OR	TOTAL
MMD3702	PROJ	Dissertation Phase - I [Company/ In-house project]	-	20	20	10	-	-	-	100	100	200
MMD3703	SEM	Seminar	-	04	04	02	-	-	-	50	50	100
MMD3801	INTR	Internship [Company/ In-house project] /	-	04	04	02	-	20	-	100	-	100
				C	)R							
MMD3981	MOOC	MOOC's / Entrepreneurship	-	04	04	02	-	-	-	100	-	100
		Total	-	28	28	14	-	-	-	250	150	400

\*Internship: -It may be in summer/winter vacation or within semester at least for three months, evaluation after fourth semester

## STRUCTURE FOR II<sup>ND</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-IV

M. Tech.	Structure	Semester – IV			CHIN HEMI		Е	XAMINA	TION S	CHEME	C	
Course Code	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ETE	TW	OR	TOTAL
MMD4704	PROJ	Dissertation Phase - II [Company/ In-house project]	-	24	24	12	_	_	-	200	200	400
MMD4982	MOOC	MOOC's	-	4	4	2	-	-	-	100	-	100
		Total	-	28	28	14	-	-	-	300	200	500

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam

#### LIST OF PROFESSIONAL ELECTIVE COURSES

Course Code	Elective-I	Course Code	Elective-II
MMD1501A	Advanced Machine Design	MMD1502A	Mechanics of Composites
MMD1501B	Mechanical Behavior of Materials	MMD1502B	Tribology in Design
MMD1501C	Analysis and Synthesis of Mechanisms	MMD1502C	Vehicle Dynamics
MMD1501D	Mathematical Methods in Engineering	MMD1502D	Robotics

Course Code	Elective-III	Course Code	Elective-IV
MMD2504A	Fatigue and Fracture Analysis	MMD2505A	Design of Material Handling Equipments
MMD2504B	Reliability in Engineering Design	MMD2505B	Computer Aided Design
MMD2504C	Mechatronics and Control Systems	MMD2505C	Multi-body Dynamics

#### LIST OF OPEN ELECTIVE COURSES

#### **OFFERED BY MECHANICAL ENGINEERING - DESIGN ENGINEERING**

Course Code	<b>Open Elective – I</b>	Course Code	Open Elective –II
MMD1601A	Advanced Materials	MMD2602A	Room Acoustics
MMD1601B	Optimization Methods	MMD2602B	Design Thinking
MMD1601C	Modeling & Simulation of Dynamic Systems	MMD2602C	Reliability Engineering

#### OFFERED BY MECHANICAL ENGINEERING - COMPUTATIONAL MECHANICS

	<b>Open Elective – I</b>		Open Elective –II
MMC1601A	Battery Management for Electric Vehicles	MMC2602A	Waste Management for Smart Cities
MMC1601B	Green Technology	MMC2602B	Electronic Cooling
MMC1601C	System Modeling and Simulation	MMC2602C	Renewable Energy Sources

#### OFFERED BY E&TC- VLSI & EMBEDDED SYSTEMS

<b>Course Code</b>	<b>Open Elective – I</b>	<b>Course Code</b>	<b>Open Elective –II</b>
MET1601A	Automotive Electronics & Applications	MET2602A	Drone Programming for Beginners
MET1601B	Industrial Drives	MET2602B	Instrumentation and Measurement
MET1601C	Basics of FPGA and CPLD	<b>MET2602C</b>	Microcontrollers and Microprocessors applications
MET1601D	Robotics	MET2602D	Electronics Implementation Platforms

#### OFFERED BY COMPUTER ENGINEERING

<b>Course Code</b>	Open Elective – I	Course Code	Open Elective –II
MCE1601A	Programming with Python	MCE2602A	Image Processing with MATLAB
MCE1601B	Software Engineering Basics	MCE2602B	Linux Essentials
MCE1601C	Basics of Machine learning	MCE2602C	Design with UML

#### OFFERED BY CIVIL- CONSTRCTION MANAGEMENT

<b>Course Code</b>	Open Elective – I	Course Code	<b>Open Elective –II</b>
MCI1601A	Project Management and Finance	MCI2602A	Contracts, Tendering and Arbitration
MCI1601B	Green Technology	MCI2602B	Total Quality Management
MCI1601C	Organization Behavior	MCI2602C	Operation Research

#### **OFFERED BY INFORMATION TECHNOLOGY- ARTIFICIAL INTELLIGENCE & DATA SCIENCE**

<b>Course Code</b>	<b>Open Elective – I</b>	<b>Course Code</b>	Open Elective -II
MDS1601A	R Programming	MDS2602A	Python for Data Science
MDS1601B	Business Analytics	MDS2602B	Introduction to Neural Networks

#### LIST OF AUDIT COURSES (Common to all Programs)

Course Code	Audit Courses-I (SEM-I)	Course Code	Audit Courses –II (SEM-II)
M_1961A	Constitution of India	M_2962A	Team Building & Leadership
M_1961B	Value Education	M_2962B	English for Research Writing
M_1961C	Stress Management	M_2962C	Disaster Management

# Course Syllabus

## Semester-I

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3. 4.				cal modeling and							
5.				research writing a							
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				should be able to		4.1					
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2. 3.				g standard proced							iipie uata.
4.				el and analyze the					, periorii		
5.				search proposal.							
6.	Write a	a conce	pt note and pre	pare to file an IP.					C	S	
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#### IE Activities:

- 1. Write a review paper based on detailed literature survey and cheque for plagiarism.
- 2. Write a research proposal on your domain specific research problem.
- 3. Write a concept note and prepare to file an IP



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Text Books:	
1.	Seshu P., "Text book of Finite Element Analysis", PHI Learning Private Ltd., New Delhi, 2010.
2.	Logan D, "First course in the Finite Element Method" Cengage Learning, 2012
<b>Reference B</b>	Books:
1.	Bathe K. J., "Finite Element Procedures", Prentice-Hall of India (P) Ltd., New Delhi.
2.	Cook R. D., "Finite Element Modeling for Stress Analysis", John Wiley and Sons Inc, 1995
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4.	Hall India.
5.	Liu G. R. and Quek S. S. "The Finite Element Method – A Practical Course", Butterworth-Heinemann,
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7. Reddy, J. N., "An Introduction to The Finite Element Method", Tata McGraw Hill, 2003.



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6.       E         Prior km       Course C         1.       1.         2.       3.         4.       2.         3.       1.         2.       3.         4.       5.         3.       5.         4.       5.         3.       5.         4.       5.         3.       5.         4.       5.         5.       5.         5.       5.         6.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5.         7.       5. <td>Calibrat Evaluation owledg Objecti To imp mechan To dese To stuc Adequa underly Outcon Apply Evalua Underss Stress a vithin Modal a Study) Static st ension Stress, S software Stress, S software Stress, S</td> <td>tion of Photoelastic ion of Stresses usin ge of: Engineering I ives: part the philosophy nics and thermal an cribe and interpret I dy approximate natu ately describes a pi ying physical princi nes: After learning General procedure te linear and non linstand and apply eler stand and apply eler nalysis of 1D bar usite the element for line analysis and stress a tress concentration strain and deflection e. (Convergence Strain ced Strength and A P., "Text book of F</td> <td>materials g Polariscope Mathematics Machin and general procedu alysis problems. Numerical solutions ure of the finite elem hysical event and es ples. the course the stude and philosophy of finear problems relate ments, mess sensitiv <b>Dart B: Finite E</b> sing linear and quad ear and quadratic bar malysis for 1-D bear factor calculation for re (Convergence Stu n analysis of any ma udy)</td> <td>ne Design, Streng re of Finite Elem for more comple nent method and c stablishing or val nts should be able nite element method d to geometry, m ity analysis and c etailed Syllabus: lement Method Description ratic elements. Sh element (Conver m (simply suppor r a plate with cen dy) achine component sis-Richard G. Bu</td> <td>th of Materia ent Method si x geometries convergence of idating a rela e to: hod to simular aterial and co onvergence st (ANY Three how the variat gence Study) ted or cantiles ter hole subje t consisting of adynas, McGr</td> <td>Total mulations a and loading f results are tionship bet e complex e ntact. udy to real 1 ) ion of stress ver beams) ( cted to axial '3-D elemen Tota awHill</td> <td>s applied to solid states. examined. examined. ween obtained engineering prob life problems. and strain Convergence loading in nts using FEA <b>l Any Three</b>)</td> <td>5 5 15 d results and blems Duration (H) 2 2 2 2 2 2 2</td>	Calibrat Evaluation owledg Objecti To imp mechan To dese To stuc Adequa underly Outcon Apply Evalua Underss Stress a vithin Modal a Study) Static st ension Stress, S software Stress, S software Stress, S	tion of Photoelastic ion of Stresses usin ge of: Engineering I ives: part the philosophy nics and thermal an cribe and interpret I dy approximate natu ately describes a pi ying physical princi nes: After learning General procedure te linear and non linstand and apply eler stand and apply eler nalysis of 1D bar usite the element for line analysis and stress a tress concentration strain and deflection e. (Convergence Strain ced Strength and A P., "Text book of F	materials g Polariscope Mathematics Machin and general procedu alysis problems. Numerical solutions ure of the finite elem hysical event and es ples. the course the stude and philosophy of finear problems relate ments, mess sensitiv <b>Dart B: Finite E</b> sing linear and quad ear and quadratic bar malysis for 1-D bear factor calculation for re (Convergence Stu n analysis of any ma udy)	ne Design, Streng re of Finite Elem for more comple nent method and c stablishing or val nts should be able nite element method d to geometry, m ity analysis and c etailed Syllabus: lement Method Description ratic elements. Sh element (Conver m (simply suppor r a plate with cen dy) achine component sis-Richard G. Bu	th of Materia ent Method si x geometries convergence of idating a rela e to: hod to simular aterial and co onvergence st (ANY Three how the variat gence Study) ted or cantiles ter hole subje t consisting of adynas, McGr	Total mulations a and loading f results are tionship bet e complex e ntact. udy to real 1 ) ion of stress ver beams) ( cted to axial '3-D elemen Tota awHill	s applied to solid states. examined. examined. ween obtained engineering prob life problems. and strain Convergence loading in nts using FEA <b>l Any Three</b> )	5 5 15 d results and blems Duration (H) 2 2 2 2 2 2 2
6.       E         Prior km       Course C         1.       7         2.       3.         4.       7         2.       1.         3.       1         5.       8         1.       S         3.       1         5.       8         1.       S         3.       1         7.       S         3.       1         7.       S         3.       1         7.       S         3.       1         7.       S         8.       8         1.       2.         3.       1         7.       3         7.       5         8.       8         9.       7         1.       2.         2.       5         8.       8         9.       7         1.       7         2.       5         8.       8         9.       7         1.       7         1.       7	Calibrat Evaluation Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Constructio	tion of Photoelastic ion of Stresses usin ge of: Engineering 1 ives: part the philosophy nics and thermal an cribe and interpret 1 dy approximate naturately describes a pi ying physical princines. After learning General procedure te linear and non lines and and apply element of the element for lines analysis of 1D bar using FEA softwar Strain and deflection e. (Convergence Stu- ced Strength and A P., "Text book of Fines ks: of Elasticity–Time	materials g Polariscope Mathematics Machin and general procedu alysis problems. Numerical solutions ure of the finite elem hysical event and es ples. the course the stude and philosophy of finear problems relate ments, mess sensitiv De Part B: Finite E I sing linear and quad- rar and quadratic bar analysis for 1-D bear factor calculation fo re (Convergence Stu n analysis of any ma udy) pplied Stress Analys inite Element Analys	ne Design, Streng re of Finite Elem for more comple nent method and of stablishing or val nts should be able nite element method d to geometry, m ity analysis and c etailed Syllabus: lement Method of Description ratic elements. Sh element (Conver m (simply suppor r a plate with cen dy) achine component sis-Richard G. Bu	th of Materia ent Method si x geometries convergence of idating a rela e to: hod to simular aterial and co onvergence st (ANY Three now the variate gence Study) ted or cantile ter hole subje t consisting of idynas, McGr g Private Ltd.	Total mulations a and loading f results are tionship bet e complex e ntact. udy to real l ) ion of stress ver beams) ( cted to axial '3-D elemen Tota awHill , New Delhi	s applied to solid states. examined. examined. ween obtained engineering prob life problems. and strain Convergence loading in nts using FEA <b>I Any Three</b> ) , 2010.	5 5 15 d results and blems Duration (H) 2 2 2 2 2 2 2
6.       E         Prior km       Course C         1.       7         2.       3.         4.       7         2.       1.         3.       7         3.       7         3.       7         3.       7         3.       7         3.       7         3.       7         4.       8         5.       8         6.       8         6.       8         7       8         6.       8         7       8         7       8         8       8         1.       8         9       8         1.       8         1.       8         1.       8         1.       9         2.       8         8       8         1.       1         2.       8         8       8         1.       1         2.       8         8       8         1.       1         1.	Calibrat Evaluation Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Construction Constructio	tion of Photoelastic ion of Stresses usin ge of: Engineering 1 ives: part the philosophy nics and thermal an cribe and interpret 1 dy approximate naturately describes a pi ying physical princines. After learning General procedure te linear and non lines and and apply element of the element for lines analysis of 1D bar using FEA softwar Strain and deflection e. (Convergence Stu- ced Strength and A P., "Text book of Fines ks: of Elasticity–Time	materials g Polariscope Mathematics Machin and general procedu alysis problems. Numerical solutions ure of the finite elem hysical event and es ples. the course the stude and philosophy of finear problems relate ments, mess sensitiv <b>Deart B: Finite E</b> sing linear and quad ar and quadratic bar analysis for 1-D bear factor calculation for re (Convergence Stu n analysis of any ma udy) pplied Stress Analys	ne Design, Streng re of Finite Elem for more comple nent method and of stablishing or val nts should be able nite element method d to geometry, m ity analysis and c etailed Syllabus: lement Method of Description ratic elements. Sh element (Conver m (simply suppor r a plate with cen dy) achine component sis-Richard G. Bu	th of Materia ent Method si x geometries convergence of idating a rela e to: hod to simular aterial and co onvergence st (ANY Three now the variate gence Study) ted or cantile ter hole subje t consisting of idynas, McGr g Private Ltd.	Total mulations a and loading f results are tionship bet e complex e ntact. udy to real l ) ion of stress ver beams) ( cted to axial '3-D elemen Tota awHill , New Delhi	s applied to solid states. examined. examined. ween obtained engineering prob life problems. and strain Convergence loading in nts using FEA <b>I Any Three</b> ) , 2010.	5 5 15 d results and blems Duratio (H) 2 2 2 2 2 2

Program	M. Tech. Mech	anical (Design En	gineering)	5	Semester :	I
Course :	Skill Developm		<u> </u>	(	Code : MMD14	05
	Teaching Scheme	2		Eval	ation Scheme	
Practical	Hours	Credit	TW	PR	OR	Total
2	2	1	50			50
Prior knowle						
Course Obje				_		
					hods and the sk	ills required to analyze
	neering problems with	h commercially ava	ailable FEA softw	are's		
Course Outco						0
	the course, the stude			software's sh	ould be able to p	bertorm:
	l dynamic linear resp					
	posite and fatigue and					
	inear dynamic analys					
3. The	shape and topological				_	
<b>I</b> • 4 6 E	iments/ Assignment		Detailed Syllabus			
<ol> <li>Deter comb</li> <li>Inves</li> <li>Perfo</li> <li>Deter</li> <li>Perfo</li> <li>Perfo</li> <li>nonlin</li> <li>Perfo</li> <li>Students can p</li> <li>Ansys, ABAQ</li> </ol>	ination of loads tigate effect of variou rm fatigue analysis u mine frequency/Tran	amic linear respon- is parameters (no. sing stress and stra sient/Random resp nic analysis of en inearity. Solve for e optimization ments using any of	nse of a 3-dimen of lay-ups and fib in life approach o ionse for members gineering compo Impact/Crash/Sho	sional engine er orientation f an engineeri s subjected to nents subject ck problems	on laminated congroups of the second	
Text Books:						
	Finite Element Metl iim (Springer)	hod and Applicati	ons in Engineerin	ng Using AN	SYS® by Mad	enci, Erdogan, Guven,
Ibrok	(Nnringer)					
		inita Elamant Aug	voia" DITLE	na Driveta I (	Mary Dalle: 2	010
<ol> <li>Sesh</li> <li>Muk</li> </ol>	u P., "Text book of F hopadhyay M and Sh Ltd., 2009.					

~	M. Tech. Mechanical	(Design Engineer	ring)		Semester : I	
Course :	Advanced Machine D	esign (Profession	nal Elective-I)		Code: MMD1501	A
	Teaching Scheme			Evalua	ation Scheme	
Lecture	Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Prior knowle						
	anced Stress Analysis					
	neering Design					
	ufacturing Processes	are essential				
Course Obje 1. To n	ake aware the students a	hout industrial de	sign practices			
	nable the students to iden			engineering pr	oblems	
	omes: After learning the				Johennis.	
	ents will realize that creat				itv.	
	ions, reliability are also i					n the highly
	petitive, dynamic and cus			U		0,
	ents will demonstrate the			stomer and con	vert them into technica	1
spec	ifications of a product.	11				
	ents will be able to gener			g the need and o	determining the specifi	cations and
	traints of a product for a					
	ents will understand the p	principals used wh	ile designing for	r manufacture,	assembly, emotions an	d
	tenance.					
	ents will know various m					
6. Stud	ents will be able to design			ngth based relia	ability	
		Det	ailed Syllabus:			
Unit		D	esc <mark>ript</mark> ion			Duratio
Dev	elopment processes and					(H)
		organizations, P	roduct Plannin	g		(H)
1. Intro					et and process cycles	
	duction to engineering	design, Product	development p	rocess, Produc	ct and process cycles	
orga	duction to engineering nization for design and particular	design, Product roduct developme	development p nt, technologica	rocess, Produc l innovation	· ·	, 7
orga Nee	duction to engineering	design, Product roduct developme lem definition, pr	development p nt, technologica oduct specificat	rocess, Produc l innovation	· ·	, <b>7</b>
orga Nee eval	duction to engineering nization for design and p I Identification and prob	design, Product roduct developme lem definition, pr s, Concept testing	development p nt, technologica oduct specificat	rocess, Produc l innovation ion, concept ge	eneration and selection	, 7 , 8
orga2.orgaIdentification	duction to engineering nization for design and p d Identification and prob dation, creativity methods	design, Product roduct developme lem definition, pr s, Concept testing , requirements, e	development p nt, technologica oduct specificat establishing the	rocess, Produc l innovation ion, concept ge	eneration and selection	, 7 , 8
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orga2.Nee eval Iden func3.Desi4.Desi	duction to engineering nization for design and p d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt	design, Product roduct developme lem definition, pr s, Concept testing , requirements, c t design specificat mbly, maintenance th based reliability	development p nt, technologica oduct specificat establishing the ion e, casting, forgir y, parallel and se	rocess, Product l innovation ion, concept ge engineering ng ries systems, ro	eneration and selection characteristics, quality obust design	, 7 , 8 , 8 , 7 , 8 , 7 , 8 , 7 , 8
2. Orga Present of the second	duction to engineering nization for design and pr d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi	design, Product roduct developme lem definition, pr s, Concept testing , requirements, c t design specificat mbly, maintenance th based reliability	development p nt, technologica oduct specificat establishing the ion e, casting, forgir y, parallel and se	rocess, Product l innovation ion, concept ge engineering ng ries systems, ro	eneration and selection characteristics, quality obust design	, 7 , 8 , 8 , 7 , 8
orga2.Nee2.evalIdentfunct3.Dest4.Dest5.Dest	duction to engineering nization for design and pr d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et t design specificati mbly, maintenance th based reliability ign for reuse, Des	development p nt, technologica oduct specificat establishing the ion e, casting, forgin y, parallel and se sign for Environ	rocess, Product l innovation ion, concept get engineering ries systems, ro ment and Desi	eneration and selection characteristics, quality obust design gn for cost and Design	, 7 , 8 , 8 , 8 , 8 , 7 , 8 , 7 , 8 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7
2. Provide the second s	duction to engineering nization for design and pr d Identification and prob- uation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality strial design: Design for	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et t design specificati mbly, maintenance th based reliability ign for reuse, Des	development p nt, technologica oduct specificat establishing the ion e, casting, forgin y, parallel and se sign for Environ	rocess, Product l innovation ion, concept get engineering ries systems, ro ment and Desi	eneration and selection characteristics, quality obust design gn for cost and Design	, 7 , 8 , 8 , 8 , 7 , 8 , 7 , 8 , 7 , 8 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7 , 7
2. Provide the second s	duction to engineering nization for design and pr d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et t design specificati mbly, maintenance th based reliability ign for reuse, Des	development p nt, technologica oduct specificat establishing the ion e, casting, forgin y, parallel and se sign for Environ	rocess, Product l innovation ion, concept get engineering ries systems, ro ment and Desi	eneration and selection characteristics, quality obust design gn for cost and Design trofit and Eco design	, 7 , 8 , 8 , 7 , 8 , 8 , 7 , 8 , 7 , 8
2. Provide the second	duction to engineering nization for design and pr d Identification and prob- uation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality strial design: Design for	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et t design specificati mbly, maintenance th based reliability ign for reuse, Des	development p nt, technologica oduct specificat establishing the ion e, casting, forgin y, parallel and se sign for Environ	rocess, Product l innovation ion, concept get engineering ries systems, ro ment and Desi	eneration and selection characteristics, quality obust design gn for cost and Design	, 7 , 8 , 8 , 7 , 8 , 8 , 7 , 8 , 7 , 8
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2. Nee eval Iden func 3. Desi 4. Desi 5. Desi for ( 6. Indu Hun Exert Books: 1. George I Reference Bo	duction to engineering nization for design and pro- l Identification and prob- uation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality strial design: Design for an behavior in design	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et t design specificati mbly, maintenance th based reliability ign for reuse, Des or Emotion and et esign", McGraw H	development p nt, technologica oduct specificat establishing the ion e, casting, forgin y, parallel and se sign for Environ experience, Intro Iill Company, 20	rocess, Production ion, concept get engineering ries systems, ro- ment and Desi- oduction to re-	eneration and selection characteristics, quality obust design gn for cost and Design trofit and Eco design Tota	, 7 , 8 , 7 , 8 , 8 , 8 , 7 , 8 , 8 , 8 , 8 , 1 , 45
2. Nee eval Iden func 3. Desi 4. Desi for ( 6. Indu Hum Fext Books: 1. George I Reference Bo 1. Prashan 2012	duction to engineering nization for design and pro- d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality strial design: Design for han behavior in design Dieter, "Engineering De poks: Kumar, "Product Design	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et design specification mbly, maintenance th based reliability ign for reuse, Des or Emotion and et esign", McGraw H	development p nt, technologica oduct specificat establishing the ion e, casting, forgir y, parallel and se sign for Environ experience, Intro- lill Company, 20 cepts and Usabil	rocess, Production ion, concept get engineering ries systems, ro- ment and Desi oduction to re- 000.	eneration and selection characteristics, quality obust design gn for cost and Design trofit and Eco design Tota conomy Edition, PHI N	, 7 , 8 , 7 , 8 , 8 , 8 , 7 , 8 , 8 , 8 , 8 , 1 , 45
2. Nee eval Iden func 3. Desi 4. Desi for ( 6. Indu Hun Exet Books: 1. George I Reference Bo 1. Prashan 2012 2. Woodsc	duction to engineering nization for design and pr d Identification and prob- lation, creativity methods tifying customer needs, tion deployment, product gn for manufacture, asser gn for Reliability, strengt gn of dis-assembly, Desi Quality strial design: Design for an behavior in design	design, Product roduct developme lem definition, pr s, Concept testing , requirements, et design specification mbly, maintenance th based reliability ign for reuse, Des or Emotion and et esign", McGraw H n, Creativity, Conc Engineering Desig	development p nt, technologica oduct specificat establishing the ion e, casting, forgir y, parallel and se sign for Environ experience, Intro- lill Company, 20 cepts and Usabil n", McGraw Hil	rocess, Production ion, concept get engineering ries systems, ro- ment and Desi oduction to re- 000.	eneration and selection characteristics, quality obust design gn for cost and Design trofit and Eco design Tota conomy Edition, PHI N	, 7 , 7 , 8 , 7 , 8 , 7 , 8 , 7 , 8 , 7 , 8 , 7 , 8 , 1 , 45

- 4. Averill M. Law and W. David Kelton "Simulation, modelling and analysis", McGraw Hill Book Company, 1991.
- 5. Pahl, G.andW.Beitz, Engineering Design–A Systematic Approach Springer, 2nd Ed., 1996.
- 6. Product Design and Development Karl T. Ulrich, Steven Eppinger

Course L	Ma		al (Design Engine			Semester: I		
L			our of Materials	(Professional E	,	Code : MMD15	01B	
L	Те	aching Scheme	1		Evalu	ation Scheme		
	ecture	Hours	Credit	IE1	IE2	ETE	Т	otal
	3	3	3	20	30	50	1	.00
Prior k	nowledge of			I		1		
a.	Material sci	ence						
b.		of materials	are essential					
	e Objectives:							
1			ials with their app		1. 1 1	P		
2 3			ify the response of					
			rpret the behaviou course, the studer			ateriai		
1.			odern materials in			IS .		
2.						omplex loading cond	litions	
2. 3.			nder forms of load				intions	
4.						on during strain hard	ening.	
5.						t loading conditions		
6.						y to engineering mat		or
	behavioural	study				1 mar 1 mar		
			Det	ailed Syllabus:				
Unit			De	escription				Duration
								<b>(H</b> )
		terials in Design			h .: f			
1.						e stress strain beha		7
			als – types, applica			ropic properties, Pla	sucs,	
			s under applied		perties		-	_
2.			Mohr's circle, Is		Anisotropic	elasticity, Anisot	ropic	8
2.			shear stress, Yiel				ropie	Ū
	Tensile testi		,		,,		-	
2		0	test, Full range s	tress-strain curv	ves, True stress	s-strain curve, Brid	gman	-
3.						on test, Three points		7
	test, Elastic r	recovery						
			ork hardening m					
4.						ading, Strain harde		8
						odels, Theory of p	lastic	Ŭ
			ure dependence of	flow stress	PERMIT	0/11		_
		Elastic-Plastic Be		tisity Dehavior	an of motols w	vith initial deforma	tions	
5.						astic-rigid body, El		7
	-		astic-Plastic bodie			istic figid body, El	astic	
	Elasto-Visco							
			models, Maxwell	model, Voigt 1	nodel, Voigt-	Maxwell model, Na	atural	
6.						rmo-Elastic effect,		8
				tic deformation	models, Rub	ber elasticity, Dam	ping,	
	yielding, effe	ect of strain rate, (	Crazing.					
						,	Total	45
	ooks:							
Text B		haviour of Materi	als, W.F.Hosford,	Cambridge Univ	versity Press, 2	2005		
	heory of Plast	icity and Metal Fo	orming Processes,	Sadhu Singh, K	hanna Publish	ers		
1. M	nce Books:							
2. The second se					1.11 <sup>1</sup>	hn Wiley & Sons		
1. M 2. Th <b>Referen</b> 1. Fr	undamentals o	of Materials Scien				ini whey & sons,		
1. M 2. Tl Referent 1. Fr 2. M	undamentals of Iechanical Me	etallurgy, George	E. Dieter, McGrav	w Hill Book Cor		ini whey & sons,		
1. M 2. Tl <b>Reference</b> 1. Fr 2. M 3. T	undamentals of fechanical Me heory of Plast	etallurgy, George ticity, J. Chakraba	E. Dieter, McGrav rty, Elsevier, 200	w Hill Book Cor 6	npany, 1988	ini whey & Sons,		
1. M 2. Tl <b>Referen</b> 1. Ft 2. M 3. T 4. Fe	undamentals of fechanical Me heory of Plast oundations of	etallurgy, George ficity, J. Chakraba Theory of Plastic	E. Dieter, McGrav	w Hill Book Cor 6 lov, Dover Publi	npany, 1988 cations, 2004	ini wiley & Sons,		

Progra			(Design Engineer			Semester : I	
Course			is of Mechanisms	s (Professional		Code: MMD15	01C
	Те	aching Scheme				ation Scheme	
L	ecture	Hours	Credit	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Prior k	nowledge of						
		y of Machines is e	essential				
Course	Objectives:		1 1				
			nalysis of simple a ries to synthesize r		chanisms		
Course	Outcomes:	Ty killematic theor	les to synthesize i	nechanisms			
		urse the students	should be able to:				
			nplex Mechanisms				
			rvature and design		h dwell		
	3. Synthe	size mechanisms	using graphical m	ethods			
	4. Apply	kinematic theorie	s to synthesis of m				
	T		Det	t <mark>ailed Syll</mark> abus	Sector Sector		I
Unit			D	escription			Duration
	Vincetia	analusia of simul		-		+	(H)
1.		analysis of simpl		of freedom	Graphical met	thod of velocity a	nd 7
1.		analysis of simp		of ficedoffi,	Graphical file	thou of velocity a	
		, 1	plex mechanisms	_			
2.					sis of complex	x mechanisms by t	he 8
			and Auxiliary Poi				
	Curvature					- C	
3.			s, Center of curva	ature, cubic of	stationary curva	ature, Inflection circ	le, 7
	Balls point.						-
			isms - Graphical		) mainta Chaha		- 6
4.						ychev spacing, types	
			re pole method & ]			ice with two and thr	ee
-			isms - Graphical		u		-
5.					d body guidance	e tasks (two, three a	nd 7
		n) for with and w		U		, í	
			nisms - Analytical				
6.						nthesis of slider cra	
••		, Complex numb	ers method of syr	nthesis, Synthes	is using dyad r	nethod (two and thr	ee
	position)	11-1-11	and staffs, a	an way to	1.4.1.2.2.241	T	45
Text B						To	tal 45
		hines and Mechar	uisms, A. Ghosh aı	nd A K Mallik	Affiliated East-	West Press	
			isms, J. E. Shigley				
						hanisms and Machin	nes, Robert l
		IcGraw-Hill,3rd E					
	•		n McGraw-Hill Pi		1		
		nd Machine Theor	y- A.G. Ambekar.	. PHI Learning I	vt. Ltd.		
	nce Books:						_
1. M	lechanism De	sign- Analysis an	d Synthesis (Vol.1	and 2), A.G. Er	dman and G.N.	Sandor, Prentice Hal	1.

Kinematic Synthesis of Linkages, R.S. Hartenberg and J. Denavit, McGraw-Hill.

110grun	m: M. T	ech. Mechanical	(Design Enginee	ring)		Semester : I		
Course			ds in Engineering		Elective-I)	Code: MMD1	501D	
	Te	aching Scheme			Evalua	tion Scheme		
Le	ecture	Hours	Credit	IE1	IE2	ETE	Т	<b>`otal</b>
	3	3	3	20	30	50	]	100
Prior k	nowledge of							
a.	Differential	and Integral Calc	ulus is essential					
	<b>Objectives:</b>							
			ts will have adequ	uate background	, conceptual cla	rity and knowledg	ge of ma	thematical
	es related to:							
1.			rs to solve Mass s		•			
2. 3.			nd Fourier transfo		ions			
3. 4.			rical methods to so nize functional pro					
	Outcomes:	variation to optim	nze runetionai pre	orems.				
		urse, the students	should be able to:					
1.					lve mass spring	g system.Solve pr	oblems	related to
			ations to Design <mark>E</mark>					
2.			s solution in speci	ial functions				
3.		ical solution of PI						
4.	Analyse the	functional optimi	zation using diffe		gy.			
			Det	ailed Syllabus:				
Unit	1.1		D	a a a win ti a m				Duration.
				escription				(H)
1.	Basic conce	ept of Laplace Tra	nsforms, Laplace		its inverse.			,
1. 2.	Laplace tra Differential	nsform of special Equations.	nsforms, Laplace functions: Unit s	transforms and i step, Unit impul	se, Periodic and	d Error. Application	-	(H)
	Laplace tra Differential Mass sprin	nsform of special Equations. g systems of m	nsforms, Laplace functions: Unit s	transforms and istep, Unit impul	se, Periodic and mulation for d	ifferential equation	-	(H) 7
2.	Laplace tra Differential Mass sprin vibration th	nsform of special Equations. g systems of me eory, Normal mod	nsforms, Laplace functions: Unit s alti degree freed le solution, Nume	transforms and step, Unit impul om, Matrix for prical computation	se, Periodic and mulation for d on of Eigen valu	ifferential equation	ons in	(H) 7 8
2. 3.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h	nsform of special Equations. g systems of me eory, Normal moo tion of differentia f Variation Introd igher order derive	nsforms, Laplace functions: Unit s ulti degree freed de solution, Nume l equations, Besso uction, Functiona ative, Approxima	transforms and a step, Unit impul om, Matrix for prical computation el's and Legend I, Euler's equation	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet	ifferential equatione.	ons in square ctional	(H) 7 8 7
2. 3. 4.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif	nsform of special Equations. g systems of me eory, Normal moo tion of differentia ? Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, <i>I</i>	nsforms, Laplace functions: Unit s alti degree freed le solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis,	transforms and istep, Unit impul om, Matrix for crical computation el's and Legend 1, Euler's equat te solution of bo oal. Explicit and Im ite difference ar	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound	ifferential equations. Least service Problem, Functions Problem, Function Problem, Rayleigh Prence scheme, State ary value problem	ons in square ctional –Ritz ability	(H) 7 8 7 8 8
2. 3. 4. 5. 6.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona	nsform of special Equations. g systems of me eory, Normal moo tion of differentia ? Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, <i>I</i>	nsforms, Laplace functions: Unit s alti degree freed le solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin	transforms and istep, Unit impul om, Matrix for crical computation el's and Legend 1, Euler's equat te solution of bo oal. Explicit and Im ite difference ar	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound	ifferential equation e. equations. Least s ric Problem, Func problem, Rayleigh erence scheme, Sta ary value problem	ons in square ctional –Ritz ability	(H) 7 8 7 8 7 8 7
2. 3. 4. 5. 6. Text Bo	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona	nsform of special Equations. g systems of me eory, Normal moo tion of differentia f Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, A I diffusion equatio	nsforms, Laplace functions: Unit s ulti degree freed de solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation	transforms and a step, Unit impul om, Matrix for crical computation el's and Legend al, Euler's equation te solution of bo oal. Explicit and Im ite difference ar a, Laplace equation	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe aalysis in bound on.	ifferential equation e. equations. Least s ric Problem, Func problem, Rayleigh erence scheme, Sta ary value problem	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona	nsform of special Equations. g systems of me eory, Normal moo tion of differentia ? Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, A I diffusion equation	nsforms, Laplace functions: Unit s alti degree freed de solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation	transforms and a step, Unit impul om, Matrix for prical computation el's and Legend and Legend and Legend te solution of bo pal. Explicit and Im ite difference ar an, Laplace equation	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound ion.	ifferential equation e. equations. Least s ric Problem, Func problem, Rayleigh erence scheme, Sta ary value problem	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1. 2.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona	nsform of special Equations. g systems of me eory, Normal moo tion of differentia ? Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, A I diffusion equation	nsforms, Laplace functions: Unit s ulti degree freed de solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation	transforms and a step, Unit impul om, Matrix for prical computation el's and Legend and Legend and Legend te solution of bo pal. Explicit and Im ite difference ar an, Laplace equation	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound ion.	ifferential equation e. equations. Least s ric Problem, Func problem, Rayleigh erence scheme, Sta ary value problem	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1. 2. Referen	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona <b>Doks:</b> Higher Eng Advanced E <b>Dice Books:</b>	nsform of special Equations. g systems of me eory, Normal moo tion of differentia ? Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, <i>A</i> 1 diffusion equation ineering Mathema	nsforms, Laplace functions: Unit s alti degree freed le solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation	transforms and i step, Unit impul om, Matrix for rical computation el's and Legend 1, Euler's equation te solution of bo oal. Explicit and Im ite difference ar an Laplace equation the computation of the computation of the pal.	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound on.	ifferential equationer equations. Least service Problem, Functoroblem, Rayleighter erence scheme, Statary value problem	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1. 2. Referen 1.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona <b>Doks:</b> Higher Eng Advanced E <b>Dice Books:</b>	nsform of special Equations. g systems of me eory, Normal mod tion of differentia f Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, <i>A</i> I diffusion equation ineering Mathema Engineering Mathema	nsforms, Laplace functions: Unit s ulti degree freed le solution, Nume l equations, Besse uction, Functiona ative, Approximat Lagrange's princip fference analysis, Applications of fin on, Wave equation thics by B.V. Ram ematics by Erwin	transforms and in step, Unit impul om, Matrix for prical computation el's and Legend 1, Euler's equation te solution of boo oal. Explicit and Im ite difference ar ana (Tata McGr Kreyszig (Wiley eter V. O'Neil (T	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet pundary value p plicit finite diffe alysis in bound on. aw-Hill). 'Eastern Ltd.)	ifferential equationer equations. Least service Problem, Functoroblem, Rayleighter erence scheme, Statary value problem	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1. 2. Referen 1. 2.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona Ooks: Higher Eng Advanced E Advanced E	nsform of special Equations. g systems of me eory, Normal mod tion of differentia F Variation Introd igher order deriva- lerkin's method, I Analysis Finite di ference method, A I diffusion equation ineering Mathema Engineering Mathema	nsforms, Laplace functions: Unit s ulti degree freed le solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation tics by B.V. Ram ematics by Erwin ematics, 7e, by Pe	transforms and a step, Unit impul om, Matrix for rical computation el's and Legend al, Euler's equation te solution of bo bal. Explicit and Im ite difference an ana (Tata McGr Kreyszig (Wiley eter V. O'Neil (T D. Greenberg (	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet oundary value p plicit finite diffe alysis in bound on. aw-Hill). / Eastern Ltd.) // homson Learnin Pearson Educati	ifferential equations. Least service of the service	ons in square etional –Ritz ability as, one	(H) 7 8 7 8 7 8 8
2. 3. 4. 5. 6. Text Bo 1. 2. Referen 1.	Laplace tra Differential Mass sprin vibration th Series Solu solution Calculus of involving h method, Ga Numerical of finite dif dimensiona Ooks: Higher Eng Advanced E Higher Eng Higher Eng	nsform of special Equations. g systems of me eory, Normal mod tion of differentia Variation Introd igher order derive lerkin's method, I Analysis Finite di ference method, A I diffusion equation ineering Mathema Engineering Mathema Engineering Mathema	nsforms, Laplace functions: Unit s ulti degree freed le solution, Nume l equations, Besso uction, Functiona ative, Approxima Lagrange's princip fference analysis, Applications of fin on, Wave equation ematics by B.V. Ram ematics by Erwin ematics, 7e, by Pe ematics, 2e, by M. tics by B. S. Grev	transforms and a step, Unit impul om, Matrix for rical computation el's and Legend al, Euler's equation te solution of bo bal. Explicit and Im- ite difference and the difference and the difference and the difference and the difference and the difference and the difference and the difference and the difference and the difference and th	se, Periodic and mulation for d on of Eigen valu re's differential ion, Isoperimet oundary value p plicit finite differential on. aw-Hill). / Eastern Ltd.) // Comson Learnin Pearson Education plication, Delhi)	ifferential equations. Least service of the service	ons in square etional –Ritz ability is, one <b>Total</b>	(H) 7 8 7 8 7 8 7 8 45

Prog	gram:	M. Tech. Mechanical			Semester :		
Cou	rse :	Mechanics of Compo	sites (Profession	al Elective-II)	Code : MN		
		Teaching Scheme				tion Scheme	
L	ecture	Hours	Credit	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Prio	r knowled						
		dvanced Stress Analysis					
Соц	b. M rse Object	Ianufacturing Processes.					
Cou	•	o make aware the studer	nts about various o	composites mate	rials and their ar	nlications	
		o enable the students to				prioutions.	
Cou		mes: After learning the					
	1. E	xhibit the ability to choo	se appropriate typ	pe of composite	for the given app	plication.	
		nderstand and apply the					
		hoose appropriate theory					
		nalyze the composite la		esses and stiffnes	SS.		
	5. D	esign the simple composition		1 1 9 11 1			
			Deta	ailed Syllabus:	110		Duration
Unit			Des	cription			(H)
	Introduc	tion to Composite Mat	erials				(11)
		ion, Classification, Poly		nposites. Metal	Matrix Compo	sites. Ceramic Matrix	
1.	Composit						7
	Terminol						
		echanical Analysis of a		and the second sec			
		ion, Review of Definit					
		Types of Materials,					
2.		nally Anisotropic)/Speci					8
		hip of Compliance an ng Constants of an Ang					
	Angle La		le Lamma, mvan		intess and Com	pliance matrices for an	
	U	Failure Theories of an	Angle Lamina				
		m Stress Failure Theory		, Failure Envelo	opes, Maximun	n Strain Failure Theory	
3.		ill Failure Theory, Tsai					7
	Theories,	Hygrothermal Stresses	and Strains in a	Lamina, Hygro	thermal Stress-S	Strain Relationships for	
	a Unidire	ctional Lamina, Hygrot	hermal Stress-Str	ain Relationship	s for an Angle L	amina.	
		chanical Analysis of a					
		ion, Volume and Mass					
4.		, Density, Void Conten					8
		Plane Shear Modulus , Expansion.	Elasticity, Utilina	ate, Coefficients	of Thermal Exp	bansion Coefficients of	
		echanical Analysis of l	aminates				
		tion, Laminate Code		Relations for a I	Laminate . One-	-Dimensional Isotropic	
_		ess-Strain Relation, St					-
5.	and Mom	ent Resultants Related t	o Mid-plane Strai	ins and Curvatur	res, In-Plane ar	nd Flexural Modulus of	7
		ate, In-Plane Engineeri	ng Constants of	f a Laminate, 1	Flexural Engine	eering Constants of a	
	Laminate						
		Analysis, and Design of					
		ion, Special Cases of L s, Anti-symmetric Lam					
6.		for a Laminate, Design					8
		Composites, Long-Te					
		Resistance, Fatigue Res		,,,,,,,, .		, r	
						Total	45
Refe	erence Boo						
		anics of Composite Mate					
		eering Mechanics of Con			el and Orilshai, (	Oxford University Press.	
		anics of Composite Mate anics and Analysis of Co			ilion and Eugen	V Morozov Elsovier	
	4. Mecha	and and Analysis of CC	mposite material	s, vaici y v. vas	sinev and Evgen	y v. morozov, Ersevier	

Cours	am: M. T	ech. Mechanical	(Design Enginee	ring)	Semester :	Ι	
			(Professional Ele	ctive-II)	Code : MN		
	Те	aching Scheme			Evalua	tion Scheme	
Ι	Lecture	Hours	Credit	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Prior	knowledge of:		•				
а	a. Fluid Mecl						
ł	-	g Metallurgy					
		Materialsa	are essential				
	e Objectives:			d ala:11a in En ain			
		friction, wear and				y with design aspect design and maintena	nce of machin
-	-		g with design of h	earing friction	wear test rig for	laboratory purpose	
	e Outcomes:	nunds on dumm	5 with design of b	euring, metion,	in our tost ng tor	inconnory purpose	
		urse, the students	will be able to:				
						e physics of the proc	cess.
			to suggest a tribo				
					rameters using	various bearing chart	s.
			g in different lubri				
			pacity in air lubric		understand the s	olution to avoid wea	r and friction
0	. understand ti	e tribbiogreat asp		ailed Syllabus:	understand the s	oration to avoid wea	r and menon.
							Duration
Unit	1.5		Des	scription			( <b>H</b> )
	Friction and	wear					
1.						roperties of bearing	7
			ries of friction and	<mark>l wear, Inst</mark> abilit	ies and stick-sli	p motion	
	Lubrication		1.12	1	T1 1 11		
2						rings, Infinitely long w) journal bearings,	
2.					ery short (narro	w) journal dearings.	
			g journal ocaring	(Petroff's solut			
		c and inflist off <b>D</b>				arings - hydrostatic,	
			earings, Heat in be				
3.		squeeze film	earings, Heat in be	earings	tion), Finite bea	arings - hydrostatic,	
3.	Circular and	squeeze film	earings, Heat in be	earings	tion), Finite bea		
3.	Circular and application to	squeeze film rectangular fla journal bearings	earings, Heat in be	earings e and alternati	tion), Finite bea	arings - hydrostatic, on pin lubrications,	7
3. 4.	Circular and application to Elasto-hydro Pressure-viso	squeeze film rectangular fla journal bearings	earings, Heat in be	earings e and alternati	tion), Finite bea	arings - hydrostatic,	7
	Circular and application to Elasto-hydro Pressure-visc spheres	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re	earings, Heat in be	earings e and alternati	tion), Finite bea	arings - hydrostatic, on pin lubrications,	7
	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b>	squeeze film rectangular fla journal bearings odynamic lubrica osity term in Re ed bearings	earings, Heat in be it plates, variable ation ynold's equation,	earings e and alternati hertz theory, E	tion), Finite bea	arings - hydrostatic, on pin lubrications, ation, lubrication of	7
4.	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b	squeeze film rectangular fla journal bearings odynamic lubrica osity term in Re ed bearings earings, hydrostat	earings, Heat in be it plates, variable ation ynold's equation, tic, hydrodynamic	earings e and alternati hertz theory, E	tion), Finite bea	arings - hydrostatic, on pin lubrications, ation, lubrication of	7
4. 5.	Circular and application to Elasto-hydro Pressure-visc spheres Air lubricate Tilting pad b Tribological	squeeze film rectangular fla journal bearings odynamic lubrica osity term in Re ed bearings earings, hydrostat aspects of Rollin	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion	e and alternati hertz theory, E and thrust beari	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7
4.	Circular and application to Elasto-hydre Pressure-visc spheres Air lubricate Tilting pad b Tribological Mechanics or	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip an	e and alternati hertz theory, E and thrust beari d rolling resistar	tion), Finite bea ng loads, pisto artel-Grubin equings with air lub ace, tribological	arings - hydrostatic, on pin lubrications, ation, lubrication of	7 8 7
4. 5.	Circular and application to Elasto-hydre Pressure-visc spheres Air lubricate Tilting pad b Tribological Mechanics or	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion	e and alternati hertz theory, E and thrust beari d rolling resistar	tion), Finite bea ng loads, pisto artel-Grubin equings with air lub ace, tribological	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7
4. 5. 6.	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, t	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip an	e and alternati hertz theory, E and thrust beari d rolling resistar	tion), Finite bea ng loads, pisto artel-Grubin equings with air lub ace, tribological	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
<ol> <li>4.</li> <li>5.</li> <li>6.</li> </ol>	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics of rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip and ts of metal rolling, ation, Camaron, L	e and alternati hertz theory, E and thrust beari d rolling resistan , drawing and ex ongman's Green	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text F	Circular and application to <b>Elasto-hydro</b> Pressure-viso spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, to <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip and ts of metal rolling.	e and alternati hertz theory, E and thrust beari d rolling resistan , drawing and ex ongman's Green	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text F	Circular and application to <b>Elasto-hydro</b> Pressure-viso spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri ence Books:	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect nciples of Lubrica bology in Machir	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip and ts of metal rolling, ation, Camaron, L ne Design, T. A. S	earings e and alternati hertz theory, E and thrust beari d rolling resistan drawing and ex ongman's Green tolarski	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text H	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricat</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri ence Books: <b>1.</b> Fundan	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect bology in Machir mental of Friction	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip and ts of metal rolling. ation, Camaron, L ne Design, T. A. S and Wear of Meta	earings e and alternati hertz theory, E and thrust beari d rolling resistan drawing and ex ongman's Green tolarski	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text H	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics of rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri ence Books: <b>1.</b> Fundan 2. The De	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect bology in Machir hental of Friction sign of Aerostatic	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip an ts of metal rolling, ation, Camaron, L ne Design, T. A. S and Wear of Meta 2 Bearings – J. W.	earings e and alternati hertz theory, E and thrust beari d rolling resistan drawing and ex ongman's Green tolarski	tion), Finite bea ng loads, pisto rtel-Grubin equ ngs with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text F	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri <b>ence Books:</b> <b>1.</b> Fundan 2. The De 3. Gas Be	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect bology in Machir hental of Friction sign of Aerostatic arings – Grassam	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip an- ts of metal rolling, ation, Camaron, L ne Design, T. A. S and Wear of Meta c Bearings – J. W. and Powell	e and alternati hertz theory, E and thrust beari d rolling resistan drawing and ex ongman's Green tolarski als – ASM Powell	tion), Finite bea ng loads, pisto artel-Grubin equings with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8
4. 5. 6. Text F	Circular and application to <b>Elasto-hydro</b> Pressure-visc spheres <b>Air lubricato</b> Tilting pad b <b>Tribological</b> Mechanics or rail contact, t <b>Total</b> <b>Books:</b> <b>1.</b> Pri <b>2.</b> Tri <b>ence Books:</b> <b>1.</b> Fundan 2. The De 3. Gas Be 4. Theory	squeeze film rectangular fla journal bearings odynamic lubric: osity term in Re ed bearings earings, hydrostat aspects of Rollin f tire-road interac ribological aspect bology in Machir hental of Friction sign of Aerostatic arings – Grassam Hydrodynamic L	earings, Heat in be at plates, variable ation ynold's equation, tic, hydrodynamic ng motion tion, road grip an ts of metal rolling, ation, Camaron, L ne Design, T. A. S and Wear of Meta 2 Bearings – J. W.	e and alternati hertz theory, E and thrust beari d rolling resistan drawing and ex ongman's Green tolarski uls – ASM Powell sh and Sterrolich	tion), Finite bea ng loads, pisto artel-Grubin equings with air lub nce, tribological trusion	arings - hydrostatic, on pin lubrications, ation, lubrication of rication	7 8 7 8

Progr				(Design Engine		Semester			
Cours	e :		,	Professional Elec	tive-II)		MD1502C		
			g Scheme	<b>a 1</b>			ation Scheme		
	Lecture		Hours	Credit	IE1	IE2	ETE		Fotal
Duion	3		3	3	20	30	50		100
a. b. c.	Automo Mechani	of Machine a bile Enginee cal Vibratior	ring,						
1. 2. 3.	To deve To make	aint with veh lop an ability e aware the s	y to evaluate tudents abo	parameters & vel the performance ut the road dynan	of vehicle				
1. 7 2. 7 3. 7 4. 7 5. 7	To invest To exami To interp To analyz	igate ISO and ne vehicle T ret Vibration we the road he op physical a	d SAE vehic ire model fo al behavior olding and d nd mathema	tical models to p characteristic of c	stem as of human res y of two axel v redict the dyna <mark>juarter car</mark> mod	ponse ehicles at differe mic response of el of an automol	ent steering inputs vehicles bile with different		citations.
Unit		12			ailed Syllabus escription	:	1	0	Duration, (H)
1	Tyre n Electrie	c, Hybrid a	ehicle tyre nd Autonor		hicle, Differen	t modeling sof	n, Basic informa tware used for ards		7
2	Perfor Equation vehicle	mance char on of motion performance	acteristics of and maxi ce, acceler	of road vehicles mum tractive eff	fort, Aerodynai distance, grade	mic forces and <mark>eabili</mark> ty, Introdu	moments, Predic ction of Static		8
3	Brakin charact		stics of a t Tractor-Ser	nitrailer, Antiloch			pping distance, F ol systems, Straig		7
4.	Handl Steady Testing	ing characte -state handli g of handling	eristics of ve ng characte characterist	ehicle			ponse to steering al stability	g input,	8
5.	Humar and ur irregula	-sprung ma	vibration, ss, Numeric ofile excitat	cal methods for	determining th	ne response of	ehicle model for a quarter-car mo bitch and bounce,	odel to	7
6.	Road - betwee	n input and o	aspects, de output, effec	terministic profil	K&C characteri	zes and differen	lation function, 1 t type of roads an		8
								Total	45
1. 2.	Rajesh ence Boo Road V	Rajamani, V oks: /ehicle Dyna	ehicle Dyna mics – Prob	Application, Raza amics & control, olems & Solutions 7. Wong, John W	Springer. 5, Rao & Dukki	-	al Edition		

Progra		I. Tech. Mechanical		ering)	Semester :			
Cours	e: R	obotics (Profession	al Elective-II)		Code : MN			
		Teaching Scheme			Evalua	tion Scheme		
Ι	Lecture	Hours	Credit	IE1	IE2	ETE	Total	
	3	3	3	20	30	50	100	
	knowledge							
a.		f Machines						
b.		· ·						
c.		Electrical and Electr	onics Engineering	gare essen	tial			
	e Objective		1					
1.	-	quainted with basic c	-	otic systems.				
2.		stand grippers, sensor						
3.		stand statistics & kine						
4.		stand dynamics of rol	oot.					
	e Outcome							
		course, the students s		1 6	1. 6			
1.	•	lifferent type of robot	-					
2.	11.2	H parameters to a rob			he kinematic par	ameters.		
3.		e velocities and static		nipulator.				
4.		dynamic analysis of the	-					
5.		able trajectory to the	-					
6.	Select ne	cessary actuators, sen			ormance of the r	obot.		
		22.0	Det	ailed Syllabus				
Unit	12		De	scription			Dura (H	atioı H)
	Introduct							
1.		classification and app				ce of robot. Positi	ions, 7	7
		ns and frames of a rig	id body, homoger	neous transform	ations.			
		ator kinematics	· · · · · · · · · · · · · · · · · · ·		10 C 10 C			
2.		ation of joints and lin		Hartenberg para	ameters, direct a	nd inverse kinema	atics 8	8
		Frames with standard	l names.					
		and static forces	C 11 1 1 1			1. 0. 1		_
3.		nd angular velocity		ty propagation,	manipulator J	acobians, Singula	arity 7	7
_		Static forces in manip	ulators					
4		s of robots	lengtion of links	Leanensien fem				0
4.		inertia of links, Acce formulation, Dynamic		Lagrangian for	mulation for dyr	iannes, newton-e	uler a	8
		y generation	, Simulation.	Li denero	++ v v u u	111		
5.	•	tions in path descr	intion Joint sna	ace schemes (	artesian snace	schemes Geom	etric /	7
5.		with paths.	iption, some spe	ce senemes, c	urtesiun spuce	senemes, Geom		,
		s, Sensors and Gripp	hers	-				
6.		al, Hydraulic and Pne		internal and ext	ternal state sense	ors used for robots	s. 8	8
	types of g		,				,	-
	<u>, 1 c</u>	11				Т	otal 4	5
Text B	looks:						I	
1	John Cra	ig, Introduction to Ro	botics, Mechanic	s and Control, 3	rd Edition, Pear	son Education, 20	09	
1.		0				elligence, McGrav		
1. 2.	K.S. Fu,	R.C. OonZaics, C.D.C				<b>U</b> /	-	
		a, Introduction to Ro		lition, McGraw	Hill Education.	2014		
2. 3.		a, Introduction to Ro		lition, McGraw	Hill Education, 2	2014		
2. 3.	S. K. Sah ence Books	a, Introduction to Ro	botics, Second Ed				on, 2015.	
2. 3. Refere	S. K. Sah ence Books S B Niku	a, Introduction to Ro	botics, Second Ec	ontrol, Applicat	ions, 2nd Edition		on, 2015.	

- 3. A Ghosal, Robotics: Fundamental Concepts and Analysis, Oxford University Press, 2013.
- 4. R K Mittal & I J Nagrath, *Robotics and Control*, McGraw Hill Publication, 2015.

Progra	m: M.Tech Mechanical	Design Eng	(ineering)		Semester :	I	
Course				<b>I</b> )	Code : MN		
	Teaching Scheme	, i i i i i i i i i i i i i i i i i i i			uation Scheme		
Practi	ical Hours	Credit	TW	PR	OR	To	tal
2	2	1	50		50	10	0
	nowledge of:						
Course	Objectives:						
	This course is to provide stud	dents the too	ols required for Si	mulate correla	ate and validate t	heoretical co	oncepts and
	understand the principles. Outcomes:						
	arning the course the students	should be ab	le to				
	Solve open ended Design prob						
	Simulate the problem and corr						
	Understand the impact of assu			ts			
	Collect data, Analyse, interpre	t and report	the results.				
Guideli		A and Dant	Des non stadauts a	1			
1. 2.	Any one subject from Part. Total experiments to be cond						
2. 3.	Total : 6 experiments 12 ho			and Three II			
0.			Detailed Sy	llabus:			
	Par	t A: Electiv	e 1- Advanced M		(ANY Three)		
Fynt			Description				Duration,
Expt.			Description				<b>(H</b> )
1.	Case Studies Based on : Fail						2
2.	Case Studies Based on : Env						2
3.	Case Studies Based on : Des						2
4.	Case Studies Based on : Des			oility.			2
5.	Case Studies Based on : Des	ign based on	Cost			Total	<u>2</u> 06
	Part A · Fla	ctive 1- Me	chanical Behavior	of Materials	(ANV Three)	Total	UO
Expt.			Description	of Materials			Duration, (H)
1.	Elasto-plastic analysis of a te	ensile test sp	ecimen using FEM	software			2
2.	Determination of full range s E8M				m specimen as pe	er ASTM -	2
3.	Experimental verification of	Three point	bending test				2
4.	Tensile test for polymer and						2
5.	Impact test for plastic	while the	the Chickense	to President	doon.		2
						Total	06
	Part A: Elect	ive 1- Analy	sis and Synthesis	of Mechanisr	ns (ANY Three)	)	
Expt.			Description				Duration,
1.	Kinematic analysis of simple	machanism	-				(H) 2
2.	Kinematic analysis of simple						2
<u> </u>	Curvature analysis simple pla						2
4.	Graphical Synthesis of path						2
5.	Graphical Synthesis of funct	ion generatin	ng mechanism				2
6.	Graphical Synthesis of rigid						2
7.	Analytical Synthesis of path						2
8.	Analytical Synthesis of funct						2
9.	Analytical Synthesis of rigid	body guidin	ig mechanism, usir	g MATLAB			2
						Total	06
	Part A: Electi	ve 1- Math	ematical Methods	in Engineeri	ng (ANY Three)	)	D (1
Expt.			Description				Duration,
1.	Solution using Matlab for Po	wer Method	-				(H) 2
2.	Solution using Matlab for M						2
3.	Solution using Matlab for Le						2
4.	Solution using Matlab for Nu			uation.			2
5.	Solution using Matlab for Nu						2
	-					Total	06

Expt	Part B: Elective 2- Mechanics of Composites (ANY Three) Description	Duration, (H)
1.	Analytical determination of strength of lamina using properties of matrix and fibres.	2
2.	Compare the theories of failure for the composite lamina using analytical formulation	2
3.	Study of various test standards for behavior testing of composite laminates.	2
4.	Determination of the stress distribution across various layers of a laminate using Classical Laminate Theory.	2
	Total	06
	Part B: Elective 2- Tribology in Design (ANY Three)	1
Expt	Description	Duration, (H)
1.	Case study on Tribological aspects of rolling motion / Tribo-characteristics of different materials / Evaluation of friction & wear through experiments under influencing parameters. Coefficient of friction using pin-on-disc type friction monitor	2
2.	Friction in Journal Bearings	2
3.	Four Ball Tester	2
4.	Study of Lubricating systems with example	2
5.	Journal Bearing Apparatus	2
6.	Tilting pad and thrust bearing apparatus	2
	Total	06
	Part B: Elective 2- Vehicle Dynamics (ANY Three)	
Expt	Description	Duration, (H)
1.	Assignment on Road holding characteristics of vehicle and its control	2
2.	Assignment on analysis and optimal control of car ride model	2
3.	Assignment on ABS or Power-steering for handling analysis - single lane event	2
4.	To simulate and understand behavior of sprung / un-sprung mass & lumped mass system MBD software.	2
	Total	06
	Part B: Elective 2- Robotics (ANY Three)	
Expt	Description	Duration, (H)
1.	Simulation of Cartesian/ cylindrical/ spherical robot.	2
2.	Simulation of Articulated/ SCARA robot.	2
3.	Virtual modelling for kinematic and dynamic verification of any one robotic structure using suitable software.	2
4.	Design, modeling and analysis of gripper	2
	Total	06

## **Course Syllabus Open Electives - I**

Program	m: M. Tech	<mark>. Compu</mark> ta	tional Mechanics	s (Mechanical Eng	ineering)	Semester: I		
Course				ehicles (Open Elec		Code: MMC1601	4	
	Teachi	ng Scheme			Evalu	ation Scheme		
Lectur	re Ho	urs	Credit	IE 1	IE 2	ETE	Т	'otal
2	2		2	20		30		50
Prior kn	owledge of:							
a.	Basics of Electr	ical Engine	ering,					
	<b>Objectives:</b>							
					pes of batterie	es used for EV application	ations	5
			nts of battery mai					
				ent Circuit Cell Mo	deling of Bat	tery		
			sant with SOC est					
				Pack Balancing and				
		mers aware	of thermal issues	of Lithium Ion batte	ery and therm	al management system	n	
	Outcomes:							
	rning the course,				100 C			
						ments of battery mana	ageme	ent systems
				f a battery using eq				
		and SOH c	of battery and dem	onstrate understand	ling of variou	s methods of battery	pack	
	balancing	1.1				1 C		
4. '	To estimate heat	generation		propose cooling str	ategy for the	battery pack.		
			E	etailed Syllabus:		1. The second		1
Unit				Description				Duration
	-	_		-				(H)
			anagement syste					
					ctrochemical	cells, Lithium- Ion (	Cells	
1.			ons and compone	ents of BMS				_
	BMS design re					<b>C</b> 11 1 1		7
						f cell and battery p		
		ell SOC and	l battery pack SC	C, Estimation of a	vailable ener	gy and power of cell	and	
	battery pack							_
	Equivalent Cir			1			1.1	
2						nce, Estimation of M		0
2.						re dependence of O		8
		eresis, usin	g the ECM to	simulate constan	t voltage/ p	ower charge/ disch	arge	
	characteristics			(/ <b>D</b>   <b>D</b>   ·				
				ttery Pack Balanci				
2						of SOC estimation: li		
3.						g, criteria for specifyi		7
						nethods for battery pa		
						ansformer-based circ	unts,	
				simplified cell mo	del			
4	Battery Therm				Dettern One			
4.						rating temperature ra		ø
						ermal management :		8
		cooning, PC.	wi based cooling	, effect of paramete	rs like cell al	rangement, spacing,	ilula	
	velocity etc.					7	1-4-1	20
Doform							otal	30
	nce Books:	t Dottom	anagament Counter	ma Voluma I. D	Modelie -	Artaah Uawaa I	<b></b>	
1. 2						, Artech House, Lond		
2.		і, Dattery M	anagement Syste	ins volume II, Equi	valent-Circui	t Methods, Artech Ho	Juse,	
2	London Gianfranco Pist	oio Domici	n Lion Dahanian	r of Lithium Iar D	ttorios in Fl-	atria Vahialas Datta		alth
3.						ctric Vehicles_Batter	гу не	aitn,
А				rnational Publicatio		nol Dublingting		
4.	Kenner_Korthat	ier, LI-I Bat	terres basics and	Applications, Sprin	ger mernatio	nai Publication		

Program				al Engineering)	Semester : I	
Course	: Green Technology Teaching S		ve-1)		Code : MMC1601B Evaluation Scheme	
Lecture		Credit	IE1	IE2		Total
2	2	2	20		30	50
b. T Course O 1. I 2. I 3. 4 4. 4 Course O 1. 4 2. I 3. 4	nvironmental study, ypes of pollutiona bjectives: After Comple Evaluate Global warming Demonstrate knowledge Apply control measures Apply high tech measures utcomes: After learning Analyse effects of Globa mplement the concept o Apply remedial action fo Apply high tech measure	ting this course g and its effect in the reduction of carbon emiss s for Reducing the course, the l warming f reduction of g r the carbon em	n of global warm sion and accumu Carbon Emissio students should global warming hission and accum	ing. lation. ns. be able to: nulation.	ground to:-	
Unit	1.1.1	-	Detailed Syl		10	Duration,
	1.1.1					<b>(H</b> )
Car Abs Prov 1. Pla univ Ger Loc	bon Problem: Accumulator orption in Nature, The cocols and its view in Inconning for the Future versally, Use of Promoteral Approach in Planning	ation, Long Ha Global Emiss lia, Effect of cli to reduce glu tional and Pun ing for the Futu Mitigative Meas	alf-Life, Heating sion Situation a imate change an <b>obal warming:</b> itive Mechanisn are, Developing sures for Global	Potential, Carbo nd its effect in I d its impact. - Steps taken to ns for Reducing Countrywide Ada Reduction of Car	f global warming, the New on Emission Factors, Carbon ndia, The Kyoto and Other Control Carbon Emissions Carbon in Atmosphere, The ptive Measures for Safety of rbon, India's National Action lia, The MRV Debate.	7
Car Indi Sou 2. Def Mea Gre Cos	bon Emissions and Accu a for control of carbon rces in India, A Logic orestation and paymen chanisms at India. cen Technologies for E	amulation, Proc emissions and cal Approach f it rates procec nergy Product Typical System	edure to develo accumulation, for Carbon Red lure for contro tion:- Various T s for Power Gen	p own Priorities a Needs a Mix of C uction, Need in lling carbon emi cechnologies Avai eration, Sources o	ssential Steps for Control of nd Business Opportunities in Green and Traditional Power India — More Forests, Less ssions and its Promotional lable for Energy Production, of Energy Production Already me Prior R&D Work.	8
Gre Car City Gre 3. Ene Tra: Indu Are	<b>en Technologies for P</b> bon Emission Reductio wide Level, Carbon Em <b>ren Technologies for</b> rgy Conservation Build nsport, Green Roads, Po ustries in India, The Cha	ersonal and C n at Personal issions from In Specific Appli ding Code (EC orts and Harbor anging Scenario ojects ,'Green'	<b>Stywide Applic</b> Level, Carbon ports. <b>ications:-</b> Prom CBC), Green He rs, Industries, Ca o in Cities, Need Infrastructure f	ation :- Measures Emission Reduct otion of 'Green' otels and Hospita rbon, Carbon Em l for Wider Applie for Municipal Se	s to be taken for Green city, ion at Local Authority and Buildings, Guidelines, The als, Green Technologies for issions from a Few Selected cation to Town Planning and rvices, Bringing up Indian	7
4. Sys Mis	tems, Use of Carbon Cap ommended Plan of A	oture and Storagetion :- India's wareness, Few	ge (Sequestration s National Action case studies o	n) ,Microorganism n Plan Take Us n Projects undert		8
2. As 3. As 4. As <b>Text Bool</b> 1. So <b>Reference</b>	signment based on Glob signment based on Cont signment based on Appl signment based on High ss: li J. Arceivala, Green Te Books	rol of Carbon E ications of gree -tech measure f echnologies, Fi	Emissions and Aden technologies. For carbon emiss	ccumulation ion reduction/ acti Graw Hill Educatio	on plan	30

2. http://cpcbenvis.nic.in/greentechnology.html

Program	n:	M. Tech. Computation	onal Mechanics (N	Aechanical Engi	ineering)	Semester : I	
Course	:	System Modeling and	l Simulation (Ope	en Elective-I)		Code : MMC1	601C
		Teaching	Scheme		Eval	uation Scheme	
Lectu	ıre	Hours	Credit	IE 1	IE 2	ЕТЕ	Total
2		2	2	20	-	30	50
rior kn	owle	dge of:					
Course C	)bjec	ctives:					
1.	Stuc	lents able to model any	physical system f	or realtime appli	cations		
2.	Stuc	lents able to simulate a	ny physical systen	n for realtime app	olications		
ourse (	Jutco	omes:					
fter lear		the course, the student					
1.		elop mathematical mo		oblem			
2.		elop Bond Graph mod					
3.		ly transfer function an					
4.	Sim	ulate the system using				timization	
			D	etailed Syllabus	:	1 million 100 mill	
Unit		100	De	scription	- 10	10.00	Duration, (H)
1.		oduction to Modelling hematical modelling, E					7
2.		d Graph Modelling of tiports Causality, Appl					m 8
3.		amic Response and Sy ck diagram/Signal flow				response	7
4.		ulation and Simulation meter Estimation, Sys		and Optimization	1	1.11	8
						Tot	tal 30
1.	Fran	ık L. Severance, Syster	n modeling and si	Text Book mulation an intro	duction. Wile	v. 2009.	6.1
	1.		F	Reference Books			780824706166

"Robudentips the logs be extern"

Program	m:	M. Tech (E&TC)-	VLSI and Embed	lded Systems		Semester: I		
Course	e:	Automotive Electr	onics and its App	olications (Open	Elective-I)	Code: MET1601	A	
		<b>Teaching Scheme</b>	1		Evalu	ation Scheme		
Lectu	ıre	Hours	Credit	IE 1	IE 2	ЕТЕ	Total	
2		2	2	20		30	50	
b. Ir c. co d. IC ourse O 1. ' 2. ' 3. ' ourse O fter learn 1	nowlet nstrum ontrol C engi bjecti bjecti To lea To lea To lea utcom ing th Acqui autom	edge of electronics & entation systems <u>ne operationa</u> ves: rn and understand th rn and understand y <u>rn and understand y</u> ees: e course, the studen re an overview of an otive industry.	re essential ne various applicat rinciples and appli arious control syst ts should be able t atomotive compon	ications of sensor tems in automotiv o: ents, subsystems	, and basics of e	CU in automotive. in automotive electr electronic control in hic control systems v	today's	
:	autom	otive system design knowledge of mod	ern technologies ir		.gn.			
Unit	0	21		Description	1		Dura (H	
1. y	with e subsys	emphasis on increaters and componer	sing role of elect ts, Body, Chassis,	tronics and software and Powertrain	w <mark>are, Ov</mark> erview El <mark>ectron</mark> ics	t trends in automoly of typical automo		7
2.	Crank	rs and Actuators: I angle position sen Air mass flow sense	sors, Fuel meteri	ng/ vehicle spee	e <mark>d sensor</mark> s, Flo <sup>r</sup>	w sensor, Temperat	ture, 8	}
3. s	systen naps,		n, EGR for exhau	st emission cont	rol. Look-up ta	and closed loop con bles and maps, Nee		7
4.	entry,	e and passive safet Immobilizers etc., E ck braking system, 1	electronic instrume	ent clusters and d	ashboard electr		vless 8	3
						Т	'otal 3	0
I 2. I Reference	Willian Butter Ronald Book	worth-Heinemann P l K. Jurgen, —Auto s:	ublications. motive Electronics	s Handbook∥, Mc	-Graw Hill.	Freedom" ing Perspectivel, Se	venth edition	,
2 3	Kienc edition Auton	n, Springer Publicat notive Electronics b	Lars, —Automoti ion. y Tom H. Denton	ve Control Syste	ms for Engine,	Driveline and Vehic . Halderman / Pears		

	ram: M.Tech (E&TC)-V		u bystellis		Semester: I		
Cou					Code: MET1601B		
	Teaching Schem	e		E	valuation Scheme		
Lect	ure Hours	Credit	IE 1	IE 2	ETE	То	tal
2	2	2	20		30	5	0
rior k	nowledge of:						
a.							
b.							
с.	,	e essential					
	Objectives:			1 . 6 1			
1. 2.	· · · · · · · · · · · · · · · · · · ·				tric drive.		
2. 3.					ng rectifiers		
4.	-						
5.	-						
	Outcomes:						
fter le	arning the course, the stude	nts should be able to	o:				
1.	Analyze the performance				litions.		
2.	Control induction motor,						
3.	Suggest a suitable electric						
4.	To analyze the performan				onditions.		
		I	Detailed Sylla	bus:			<b>D</b> (1
Unit	1.5	]	Description				Duration
	Selection of Motor Powe	n Datinga Tharm	al Model of I	Motor for Ha	ating and Cooling C	lasson of	<b>(H)</b>
	Motor Duty, Determinatio						
1.	dc Drives, Single and three						7
1.	Motor, Rectifier Control						,
	Current, Chopper Control					III MOtor	
	Induction Motor Drives					alvsis of	_
•	Induction Motor Fed from						0
2.	Speed Control Techniques						8
	Sources.						
	Voltage Source Inverter						
3.	Converter Rating for VSI						7
	from a Current Source,			e	lated voltage source	inverter	-
	control, and speed control	- · ·			1	1	
	Synchronous Motor D				supply-starting, syn	chronous	
			arive emplo	where land a			
	Permanent Magnet ac (Pr	(AC) Motor Drive			ommutated thruster		
1	Drives	AAC) Motor Drive			ommutated thruster r Drives, Brushless		8
4.	Drives. Stepper Motor Drives:		s, Sinusoidal	PMAC Moto	r Drives, Brushless	dc Motor	8
4.	Stepper Motor Drives:	Variable Reluctand	s, Sinusoidal ce, Permanen	PMAC Moto t Magnet, In	r Drives, Brushless	dc Motor	8
4.	Stepper Motor Drives: Motors, Torque Versus Sto	Variable Reluctance	s, Sinusoidal ce, Permanen teristics, Driv	PMAC Moto t Magnet, In e Circuits for	r Drives, Brushless of nportant Features of Stepper Motor.	dc Motor	8
4.	Stepper Motor Drives:	Variable Reluctance	s, Sinusoidal ce, Permanen teristics, Driv	PMAC Moto t Magnet, In e Circuits for	r Drives, Brushless of nportant Features of Stepper Motor.	dc Motor	8
	Stepper Motor Drives: Motors, Torque Versus Ste Industrial Drives: Textile	Variable Reluctance	s, Sinusoidal ce, Permanen teristics, Driv	PMAC Moto t Magnet, In e Circuits for	r Drives, Brushless of nportant Features of Stepper Motor.	dc Motor f Stepper	
ext Bo	Stepper Motor Drives: Motors, Torque Versus Ste Industrial Drives: Textile	Variable Reluctance pping Rate Charace Mills, Steel Rollin	s, Sinusoidal ce, Permanen teristics, Driv g Mills, Cran	PMAC Moto t Magnet, In e Circuits for es and Hoists,	r Drives, Brushless of nportant Features of Stepper Motor. Machine Tools.	dc Motor f Stepper	
ext Bo	Stepper Motor Drives: Motors, Torque Versus Sta Industrial Drives: Textile poks: . Gopal K Dubey , Fundan	Variable Reluctance pping Rate Charace Mills, Steel Rollin mentals of the electr	s, Sinusoidal ce, Permanen teristics, Driv g Mills, Cran ical drives Na	PMAC Moto t Magnet, In e Circuits for es and Hoists, rosa publicati	r Drives, Brushless of nportant Features of Stepper Motor. Machine Tools.	dc Motor f Stepper Total	
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ext Bo 1. 2. 3. 4. 5. eferer 1. 2. 3. 4.	Stepper Motor Drives:         Motors, Torque Versus State         Industrial Drives: Textile         boks:         Gopal K Dubey , Fundand         N. Mohan T.M. udeland         Vedam Suryavanshi, Elee         B.K. Bose, Advanced po         S.K.Pillar, Analysis of the         nce Books:         N.K De,P.K. Sen , Electric         Gobal K.Dubey, Fundam         Shepherd Hullay & Liag         Gopal K Dubey, Power S	Variable Reluctance pping Rate Charace Mills, Steel Rollin mentals of the electro & W.P.Robbins , P ctrical Drives Conce wer Electronics & A yristor power condi- ic Drives PHI Learne entals of Electrical Power Electronics emiconductor cont	s, Sinusoidal ce, Permanen teristics, Driv <u>g Mills, Cram</u> ical drives Na ower Electron ept and applic A.C. Drives tioned motors ning 1 st Editi Drives- Alph & Motor Cor rolled Drives,	PMAC Moto t Magnet, In e Circuits for es and Hoists, rosa publicati ics converter ation on, 2009 a Science Int. trol -, Cambri - Prentice Ha	r Drives, Brushless of nportant Features of Stepper Motor. <u>Machine Tools.</u> on application J.Wiley & Ltd., idge Univ. Press Il pub.	dc Motor f Stepper Total & sons	
ext Bo 1. 2. 3. 4. 5. eferer 1. 2. 3. 4. 5. 5. 4. 5. 5. 5. 5. 6. 6. 6. 6. 6. 6. 7. 7. 7. 7. 7. 7. 7. 7. 7. 7	Stepper Motor Drives:         Motors, Torque Versus State         Industrial Drives: Textile         Doks:         Gopal K Dubey , Fundam         N. Mohan T.M. udeland         Vedam Suryavanshi, Ele         B.K. Bose, Advanced po         S.K.Pillar, Analysis of the         nce Books:         N.K De,P.K. Sen , Electr         Gobal K.Dubey, Fundam         Shepherd Hullay & Liag,         Gopal K Dubey, Power S         R. Krishnan, Electric Mo	Variable Reluctance pping Rate Charace Mills, Steel Rollin mentals of the electr & W.P.Robbins , P ctrical Drives Conce wer Electronics & A yristor power condi- ic Drives PHI Learn entals of Electrical Power Electronics emiconductor cont tor Drives-Modelli	s, Sinusoidal ce, Permanen teristics, Driv g Mills, Cram ical drives Na ower Electron ept and applic A.C. Drives tioned motors ning 1 st Editi Drives- Alph & Motor Cor rolled Drives, ng, Analysis a	PMAC Moto t Magnet, In e Circuits for es and Hoists, rosa publicati ics converter ation on, 2009 a Science Int. trol -, Cambri - Prentice Ha	r Drives, Brushless of nportant Features of Stepper Motor. <u>Machine Tools.</u> on application J.Wiley & Ltd., idge Univ. Press Il pub.	dc Motor f Stepper Total & sons	
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Program:		M.Tech. (E&TC)-	emester : I					
Course :		Basic of FPGA an	ode : MET1601C					
		<b>Teaching Schem</b>	e		Evalua	tion Scheme		
Leo	cture	Hours	Credit	IE1	IE2	ЕТЕ	Total	
	2	2	2	20		30	50	
b. ourse 1. 2. 3. ourse	Knowled Objective To make To under To make FPGA an Outcome	es: students familiar wir stand the architectur the students familiar d CPLD. s:	lescription language. th programmable logi e and features of FPG with the design proc	c devices and its A and CPLD .	s architectures.	ed to the existing har	dware in	
1. 2. 3.	To under To design To demo	n a system using FPC nstrate an understand	PLD and FPGA archi GAs. ling of interfacing of flow of FPGA and C	different externa				
Unit	Description							
1.	<b>Introduction:</b> Introduction to Hardware Description language, Need of Programmable logic devices, PLA PAL, CPLD, FPGA: General Architecture, features CPLD Architecture: overview, specification and applications, Features of XC9500 series of CPLD family.							
2.	<b>FPGA Architecture:</b> Xilinx Logic Cell Array, Configurable Logic Block, I/O Block, Programmable Interconnects, Programming methods, Advanced features of Xilinx 4000 series Technology Trends: Device capacity, Utilization and Gate Density, Programming methods, General Design Flow, General Design Guidelines.							
3.	<b>Interfacing with FPGA/CPLD:</b> The purpose of interfacing, interfacing of external devices such as WiFi Module, Bluetooth Module, GPS Module, Zigbee Module, Different types of display devices with FPGA/CPLD							
4.	Case Studies-FPGA/CPLD: Xilinx Virtex-6, Spartan-6, Z-board Advanced features in FPGA based on Case studies. Logical Design by FPGA/CPLD: Complete design of any combinational circuit by gates, Boolean Algebra, Design of sequential circuits							
						Total	30	
1. 5	P.K.Ch Ronald practice Design <b>ce Books</b> S. Trimbe	Sass and Andrew esl, Morgan Kaufma manuals of Altera, 2	Kilinx and Actel.	v Technology, K	design with p	latform FPGAs: Price of the second se	inciples and	

- 4. S. Brown, R. Francis, J. Rose, Z. Vransic, Field Programmable Gate Array, BSP, 2007.
- 5. S. Brown and J. Rose, "Architecture of FPGAs and CPLDs: A Tutorial", IEEE Design & Test of Computers, Vol. 13, No. 2, pp. 42-57, 1996.
- 6. S. Brown Zvonko Vranesic Fundamentals of Digital Logic with VHDL design, McGraw Hill 2000

Progra	am: N	I. Tech. (E&TC)-VLS	SI and Embedded	Systems	Semes	ster : I			
Cour	se: R	Robotics (Open Electiv	ve-I)		Code	: MET160	1D		
		<b>Teaching Scheme</b>			Eval	uation Sch	eme		
Lecture 2		Hours	Credit	IE1	IE2	ETE	Tot	al	
		2	2	20		30	5(		
Prior K									
		and actuators		accontial					
b. I Course		ming language 'C', M	AILADale	essential					
		vledge on							
		mechanical elements o	f robots						
		system for robot autor							
		g robots designed for v	arious applications						
Course		nes: e course the students sh	ould be able to:						
1.		tand kinematics, statis		f robots					
2.		concepts of industrial a			for selection of r	obots			
3.		sensing and actuating e					nts		
4.	Integra	te and design control s	ystem and information	tion system f	or various applic	ations.			
	_		Deta	ailed Syllabu	15:	20	Sec. 1		
Unit	Description								
1.	<b>Introduction to robotics:</b> Evolution of Robotics, Elements of robots; Kinematics of serial and parallel robots; Velocity and static analysis of robots; Dynamics of robots; Motion planning and control; Flexible manipulators; Wheeled mobile robots, classification of Robots							7	
2.	Advanced concepts in robotics: Introduction to Cloud and Fog robotics; Basic concepts of industrial automation and communication protocols for PLC, DCS, SCADA systems; Introduction to Internet of Things, Protocols and real time applications.								
3.	Sensing Elements <b>for robots:</b> Classification of Sensors, Encoders and Dead Reckoning Infrared Sensors, Ground-based RF Systems, Active Beacons, Ultrasonic Transponder Trilateration, Accelerometers, Gyroscopes, Laser Range Finder, Vision-based Sensors, Color- tracking Sensors, safety and motion sensors, Force/ Torque Sensors, Tactile Sensors, DC Motors, Controlling a DC Motor, Pulse Width Modulation, Stepper Motors, Servo Motor.								
4.	Control System of Robots: Automatic-Feedback Control System, Control Elements, Control System Design, A Robot's System Dynamics, Sensory Feedback, Control Algorithms and Performances, Space Control, Introduction to Information System of Robots.								
		- 164304					Total	30	
Text Bo	oks:				1.000			1	
1. 2. 3.	Appin	C, Introduction to Rob Knowledge Solutions, Kie, Fundamentals of R	Robotics (2007)	"Knowle	edge Bring		dom"		
Referen	U		8			Confide	anae /		
1.		s Bräunl, Embedded R				allan a			
2. 3.		S and Sciavicco L, Rol , Ralph G and Lee C S					ta McGraw-Hi	11	
4.	Mukho	padhyay S, Sen S and	Deb A K, Industria V, Internet of Thing				on, Jaico (1999		
Progra	am: I	M.Tech (Comput	er Engineering)			Semester : I			
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Cours	se: I	Programming wit	h Python (Open E	lective-I)		Code: MCE1601A			
		Teaching Scheme			Evaluati	on Scheme			
Lectu	ire	Hours	Credit	IE 1	IE 2	ETE	Total		
2		2	2	20		30	50		
	wledge								
		Programming							
	bjective								
			hon and R program						
			with conditionals a		tructures				
	utcomes		nalysis methods to	a problem					
			s should be able to:						
			h functions, Strings	. List. Tuples and D	Dictionaries in P	vthon			
			ogramming in Pytho			<i>J</i> • • • • • • • • • • • • • • • • • • •			
			l accurately in a pro		1000				
			D	etailed Syllabus:	1100				
Unit		18		Description		6. A.	Duratio		
1.	environ Editor	ment in Window for Python code,	s and Linux, basic	es of Python interp Data types. Flow of	oreter, Executio control if if els	and setting Python n of python program, se, for, while, range()	7		
2.	dictiona	aries, dictionaries	& lists. Tuples and	Files : reading and	writing	onaries: looping and	8		
3.	Functions: Definition, Call, Arguments ,Input output file handling.         Object Oriented Programming features in Python: Classes, Objects, inheritance,Errors and Exceptions: try, except and else statements, Exception Objects, Regular expressions.						7		
4.	Numpy Statistic Pandas Mappin	y and Matplotlib cs. Matplotlib: Intr Look Ups, Selec ng, Data Frames, R	:Array operations, oduction, Simple pl	Numpy Side Effec lots, Line API, Leg Filling Methods, S ng, Joins,	ts, 2D Numpy end API, Figure	Arrays, Numpy Basic	8		
						Total	30		
2. Peng,	B Downe Roger D		IONI, O_Rielly, ISE atsui, —The Art of I			ian Reprint 2015 e Who Works with Data	. <mark>Sky</mark> bru		

#### Consulting 200 (2015): 162 Reference Books:

1. Zed A. Shaw, Learn Python the Hard Way

"Knowledge Brings Freedom"

M. Tech – Design Engineering (Mechanical Engineering)), PCCoE Pune

	m: M.Tech (Compu	iter Engineering	)		Semester : I				
Cours	e: Software Engine	eering Basics (Op	pen Elective-I)		Code : MCE1601B				
	<b>Teaching Schem</b>	e		Eval	uation Scheme				
Lectu	re Hours	Credit	IE 1	IE 2	IE 2 ETE				
2	2	2	20		30		50		
	owledge of:- None								
	<b>)bjectives:</b> To learn and understand	the main similar of	Software Engineer	ina					
1. 2.	To be acquainted with n				nolyzing software requ	iromon	to		
2. 3.	To apply Design and Te				inaryzing software requ	memen	15.		
4.	To understand project n								
5.	To understand software		<u></u>	Frederic					
Course C	<b>Jutcomes:</b>	1 2							
After lear	ning the course the stude	nts should be able	e to:						
1.	Decide on a process mo								
2.	Classify software applic		y unique features of	of various don	nains				
3.	Design test cases of a so								
4.	Understand basics of IT								
5.	Plan, schedule and exec			inagement.					
6.	Apply quality attributes	In software develo	Detailed Syllab			_			
			•	us.			Duration		
Unit			Description				(H)		
	Introduction to Softw	are Engineering	g and Software	Process Mod	lels: Software Engine	ering			
	Fundamentals: Nature o	f Software, Softw	are Engineering P	ri <mark>nciples, The</mark>	Software Process, Soft	tware			
1	Myths. Process Models :A Generic Process Model, Prescriptive Process Models: The Waterfall, Incremental Process(RAD), Evolutionary Process, Unified								
1.									
	Process, Concurrent. A			ls: Agile sof	tware development:	Agile			
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2		and non-function	onal requirements,	Types & M	etrics, A spiral view of	of the	8		
2.	requirements engineeri	and non-function ng process. Soft	onal requirements, tware Requirement	Typ <mark>es</mark> & Mo nts Specifica	etrics, A spiral view of tion (SRS): The soft	of the tware	8		
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	erative distance-based					8				
	Constructing a hierarchical cluster; K-Medoids, k-Mode and density-based clustering; Measures of quality of clustering									
		ana Classifian Mar		Dachahilita aatia	mation. Descined date	+				
	lassification: Naïve B ocessing; M-estimates				nation; Required data					
	-Nearest Neighbors:				while designing K-	7				
	earest Neighbor Suppor	e								
	ssociation Rule min									
	ecommendation Engine									
	ssociation Rules; Apric									
<b>4.</b> di	scovered association ru	les; Application examination	mples; Association	n analysis vs. cla	assification ; FP-trees	8				
	esearch Aspects: App					0				
	ublication in Quality		al Journals/ Cont	ferences;Practica	al Implementation of					
In	dustry Projects/Applica	ations; IPR								
					Tota	l 30				
	D TTL.1	<b>T</b> 1 <b>T</b> 1	C C 4 4 4 1 1 1							
. T. Hastie	, R. Tibshirani, J. Fried			ing, 2e, 2008.						
. T. Hastie . Christoph	er Bishop. Pattern Rec			ing, 2e, 2008.						
	er Bishop. Pattern Rec			ing, 2e, 2008.						

Progr	am: M.	Tech. (Civil)	Construction Man	agement		Semester : I		
Cour	se: Pro	ject Manager	nent and Finance (	Open Elective-	I)	Code : MCI1601A		
	Tea	ching Scheme	e		Evalu	ation Scheme		
Lectu	ure	Hours	Credit	IE 1	IE 2	ЕТЕ	Total	
2		2	2	20		30	50	
	owledge of:							
	Basics of Ma	nagement,	accontial					
	<b>bjectives:</b>	lanceare	essential					
	0	course, stude	nt will have adequat	te background to	)			
			and understanding			nt principles.		
			an individual, and a					
		d the concepts	s of finance and acc	ounts carried ou	t in project man	agement.		
	<b>Dutcomes:</b>	rsa tha studar	ts should be able to					
			ends and choose pro					
		ct feasibility r						
			oject effectively me	eeti <mark>ng govern</mark> me	nt norms and co	onditions.		
			ole and responsibilit					
5. A	Ability to cho	bose projects v	which benefit the so					
				Detailed Syllabu	IS:		Duration.	
Unit			]	Description			(H)	
	Introducti	ion to Manag	ement	and			()	
1			's Need ,Importanc	e & Purpose, Ev	ol <mark>ution o</mark> f Mana	agements thought,	7	
1		Schools/ appro	aches to Manageme	ent: Behavioral,	<mark>Quantitat</mark> ive, Sy	ystems, Contingency	,	
	Approach				1	00		
			n, Monitoring and		wanted with al	institute of emperization		
2.						ojective of organization, ing, Resource allocation,	8	
2.						of contracts in projects:	Ū	
			anagement: Format			I J		
	Organizin		11-1-1		100			
						Different Structures of	11 C L -	
2						anization: Characteristics,	8	
3.	Features, their Merits and Limitation, Ownerships of Organization: Sole Proprietorship, Partnership, Private Ltd., Public Ltd., Introduction to Organizational climate, Decision Making, Group Decision							
	Making, Staffing: What is Staffing? Steps involved in Staffing, Recruitment, Staffing, Performance							
		Development	is staring. steps			,		
		<u> </u>	nd Their Analysis	knowledg	e Brings I	Freedom"		
4.			ial Statements and				7	
	Account, F	Ratio Analysis	, Fund Flow Analys	sis, Statement of	Changes In Fin			
	Ļ			<u>Ohimer</u>	an i sailan	Total	30	
<b>ext Boo</b> 1. I		acoment Institu	uta A Guida ta tha I	Project Managan	ant Dody of V	nowledge PMBOK Guide	Givth	
	Edition), Sep	-	ate A Ourde to the r	Toject Managen	lent body of Ki	nowledge r wibok Oulde	SIXII	
			amentals of Financi	al Management,	Person Educati	on 2004.		
		.,Project Mana	agement, PHI 2011.					
	e Books:							
	Kuster J., H 2015.	uber, E., Lippı	nann, R., Schmid, A	A., Schneider, E.	, Witschi, U., V	Vust, R. Project Manageme	ent Handbool	
			al Management, Ta		, 2008.			
			Reeve, Jonathan Du	ichac.				
			Accounting, 2016		DIII 2011			
5. I	raneer Selva	m, K., and Sei	nthilkumar, P., Proj	ect Management	, рні, 2011.			

Progr	ram:	M. Tech. (Civil) Con	nstruction Manage	ement		Semeste	er:I	
Cour		Green Technology (	<b>Open Elective-I</b> )				MCI1601B	
		Teaching Scheme			Eva	luation	Scheme	
Lect	ure	Hours	Credit	IE 1	IE 2	2	ETE	Total
2 Prior ki a.	nowled	2 ge of: onmental study,	2	20			30	50
a. b.		of pollutionare es	ssential					
Course								
1. 1 2. 1 3. 1	Го learr Го dem Го learr	ng this course, student a about Global warming onstrate knowledge in t a the control measures o a high tech measures fo	g and its effect the reduction of glo of carbon emission	bal warming. and accumulation		nd solve t	he problem involvin;	g:
Course			i iteaating caroor	2				
		he course, the students	should be able to:					
		the effects of Global wa						
		nent the concept of red						
		stand the remedial action			nulation.			
4.	Apply	high tech measures for						
				etailed Syllabus:			Sec. 1	Duration,
Unit			D	escription				(H)
1.	Carbo Absor Protoc <b>Plann</b> univer Gener Local	al Warming and its of on Problem: Accumular ption in Nature, The cols and its view in Ind ing for the Future rsally, Use of Promoti al Approach in Plannin People, Developing M on Climate Change (NA	tion, Long Half-Li Global Emission ia, Effect of climat to reduce global onal and Punitive ng for the Future, D litigative Measures	fe, Heating Poten Situation and its e change and its ir warming:- Steps Mechanisms for Developing Countr for Global Reduc	tial, Carbon effect in In npact. s taken to Reducing C ywide Adap tion of Carbon	n Emission ndia, The Control Carbon ir ptive Mea bon, Indi	on Factors, Carbon e Kyoto and Other Carbon Emissions a Atmosphere, The asures for Safety of a's National Action	7
2.	Oppo Carbo in Ind Sourc Defor Mech Green Cost Alread	rtunities in Control of n Emissions and Accu ia for control of carbor es in India, A Logica estation and payment anisms at India. n Technologies for En Comparison of a Few dy in Use, Alternative I nologies Needing some	of Carbon Emission imulation, Procedure emissions and acc Approach for C rates procedure ergy Production: 7 Typical Systems Methods Ready for	ons and Accumul re to develop owr cumulation, Needs arbon Reduction, for controlling c - Various Technol- for Power Gene	ation:- Ess n Priorities a Mix of C Need in I arbon emis ogies Avail	sential St and Busi Green and India —M ssions ar lable for 1	eps for Control of ness Opportunities l Traditional Power More Forests, Less id its Promotional Energy Production,	8
3.	Green Carbo Cityw Green Energ Trans Indust and A Devel Service	n Technologies for Pe on Emission Reduction ide Level, Carbon Emi n Technologies for S y Conservation Buildi port, Green Roads, Por tries in India, The Cha area Re- opment Projects, 'Green ces for Crematoria, Spr	rsonal and Cityw a at Personal Leve issions from Impor pecific Application ing Code (ECBC) rts and Harbors, Im- nging Scenario in a Infrastructure for eading Message to	el, Carbon Emissi ts. ons:- Promotion of , Green Hotels and dustries, Carbon, of Cities, Need for Municipal Servic all Stakeholders.	on Reducti of 'Green' nd Hospita Carbon Em Wider Apj es, Bringin	ion at Lo Building Is, Greer issions fr plication g up Indi	an Villages, Green	7
4.	Based Analy <b>Reco</b> Missie	High-tech Measures Systems ,Use of Carb sis. mmended Plan of Ac ons Help Develop Aw ive Measures Essential	oon Capture and St tion :- India's Nat vareness, Few case	orage (Sequestrati ional Action Plan e studies on Proje	on) ,Micro Take Us t ects underta	organism to a Low aken by	s, A Quick SWOT -Carbon Path, The Various Countries,	8
							Total	30
Text Bo		Tream Testerslevice C	1; T A		tion			
Dofess		Green Technologies, So	bii J. Arceivala, Mc	e Graw Hill Educat	tion.			
Referen	1. 0	ks Green Technologies and http://cpcbenvis.nic.in/g			l by Ritu Si	ingh, San	jeev Kumar	

Program:	M. Tech. (Civil) C	Construction Ma	anagement		Semester: I		
Course:	Organization Beha	avior (Open Ele	ective-I)		Code: MCI1	601C	
	Teaching Sch	eme			<b>Evaluation Sch</b>	neme	
Lecture	Credit	Hours	IE -1	IE-2	ETE	Tot	al
2	2	2	2	-	30	50	)
	owledge of:						
	ifferent types of Organ						
	ojective: To introduce				Project.		
	itcomes: At the end of	,					
	nderstand important a						
	pply different learning						
	ppraise group behavio			olitics in organis	sation.		
4. R	elate to organisation c	ulture, climate a		llahaa			
			Detailed Sy	mabus:			Duration
Unit			Descripti	ion			(H)
	Introduction to OB						
1.	Opportunity for C				tional Behaviou	ur, Inherited	7
	characteristics, Learn						
	Motivation and beh						8
2.	motivation from concept to applications, Designing motivating jobs, Group Decision Making,						
	Differences Between Groups and Teams, Types of Teams, Creating Effective Teams						
2	Leadership, Power and Politics: Trait Theories, behavioural Theories, Contingency Theories,						-
3. Authentic Leadership: Ethics and Trust, A Definition of Power, Bases of Power, Power Tactics, Causes and Consequences of Political behaviour						7	
				monte signifan	a of oulture in	organization	
	<b>Organization culture, climate and stress management:</b> signifance of culture in organization, creating sustainable cultures, Creating a Positive Organizational Culture, Creating a Culture for						
4.	Change, Work Stress						8
	projects.	s and its Manage	ment, Case stu	dies of OD liner	vention sin mega	-construction	
	projects.					Total	30
						LOLA	50

 Gregery Moorhead, Ricky W. Griffin, Organizational Behaviour: Managing People and Organizations, 3rd Edition, Houghton Miffin Company, 2000

2. Stephen, P Robbins, Organizational Behaviour, 9th edition, Pearson Education Asia, New Delhi, 2001

3. Wendell L French, Cecil H. Bell, Jr., Organization Development: Behavioural Science Interventions for Organization Improvement, 6th edition, Pearson Education Asia, New Delhi, 2001.

4. Jit. S. Chander, Organizational Behaviour, 3rd edition, Vikas Publishing House Pvt. Ltd.,, New Delhi, 2005.

Program:	M. Tech. (Ar	tificial Intelligence a	and Data Science)	)	Semester : I		
Course :	R Programm	ing (Open Elective-	I)		Code :MDS1601	Α	
	Teaching So	cheme			<b>Evaluation Sch</b>	eme	
Lecture	Hours	Credit	IE1	IE2	ETE	Tota	al
2	2	2	20	-	30	50	
a. Knu b. Prid Course Ol 1. To us 2. To ur 3. To in 4. To ur Course Ou After learn 1. Expla 2. Apply	or Knowledge of ojectives: e R and R Studi- iderstand different terface R with or iderstand the use of the course, the ing the course, the in the basics in a y the use of R for	nt data types and con	trol structures in F alytics. able to: rms of constructs,		ements, string fur	nctions.	
		d apply the R program			ective.		
Unit			Description	l			Duration (H.)
		with R Programm Structures in R,Rea			R-Studio, user-i	nterface, Basic	7
<b>2.</b> R D	ows and Colum imension Reduc	<b>And Lists:</b> Creatinns, Adding and deletion, Higher Dimension property and values.	ting rows and col sional arrays, Lis	umns, Vect ts, Creating	tor/Matrix Distin g lists, General l	ction, Avoiding	8
<ul> <li>Accessing list components and values, Applying functions to lists, Recursive lists</li> <li>Data Frames: Creating Data Frames, Matrix-like operations in frames, Merging Data Frames, Applying functions to Data frames, Factors and Tables: factors and levels, Common functions used with factors, Working with tables, Other factors and table related functions, Control statements: Arithmetic and Boolean operators and values, Default values for arguments, Returning Boolean values, Environment and Scope issues: Writing Upstairs – Recursion ,Replacement functions, Tools for composing function code, Math and Simulations in R</li> </ul>						8	
4.       Interfacing: Interfacing R to other languages, Parallel R, Basic Statistics, Linear Model, GeneralizedLinear models, Non-linear models, Time Series and Auto-correlation – Clustering						7	
						Total	30
<ol> <li>Norman</li> <li>Reference</li> <li>Jared P.</li> <li>2013</li> <li>Robert F</li> </ol>	rdener, "Begini Matloff, "The A <b>Books:</b> Lander, "R for H Knell, "Introduct	ning R – The Statistic Art of R Programming Everyone: Advanced ory R: A Beginner's o on Digital South Asia	g: A Tour of Statis Analytics and Gra Guide to Data Visu	tical Softwa phics", Add alization, S	are Design", No S lison-Wesley Dat	a & AnalyticsSeri	es,

Lecture         2         Prior knowledge         a. Machine         b. Data Sci         Course Objectiv         1. Understand         2. Understand         3. Understand         Analytics.         4. Evaluate diff         Course Outcome         Analytics.         4. Evaluate diff         Course Outcome         Analytics.         2. Evaluating b         3. To perform         Analytics.         4. Evaluate diff         Unit         Introdu         What is         model b         current f         Analytic         2.         Program         logistic         Introduce	e Learning ienceare essen /es: the different basic c the concept of Proba the practical applic ferent data analytics es: e course, the student owledge of basic co basic concepts of pro- n practical application fferent tools. Inction business analytics? puilding, Deployme	Credit 2 tial oncept / fundament ability and its usag ation of Descriptive tools. s should be able to ncept / fundament obability and performer on by taking mar D , Business Analyti	e in various ve and Inferd o: tals of busine orm probabil nagerial dec <b>Description</b> ics process:	IE2 - ness statistics business applential Statistic ess analytics. lity theoretica ision and eva abus: n problem fram	l distributions. aluating the C	Scheme Total 50 d their uses forBusir Concept of Business	
2       Prior knowledge a. Machine b. Data Sci       Course Objectiv       1. Understand f       2. Understand f       3. Understand f       3. Understand f       3. Understand f       Analytics.       4. Evaluate diff       Course Outcome       After learning the       1. Gaining Kne       2. Evaluating b       3. To perform Analytics.       4. Evaluate diff       Unit       Unit       Introdu       What is model b       current f       Analytic       2.       Introdu       What is       model b       current f       Analytic       Program       logistic       Introduc	Hours  Provide the different basic c the concept of Probatile the practical applic ferent data analytics es:  Provide the student owledge of basic concepts of provide the practical application of the practical application ferent tools.  Provide the tools of the practical application of the practical appli	Credit 2 tial oncept / fundamen ability and its usag ation of Descriptiv tools. s should be able to ncept / fundament obability and perfo on by taking mar D	20 tals of busing tals of busing tals of busing orm probabiling nagerial dec <b>betailed Syllis</b> <b>Description</b> ics process:	- hess statistics business appendial Statistic ess analytics. lity theoretica ision and eva abus: h	ETE 30 lications. es concepts and l distributions. aluating the C	Total 50 d their uses forBusin Concept of Business leling,	Duration (H)
2       Prior knowledge a. Machine b. Data Sci       Course Objectiv       1. Understand f       2. Understand f       3. Understand f       3. Understand f       3. Understand f       Analytics.       4. Evaluate diff       Course Outcome       After learning the       1. Gaining Kne       2. Evaluating b       3. To perform Analytics.       4. Evaluate diff       Unit       Unit       Introdu       What is model b       current f       Analytic       2.       Introdu       What is       model b       current f       Analytic       Program       logistic       Introduc	2         e of:         e Learning         ienceare essen         res:         the different basic c         the concept of Probatic         the practical applic         ferent data analytics         es:         e course, the student         owledge of basic co         basic concepts of probatic         in practical application         fferent tools.	2 tial oncept / fundament ability and its usag ation of Descriptive tools. s should be able to ncept / fundament obability and performer on by taking mar D , Business Analyti	20 tals of busing tals of busing tals of busing orm probabiling nagerial dec <b>betailed Syllis</b> <b>Description</b> ics process:	- hess statistics business appendial Statistic ess analytics. lity theoretica ision and eva abus: h	30 lications. es concepts and l distributions. aluating the C	50 d their uses forBusin Concept of Business	Duration (H)
Prior knowledge         a.       Machine         b.       Data Sci         Course Objectiv         1.       Understand f         2.       Understand f         3.       Understand f         Analytics.       4.         4.       Evaluate diff         Course Outcome       Analytics.         4.       Evaluating b         3.       To perform         Analytics.       4.         Evaluate diff       Unit         Introdu       What is         model b       current f         Analytic       Optimiz         program       logistic         Introduc       Probab	e of: e Learning ienceare essen /es: the different basic c the concept of Proba the practical applic ferent data analytics es: e course, the student owledge of basic co basic concepts of pro- practical application fferent tools.	tial oncept / fundamen ability and its usag ation of Descriptiv tools. s should be able to ncept / fundament obability and perfo on by taking mar D	ntals of busing ge in various ve and Inferd o: tals of busine orm probabil nagerial dec <b>Description</b> ics process:	business app ential Statistic ess analytics. lity theoretica ision and eva abus: problem fram	lications. es concepts and l distributions. aluating the C	d their uses forBusir	Duration (H)
a. Machine b. Data Sci Course Objectiv 1. Understand 1 2. Understand 1 3. Understand 1 3. Understand 1 4. Evaluate diff Course Outcome After learning the 1. Gaining Kno 2. Evaluate diff 3. To perform Analytics. 4. Evaluate diff Unit Unit 1. Evaluate diff Unit 1. Course Outcome After learning the 3. To perform Analytics. 4. Evaluate diff Unit 1. Course Outcome Analytics 1. Course Outcome Analytics 1. Course Outcome Analytics 1. Course Outcome Analytics 1. Course Outcome Analytics 2. Course Outcome Analytics 1. Course Outcome Analytics 2. Course Outcome Analytics 2. Course Outcome Analytics 1. Course Outcome Analytics 2. Course Outcome Analytics 2. Course Outcome Analytics 1. Course Outcome Analytics 2. Course Outcome Analytics 3. Course Outcome Analytics 3. Course Outcome Analytics 4. Evaluate diff 4. Course Outcome Analytics 5. Course Outco	e Learning ienceare essen /es: the different basic c the concept of Proba the practical applic ferent data analytics es: e course, the student owledge of basic co basic concepts of pro- n practical application fferent tools. Inction business analytics? puilding, Deployme	oncept / fundamen ability and its usag ation of Descriptiv tools. s should be able to ncept / fundament obability and perfo on by taking mar D	e in various ve and Inferd o: tals of busine orm probabil nagerial dec <b>Description</b> ics process:	business app ential Statistic ess analytics. lity theoretica ision and eva abus: problem fram	l distributions. aluating the C	Concept of Business	Duration (H)
4. Evaluate difference Unit Init 1. Introdue What is model be current to Analytic Optimiz program logistic Introdue Probab	<b>iction</b> business analytics? building, Deployme	, Business Analyti	Description	problem fram			(H)
Introdu       What is       model b       current to       Analyti       Optimiz       program       logistic       Introduc       Probab	business analytics? building, Deployme	, Business Analyti	ics process:	problem fram			<b>(H</b> )
What is       model b       current t       Analytic       Optimiz       program       logistic       Introduct	business analytics? building, Deployme						8
2. Analyti Optimiz program logistic Introduc	trends, roles within	nt, Different type data analytics tean		s analytics, a		business analytics,	
	ics Techniques tation techniques: L nming, Predictive n regression, linear d ction to supervised a	inear Programmin nodelling :- regre iscriminate analy	ng, Goal Pro ession, mult sis, Data Mi	iple linear re ning:	gression for p		8
Theoret3.Concept	ility Theory & Dist lity: Theory of Pro- ical Distributions: C t of Business Analy analyze data-Descr	<b>ribution</b> bability, Addition concept and applic tics- Meaning typ	n and Mult ation of Bin pes and appl	iplication La omial; Poisso ication of Bu	w, Baye's Th n and Normal	distributions.	8
	nalytics tools sualization using Ta	bleau/Python/R/S	QL. Case stu	ıdy.			6
						Total	30
<b>Fext Books:</b>							
Reference Books 1. James Ev	sad, Seema Acharya	ı, "Fundamentals o	of business a	nalytics", Wi	iley		

# Course Syllabus Audit Course -I

Program:	M.Tech. (Design Engin	neering)			Semeste	r: I and II	
Course :	Audit Courses (Semest	ter I and II)			Code :	M_1961 M_2962	
	Teaching Scheme				Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	II	E <b>2</b>	ЕТЕ	Total
1	1			-	-		
<b>Guidelines:</b>	audit courses are common	to all M Tech Co	ourses				

2. 3. Students can select any audit course from list of audit courses for semester I and II

These are non-credit courses but mandatory to comply the submission of the semester.

#### LIST OF AUDIT COURSES (Common to M.Tech and MCA programs)

1.00	SEM-I
M_1961A	Constitution of India
M_1961B	Value Education
M_1961C	Stress Management
THE P	

# "Knowleitige the bigs Freedom"

Program	M.Tech(Design Eng	gineering)			Semester: I		
Course				Code : M_1961A			
	Teaching Schem	e		Evalua	tion Scheme		
Lecture	Hours	Credit	IE 1	IE 2	ETE	Total	
1	1	-					

**Course Objectives:** 

a. To understand the constitution and the centre-state relations and functioning

b. To understand the rules and regulations under which public and private sector work

c. To understand E-governance through computers and knowledge of cyber laws

#### **Course Outcomes:**

After learning the course, the students should be able to

1. Understand the functions of the Indian government and identify and explore the basic features, modalities about Indian constitution and assessment of the Parliamentary System in India.

2. Differentiate the functioning of Indian Political system at Central and State level and comprehend the fundamental rights and abide the rules of the Indian constitution

Unit	Detailed Syllabus: Description	Duration (H)
1.	Introduction to Constitution & System of Government Meaning of the constitution law and constitutionalism, making of constitution, Salient feature and characteristics of the Constitution of India, Preamble, Fundamental Rights, Directiv Principles of State Policy, Fundamental Duties and it's legal status, Citizenship. Structure and Function of Central Government, President, Vice President, Prime Minister Cabinet, Parliament, Supreme Court of India, Judicial Review, Federal structure and distribution of legislative and financial powers between the Union and the States, local self-government	re <b>6</b>
2.	Judiciary and Constitution Functions: Governor, Chief Minister, Cabinet, State Legislature Judicial System in States, High Courts ar other Subordinate Courts, Parliamentary Form of Government in India. Constitution Functions: Indian Federal System and it's characteristics, Center& State Relation President's Rule, Constitutional Amendments and powers, Constitutional Functionarie Emergency Provisions, Assessment of working of the Parliamentary System in India.	s, <b>6</b>
	Tot	al 12

**Text Books:** 

1. Durga Das Basu, "Introduction to the Constitution of India ", Prentice Hall of India, New Delhi,24th edition, 2020, ISBN-109388548868

2. Clarendon Press, Subhash C, Kashyap, "Our Constitution: An Introduction to India's Constitution and constitutional Law", NBT, 5th edition, 2014, ISBN-9781107034624

**Reference Books:** 

- 1. Dr J N Pandey : Constitutional Law of India
- 2. <u>https://www.meity.gov.in/divisions/national-e-governance-plan</u>
- 3. https://www.meity.gov.in/DeitY e-book/e-gov policy/download/Policy%20Document.pdf
- 4. http://www.iibf.org.in/documents/cyber-laws-chapter-in-legal-aspects-book.pdf

5. Maciver and Page, "Society: An Introduction Analysis", Laxmi Publications, 4th edition, 2007, ISBN-100333916166

6. PM Bhakshi, "The constitution of India", Universal Law Publishing - An imprint of Lexis Nexis, 14th edition, 2017, ISBN-108131262375

ching Scheme		s-I)	Evalua	Code : M_1961B ation Scheme		
			Evalua	ation Scheme		
Hours			Evaluation Scheme			
Lecture     Hours     Credit     IE 1     IE 2     ETE       1     1     -				ETE	Total	
1	-					
dents to Family dent to understa dents to understa urse the studen areness levels, titudes / beha l other life skill	y Relations and Creative Think tand Humanistic E ats should be able t knowledge and un aviour of students ls	king and Problem Education. o: derstanding of stu	Ident	on improved teamwork	c, institution	
		Detailed Syllabus	:			
10	1	Description		10 and 10	Duration (H)	
Why Human Relations are so important? Understanding Behaviour, Human Relations, and Performance, Personality, Stress, Learning, and Perception, Attitudes, Self-Concept, Natural acceptance of human values, and Ethics, Dealing with Conflict, Leading and Trust						
	1.00			Total	12	
	d develop Atti dents to Family lent to underst lents to underst lents to underst urse the studen areness levels, titudes / beha other life skil in social health un Relations ar ling Behaviou Attitudes, Se eading and Tru Jumankind, Nu istic Education	d develop Attitude and Core Fait dents to Family Relations lent to understand Creative Thinl lents to understand Humanistic E urse the students should be able t areness levels, knowledge and un titudes / behaviour of students other life skills in social health and attitude.	d develop Attitude and Core Faith values dents to Family Relations lent to understand Creative Thinking and Problem lents to understand Humanistic Education. urse the students should be able to: ureness levels, knowledge and understanding of stu- titudes / behaviour of students with regards to other life skills in social health and attitude. <b>Detailed Syllabus</b> <b>Description</b> un Relations are so important? ling Behaviour, Human Relations, and Performan Attitudes, Self-Concept, Natural acceptance of h eading and Trust Humankind, Nurturing and Exploitation, Definitive istic Education, Humanistic Constitution and Human Humanistic Constitution and Human Human Humanistic Constitution and Humanistic	d develop Attitude and Core Faith values dents to Family Relations lent to understand Creative Thinking and Problem solving lents to understand Humanistic Education. urse the students should be able to: ureness levels, knowledge and understanding of student titudes / behaviour of students with regards to their education other life skills in social health and attitude. Detailed Syllabus: Description un Relations are so important? ling Behaviour, Human Relations, and Performance, Personality Attitudes, Self-Concept, Natural acceptance of human values, a eading and Trust Humankind, Nurturing and Exploitation, Definitiveness of Ethical istic Education, Humanistic Constitution and Humanistic Univer-	d develop Attitude and Core Faith values dents to Family Relations lent to understand Creative Thinking and Problem solving lents to understand Humanistic Education. urse the students should be able to: ureness levels, knowledge and understanding of student titudes / behaviour of students with regards to their education improved teamwork other life skills in social health and attitude. Detailed Syllabus: Description an Relations are so important? ling Behaviour, Human Relations, and Performance, Personality, Stress, Learning, and Attitudes, Self-Concept, Natural acceptance of human values, and Ethics, Dealing with eading and Trust Humankind, Nurturing and Exploitation, Definitiveness of Ethical Human Conduct, Basis istic Education, Humanistic Constitution and Humanistic Universal Order, Competence	

- 1. Human Relations in Organizations Applications and Skill Building" Robart Lussier, eighth edition, McGraw-Hill (2014).
- 2. Atkinson and Hilgard's, "Introduction to psychology" Nolen-Hoeksema, S., Fredrickson, B. L., Loftus, G. R., & Lutz, C., Cengage Learning EME.

2. To 3. To 4. To	overcome stress achieve overall health of bo learn to achieve the highest	Credit - dy and mind	IE 1 	E IE 2 	Code : M_1961C Evaluation Scheme ETE	Total							
<b>1</b> ourse Obj 1. To 2. To 3. To 4. To	Hours Hours 1 ectives: overcome stress achieve overall health of bo learn to achieve the highest	- dy and mind		IE 2	ЕТЕ								
<b>1</b> ourse Obj 1. To 2. To 3. To 4. To	1 ectives: overcome stress achieve overall health of bo learn to achieve the highest	- dy and mind											
ourse Obj 1. To 2. To 3. To 4. To	ectives: overcome stress achieve overall health of bo learn to achieve the highest												
1. To 2. To 3. To 4. To	overcome stress achieve overall health of bo learn to achieve the highest				1 1								
1. Dev	1	mind, pleasing perso			n								
		Detailed	<mark>l Sylla</mark> bus:	111									
nit	100	Descript	ion		1000	Duration (H)							
1 Yan	nitions of Eight parts of Yo a and Niyam. a and Don't's in life.	g. (Ashtanga )			15	6							
2. Reg Typ	ayam ularization of breathing tech es of pranayama roach to day to day work an	•				6							
	the second se	1.44			Tota	al 12							
ext Books					1	-							
. Yogic eference H	Asanas for Group Tarining-	Part-1" : Janardan Sw	ami Yogabh	yası Manda	II, Nagpur								

2. Wendelin Küpers, David J. Pauleen, A Handbook of Practical Wisdom Leadership, Organization and Integral Business Practice, 2016

3. A Foundation Course in Human Values and Professional Ethics Presenting a Universal Approach to Value Education -Through Self-exploration



Progra		M. Tech. Mechanical		ring)	Semester			
Course	:	Optimization Techni	ques in Design		Code : M			
		Teaching Scheme			Evalua	ation Scheme		
L	ecture	Hours	Credit	IE1	IE2	ETE	Total	
	3	3	3	20	30	50	100	
	nowledg							
		ng Mathematics is esse	ential					
	<b>Objecti</b> introduc	ves: e students to the mode	ling of constraine	d decision-mak	ing problems an	d optimization.		
		dents with the basic m						
		dents with the modelli						
		dents with the skills ne	ecessary to solve a	nd interpret opt	imization proble	ems in engineering.		
	Outcom							
		e course, the students s						
		mathematical program				al optimization techn	iques	
		he results of linear pro			insights			
		timum parameters for	non-linear probler	ns.				
		he optimized model.		h a da				
		are to solve problems ology optimization for		nods.				
0. F	apply top	ology optimization for	U U	iled Syllabus:		1		
T		10 M					Duration,	
Unit			Des	cription			(H)	
	Classical Optimization Techniques							
1.		matical Modeling, C			variable optim	nization and multi	7	
		le optimization, with a	nd without constra	ai <mark>nts.</mark>				
2.		Programming					8	
2.		hase simplex method,	primal and dual S	implex Method	, revised simple	ex method.	0	
		inear Programming						
3.		ation and iterative r	nethods for one-	dimensional m	ninimization an	d multi dimension	7	
		ization.						
		n Methods of Optim					0	
4.		c algorithms, Simu	lated Annealing,	Particle Swa	arm Optimizat	ion, Ant Colony	8	
_		ization, etc.						
F		ation Modeling	tupos limitat	no voniono 1	one of media	ing Monto Carl	-	
5.		action, definition and				ing, Monte Carlo	7	
		d, applications, advant	ages and minitatio	ns or siniuratio		2011		
6.		m formulation and par	ameterization of d	lesion solution	methods topol	ogy optimization as	8	
0.		in tool, Complications,				ogy optimization as	Ū	
	4 40512	,,	comented reper		SP	Total	45	
Text Bo	oke.					I Utdl	5	
<b>1ехі Б</b> ( 1.		ering Optimization: Th	eory and Practice	Singiresu S R	ao John Wiley	& Sons		
2.	0	al Optimization Metho	•					
<u> </u>		ation for engineering			115, 111. 1 15g.141 1	shatti, springer		
	ce Book	6 6	<i>,,</i> ,.,					
1.		gy Optimization – The	ory, Methods and	Applications, I	M. P. Bendse, Q	. Sigmund		
2.	·	onary Topology O		11			tions, X. Hua	
		ie, Wiley			,	11		
3.		al Optimization, Raph				nic Publishers		
	Mathen	natical Modelling, J N	Kanur New age i	ntornational nu	hlipption			
4.		ation concepts and ap						

Progra				(Design Enginee	ering)	Semester :		
Cours	e :		<mark>ed Vibrations</mark> ing Scheme	and Acoustics		Code : MN	MD2407 tion Scheme	
		<u>l eacr</u>						
I	Lecture		Hours	Credit	IE1	IE2	ETE	Total
	3 knowled		3	3	20	30	50	100
a. P b. E c. D Course 1. T ro 2. S	Physics Engineeri Dynamics <b>e Object</b> To enabl esponse Students	ng Mathe s of Mach tives: e student to differe will be ab	ninerya to analyse and excitation co	model physical s			principles of Vib	
After le 1. <b>F</b>	'ormulat	the course te and Ev	aluate problen	should be able to: ns of MDOF mech lels Transient Vib			derstanding to des lesign of system.	ign the system.
4. U 5. U co	Understar Understar omplianc	nd Randon nd Basic ce to nois	m process para principles in e regulations.		se vibration resp rement of sou	oonse of single d nd Power and a	egree linear system apply to analyze control.	
			-		ailed Syllabus:			
Unit		- 51	1000	Des	cription			Duration,
c int					cription			(H)
1.	Multi Degree Freedom System Free vibration equation of motion, influence coefficient i) stiffness coefficient (ii) flexibility coefficient generalized coordinates, coordinate couplings, Lagrange's equations matrix method Eigen values Eigen vector problems, modal analysis, forced vibrations of un-damped system and modal analysis.							
2.	Transie Respon	ent vibra	tions mpulsive input	, <mark>Response</mark> to ste	p input, Respon	se to a pulse inp	ut-rectangular pul	se 8
3.	Balanci	n and vib	tating machine				requency, vibration	
4.	Rando Probabi	<b>m Vibrat</b> ility, Aut	o and cross co		n, spectral dens	ity, response of	linear systems, ar	nd 8
5.	analysis of narrow band systems         Acoustics         Basics of acoustics – Terminologies speed of sound, wavelength, frequency, and wave number, acoustic pressure and particle velocity, acoustic intensity and acoustic energy density, spherical wave, Directivity factor and directivity index, levels and the decibel, combination of sound sources, octave bands, weighted sound levels. Sound Power measurement in a reverberant room, Sound							al 7
6.	Acoust Transm inciden region-	ics of Pan ission of ce, sound mass-cor	rtitions, Enclo Sound: change transmission t ntrolled region	noic, sound power sures, Barriers a s in media with n hrough a wall, tra - damping-contro se control strategi	nd Mufflers ormal incidence nsmission loss lled region, Des	e, changes in med for walls - stiffne sign of Acoustic	ess-controlled	8
							Tot	al 45
1. 2.	Mech Theor Indus Noise ence Boo Mecha Funda	ry of Vibi trial Nois and Vibi oks: anical Vib mentals o	rations with Ap e Control, Ran ration Control, prations, G K C of Vibration, Le	Rao, Pearson Edu plications, W. T. dell Barron, Marc <u>M L Munjal, Wor</u> Groover, Nem Cha conard Meirovitch	Thomson, Pears cel Dekker, Inc. rld Scientific Pu and & Bros, Roo n, McGraw Hill	iblishing Co. Ltd orkee, India International Ed	ison	
3. 4. 5.	Mecha	anical Vib	orations, AHC	l: Ashok Kumar I Church, John Wile se Engineering, A	y & Sons Inc			

Cours	am: M. Tech. Mechar e : Professional Core				Semester : II Code : MMD2408	
Jours	Teaching Schem			Fya	uation Scheme	
Pract		Credit	TW	PR	OR	Total
2		1	50		50	100an
	knowledge of:	L	50		50	100
a.		cs is essential				
1. 2. Cours	e Outcomes: earning the course, the stu	ne skills necessary dents should be al	to solve and interplate to:	oret optimizat	ulate optimization probler ion problems in engineerin	
1. 2. 3.	interpret the results of a	model and preser			y)	
Juide	lines :					
1.	I I I I I I I I I I I I I I I I I I I		hree from Part A	and Three fr	om Part B	
2.	Total : 6 experiments	12 hours				
			Detailed Syllab			
	P	art A: Optimiza	tion Techniques in	i Design ( Ar	Y Inree)	Duration,
Expt.			Description			(H)
1.	Mathematical modeling	of a real life pro	blem			2
2.	Primal dual simplex me					2
3.	Sensitivity analysis of li					2
4.	Optimization using non-	-				2
5.	Optimization using mod					2
					Total (Any Three)	6
Cours After 1 1	rr J	e understanding of dents should be a trement technique scipals in acoustic	of system. ble to: es and Analyse usir	ig modern too	ANG YOR	
		gulations.	Detailed Syllab	16.		
	Р	art B: Advanced	Vibrations and A		NY Three)	
Expt			Description	, ,		Duration,
anpr	Coso Study on Time de		-			( <b>H</b> )
-	analysis / machine condit	tioning and monit	ency domain analys coring / fault diagno		experimental modal	(H) 2
1.		tioning and monit nite element Ana ilysis analysis	ency domain analys coring / fault diagno		experimental modal	
1. 2.	analysis / machine condit Simulation study using fi a. Modal ana b. Harmonic c. Transient Modal Analysis with Imp	tioning and monit inite element Ana alysis analysis analysis pact Hammer Test	ncy domain analys oring / fault diagno lysis Tool on t	osis		2
1.       2.       3.	analysis / machine condit Simulation study using fi a. Modal ana b. Harmonic c. Transient Modal Analysis with Imp Electro Dynamic Shaker	tioning and monit inite element Ana ilysis analysis analysis pact Hammer Test to Obtain Natural	ncy domain analys oring / fault diagno lysis Tool on t I Frequency and Dy	vnamic Studie	s of a Cantilever Beam.	2
1.       2.       3.       4.	analysis / machine condit Simulation study using fi a. Modal ana b. Harmonic c. Transient Modal Analysis with Imp	tioning and monit inite element Ana ilysis analysis analysis pact Hammer Test to Obtain Natural	ncy domain analys oring / fault diagno lysis Tool on t I Frequency and Dy	vnamic Studie	s of a Cantilever Beam.	2 2 2 2
1.       2.       3.       4.       5.	analysis / machine condit Simulation study using fi a. Modal ana b. Harmonic c. Transient Modal Analysis with Imp Electro Dynamic Shaker Case study Analysis mac	tioning and monit inite element Ana ilysis analysis analysis pact Hammer Test to Obtain Natural	ncy domain analys oring / fault diagno lysis Tool on t t l Frequency and Dy	vnamic Studie	s of a Cantilever Beam.	2 2 2 2 2 2

- 1. Optimization Concepts and Applications in Engineering, Belegundu, Chandrupatla,
- 2. Machinery Condition Monitoring: Principles and Practices, A. R. Mohanty, CRC Press, 2014
- 3. Vibration and Acoustic: Measurement and Signal Analysis, C. Sujatha, Tata McGraw Hill Education Pvt. Ltd

Progr		Tech. Mechanical				Semester : II	
Cours		tigue and Fracture	Analysis (Profes	sional Elective	,	Code : MMD2504	A
	]	eaching Scheme			Evalua	ation Scheme	
	Lecture	Hours	Credit	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Prior	knowledge o						
a.							
b.		ng Metallurgy					
Courr	se Objectives	cienceare esser	ntial				
1.	•	: fatigue life at differe	ent loading condit	ions			
2.		ware about the anal			chanical compo	onents	
	se Outcomes		<i>j</i> 515 01 1 1 <b>1 1 1 1 1 1 1</b> 1 1				
After	learning the c	ourse, the students	should be able to:				
1.		nd describe the basic					
2.		d experimental tech			g and standards		
3.		nd evaluate fatigue f					
4.		ear elastic fracture m					
5. 6.		d Crack resistance a				d application of such	noromotors f
0.		l brittle materials	etween clack up	opening displac	ement, SII <sup>*</sup> and	a application of such	i parameters i
	ductile un		Det	ailed Syllabus			
Unit	D	A 44		<u> </u>			Duration,
	Descriptio	n					<b>(H</b> )
	Fatigue M						
1.		ing uniaxial, biaxi					7
		tigue damage theor	ies of crack initiat	ion, stress based	and strain bas	ed approach	
2	Fatigue Te		ntation alassical	mathada of fat	ious testing	ACTM stondards	8
2.	-	sition and instrume reparation, procedur		methods of fat	igue testing, A	ASTIM standards -	ð
		ses in Fatigue		_	_		
3.		alysis in frequency	domain, vibration	n fatigue, fatigu	e of welded s	tructure, corrosion	7
		h temperature and lo					
	Linear Ela	stic Fracture Mech	anics				
4.		s of fracture, initiat					8
т.		ffects of geometry,			cept – Griffith	theory of fracture,	0
		nce during crack gr					
-		nsity factors – Con					_
5.	crack, roun criterion	d hole with crack,	superposition of	stress intensity	factors, leak be	efore break (LBB)	7
		lastic Fracture Me	chanics		_		
		n, crack tip stress		pproximation.	Dugdale's app	roximation, crack	8
6.			the plastic zone -				0
6.		placement, shape of					45
0. 		placement, shape of				Total	
	Books:	•					
	Books: 1. Fatigu	e Testing and Anal	ysis – Theory and	Practice, YUNC			
	Books: 1. Fatigu 2. Fatigu	e Testing and Anal	ysis – Theory and Materials, Japp S	Practice, YUNC chijve, Kluwer A	Academic		
	Books: 1. Fatigu 2. Fatigu 3. Metal	e Testing and Anal te of Structures and Fatigue in Engineer	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V	Practice, YUNC chijve, Kluwer A Viley-Interscien	Academic ce	vier	
	Books: 1. Fatigu 2. Fatigu 3. Metal	e Testing and Anal	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V	Practice, YUNC chijve, Kluwer A Viley-Interscien	Academic ce	vier	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Eleme ence Books:	e Testing and Anal te of Structures and Fatigue in Enginee ents of Fracture Mec	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I	Practice, YUNC chijve, Kluwer A Viley-Interscien Kumar, Mc Grav	Academic ce v Hill Educatio	vier	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Eleme ence Books: 1. Metal	e Testing and Anal te of Structures and Fatigue in Enginee ents of Fracture Mec Fatigue Analysis H	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I fandbook, YUNG-	Practice, YUNC chijve, Kluwer A Viley-Interscien Kumar, Mc Grav LI LEE, Elsevie	Academic ce v Hill Educatio	ovier on	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Element ence Books: 1. Metal 2. Desig	te Testing and Anal te of Structures and Fatigue in Enginees ents of Fracture Mec Fatigue Analysis H n & Analysis of Fat	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I fandbook, YUNG- igue Resistant We	Practice, YUNC chijve, Kluwer A Wiley-Interscien Kumar, Mc Grav LI LEE, Elsevie elded Structure, J	Academic ce v Hill Educatio	vier	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Element Pence Books: 1. Metal 2. Desig 3. Fractu	te Testing and Anal te of Structures and Fatigue in Enginees ents of Fracture Mec Fatigue Analysis H n & Analysis of Fat tre Mechanics Ande	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I fandbook, YUNG- igue Resistant We erson T.L., CRC P	Practice, YUNC chijve, Kluwer A Wiley-Interscien Kumar, Mc Grav LI LEE, Elsevie Elded Structure, I ress	Academic ce w Hill Educatio er Dieter Radaj, W	ovier on	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Eleme ence Books: 1. Metal 2. Desig 3. Fractu 4. Fractu	te Testing and Anal te of Structures and Fatigue in Enginee ents of Fracture Mec Fatigue Analysis H n & Analysis of Fat tre Mechanics Ande tre Mechanics, Nest	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I andbook, YUNG- igue Resistant We rson T.L., CRC P or Perez, , Kluwer	Practice, YUNC chijve, Kluwer A Wiley-Interscien Kumar, Mc Grav LI LEE, Elsevie elded Structure, I ress r Academic Publ	Academic ce w Hill Educatio er Dieter Radaj, W	ovier on	
Text I	Books: 1. Fatigu 2. Fatigu 3. Metal 4. Eleme ence Books: 1. Metal 2. Desig 3. Fractu 4. Fractu 5. Fractu	te Testing and Anal te of Structures and Fatigue in Enginees ents of Fracture Mec Fatigue Analysis H n & Analysis of Fat tre Mechanics Ande	ysis – Theory and Materials, Japp S ring, Ali Fatemi, V chanics, Prashant I andbook, YUNG- igue Resistant We erson T.L., CRC P or Perez, , Kluwer Introduction, Gdo	Practice, YUNC chijve, Kluwer A Wiley-Interscien Kumar, Mc Grav LI LEE, Elsevie elded Structure, I ress r Academic Publoutos E. E., , Spr	Academic ce v Hill Educatio er Dieter Radaj, V lishers inger	ovier on	

Program:       M. Tech. Mechanical Oesign Engineering       Sector         Course :       Reliability in Engineering Design (Professional Elective-III)       Code : MMD2504B         Image: Course :       Hours       Credit       IE1       IE2       ETE       Tot         3       3       20       30       50       10         Prior knowledge of:       a. Engineering Mathematics is essential       Engineering Mathematics       For onput reliability engineering analysis.       To operform reliability engineering analysis.       To comput reliability engineering analysis.       To comput reliability engineering mathematics to the overall system reliability.       Develop fault trees for a sub-system and apply various reliability models on fault analysis.       Hourse and the impacts to the overall system reliability.       Develop fault trees for a sub-system and apply various reliability ongles on fault analysis.       Image: Sub-system and apply various reliability analability, availability.       Develop fault trees for a sub-system and apply various reliability models on fault analysis.       Image: Sub-system and apply various reliability models on fault analysis.       Image: Sub-system and apply various reliability analability, availability.       Develop fault trees for a sub-system and apply various reliability analability, availability, failure rate, hazard rate, MTTF, MTBF, maintainability, availability, and to configuration, k- out of n structure, complex systems- comperation method, configuration, k- out of n structure, complex systems- commeration method, conditional probability distributions binomial, normal, Poi			
Teaching Scheme         Evaluation Scheme           Lecture         Hours         Credit         IE1         IE2         ETE         Tot           3         3         3         20         30         50         10           Prior knowledge of: a. Engineering Mathematics is essential         20         30         50         10           Course Objectives: 1. To perform reliability engineering analysis. 2. To compute reliability engineering parameters and estimates for applications in mechanical devinanulacturing environments.         After learning the course, the students should be able to: 1. Identify the possible faults in systems and their impacts to the overall system reliability. 2. Develop fault trees for a sub-system and apply various reliability models on fault analysis. 3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools. Detailed Syllabus: Unit         Du           Vinit         Fundamental concepts – I Failure density, failure rate, hazard rate, MTTF, MTBF, maintainability, availability, pdf, cdf, Life characteristic phases, modes of failure, Areas of reliability.         Pu           Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability           System reliability         Series, parallel, mixed configuration, k- out of a structure, complex systems- enumeration method, conditional probability method, cut set and ties et method, conditional probability of objectives apportion			
3       3       20       30       50       10         Prior knowledge of:			
Prior knowledge of:       a. Engineering Mathematics is essential         Course Objectives:       1. To perform reliability engineering parameters and estimates for applications in mechanical devine manufacturing environments.         Course Outcomes:       1. To perform reliability engineering parameters and estimates for applications in mechanical devine manufacturing environments.         Course Outcomes:       After learning the course, the students should be able to:         1. Identify the possible faults in systems and their impacts to the overall system reliability.       2. Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.       Dutit         Pundamental concepts – I       Failure density, failure rate, hazard rate, MTTF, MTBF, maintainability, availability, pdf, cdf, Life characteristic phases, modes of failure, Areas of reliability.       Dutit         Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.       System reliability         3. Series, parallel, mixed configuration, k- out of n structure, complex systems- enumeration method, conditional probability method, cut set and tie set method,       Redundancy         4. Element redundancy, unit redundancy, standby redundancy- types of stand by redundancy, parallel components single redundancy, multiple redundancy. Markov analysis.       System reliability apportionment, Reliability apoprtionm	otal		
a.       Engineering Mathematics is essential         Course Objectives:       1.         1.       To perform reliability engineering analysis.         2.       To compute reliability engineering parameters and estimates for applications in mechanical devinanufacturing environments.         Course Outcomes:         After learning the course, the students should be able to:         1.       Identify the possible faults in systems and their impacts to the overall system reliability.         2.       Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3.       Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit         Fundamental concepts - I         2.       Quality and reliability sasurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         3.       System reliability         Series, parallel, mixed configuration, k- out of n structure, complex systems- enumeration method, conditional probability method, cut set and tie set method.	00		
Course Objectives:         1.       To perform reliability engineering parameters and estimates for applications in mechanical devimanufacturing environments.         Course Outcomes:         After learning the course, the students should be able to:         1.       Identify the possible faults in systems and their impacts to the overall system reliability.         2.       Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3.       Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit         Fundamental concepts - 1         1.       Failure density, failure rate, hazard rate, MTTF, MTBF, maintainability, availability, pdf, cdf, Life characteristic phases, modes of failure, Areas of reliability.         Fundamental concepts - II         2.       Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability         3.       Series, parallel, mixed configuration, k- out of n structure, complex systems- enumeration method, conditional probability method, cut set and tie set method.         Redundancy         4.       Element reliability Analysis         5.       Reliability app			
1. To perform reliability engineering analysis.         2. To compute reliability engineering parameters and estimates for applications in mechanical devine manufacturing environments.         Course Outcomes:         After learning the course, the students should be able to:         1. Identify the possible faults in systems and their impacts to the overall system reliability.         2. Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit         Fundamental concepts - I         Fundamental concepts - I         Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability         System reliability         A eliability apportionment, edudancy, standby redundancy- types of stand by redundancy, parallel components single redundancy, standby redundancy- types of stand by redundancy, parallel components single redundancy, multiple redundancy. Markov analysis.         System reliability apportionment.         Failure Mode, Effects and Criticality Analysis         Failure Mode, Effects and Criticality Analysis <td <="" colspan="2" td=""><td></td></td>	<td></td>		
2. To compute reliability engineering parameters and estimates for applications in mechanical devinanufacturing environments.         Course Outcomes:         After learning the course, the students should be able to:         1. Identify the possible faults in systems and their impacts to the overall system reliability.         2. Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit       Description       Du         Interacteristic phases, modes of failure, Areas of reliability, availability, availability, pdf, cdf, Life characteristic phases, modes of failure, Areas of reliability.         Pundamental concepts - I         Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability       System reliability         3.       Series, parallel, mixed configuration, k- out of n structure, complex systems - enumeration method, conditional probability method, cut set and tie set method.         Components single redundancy, standby redundancy- types of stand by redundancy, parallel components, afgler edundancy, standby redundancy - types of stand by redundancy, parallel components, afgler edundancy, standby redundancy - types of stand by redundancy, parallel components single redundancy, standby redundancy - types of s			
manufacturing environments.       Imanufacturing environments.         Course Outcomes:         After learning the course, the students should be able to:         1. Identify the possible faults in systems and their impacts to the overall system reliability.         2. Develop fault trees for a sub-system and apply various reliability models on fault analysis.         3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit         Fundamental concepts – I         Failure density, failure rate, hazard rate, MTTF, MTBF, maintainability, availability, pdf, cdf, Life characteristic phases, modes of failure, Areas of reliability.         Fundamental concepts – I         Quilty and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability       Series, parallel, mixed configuration, k- out of n structure, complex systems- enumeration method, conditional probability method, cut set and tie set method.         Redundancy       System reliability aportionment, Reliability aportionment techniques – equal apportionment, AGREE, ARINC, feasibility of objectives apportionment.         System reliability apportionment, Reliability aportionment, failure mode, Effects and Criticality Analysis         6.       Failure Mode, Effects and Criticality Analysis         6.	vices and		
Course Outcomes:         After learning the course, the students should be able to:       1. Identify the possible faults in systems and their impacts to the overall system reliability.         2. Develop fault trees for a sub-system and apply various reliability models on fault analysis.       3. Evaluate maintenance schedules and assess the corresponding risk with appropriate techniques and tools.         Detailed Syllabus:         Unit       Description       Du         Intermediate and their impacts to the overall system reliability.         Unit       Detailed Syllabus:         Unit       Description         Fundamental concepts – I         1.       Fundamental concepts – I         Quality and reliability assurance rules, product liability, probability distributions binomial, normal, Poisson, lognormal, Weibull, exponential, standard deviation, variance, skewness coefficient.         System reliability         Series, parallel, mixed configuration, k- out of n structure, complex systems- enumeration method, conditional probability method, cut set and tie set method.         Redundancy         Element redundancy, unit redundancy, standby redundancy- types of stand by redundancy, parallel components single redundancy, multiple redundancy. Markov analysis.         System reliability Analysis	lees and		
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<ol> <li>M.L. Shooman, Probabilistic, Reliability, McGraw-Hill Book Co., 1968.</li> <li>P.D.T. Conor, Practical Reliability Engg., John Wiley &amp; Sons, 1985.</li> </ol>			
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6. A.Birolini, Reliability Engineering, Theory and Practice, Third Edition, Springer, 1999			

Progra Cours		M. Tech. Mechanica Mechatronics and C	M. Tech. Mechanical (Design Engineering)       Semester : II         Mechatronics and Control Systems (Professional Elective-III)       Code : MMD2504C				
cours	<b>c</b> .	Teaching Scheme	one of Systems (1			ation Scheme	040
Lec	ture	Hours	Credit	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Prior 1	knowled	ge of:	-				
a.		ering Mathematics					
<u>b.</u>		tronicsare ess	ential				
2 <b>ours</b> 1.	e Object Select	and Apply various sen	sors/transducers fo	r suitable applic	ation		
2.		sensors/transducers ba					
3.	Unders	stand and apply, interfa	acing with DAQ mi	icrocontroller			
4.		mechanical and electro					
5.		n controller in time and				1	
6.	applica	stand control actions s	such as Proportion	al, derivative a	nd integral an	d study its significa	ance in industr
Cours	e Outcor						
		he course, the students	should be able to:				
1.		se static and dynami		of instruments	and Select a	nd Apply sensors,	transducers
2		rements of physical qu		. 1 .	6	1	1 1 61.
2.		interfacing technique ques to attenuate measu		asurement data	from externa	al environment and	a apply filteri
3.		late the mathematical r		ransfer function	and state space	e modelling approa	ch.
4.		ze system stability base					
5.		the control system for	r meeting desired s	pecification in ti			
6.			frequency domain	and Analyze sy	stem stability	in open and closed	loop in frequen
6.		the control system in h by Bode plot.			stem stability	in open and closed	loop in frequen
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	domain Fundar Classifi	n by Bode plot. nentals of Instrument cation of instruments;	Deta Desc tation Characteristics of 1	niled Syllabus: cription Measurement sy	rstem: Static a	nd Dynamic; Senso	Duration (H)
	domain Fundar Classifi and Tr	n by Bode plot. nentals of Instrument cation of instruments; ransducers: Force, S	Deta Desc tation Characteristics of I peed Measurement	niled Syllabus: cription Measurement sy nt, Strain Mea	stem: Static a asurement, V	nd Dynamic; Senso ibration and Noi	Duration (H) rs se 7
U <b>nit</b>	domain Fundar Classifi and Tr Measure	n by Bode plot. nentals of Instrument cation of instruments; ransducers: Force, S ement: Accelerometer	Deta Desc tation Characteristics of I peed Measurement r, Laser Doppler	niled Syllabus: cription Measurement sy nt, Strain Mea Vibrometer, 7	rstem: Static a asurement, V Femperature:	nd Dynamic; Senso ibration and Noi Pyrometer, Varyin	Duration (H) rs se 7
Unit	domain Fundar Classifi and Tr Measur Resistar	n by Bode plot. nentals of Instrument cation of instruments; ransducers: Force, S ement: Accelerometer nce; pressure: Pirani, M	Deta Desc tation Characteristics of I peed Measurement r, Laser Doppler fcleod; flow rate: U	niled Syllabus: cription Measurement sy nt, Strain Mea Vibrometer, 7	rstem: Static a asurement, V Femperature:	nd Dynamic; Senso ibration and Noi Pyrometer, Varyin	Duration (H) rs se 7
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Unit 1. 2.	Fundar Classifi and Tr Measur Resistar Data A Success Band Pa Mather Classifi space m Stabilit Poles a	n by Bode plot. nentals of Instrument cation of instruments; cansducers: Force, S ement: Accelerometer nce; pressure: Pirani, M cing with Microcontra cquisition System, A ive Approximation, D ass and High Pass; Internation of modelling of I cation of modelling of I cation of modelling, M modelling, Block diagra y analysis of Dynami nd Zeros, System res	Deta Desc Desc tation Characteristics of I peed Measuremen r, Laser Doppler fcleod; flow rate: U oller nalog and Digital Dual slope, DAC: orfacing of sensors/ Dynamic Systems fodelling of Mecha m representation an ic Systems sponse of second	niled Syllabus: cription Measurement synt, Strain Measurement synt, Strain Measurement synt, Strain Measurement, Strain Measurement, Strain Measurement, and handle strain and s	rstem: Static a asurement, V Femperature: umidity measu lwidth, Samp veighted, Nois rduino mechanical, Tr Transient res	nd Dynamic; Senso ibration and Noi Pyrometer, Varyin arement. ling theorem, ADG se Filters: Low Pas ansfer function, Sta ponse specification	Duration (H) rs se 7 ng 7 C: 8 s, 8 te 7
Unit 1. 2. 3.	Fundar Classifi and Tr Measur Resistar Data A Success Band Pa Mather Classifi space m Stabilit Poles a Absolut	n by Bode plot. nentals of Instrument cation of instruments; ransducers: Force, S ement: Accelerometer nce; pressure: Pirani, M cing with Microcontra cquisition System, A ive Approximation, D ass and High Pass; Internation of modelling, M indical Modelling of I cation of modelling, M indelling, Block diagra y analysis of Dynami nd Zeros, System res- e and relative stability	Deta Desc Desc tation Characteristics of I peed Measuremen r, Laser Doppler Icleod; flow rate: U oller nalog and Digital Dual slope, DAC: orfacing of sensors/ Dynamic Systems Indelling of Mecha m representation and ic Systems sponse of second , System Stability	niled Syllabus: cription Measurement synt, Strain Measurement synt, Strain Measurement synt, Strain Measurement, Measurement, Strain Measurement, and strain Measurement of the system, analysis using P	rstem: Static a asurement, V Femperature: umidity measu lwidth, Samp veighted, Nois rduino nechanical, Tr Transient res	nd Dynamic; Senso ibration and Noi Pyrometer, Varyin arement. ling theorem, ADG se Filters: Low Pas ansfer function, Sta ponse specification s of System, Stabili	Duration (H) rs se 7 ng 7 C: 8 s, 8 te 7
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- 2011
- 3. Control System Engineering, Norman Nise, 6th Edition, John Wiley and Sons

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- 1. Mechanical Measurements, S.P. Venkateshan, Ane Books Pvt. Ltd.
- Measurement Systems-Application and Design, Doebelin E.O, McGraw Hill Publication 2.
- Park & Mackay, Practical Data Acquisition for Instrumentation & Control System, Elsevier, 2003 3.
- Dorf& Bishop, Modern Control Systems, 12<sup>th</sup> Ed, Prentice Hall Ogata, Modern Control Engineering, 4<sup>th</sup> Ed, Prentice Hall 4.
- 5.
- Golnaraghi & Kuo, Automatic Control Systems, John Wiley publications, 2010 6.
- C. D. Johnson, Process Control Instrumentation Technology, Prentice Hall, New Delhi 7.
- Astrom & Hagglund, PID Controllers: Theory, Design & Tuning, Chapter 2, 2<sup>nd</sup> Ed, Instrument Society of America, 8. 1995.
- 9. J. P. Holman; "Experimental Methods for Engineers" McGraw Hill International Editions, Mechanical Engineering Series. ISBN 0-07-113354-2



Program:	M. Tech. Mechanical (De				Semester : II		
Course :	Design of Material Hand	ling Equipm	ent (Profession			05A	
	Teaching Scheme			Evalua	ation Scheme		
Lecture	Hours	Credit	IE1	IE2	ETE	Total	
3	3	3	20	30	50	100	
rior knowle							
	ry of Machines	· 1					
	nine Designare essen	tial					
Course Obje	cuves: asilze the importance of mate	mials in both	n product and a	amilaa			
	erstand the benefit of an effici						
	ify and select various types o						
	gn of material handling system				facturing and service	industry.	
Course Outco			1	0		•	
After learning	the course, the students shou	ld be able to					
1. Iden	ify the use and importance of	f material han	dling				
	ify different loads and classif						
	y the design procedures of va	rious materia	<mark>l handling</mark> equip	pment & compo	onents and design the	material	
	ling system.	1		1	c	6	
	gn load lifting & load movem nation in material handling.	ient attachme	its with proper	design consider	ation understand the	use of	
	gn the auxiliary equipment						
5. 2051	si ule adminar y equipment	Det	ailed Syllabus:				
T						Duration	
Unit		Des	cription			<b>(H</b> )	
	Material handling system						
	Principles and features of material handling system, importance, terminology, objectives and benefits of better material handling, classification of material handling equipment						
	ction of material handling e			iunaning equipi			
	ice of material handling of		actors affecting	g for selection	, general analysis	8	
	edures, basic analytical techr	iques, the uni	t load concept				
	gn of cranes						
	d-propelled and traveling					7	
cons	derations for structures of re				overhead traveling		
	es, stability of stationary rota ign of cranes	ry and traven	ng rotary cranes	8,			
Flac	tric overhead travelling cran	e - essential r	arts design pa	rameters struct	ural considerations		
	carriages, long and cross tra					8	
	trical control system						
Loa	d lifting attachments						
	d chains and types of ropes us					7	
	cs, crane grabs and clamps; g		lectromagnet; c	lrums, sheaves,	sprockets		
	ly of bulk material handling		atives of store	an hullt motorie	al handling, gravity		
	ign consideration for convey of solids through slides and					8	
	eyor, pneumatic & hydraulic						
	ojon, priodinalio co njaradile			es, principies es	Total	45	
<b>Fext Books:</b>							
	I. N. Rudenko, 'Material H	andling Equip	oment', Peace P	ublishers			
	2. James M. Apple, 'Materi			John-Wiley and	d Sons		
,	3. John R. Immer, 'Material	Handling' M	cGraw Hill				
Reference Bo	oks:		alaina Classer >	In align and D-11	action Co. I 11		
Reference Bo	<b>oks:</b> 1. Colin Hardi, 'Material H				cation Co. Ltd.,		
Reference Bo	<b>oks:</b> 1. Colin Hardi, 'Material Ha 2. M .P. Nexandrn, 'Materia	al Handling E	quipment <sup>°</sup> , MIF	R Publication,			
Reference Bo	<b>oks:</b> 1. Colin Hardi, 'Material H	al Handling E , 'Bulk Solid I	quipment <sup>°</sup> , MIF Handling <sup>°</sup> , Leor	R Publication, nard Hill Public	ation Co. Ltd.,	blishers	

Program:	M. Tech. Mech				Semester :			
Course :	Computer Aide		gn (Professiona	l Elective-IV)	Code : MN			
	Teaching Sch	neme			Evalua	tion Scheme		
Lectur	e Hour	rs	Credit	IE1	IE2	ETE	Total	
3	3		3	20	30	50	100	
Prior knowl	edge of:			<b>II</b>				
	ors, Programming				_			
	recommended to ha	ave knov	wledge of any ge	eometric modelir	ng software	are essential		
Course Obje		1	incient interes			a of the much of the		
	tion, geometric mo		-	*	-	es of the product dev	elopment II	
Course Outo	*	aening,	design and grap	mear representat	1011.			
	g the course, the stu	idents sh	ould be able to:					
	uate mathematical				bodies.			
	gn & model curves							
	elop codes to solve							
4. Imp	ement various algo	orithms s			110			
				ailed Syllabus:	1110		Duration	
Unit			De	scription			(H)	
Con	puter aided Desig	gn – An	insight				(11)	
				computers for	design. CAD to	ools for the design	7	
proc	process, Hardware requirements in CAD, Input / Output devices; Graphics Displays, graphical							
	memory, Concept of Coordinate Systems, Software requirements in CAD							
	metric Transform		Translation Co.	line Minner De	flastian Datati	Chassing in 2D	0	
	3D; Orthographic a				nection, Rotatio	on, Shearing in 2D	8	
	ves and Surfaces	ind persi	peenve projeene	/13.				
		algorit	hms for lines	point on a line	parallel lines	perpendicular lines,		
						rves (parabola and		
	erbola),			-			7	
						operties; Properties		
		Splines	and NURBS. V	arious types of	surfaces along	g with their typical		
	ications. <b>puter Aided Geo</b> 1	motria T	Design Curryos		_			
Plar					Parametric curve	es. The de Casteljau		
4. Alg	orithm, de Boor Alg	gorithm,	NURBS Theory	y, Properties And	Algorithms, Ge	eometric continuity,	8	
	ection Of Point On							
	puter Aided Geor							
						Algebraic Equation,	7	
Cur	ve And Surface F resection, Projection	0.	1			on, Surface-Surface		
	d Modelling and A			, Projection Of S	urface On Surfa	ces		
Intro	U			of Topology, B	oundary Repres	sentations (B-Rep),		
						ssembly, Drawings,	8	
Extr	usion, Revolve, She	ell, Draf	t, Patterning, Su	rface and Solid I	Boolean Operati	ons		
						Total	45	
Fext Books:	A 1 3 # -1	. 171		1		TIL N. D. II. and D.	1	
						ill, New Delhi, 2 <sup>nd</sup> Ed - Prentice Hall, 3 <sup>rd</sup> Ed		
	r graphics, Schaum				conomy Edition	- i tenuce riall, 5 E	JILIOII, 1980	
	r graphics- Foley V				1996			
Reference B			,	,,,,,,				
1. Rooney	, J. and Steadman,							
	Hua Chang, Produc			g CAD/CAE - T	he Computer Ai	ded		
3. Engine	ring Design Series,	, Elsevie	er Inc., 2014					

Progra				l (Design Engineer	<u> </u>	Semester :			
Course	:		ti-body Dynamic eaching Scheme	<mark>s (Professional El</mark>	ective-IV)	Code : MN	AD2505C ation Scheme		
		1			101				
Le	cture		Hours	Credit	IE1	IE2	ETE	Total	
	3	-	3	3	20	30	50	100	
Prior k a.			I: Machines						
а. b.				are essential					
Course									
1.				amically analyse pl	anar bodies				
2.				amically analyse rig					
Course									
				ts should be able to		h - d		-1	
1. 2.				hods of formulating			vith three dimensiona	al motion.	
2. 3.				nstrained differentia					
4.							ody systems includin	g the kineto-	
	static						5 5	0	
			1.000	De	tailed Syllabus	5	A		
Unit				Des	cription			Duration,	
	<b>D</b> •	•			-			(H)	
				is of multi-body sy		ismotia goor or	d cam pairs. The		
								7	
	automatic assembly of the systems of equations for position, velocity and acceleration analysis Iterative solution of systems of non-linear equations.								
			on of Forces, pla						
							outation of planar	8	
	-			al forces and for ac	ctuator-spring-d	amper element.			
			on of Forces, sp		1.6		с <i>с</i> с	_	
			on of spatial gen nge's multi- plier		external force	s. Computation	of reaction forces	7	
			of Planar Systen		_				
				, Simple application	ns of inverse an	d forward dynan	nic analysis.	8	
	Kiner	natic	s of rigid bodies	in space					
							parameters. Screw	7	
						Relationship be	etween the angular	,	
				derivatives of Eule	r parameters.				
			analysis of spati natic constraints		ames. The cons	traints required	for the description		
							rical). Equations of	8	
			onstrained spatia				· ·		
							Total	45	
Fext Bo									
1.				f Systems of Rigid I					
2. 3.				Dynamics: Theory Aided Analysis of M			all Inc., Englewood	Cliffs NI 198	
4.							Verlag, Berlin, 1988		
5.		, E.J.					s-Basic Methods, Al		
6.				mamics, Butterwor					
7.				Systems Handbook				100.4	
8. 9.							tems, Springer-Verl	ag, 1994.	
9. Referen			n.A., Computatio	nal Dynamics, John	n whey & Sons	, 1774.			
1.	"Why	/ Do			' by Rajiv Ra	mpalli, Gabriel	e Ferrarotti & Mic	chael Hoffmar	
n				ations, January 12	wood Indiad	Drantica Uall			
2.	riin	cipies	S of Dynamics D	y Donald T. Green	woou, 2110 ed.,	пенисе пан			

Program Course :	: M.Tech. Mechanic Professional Electi			<b>IV</b> )	Semester Code : I		06
course.	Teaching Schem		Ve III & Elective	,	ation Scheme	VIIVID 25	00
Practica		Credit	TW	PR	OR	,	Total
2	2	1	50		50		100an 100
_	owledge of:	1	50		20		100
	bjectives:						
	se is to provide students	the tools require	d for Simulate, co	orrelate and vali	date theoretical c	oncepts a	and understan
the princi						1	
	<b>Jutcomes:</b>						
	ning the course the stud						
	Solve open ended Desig Simulate the problem an			to.			
	Understand the impact of						
	Collect data, analyse, in			Juito			
Guidelin		<u></u>					
	Any one subject from I	Part A and Part	<b>B</b> as per students	elective choices			
	Fotal experiments to be						
3.	Fotal : 6 experiments 1	2 hours			24		
		<u> </u>	Detailed S			_	
	Part	A: Elective 1- Fa	atigue and Fract	ure Analysis ( A	NY Three)		D. (1
Expt.			Description				Duration,
-	Case Studies based or						(H)
1.	Rain Flow Counting					-	2
2	-						2
<u>2.</u> 3.	Stress / Strain Based FEA Simulation of fa		Problem				$\frac{2}{2}$
<u> </u>	Crack tip stresses usin						2
5.	Stress Analysis using	*					2
		iniuge i rocessing	>	-		Total	06
	Part A	: Elective 1- Rel	iability in Engin	eering Design (	ANY Three)	1000	
Expt.			Description				Duration,
			_				(H)
1.	Characteristics of Bin						2
2.	Characteristics of Nor	U					2
<u> </u>	Determination of MT Evaluation of basic pr		<b>i</b>	allal systems			2 2
<u>4.</u> 5.	Markov Analysis of s	2	for series and par		town		2
<u> </u>	Reliability allocation		to the work	10 F F F F F			2
7.	Failure mode effects a		/ criticality				2
		j,				Total	06
	Part A.	Elective 1- Mecl	hatronics and Co	ntrol Systems	(ANV Three)	Total	
		Elective 1- Micel		ind of Systems	(mul inice)		Duration,
Expt.			Description				(H)
1.	Interfacing of any sen				100 million (1990)		2
2.	Modelling and Analy		in: State Space M	lodelling of MIN	MO/SISO System	using	2
2.	MATLAB and Simul						
3.	Modelling and Analy		Domain: Transfe	Function Mode	elling of MIMO/S	SISO	2
4.	System using MATL Mapping of pole- zer		evetor stability	f machanical as	stom		2
<u>4.</u> 5.	Design of full state fe						2
5.	Design of full state fe	euback controller		software based)		Total	06
	Part R: E	lective 2- Design	of Material Har	dling Equipme	nt ( ANY Three)		00
<b>T</b> :		eeure a Design				,	Duration,
Expt.			Description				(H)
1	Case Studies Based o						
1.	Use and importance of	f different materi	al handling equip	ment's.			2
2.	Safety in Material has						2
3.	Design aspects and fa						2
4.	Design of any one ma	terial handling sy	stem based on $\overline{M}$	anufacturing ass	embly and cost	T	2
ч.	consideration.						
	1					Total	06

	Part B: Elective 2- Computer Aided Design (ANY Three)	
Expt.	Description	Duration, (H)
1.	Curves: Line DDA, Line Bresenham, Circle Bresenham	2
2.	Curves & Clipping: Mid-point ellipse, Window Clipping	2
3.	Transformations: Translation, Rotation, Scaling, Shear, Mirror	2
4.	Transformations: Combination of above	2
5.	Curves: Bezier curve, B-spline Curve, Hermite Curve,	2
6.	Surfaces: Lofted Surfaces, Bezier surface, B-spline Surface	2
	Total	06
	Part B: Elective 2- Multi-body Dynamics (ANY Three)	
Expt.	Description	Duration, (H)
1.	Velocity and acceleration analysis of planar systems	2
2.	Constraint analysis for planar kinematic analysis for revolute, prismatic, gear and cam pairs	2
3.	Dynamic analysis of planar systems	2
4.	Inverse and forward dynamic analysis	2
5.	Kinematic analysis of rigid bodies	2
6.	Kinematic analysis of spatial systems	2
7.	Reaction forces from actuator-spring-damper system	2
	Total	06



Program	n: M. Tech. Mech	anical (Design Eng	gineering)		Semester : II	
Course			2		Code : MMD2701	
	Teaching Scher			Eval	uation Scheme	
Practi		Credit	IE2	TW	OR	Total
6	6	3	50		50	100
Prior kı	nowledge of:				· · · ·	
a. b.	Basics of Design, Finit Basics of MATLAB ar				posites	
Course	Objectives:					
1.	To understand the 'Pro				ough Mini Project.	
2.	To plan for various act					
3.	To build, design and	implement real t	time application	preferably m	ultidisciplinary domain	n using available
	platforms.					
	Outcomes:					
	arning the course the stu					
1.	Understand, plan and e		ect.			
2. 3.	Design real time applic Prepare a technical rep		ni project			
3. 4.	Deliver technical semin			arried out		
+. 5.	Understand publication		5	arried out.		
	nes : Total : 36 hours	r and copyright proc	cess of research.			
1.	Individual student need	to design and dem	onstrate Mini-pro	iect under the	guidance of allocated g	uide.
2.	Students can choose					
	implementation in Maj			1		0
3.	The hardware impleme			nulation is con	npulsory.	
4.	Mini-Project Report sh					
5.	Paper publication asso				reciable.	
6.	Mini-project work pref	erably should be co		tory.		
			<b>Detailed Syllab</b>			-
		In		us:		
Sr. No.	8		ntegrated Mini-P	us:		
1.	Week 1 & 2 : Mini-pr work	100	ntegrated Mini-P Activity	us:		Duration, (H)
		oject guide allotme	Activity	us: roject	orm, Planning of the	
2.	Week 3 & 4: Literatur	re review and specif	Activity nt, finalization of	us: roject topic and platf		(H)
2.	finalization of topic as	re review and specifind specification.	Activity nt, finalization of fication and Meth	us: roject topic and platf odology Finali	zation, Review 1 for	(H) 7
2. 3.	finalization of topic at Week 5 & 6 : Simulat	re review and specifind specification.	Activity nt, finalization of fication and Meth	us: roject topic and platf odology Finali	zation, Review 1 for	(H) 7
3.	finalization of topic at Week 5 & 6 : Simulat platform	re review and specifind specification.	Activity nt, finalization of fication and Meth opriate software t	us: roject topic and platf odology Finali	zation, Review 1 for cation of hardware	(H) 7 8 7
	finalization of topic at Week 5 & 6 : Simulat platform Week 7 & 8 : understa	re review and specifind specification. ion of Idea on appro- anding platform imp	Activity nt, finalization of fication and Meth opriate software t plementation and	us: roject topic and platf odology Finali ools and finaliz related softwar	zation, Review 1 for cation of hardware	(H) 7 8
3. 4.	finalization of topic at Week 5 & 6 : Simulat platform Week 7 & 8 : understa block level design , R	re review and specifind specification. ion of Idea on approaching platform impeview 2 to understa	Activity nt, finalization of fication and Meth opriate software t plementation and nd the progress o	us: roject topic and platf odology Finali cools and finaliz related softwar f the project	zation, Review 1 for cation of hardware re flow and execute	(H) 7 8 7 8 8 8
3. 4. 5.	finalization of topic a Week 5 & 6 : Simulat platform Week 7 & 8 : underst: block level design , R Week 9 & 10: Mini P	re review and specifind specification. ion of Idea on appro- anding platform impeview 2 to understa roject Report writin	Activity nt, finalization of fication and Meth opriate software t plementation and nd the progress o g and publication	us: roject topic and platf odology Finali ools and finaliz related softwar f the project or copyright p	zation, Review 1 for cation of hardware re flow and execute lanning and execution.	(H) 7 8 7 8 7 8 7 7
3. 4.	finalization of topic at Week 5 & 6 : Simulat platform Week 7 & 8 : understa block level design , R Week 9 & 10: Mini P Week 11 & 12: Demo	re review and specifind specification. ion of Idea on appro- anding platform impeview 2 to understa roject Report writin	Activity nt, finalization of fication and Meth opriate software t plementation and nd the progress o g and publication	us: roject topic and platf odology Finali ools and finaliz related softwar f the project or copyright p	zation, Review 1 for cation of hardware re flow and execute	(H) 7 8 7 8 7 8 8 7
3. 4. 5.	finalization of topic a Week 5 & 6 : Simulat platform Week 7 & 8 : underst: block level design , R Week 9 & 10: Mini P	re review and specifind specification. ion of Idea on appro- anding platform impeview 2 to understa roject Report writin	Activity nt, finalization of fication and Meth opriate software t plementation and nd the progress o g and publication	us: roject topic and platf odology Finali ools and finaliz related softwar f the project or copyright p	zation, Review 1 for cation of hardware re flow and execute lanning and execution.	(H) 7 8 7 8 7 8 7 8 8

# **Open Electives- II Syllabus**

Program: Course:		- ement for Smart	· · · · · · · · · · · · · · · · · · ·	ical Engineering) Elective-II)	Code: MM	C2602A	
course.	e	ng Scheme			Evaluation Sci		
Lecture	Hours	Credit	IE 1	IE 2	ETE		tal
2	2	2	20		30		0
2. To 3. To 4. To 5. To ourse Outo The lea 1. Ide me 2. Ev eff	provides an in-de make aware about equip with the m provide an in-dep be able to design comes: arrners will be entify and evaluate thods of municipa aluate and analysi ects.	at regulations in the ethods of environ oth understanding the land-fields for the sources; con al waste treatment is the risk and me	he area municipa ment risk assessi of Physiochemic or the smart cities nposition; genera t. thods of handling	cal and biological  tion rates, method ; the hazardous and	ent. treatment of Muni s of separation an d radioactive wast	icipal waste.	ealth
				its treatment and doubter to the second seco			
Unit			Descriptio	č			Duration (H)
1. Fu tra ma	nsport of waste, th	ces; composition, reatment and disp andling rules fo	generation rates osal options. Mu	s, collection of wa nicipal waste nazardous waste,	-		7
2. Fu Fu		racterization of es, measures and	waste, fate an health effects; no	nd transport of uclear power plant s			8
3. Ph (co ph	ombustion, stabiliz	eatment of Solid zation and solidif ocesses for haza	and Hazardous V ication of hazard rdous wastes (so	oil vapour extract	-		7
4. Bi co La	composition of so -metabolism; oxid	ent of Solid and lid waste; princip lative and reduction adfill design for a	nd Hazardous les of biodegrada ve processes; slu	sign Waste Composti ation of toxic wast rry phase bioreact lous wastes; leach	e; inhibition; or.		8
						Total	30
2. LaGi	Pichtel, Waste M			Faylor and Francis lous Waste Manag			

**References:** 

- 1. Richard J. Watts, Hazardous Wastes Sources, Pathways, Receptors John Wiley and Sons, New York, 1997.
- 2. Basics of Solid and Hazardous Waste Mgmt. Tech. by Kanti L.Shah 1999, Prentice Hall.
- 3. Solid And Hazardous Waste Management 2007 by S.C.Bhatia Atlantic Publishers & Dist.

Program		M. Tech. Computati		chanical Engine			
Course	urse:     Electronic Cooling (Open Elective-II)     Code: MMC2602       Teaching Scheme     Evaluation Sci						
Lecture		Hours Credit IE 1		IE 2	ETE		
	2	2	2	20		30	50
	knowle						
		lynamics,					
		echanics,					
		nsferare ess	ential				
	se Objec		antending of best tran	ofon in alastroni	a aquinmant		
1. 2.		blish fundamental under ct a suitable cooling pr					
2. 3.		ease the capabilities in					
3. 4.		lysis the thermal failure					
Outco		sis the thermal failure	e for electronic compe		the solution.		
Outer		earning the course, the	students should be ab	le to			
1.		tand Heat transfer proc					
2.		e thermal failure for ele			lution.		
3.		the best cooling metho					
4.		cooling system for any			kaging approach fo	r any design.	
	0			ed Syllabus:	0011	, ,	
					100		Duration
Unit			Descript	tion			(H)
	Introd	action to Electronics (	Cooling		18-1-21		
		ction, Packaging Trend		<mark>geme</mark> nt, Basics o	of Heat Transfer, C	onduction	
1.		ransfer, Multi-Dimens					7
		nic Devices, Forced (	Convection Heat Tran	nsfer, Radiation	Heat Transfer, co	ontact and	
		ng resistances.		1	1 1 2		
		nics Cooling Methods				51.	
2.		l interface and phase					8
		Heat Pipes in Electron				n Cooling	
		and Two-phase), Cool		igh Density Elec	tronics		_
		ing of Electronic Equ		la stancia E a l	and Can I with		
3.		nents of Electronic Sys				for	7
		g for Chassis and Circu	-		gmenting near trans	ler.	111
		l Parameters Measur					0
4.		ature & humidity req	juirement, CFD anal	ysis for Airflow	v & temperature e	valuation,	8
	tnermo	graphy etc	Souther State			Total	30
						LOTOL	30

S. J. Kim and Sang Woo Lee, "Air cooling Technology for Electronic Equipment", CRC press, London, 1996.

3. F. P. Incropera, "Liquid Cooling of Electronic Devices by Single-Phase Convection", John Wiley& sons, inc, 1999.

#### **Reference Books:**

1. J. L. Sloan, "Design and Packaging of Electronic Equipment", Van Nostrand Reinhold Company, 1985.

2. F. P. Incropera, "Introduction to Heat Transfer", Fourth Edition, John Wiley, 2002.

3. C. Belady, "Standardizing Heat Sink Performance for Forced Convection, Electronics Cooling", Vol. 3, No. 3, September, 1997.

4. C. Biber, Wakefield Engineering, Wakefield, Massachusetts, "Characterization of the Performance of Heat Sinks,", Personal Communication, October 1997.

5. A. B.-Cohen, —Encyclopedia of Thermal Packaging volume 1 to 6l, February 2013, World Scientific Publication

Program: Course:	M. Tech. Computa Renewable Energy			gmeering)	Semester: II Code: MMC260	20
Jourse.	Teaching Scheme	Sources (Open Ele		Evalua	ation Scheme	
Lecture	Hours	Credit	IE 1	IE 2	ЕТЕ	Total
2	2	2	20		30	50
b. Fluid A c. Heat T d. Eleme Course Object Following conc 1. Demon 2. Expose 3. Enable	odynamics; Mechanics; 'ransfer; nts of Electrical Engine	students, alysis solar and Win and design renewab analyze, implement	nd Resources So le energy applia and asses the re	nces and equip al-life systems	ment	
deployr			0			
<ol> <li>Determ</li> <li>Estimat</li> <li>Demon energy</li> </ol>	he course, the learners of ine the fundamental per e the potential of solar strate understanding of conversion systems ine the economic feasib	rformance character and wind energy res the fundamentals of pility of renewable e	ources energy convers nergy technolog	ion from bioma		
		Deta	iled Syllabus:			
Unit		Desci	ription			Duration (H)
capaci1.Solarsolar cSolar 1	energy: Potential of ty, Estimation of solar in thermal collectors – ( ollectors, characteristic Photovoltaic Systems- s parameters on output	adiation General description equation for perform - Working, Construct	and characteris mance evaluatio ctional details &	tics of flat plat n	te and concentratin	<sup>g</sup> 7
Wind2.	energy: Principles and nance, Site selection generator components	l classification of w considerations, Wir	ind energy con nd resource / e	nergy potential		
3. – Ener conver	y from biomass : Sour gy through fermentatio sion, Biogas plants – T	n – Pyrolysis, gasifi ypes of plants –oper	cation and com	oustion – Aerob	bic and anaerobic b	io- 7
4 Geothe Enviro limitat	ermal, Tidal or Wave ermal energy: hot spri nmental impacts, Econ ions, and tidal energy –Scop	ngs and steam ejec omic and social con	tion site selecti nsiderations, Av	ailability, syste	em development and	
					Tota	al 30
Delhi, 199 2. Garg H.P., Company, 3. V.V. N. K and Resou Reference Boo	Prakash J., Solar energ New-Delhi, Latest Edi ishore, Editor, Renewal rces Institute, New Del	y Fundamentals and tion ble Energy Engineer hi, 2008	I Applications, T	Fata Mc Graw I logy, A knowle	Hill Publishing	The Energy
<ol> <li>D.Y.Gosw</li> <li>J F Manw and Sons,</li> <li>R D Bega</li> </ol>	and W.A.Beckman, Syami, F.Kreith and J.F.J ell, J.G.McGowan, A.L May 2002. mudre, Energy Convers Energy Efficiency – V	Kreider, Principles o Rogers, Wind Ener sion Systems, New A	of Solar Enginee gy Explained: T	ring, Taylor and Theory, Design	d Francis, Philadelp and Application, Jo	bhia, 2000. bhn Wiley

K D Begamudre, Energy Conversion Systems, 2
 Bureau of Energy Efficiency – Volume 1

TTUg	ram: 1	M.Tech (E&TC)-VLS	and Embedded S	ystems	· · · · · · · · · · · · · · · · · · ·	Semester: II				
Cou	Irse:Drone Programming for Beginners (Open Elective-II)Code: MET2602Teaching SchemeEvaluation Scheme									
		Teaching Scheme			Evaluatio	on Scheme				
L	ecture	Hours	Credit	IE 1	IE 2	ЕТЕ	Total			
	2	2	2	20		30	50			
ior k	nowledge					_				
a.		derstanding of physics (								
b.	Objective	systems, Modelling Bas	ics –MATLB & SI	MULINK, Progra	amming in pyth	onare esse	ential			
		es: stand the physics behind	drones							
		the mathematical mode		ne from simple m	nathematics & H	Experimental da	ta			
		nent model into Simuli				r				
ourse	Outcome	s:		*						
fter lea		course, the students sho								
1.		& select different access								
2.		the mathematical mod								
3.	Design S	imulink model simulati	· · ·		opter drone.					
			Detail	ed Syllabus:	- C.		Duration			
Unit			Descript	tion			(H)			
		ction to drones: Unma								
1.	-	orogramming and Devel ating a UAS, concerns	1	U	U U	0 0	7			
	-	ccessories and Applica								
2.		orking on a Flight, Prin					8			
		ystems, Control drone (				studie una	0			
		ontrol system develop				adcopter with				
3.	actuator	& propellers functional	ity block. Sensing d	& estimation fund	tionality block	controller	7			
5.		er propenters raneasina		e commanon rune	dionanty block,	controller	/			
5.		ality block, Motor mixin	ng algorithm (RPY)	T) functionality b	lock	100 M	,			
-	Modelli	ality block, Motor mixin ng, Simulation & Fligh	ng algorithm (RPY at control design: 1	T) functiona <mark>lity b</mark> Dynamic quadcor	lock oter system Mod	lel, flight				
4.	Modellin control d	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization	ng algorithm (RPY at control design: I , testing & Tuning	T) functionality b Dynamic quadcor the model, Fligh	lock oter system Mod	lel, flight	8			
-	Modellin control d	ality block, Motor mixin ng, Simulation & Fligh	ng algorithm (RPY at control design: I , testing & Tuning	T) functionality b Dynamic quadcor the model, Fligh	lock oter system Mod	lel, flight pplicable	8			
4.	Modellin control d software	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization	ng algorithm (RPY at control design: I , testing & Tuning	T) functionality b Dynamic quadcor the model, Fligh	lock oter system Mod	lel, flight	X			
4. Text b	Modellin control d software ooks:	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro	ng algorithm (RPY at control design: I , testing & Tuning cessing, and analys	T) functionality b Dynamic quadcop the model, Fligh is	lock oter system Moo it operations, A	lel, flight pplicable Total	8			
<b>4.</b> <b>Fext b</b>	Modellin control d software ooks: . John Ba	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro aichtal ,Building your o	ng algorithm (RPY at control design: I , testing & Tuning cessing, and analys wn drones, a beginn	T) functionality b Dynamic quadcop the model, Fligh is	lock oter system Moo it operations, A ones, UAVS, an	lel, flight pplicable <b>Total</b> d ROVs	8			
<b>4.</b> <b>Text b</b> 1 2 <b>3</b>	Modellin control d software ooks: . John Ba . Muham . Ryan G	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro aichtal ,Building your o umad Usman , Quadcop ordon , Model based de	ng algorithm (RPY at control design: I t, testing & Tuning cessing, and analys wn drones, a beging ter modelling and c ssign of a quadcopte	T) functionality b Dynamic quadcop the model, Fligh is ner's guide to dro ontrol with Matla er	lock oter system Moo to operations, A ones, UAVS, an ab/Simulink imp	del, flight pplicable <b>Total</b> d ROVs plementation	8			
<b>4.</b> <b>Text b</b> 1 2 3 4	Modellin control d software ooks: . John Ba . Muham . Ryan G . K.S.Fu,	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro- aichtal ,Building your o mad Usman , Quadcop ordon , Model based de R.C.Gonzalez, C.G.Le	ng algorithm (RPY at control design: I t, testing & Tuning cessing, and analys wn drones, a beging ter modelling and c sign of a quadcopte e, Robotics contro	T) functionality b Dynamic quadcop the model, Fligh is ner's guide to dro ontrol with Matla er ol, sensing, vision	lock oter system Moo to operations, A ones, UAVS, an ab/Simulink imp and intelligence	del, flight pplicable <b>Total</b> d ROVs plementation e	8			
<b>4.</b> <b>Text b</b> 1 2 3 4 <b>Refere</b>	Modellin control d software ooks: . John Ba . Muham . Ryan G . K.S.Fu,	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro- aichtal ,Building your o mad Usman , Quadcop ordon , Model based de R.C.Gonzalez, C.G.Le	ng algorithm (RPY at control design: I t, testing & Tuning cessing, and analys wn drones, a beging ter modelling and c sign of a quadcopte e, Robotics contro	T) functionality b Dynamic quadcop the model, Fligh is ner's guide to dro ontrol with Matla er ol, sensing, vision	lock oter system Moo to operations, A ones, UAVS, an ab/Simulink imp and intelligence	del, flight pplicable <b>Total</b> d ROVs plementation e	8			
4. Text b 1 2 3 4 Refere 1	Modellin control d software ooks: . John Ba . Muham . Ryan G . K.S.Fu, ence Book R.K.I	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro aichtal ,Building your o umad Usman , Quadcop ordon , Model based de , R.C.Gonzalez, C.G.Le s: Mittal , I.J.Nagrath,Rob	ng algorithm (RPY at control design: I , testing & Tuning cessing, and analys windrones, a begin ter modelling and c esign of a quadcopte e, Robotics control	T) functionality b Dynamic quadcop the model, Fligh is ner's guide to dro ontrol with Matla er bl, sensing, vision	lock oter system Moo at operations, A ones, UAVS, an ab/Simulink imp and intelligence	del, flight pplicable Total d ROVs olementation e e	8			
<b>4.</b> <b>Text b</b> 1 2 3 4 <b>Refere</b>	Modellin control d software ooks: . John Ba . Muham . Ryan G . K.S.Fu, nce Book R.K.I . Ben Ru	ality block, Motor mixin ng, Simulation & Fligh lesign, 3D visualization for data collection, pro aichtal ,Building your o mad Usman , Quadcop fordon , Model based de , R.C.Gonzalez, C.G.Le	ng algorithm (RPY at control design: I , testing & Tuning cessing, and analys windrones, a beginn ter modelling and c e , Robotics control otics and control mate guide), , Creat	T) functionality b Dynamic quadcop the model, Fligh is ner's guide to dro ontrol with Matla er ol, sensing, vision wedge Br teSpace Independ	lock oter system Moo at operations, A ones, UAVS, an ab/Simulink imp and intelligence ings Free lent Publishing	del, flight pplicable Total d ROVs olementation e com Platform	8			

Course :		am: M. Tech (E&TC)-VLSI and Embedded Systems Semester: II							
	se :       Instrumentation and Measurements (Open Elective-II)       Code: MET2602B							3	
	Те	eaching Scheme		_	I	Evalua	ation Scheme	е	
Lectu	Lecture Hours Credit IE 1 IE 2 ETE								Total
2		2	2	20			30		50
b. B c. A ourse Ob o impart k 1. B 2. F 3. C 4. V 5. V ourse Our fter learnin 1. A 2. D 3. U	asics of s asic of El nalog and <b>jectives:</b> nowledge asic func undamen compariso various sta various tra <b>tcomes:</b> ng the co nalyse di Design and understand	ensors and Actuat lectronics d Digital Systems e on the following tional elements of tals of electrical a on between variou orage and display ansducers and the urse, the students fferent measuring d evaluate charact d different types of	are essential Topics - f instrumentation nd electronic instr s measurement teo	ruments chniques ystems y electronics/me tt types of mech analyzer.	atronics/ el	lectric	al/ electronic	system	
			*	etailed Syllabu	-				
Unit	1.5	S		scription	10-1 m	Co	llea		Duration (H)
1. ar br C m	nd their a ridge, A onnection neter, A	analysis, Standar C bridges – Kel 1. Electronic Instr	ccuracy, Precision ds of measureme vin, Hay, Maxw uments for Measu ue- RMS respor	nt. Bridge Mea ell, Schering a ring Basic Para	asurement: and Wien meters: An	DC bridge	oridges- whe es, Wagner d DC	atstone ground	7
2. O Pi Sj w	scillosco robes and pecial Os vave generation	pes: Cathode Ra Transducers, Spe scilloscopes – Sto rator, Frequency -	y Tube, Vertical ecification of an O orage Oscilloscop - Synthesized Sign and square wave g	Oscilloscope. Os e, Sampling Os nal Generator, S	cilloscope scilloscope weep	measu . Sign	rement Tech	niques,	8
3. C	ounter; N	leasurement error	lyzer, Spectrum s; extending frequ cement Transduce	ency range of c	ounters Tra	ansduc	ers:		7
4. D	vigital Da ystem. In	ta Acquisition Sy strumentation Arr	stem: Interfacing plifier, Isolation A ystems.IEEE-488	transducers to Amplifier. An Ir	Electronic	cs Con			8
C	1								

**Reference Books:** 

- Electronics Instruments and Instrumentation Technology Anand, PHI
   Doebelin, E.O., Measurement systems, McGraw Hill, Fourth edition, Singapore, 1990.

Progra				Ided Systems	(0 == :		ter : II
Course			Microproces	sors Applications		/	: MET2602C
	Teaching	Scheme	1		Evalua	tion Scheme	
	Lecture	Hours	Credit	IE1	IE2	ETE	Total
	2	2	2	20		30	50
	owledge of:						
	Digital Electroni	cs					
ourse (	<b>Objectives:</b>						
1.	To explain archite						
2.	To make students						
3.	To explore interfa	acing of real-v	vorld periphe	ral devices, variou	is hardware and	software tools fo	or developing
4	applications.	hitaatura and	***	'a model of odver	and propagar a	nd microcontroll	~*
4. 5.	To explain the arc						
	To acquaint the le Dutcomes:	earner with ap	plication list	ruction set and log	gie to build asse	mory language p	rograms.
	ning the course, th	e studente che	ould be able t	0.			
1.	Learn importance				signing embedd	led application	
2.	To apply the prog					ied application	
3.	Learn use of hard				a approation.		
4.	Develop interfacin						
		0		Detailed Syllabus	:	100	
Unit	1.8	1		escription	-		Duration, (H)
1.	Introduction to s architecture, 8051 timers and serial c	assembly lan	iguage progra				ts, 7
2.	Microcontrollers Development Env Debugging and Si	vironment: ass	embler, com	piler and integrate			em <b>8</b>
3.	System level inter Pentium; Introduc methodologies, er	rfacing designation to RISC	<b>n;</b> Advanced processors; A	Microprocessor A RM microcontrol	llers; Embedded	system design	7
4.	Microcontroller actuators, and men					es, Sensors,	8
		1.19	1			To	tal 30
ext Boo	ks:						222
1.	BarryB Brey, The Delhi, 2003.ISBN				ming and interf	acing, Prentice h	all of India, New
2.	Mohammad Ali N Pearson education						led Systems
eferenc	e Books:			ni/omeage	prings i	recourt	
1.	Chris H. Pappas, 10: 0078812429,			86 Microprocesso	r Handbooksl, I	McGraw-Hill Os	borne Media, ISBN
3.	Walter A. Triebel, 0137877307, 978		Dx Micropro	ocessor: Hardware	, Software, and	Interfacing, Pears	son, Education, ISE
4.	Mohammad Rafic -10:0966498011,			sors: Theory and A	Applications: Int	el and Motorola'	, Prentice Hall, ISI
2.	K. Bhurchandi, A ISBN: 978-1-25-9	. Ray, —Adv		processors and Per	ipherals, McGra	aw Hill Education	n, Third Edition,

Program:	M. Te	ech (E&TC)- VLS	I & Embedde	ed Systems		Semester: II	
Course:	Electi	ronics Implementa	ation Platform	n (Open Elec	tive-II)	Code: MET2602D	
	Tea	ching Scheme			]	Evaluation Scheme	
Lectur	e	Hours	Credit	IE1	IE2	ЕТЕ	Total
2		2	2	20		30	50
b. Pyth c. Elect ourse Obje	nguage, on tronic ci ctives:	rcuitsare estout the Arduino, Ra		Ds and all of	her associate	d platforms	
2. Un 3. Dis	derstand cuss bas		of micro cont d structures r	rollers and co equired for ba	mputers in sc sic operation	cience and technology.	
1. Apj 2. Acc 3. Uno	the couply logic quire kno derstand	rse, the students sh cal thinking and pro owledge about Rasp Digital Signal proc ing rapid prototypi	blem-solving pberry pi for i cessing impla	skills with A implementatic ntation basics	n of applicat		
		<u>8119</u>		Detailed Sylla	abus:		
Unit	1.	8.00	D	Description	Nad	Colle	Duration (H)
	uino: A Debugg		vare, Working	g, Interfacing	, Codi <mark>ng ba</mark>	sics and small applications	7
2. Rasj	pberry p	i : Working, Interfa	acing, Coding	basics and sn	nall ap <mark>plication</mark>	ons and Debugging.	8
		sor for Real time Volume Provident		ge Processing	g. : Wor <mark>king</mark> ,	, Interfacing, Coding basics	7
4 Prog		ole Logic devices:		ing, Interfacir	ng, Coding ba	asics and small applications	8
			奥			Total	30
Program 2. Derek 1 3. Avtar S from T	nming S Molloy I <mark>ingh , D</mark> MS3200	Step by Step, 2019 Exploring Raspberr Digital Signal Proce C54XX),2003	y Pi: Interfaci ssing Implem	ing to the Rea entations : Us	l World with ing DSP Mic	iate Guide to Learn Arduino Embedded Linux 1st Editic croprocessors (with example Implementation of Signal	on,2006
	0,	tems, Second Edition	on, 2017	61000	84 C. WAR	any Confidence	
<b>Reference Bo</b> 1. Mark To 2018		ARDUINO - ARDU	JINO PROGR	AMMING	ARDUINO F	FOR BEGINNERS, Second	Edition June 7,
3. Sen M.	Kuo ,Re				ntations, App	lication and Experiments w	ith the
TMS320	)C55X,	2001		14 EDCA I			0.17

4. Cem Unsalan, Bora Tar, Digital System Design with FPGA: Implementation Using Verilog and VHDL, 2017

Progra		M.Tech (Computer Engineering)       Semester : II         Image Processing with MATLAB (Open Elective-II)       Code: MCE2602A						
Cours	se :	•	<u> </u>	<b>Open Elective-II</b> )	I			
		<b>Teaching Schem</b>	e		Evalu	ation Scheme		
Lecture		Hours	Credit	<b>IE 1</b>	IE 2	ETE	Total	
2		2	2	20		30	50	
	owledge							
a.		mming Basics						
	<b>bjectiv</b>		he field of image pro	cossing				
1. 2.			d algorithms that are		rital image pr	ocessing		
2. 3.			ence in using comput			occssing.		
4.			B Image Processing	-	500.			
	outcome		88					
1.			the students should b	e able to:				
2.					ge transforms	and their properties.	2:	
			s employed for the er					
3.			mage compression an	nd to learn the spat	ial and freque	ency domain techniqu	ies of image	
	compre				1110			
4.			traction techniques for	o <mark>r image ana</mark> lysis a	and recognition	on.		
5.	Develo	p any image proce	* * *					
			De	etailed Syllabus:			Duratio	
Unit			D	escription			(H)	
	Introdu	iction:					(==)	
	What is	image processing	?, What are the fund	amental issues?, V	What is the rol	le of perception? Ima	.ge	
1.	samplin	g and quantization	n, Basic relationship	between pixels, <mark>M</mark>	ATLAB oriei	ntations.	7	
1.		<b>Transformations</b>						
				DFT, FFT, Con	volution, Cor	relation, Discrete co	sine	
		m, Discrete Wave				and the second		
		Enhancement Te		1	TT: /	$\langle \cdot, \cdot, \cdot \rangle$		
2						am processing, Ima		
2.			ging, Spatial filtering,			moothing and Ima	8	
		ing using frequence		y domain intern	ig, image s	and fina	ge	
		mage processing:					3	
			or models, Color trans	sformation. Smoot	hing and Shar	rpening		
2		Compression:	A		0	1 0		
3.	Fundan	nentals, Encoder-I	Decoder model, Type	es of redundancie	s, Lossy and	Lossless compression	on, <b>7</b>	
		-	-	-	-	ransform coding, Ru	in-	
			sless predictive codin	g, Lossy predictiv	e coding, Wa	velet coding.		
		ological Image pr	0		Brings F	reedom"		
						ndary Detection, Ho	ble	
4.			nents, Convex hull, 7 d Representation:	ninning, Thickeni	ng, Skeletons	s, Pruning.	8	
4.			ction, Edge linking a	nd Boundary dete	ction Thresh	olding	0	
						notion in segmentation	on	
	2 4510 8	, and the shirt and by	o ibu b interneu, 11081	en eusea seguiena				
						То	tal 30	
ext Boo								
			igital Image process		on, Inc3/e,200	08.		
			gital Image Processir	ng∥, PHI,1995				
	e Books		TT 11 1					
			g Handbookl, (5/e), (			.11 2002		
- К (`(	onzalez	& K.E. Woods; -I	Digital Image Process	sing with MATLA	BI, Prentice H	an, 2003		
	Dect D		aging Labor WV1					
.W. K.		igital Image Proce	essing, John Wiley & CGraw -Hill, 1994.					
ourse Out fter learnin 1. 2. 3. 4. Unit In S 1. (( w	Teaching         re       Hours         2       2         ledge of:       Ectives:         To acquire knowledge       To develop programs         To acquire skills relate       To acquire skills relate         comes:       Its common and simp         Demonstrate programm       Develop collaborative	Scheme Credit 2 e of basic Linux OS using Shell scriptin ed to Linux file syst s should be able to: ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	g tem ls Jnix Shell rite <mark>re</mark> search-paper	Evaluatio IE 2  erminologies s using LaTex	Code: MCE2602B	Total 50 Duration		
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2 rior knowl ourse Obj 1. 2. 3. ourse Out fter learnin 1. 2. 3. 4. Unit In S 1. ((w	e         Hours           2         2           ledge of:         2           ectives:         To acquire knowledge           To develop programs         To acquire skills relate           To acquire skills relate         2           to develop programs         To acquire skills relate           to develop collaborative         1           Demonstrate program         Develop collaborative           Apply a solution clear         1           introduction to Linux:         1           oftware Licensing and         1           direct and using virtual         1	Credit 2 e of basic Linux OS using Shell scriptin ed to Linux file syst s should be able to: ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	20 , commands, and te g tem Jnix Shell rite research-paper I Linux environmen etailed Syllabus:	IE 2  erminologies s using LaTex	ЕТЕ	50		
2 rior knowl ourse Obj 1. 2. 3. ourse Out fter learnin 1. 2. 3. 4. Unit In S 1. ((w	2         ledge of:         ectives:         To acquire knowledge         To develop programs         To acquire skills relate         comes:         g the course the students         Use common and simp         Demonstrate programs         Develop collaborative         Apply a solution clear         introduction to Linux:         oftware Licensing and         direct and using virtual	2 e of basic Linux OS using Shell scriptin ed to Linux file syst s should be able to: ole Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	20 , commands, and te g tem Jnix Shell rite research-paper I Linux environmen etailed Syllabus:	erminologies s using LaTex		50		
ourse Obj 1. 2. 3. ourse Oute fter learnin 1. 2. 3. 4. Unit In S 1. (0 w	ledge of: ectives: To acquire knowledge To develop programs To acquire skills relate comes: g the course the students Use common and simp Demonstrate program Develop collaborative Apply a solution clear	e of basic Linux OS using Shell scriptin ed to Linux file syst s should be able to: ole Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	, commands, and te g tem ls Jnix Shell rite research-paper I Linux environmer etailed Syllabus:	s using LaTex				
ourse Obj 1. 2. 3. ourse Oute fter learnin 1. 2. 3. 4. Unit In S 1. (0 w	ectives: To acquire knowledge To develop programs To acquire skills relate comes: If the course the students Use common and simp Demonstrate programs Develop collaborative Apply a solution clear introduction to Linux: oftware Licensing and direct and using virtual	using Shell scriptin ed to Linux file syst s should be able to: ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	g tem Jnix Shell rite research-paper a Linux environmer etailed Syllabus:	s using LaTex		Duration		
1. 2. 3. ourse Out fter learnin 1. 2. 3. 4. Unit In S ((www. www. Unit)	To acquire knowledge To develop programs To acquire skills relate comes: In the course the students Use common and simp Demonstrate programs Develop collaborative Apply a solution clear Introduction to Linux: oftware Licensing and direct and using virtual	using Shell scriptin ed to Linux file syst s should be able to: ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	g tem Jnix Shell rite research-paper a Linux environmer etailed Syllabus:	s using LaTex		Duration		
3. ourse Out fter learnin 1. 2. 3. 4. Unit In S 1. (0 w	To develop programs To acquire skills relate comes: In the course the students Use common and simp Demonstrate programs Develop collaborative Apply a solution clear	using Shell scriptin ed to Linux file syst s should be able to: ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	g tem Jnix Shell rite research-paper a Linux environmer etailed Syllabus:	s using LaTex		Duration		
ourse Out fter learnin 1. 2. 3. 4. Unit In S 1. (( w	To acquire skills relate comes: Ig the course the students Use common and simp Demonstrate program Develop collaborative Apply a solution clear ntroduction to Linux: oftware Licensing and direct and using virtual	ed to Linux file system s should be able to: one Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	ls Jnix Shell rite research-paper I Linux environmer etailed Syllabus:			Duration		
fter learnin 1. 2. 3. 4. Unit 1. S 1. (0 w	g the course the students Use common and simp Demonstrate program Develop collaborative Apply a solution clear <b>ntroduction to Linux:</b> oftware Licensing and direct and using virtual	ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	Jnix Shell rite research-paper Linux environmer etailed Syllabus:			Duration		
1. 2. 3. 4. <b>Unit</b> <b>I.</b> (0 w	Use common and simp Demonstrate program Develop collaborative Apply a solution clear <b>ntroduction to Linux:</b> oftware Licensing and direct and using virtual	ble Linux command ming ability using U ly using GIT and w ly and accurately in De Linux introduction	Jnix Shell rite research-paper Linux environmer etailed Syllabus:			Duration		
2. 3. 4. <b>Unit</b> 1. (0 w	Demonstrate program Develop collaborative Apply a solution clear <b>ntroduction to Linux:</b> oftware Licensing and direct and using virtual	ming ability using U ly using GIT and w ly and accurately in De Linux introduction	Jnix Shell rite research-paper Linux environmer etailed Syllabus:			Duration		
3. 4. Unit 1. (0 w	Develop collaborative Apply a solution clear <b>ntroduction to Linux:</b> oftware Licensing and direct and using virtual	ly using GIT and w ly and accurately in De Linux introduction	rite research-paper 1 Linux environmen etailed Syllabus:			Duration		
4. Unit 1. (0 w	Apply a solution clear <b>ntroduction to Linux:</b> oftware Licensing and direct and using virtual	ly and accurately in De Linux introduction	Linux environment Etailed Syllabus:			Duration		
Unit 5 1. (0 w	ntroduction to Linux: oftware Licensing and direct and using virtual	De I Linux introduction	etailed Syllabus:	11		Duration		
1. (c	oftware Licensing and lirect and using virtual	I Linux introduction		1110		Duration		
1. (c	oftware Licensing and lirect and using virtual	Linux introduction	Description			Duration		
1. (c	oftware Licensing and lirect and using virtual	Linux introduction	-					
1. (c	oftware Licensing and lirect and using virtual		TT 1	1'11C.T.'	TT 1	(H)		
1. (c w	lirect and using virtual	Linux Distribution						
W						7		
				grams. Emax a	esktop environment,	/		
U	Inderstanding and manage			ice drivers, Displ	lay etc.;			
	asic Commands and S					1		
	ariables,getcwd() and p							
S	cope,test, return value of				while loop, switch			
<b>2.</b>	ase; Shell functions, pip	e and redirection,	wildcards, escape	<mark>chara</mark> cters; Awk	script: Environment	8		
	<mark>ndwo</mark> rkflow, syntax,		ors, regular exp	pressions, array	ys, control flows,			
le	oops,functions, output re	directions						
L	inux File System and N	Networking:	1	1	1-1-6-1			
	ile System - Manipulati							
	nd relative path; Manij							
L	Directory commands; U		x file system; Ne	etworking - Uno	derstanding network	,		
	eatures; Configuring a ne							
	esting a network connec							
	ssential System Admin		1.0					
	J <mark>sers and Group Mana</mark> ser and group; Comman							
Ν.	In a sumarship and	normission		• • •				
P	rocess and PackageM	anagement: Unde	erstanding nackage	management n	ackage management			
	ommands like rpm, yum							
	og files.		a subserve read					
	)r					8		
	ntroduction to GIT and							
	aTEX:Basic syntax, con							
-	aragraphs; Adding Ima	0		e, graphs; Add	ing references, and			
	ibliography; Installation HT: Creating a project u			h and Marga: Cl	oning a remote reno			
	vorking with a remote rep				oning a remote repo,			
	ashion; Hands-on of GIT		lojeet in a aistribut	cu				
	,				Total	30		
ext Books:								
	Christine Bresnahan, Rich	nard Blum —Linux	Essentials, Sybex,	ISBN 97811190	92063			
	umitava Das, Unix Conc							
eference B	Books:							

Progra	am: M	.Tech (Comput	er Engineering)			Semester : II	
Cours			C (Open Elective-II	[)		Code: MCE2602C	
		eaching Scheme		,	Evaluat	tion Scheme	
Lectu	re	Hours	Credit	IE 1	IE 2	ETE	Total
2		2	2	20		30	50
rior kno	wledge of	•					
a. E	Basic under	standing of com	puter programming				
b. F	Related pro	gramming parad	ligmsare essen	tial			
ourse O	bjectives:						
1.	To introdu	ice the concept of	of Object-oriented d	esign			
2.	To underst	tand and differen	ntiate Unified Proce	ss from other appro	oaches		
3.	To design	static and dynar	nic UML diagrams				
	utcomes:						
fter lear	ning the co	urse the students	s should be able to:				
			and elements of the				
			lel structural and be				
3.	Apply the	concepts of arch	nitectural design for		e for software.		
			D	e <mark>tailed Sylla</mark> bus:			1
Unit		10		Description		1000	Duration (H)
1.			nportance of model JML, Architecture,			ect-oriented modeling,	7
2.	Advanced	d Structural Mo	g: Classes, Relation deling: Advanced Object Diagrams			diagrams. Interfaces, Types and	8
3.	Diagrams Advanced	, Activity Diagr	ams. deling Events and s			s. Use cases, Use case and Threads, time and	7
4.		ural Modeling: modeling techn		rment, Compone <mark>nt</mark>	diagrams and	Deployment diagrams.	8
	4000		10 1			Total	30
2. Jam	dy Booch, es Rumbau 978-01301	igh. Micheal Bla				, ISBN: 0-201-57168 ∠: Pearson Education Ind	lia, ISBN-

#### Reference Books:

- 2. Charles Ritcher Designing Flexible Object-Oriented systems with UML. New Riders Publishing.
- 3. Jackson, Burd Thomson Object Oriented Analysis & Design. Thomson Course Technology.
- 4. Mike O'Docherty Object-Oriented Analysis and Design: using UML. Wiley Publication
- 5. Joseph Schmuilers Teach Yourself UML in 24 Hours. Sams publishing.

Program:	M. Te	ch. (Construction	Management)			Semester : II				
Course :	Contra	Contracts, Tendering & Arbitration (Open Elective-II)     Code : MCI2602A       Evaluation Scheme       e     Hours     Credit     IE 1     IE 2     ETE     Total								
	,	<b>Feaching Scheme</b>			Ev	valuation Scheme				
Lectu	re	Hours	Credit	IE 1	IE 2	ETE	1	Total		
2		2	2	20		30		50		
rior knowl		None								
2. To 3. To course Out	equipped study pri- learn bas comes:		cations for making t pitration in the conte			aspects.				
			e for making constru	action contracts &	& Tenders					
			as per conditions of							
			to resolution of disp		on project	ts.				
			Detai	il <mark>ed Syll</mark> abus:	111					
Unit		1.00	Desc	ription	-	Chen The		Duration (H)		
1. Inc	lian Con jectives	of the act. Introduc		<mark>n legal sy</mark> stem, L		, Voidable, Void contra		7		
2. Co	nstructi aluation ntract do	on Contract Docu of contract docun	ments: nents, need for doc	cuments, present		national and internation of parties to the contr		8		
3. Pro	<b>ages in C</b> eparation	Contracting: of tender docume	ents estimating, pre payments, contracts			uation, award of contr	act,	7		
4. Co	bitration mparison	n: 1 of Actions and	1.5 /	nents, subject r	1	plations- Appointment	of	8		
			1-1-1			Te	otal	30		
2. The In	Engineer idian Co rbitration	ntract Act (9 of 187	72), 1872- Bare Act	- 2006 edition, Pr	ofessional	5 Edition, reprinted in 20	009.			
<ol> <li>Law of 2. Arbitr 2005-</li> <li>The W</li> <li>Standard Govern</li> </ol>	of contract ation, Co Asia Lav Vorkmen ard Gene rnment of	onciliation and Alte w House Publishers _s Compensation A ral Conditions for 1	s. Act, 1923 (8 of 1923	solution Systems- ) Bare Act- 2005-	- Dr. S.R. - Professio	w Agency. Myneni- 2004 Edition, onal Book Publishers. cs and Program Implem	-			

FIDIC Document (1999).
 Dispute Resolution Board foundation manual-www.drbf.org. 30 Edition

Prog	ram:	M. Tech. (Civil)	Construction Mana	gement		Semes	ter : II		
	rse :		nagement (Open El	0		Code :	: MCI2602B		
		Teaching Scheme			Eva		Scheme		
Lec	ture	Hours	Credit	IE 1	IE		ЕТЕ		Total
		2	2	20			30		50
<b>Prior kn</b> a. b.	owledge TQM & N Awarenes	of: AIS at UG Level as of Quality Constru	ction Aspects						••
1. 2. 3. 4. <b>Course (</b> After lea	To <b>apply</b> To <b>apply</b> To <b>apply</b> <b>Outcomes</b> rning the o	stand the need of Q necessary trainings effectively the eight Six Sigma tool for 7 : course, the engineers	M in construction an for the effective utili principles of ISO for rQM in construction s should be able to: M philosophy in con	zation of resources or quality processes project					
2. 3.	Able to us Apply ISC	se effectively QC too	ols. ctive Quality proc <mark>ess</mark>						
			Detai	iled Syllabus:					
Unit		1.8.4	Desc	cription			100		Duration, (H)
1.	A) Defin Quality A Need for Quality 1	Assurance (QA/QC) r TQM in construct manual-Contents, data	given by Deming, b. Total quality cont ction industry. Orga ata required, prepara s in every phase in th	rol (TQC) and To inization necessary ation, responsibility	otal Quali y for imj y matrix,	ty Man plement monito	agement (TQM tation of quali pring for quali	Л), ty,	7
2.	Quality Histogram control c	Control Tools m, Pareto diagram, f construction mate	Fish-bone diagram, rial used in RCC V ecessity, Benchmark	Quality control of Vork- destructive	chart-Test	ting req	uired for qual		8
3.	Study of Purpose 9001. Ce for an ef for achie Develop	<b>ISO 9004- Quality</b> of ISO Standards. D rtification bodies in fective quality proce- ving implementation	System Standards. ifference between IS volved. Eight Princip ess in the organization of or quality system s eles, quality inspection	SO 9001 and ISO 9 bles of ISO-Basic 1 bn. Management su standards.	neaning, apport an	applyin d comn	g these princip nitment necessa	les ary	8
4.	<ul> <li>A) Six Si</li> <li>Definitio</li> <li>sigma tra</li> <li>B) Appli</li> <li>i) RCC V</li> </ul>	igma n of six sigma, evol ining, six sigma as a cation of Six Sigma Vork in building	ution – Historical as an effective tool in T n nstruction process fro	QM.					7
	(11) 1 10000	senione of overall con	is a dealer process in	en concept to com	pretion of	0115	To		30
Text Boo 1. 2. 3.	Quality Total Er 3.Total I	ngineering Quality N	uality Management I Ianagement – Sunil S – The Indian Conte:	Sharma – Macmilla	an India L	.td.			
1. 1 2. 1 3. 2	Mantri Ha Juran_s Q	ndbook – A to Z of uality Handbook – J	ization – ISO 9001 a Construction – Mant oseph M. Juran, A. E ems – Gordon B. Da	ri Publications Blanton. Godfrey –					

Progr	am:	M. Tech. (Civil	Engineering)			Semester : II		
Cours	se :	<b>Operations Res</b>	search (Open Elect	ive-II)		Code : MCI260	2C	
	1	<b>Teaching Schem</b>	ie		Ev	aluation Schem	e	
Leo	cture	Hour s	Credit	IE 1	IE2	2 ETE	To	tal
	2	2	2	20	-	30	5	50
rior kr	nowledge							
a			ncluding Calculus a					
b			us-Based Probability		essential			
			ims at enabling studes and techniques of I		ar Program	nming Problems		
			al solution for Trans					
			select and execute				/ <b>.</b>	
4. T	'o constru	ct network diagram	ms with single and th	nree time estimates	ofactivitie	s involved in the	project.	
			the course, the stude		e to:			
			nd Nonlinear Progra		( D. 11			
			imization Transport select and execute v					
			and expected comp			g decision theory		
		5		Detailed Syllabus				
							1.1	Duratio
Unit		1.0		Description			A 10	<b>(H)</b>
		ction to Operati						
		-	research approach		-	-	-	
		-	lethods for solving	operations resear	ch models,	, Methodology o	of operations	
1.		, Advantages. Programming						7
			of Linear programn	ning Model, Adv	antages. L	imitations. Assu	mptions and	
			ogramming, Guidel					
			l Method and Simpl			0 1		
			ignment Problems		1. E.		1921	
			Transportation Prob					8
2.			Optimality. Mathen	natical Models of	Assignmen	it Problem, Solut	10n Methods	
		nment Problem. <b>1 Theory and G</b> a	mos Thoory				24	
			g Process, Types of	Decision- Makin	g Environ	ment. DecisionM	aking Under	
3.			ory: Introduction, T					7
			: Games with Sadd					
	The Rul	es of Dominance.	, Solution Methods	of Games without	Saddle Poi	nt.		
	Project	Management	11	Knowledge	Bring	s Freedom	10	
4.			rence between PER					8
		-	d Precedence Relation of project c	-	Path Anal	lysis. Project sch	eduling with	
	uncertai	ractivity times, E	sumation of projecte	ompieuon unie.		01947-1	Total	30
'ext Bo	oks			continue a			ittal	50
		a, "Operations Re	search: Theory and	Applications". Tr	inity Press	5th Edition ISBN	No. 978935(	)593363.
			ieberman, "Introduc					
	o.007113							
	ce Books							
<b>eferen</b> 1. ( 2. (	<b>ce Books</b> Gerald Lie Gupta Pre	<b>:</b> eberman, "Operat m Kumar and Hi	tions Research: An I ra D.S, "Problems in ations Research App	n Operations Rese	arch", S. Cl	hand, ISBN No.9	78-812190	96

Wayne L. Winston, "Operations Research Applications and Algorithms", Cengage Learning, 4th Edition, 1987
 P Sankara Iyer, "Operations Research", Sigma Series, TMH, 1st Edition, ISBN No.978-0070669024.

Progra Cours	1			al Intelligence a Science (Open F		ence)	Semester: 1 Code : MD		
Cours	е.	ĩ	ching Scheme	science (Open I			Evaluatio		
Ιe	cture	Ita	Hours	Credit	IE1	IE2	Evaluatio	Total	
	$\frac{cture}{2}$		2	2	20	-	30	<u> </u>	
	Python Statist	basic		ethodsare e					
1. 2. 3. 4.	Apply Explo Desig Use v	y vario ore var n appl arious	ious steps of da lications applyi data visualizat	structures to effo ata science pipeli ng various opera tion tools for effe	ne with role tions for data ective interpr	of Python a cleansing etations and	and transform 1 insights of d	ation.	
ourse C 1.				he course, the stunding of data scie					
1. 2. 3. 4.	Expla Perfor	in the rm hig	essential conce	epts of Python pronatical computati	ogramming. ons.			its.	
Unit			18		Detailed Sy Description			200	Duration (H)
1.	expre Dictio	ssions	, objects and f and operations	functions. Python them	data structu	res includi	ng String, Ar	ata types, variables, ray, List, Tuple, Set,	6
2.	core of of produced data a Pytho Grasp devel for ir Experi for I comp using matpl	compe ogram analys on's R bing P opmen denta riment Data S uting Sciki otlib,	tencies of a da ming, Creating is, Learning fro ole in Data S lython's Core I nt goals, Work tion, Working tation, Conside Science, Acce- using NumPy, t-learn, Going Creating grap	ta scientist, Link g the Data Scien om data, Visualiz cience, Introduc Philosophy, Cont ing with Python, at the command ring Speed of Ex- ssing scientific Performing data for deep learnin hs with Network	ting data science Pipeline, zing, Obtaining ring Python' tributing to detting a tributing to detting a tributing to detting a tributing to detting a tributing detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting detting det	ence, big da Preparing ng insights s Capabilit data scienc aste of the the IDE, P ualizing Pc SciPy, P sing pandas s and Ten HTML docu	ta, and AI, U the data, Per- and data pro- ies and Won e, Discoverin language, Un reforming Ra ower, Using the erforming fu s, Implementi sorFlow, Plo iments using I	-	9
3.	multi Form color	ple lir atting s, Ado	the axes, Add	aving your work ing grids, Defin	to disk, Set to the Line	ting the Ax Appearance	tis, Ticks, Grace, Working	g the plot, Drawing ids, Getting the axes, with line style, Using bels, Annotating the	7
4.	Data Defin Demo Perfo on M	Wrai ing a onstrat rmanc lultipl	ngling: Wrangl pplications for ing the hashir e, Benchmarki e Cores, Perfo	r data science, ng trick, Workin	Performing g with dete Vorking with	the Hashi rministic so	ng Trick, Us election, Con	asses in Scikit-learn, sing hash functions, sidering Timing and Running in Parallel	8
								Total	30
<ol> <li>Prog</li> <li>Pand</li> <li>Referent</li> <li>1. In</li> </ol>	on for ( grammi as for ( ice Boo troduc	ing thr everyc o <b>k</b> ing D	ough Python, None :Python Da	mies 2nd Edition M. T. Savaliya, R ta Analysis, Dan g Data, Machine	. K. Maurya iel Y. Chen,	a, G. M. Ma Pearson	agar, STAREI		0

Program	M. Tech. (A	Artificial Intellig	gence & Data Sci	ence)	Semester : II		
Course :			works (Open Ele		Code : MDS2602	2B	
	Teaching Sche	me		]	Evaluation Scheme		
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Tota	al
2	2	2	20	-	30	50	
a. Linea b. Math	wledge of : r Algebra ematicsare bjectives:						
funda	amentals		sign the required a		e understanding of net stems	iral networks	
Course O 1. Demu 2. Defin 3. Ident 4. Expla 5. Anal	utcomes: After 1 onstrate ANN str ne foundations an ify structure and ain Feed forward.	earning the cours ucture and activa d learning mecha learning of perce , multi-layer feed Function Networ	e, the students sho tion Functions unisms and state-sp ptions forward networks ks, Regularization	ould be able t pace concepts s and Back pr and RBF net	o: s opagation algorithms		
			Detailed	Syllabus:			
Unit			Desc	ription			Duration (H)
<b>1.</b> I	ntroduction and				icial neurons. Mode chitectures.	l of an ANN.	6
2. N	pace concepts, C	ndations and Le oncepts of optim	earning mechanisr nization, and Erro earning. Competiti	r-correction 1	g vector and matrix; earning.	algebra, State-	8
<b>P</b> S <b>3.</b> B	erceptrons ingle-layer perce	ptrons, Structure	and learning of	perceptrons,	Pattern classifier, inton convergence. Lir		7
4. F	eed forward AN ack propagation	- training and	Multi-layer feed	nctional appr	works. Back propaga roximation with back		9
				0		Total	30
2. Sir 3. Sa <b>Reference</b> 1. No 2. Pa <b>MOOC Co</b> 1. Deep 2. Neu	troduction to Arti mon Haykin, "Net tish Kumar, "Net e <b>Books:</b> eural Networks: A ttern Recognition purses- p Learning Part-I ral Networks and	ural Networks: A aral Networks: A A Systematic Intro- and Machine Le , Swayam Prof.M Deep Learning,	tems, Jacek Zurad comprehensive f classroom approa oduction, Raúl Ro earning, Christoph litesh M. Khapra Coursera, Andrew Prof. Vineeth N Ba	oundation", S ich", Tata Mc jas, 1996 er Bishop, 20 7 Ng	Second Edition, Pears Graw Hill, 2004 007	on Education As	sia.

Progra			nical (Design Eng			Semester : II		
Course	e :		ent Lab - II (Soft	Skills and Englis		Code: M_2101		
		<b>Teaching Schem</b>	e		Eval	uation Scheme		
Pract	tical	Hours	Credit	TW	PR	OR	Г	otal
2		2	2	50		-		50
Course	e Objec	tives:						
1.		cilitate holistic gro						
2.		ake the students av						
3.		evelop the ability o						
4.		*	ght attitude and be	ehavioral aspects a	nd build the s	ame through vario	us activiti	es
	e Outco							
After le		the course the stud						
1.		ess effectively thro						
2.		re for group discu					2	
3.						ugh the knowledg	ge of tear	n work, inte
		nal relationships, o	conflict manageme	ent and leadership	activities			
Guide			1 . 1 . 6'					
1.		experiments to be		out of eight				
2.	Tota	: 6 experiments	12 hours			1 A		
			CI-411 D	Detailed Syllab				
		-	SKIII DO	evelopment Lab (	ANY FIVE)			Duration
Expt				Description				Duration, (H)
	Crour	Discussion: Ma	ka studants awar	of proper and a	obally accord	ted ethical way to	handla	(11)
						speak up one's opin		
1.						arguments making		3
		outors in any team.		ig solution-unver	anaryticar	arguments making	g them	
		c Speaking:						
		one of the followin	activities may be	conducted.				
2.					et 10 minutes	to prepare the spe	ech and	3
4.						ontaneously for 5		5
		n a given topic)	Extempore spece	I (Students denve	r specenes sp	ontaneously for 5 h	linnutes	
			n Any Social Is	sue: Build writin	g skills, imr	prove language an	nd gain	
3.		edge about how to			ig bitilis, imp	nove nunguage a	ia guin	3
					pairs, Each	pair will be given a	article	
						article one by one		
4.						needful correction		3
		. The facilitator ca						
-						t to present forcefu	ul	2
5.		ents while respecti						3
						ectively over the	phone.	
	Stude	nts will be divided	into pairs. Each p	air will be given	lifferent situa	tions, such as pho	ne call	
6.						phone call for requ		3
	of urg	ent leave from hig	her authorities. St	udents will be giv	en 10 min to j	prepare. Assessme	nt will	
	be do	ne on the basis of p	performance during	g the telephone ca	1.			
7.	Emai	l etiquettes: To pr	ovide students wit	h an in-depth und	erstanding of v	writing formal ema	ails.	3
8.	Mock	interviews: Guid	e students and con	duct mock intervi	ews			3
0.							Total	15
Tor-4 D	aalaa						IUIAI	13
Text B		ronality Davalar	mont and Coft Cl-1	110				
		ersonality Develop		115				
		e Art of Public Spe	шліпу					
	ence Bo	Empowering Emp	lovos Theore D	asia Shilla				

2. G. Ratigan, Aced: Superior Interview Skills to Gain an Unfair Advantage to Land Your DREAM JOB!



Program:	M.Tech. (Design Engir	neering)			Semeste	r: I and II	-	
Course :	Audit Courses (Semest	ter I and II)			Code :	M_1961 M_2962		
	<b>Teaching Scheme</b>				Evalu	ation Scheme		
Lecture	Hours	Credit	IE1	IF	22	ETE	Total	
1	1				-			
Guidelines: 4. The audit courses are common to all M.Tech Courses. 5. Students can select any audit course from list of audit courses for semester I and II								

6. These are non-credit courses but mandatory to comply the submission of the semester.

### LIST OF AUDIT COURSES (Common to M.Tech and MCA programs)

	SEM-II
M_2962A	Team Building & Leadership
M_2962B	English for Research writing
M_2962C	Disaster Management

# Recondenting the bigs Free entories'

Program	n	M.Tech(All Bran	ches)/MCA			Semester: II		
Course:		Team Building &	Leadership (Aud	lit Courses-II)		Code: M_2962	2A	
		<b>Teaching Scheme</b>			Evaluati	on Scheme		
Lect	ure	Hours	Credit	IE 1	IE 2	ETE		Total
1	l	1	-					
1. 2.	Become	es: and strengthen inte familiar with and d ize students with th	iscuss different lead					
	Outcome			eenn eeneng.				
After lea		course, the student						
1.		ership and teamwo						
2.	To deve	lop the capacity to v			_			
Unit				tailed Syllabus: Description	110			Duration
	<b>x</b> ,	1		-	16.1 1 1	1 10 1		(H)
1.	power transmi means,	ship: Will and responsibly and responsibly and rest t that vision to oth Types of leaders atic, charismatic, particle of the state of t	pectfully: the leadeners. Taking the in the second	er as a team-buil itiative and stim legal, and legit	der, Ability to pl nulate others. Wh imate leader. Ca	an future actions at the word "lea	and der"	6
2.	Team v Why is disadva Traditio organiz Strateg persona		at? The evolution fr the to determine the second second second the second second second second the second second second second the second second second second the second second second second second the second second second second second the second second second second second second second second the second second the second	om group to team e roles in a team. ive and balanced ative environmen vision, values, s e and tasks in	n: development sta teams, Strengthea t. and objectives. S	ning teams within Shared objectives	n the	6
						Γ	otal	12
2. Ro	ephen Co nald A. H	ovey, The Seven Ha leifetz, Leadership Porter, Competitive	without Easy Answ	vers, Belknap Pre				
	ce Books		AND DESIGNA	the lot pe	Fruudo	100 <sup></sup>		
		, Leading Change:						
		aka, The Knowledg est, The Secrets of S			2 "Self-Manage	ement "ngs $32-6$	1	
J. 1011			accessiui i calli Mi	anagement, Chap	. 2, Sen-mailage	mem, pgs. 32-0	1	

Progra	m	M.Tech(All Bran	ches)/MCA			Semester: II	
Course	:	English For Rese	arch Paper Writing	(Audit Courses	s-II)	Code : M_2962B	1
		<b>Teaching Scheme</b>	<del>5</del>		Evalua	ation Scheme	
Leo	cture	Hours	Credit	IE1	IE2	ETE	Total
	1	1	-				
1. U 2. I 3. U 4. I Course	Learn abou Understand Ensure the Outcome arning the	t that how to improve t what to write in each the skills needed v good quality of pap s: course the students	when writing a Title er at very first-time s should be able to:	ubmission			
1. 2.	1	• 1	and prepare and resear ew article, thesis chap	oter and other rel	1	research text effecti	vely
		_	Detai	led Syllabus:	147		Duration
Unit			Desc	ription			(H)
1	Sentence Clarifyin Plagiaris	s, Being Concise an g Who Did What, 1 m, Sections of a Pa he Introduction, Re	Word Order, Breakin ad Removing Redund Highlighting Your Fin per, Abstracts. eview of the Literatur	ancy, Avoiding and	Ambiguity and and Criticizin	l Vagueness, ag, Paraphrasing and	6
2	Key skil Discussio	ls needed: Title,	Abstract, Introductions for the seful phrases, how to				6
	inov um	• Sublinistici				Total	12
Text Bo		006) How to Write	and Publish a Scienti	fic Paper, Camb	ridge Universit		31
Referei 1.	ce Books		a Calana V.I. IV	ne ne iter D			- L.
			or Science, Yale Univ			gle Books) [. Highman's book .	
2.	Highman	$1 \times (1998) Handne$	$\alpha k \alpha t w riting for the$	Mainemancal	CIENCES STAN		

conducting the bigs to extern

Progra	m	M.Tech(All Bra	nches)/MCA		Semester	r: II		
Course	:	Disaster Manag	ement (Audit Cou	rses-II)	Code : N	1_2962C		
	]	<b>Feaching Scheme</b>			Evalua	tion Scheme		
Le	ecture	Hours	Credit	IE-1	IE2	ETE	Total	
	1	1	-					
1. 2. 3.	To teach th Manageme	ngineers about var the concept of Disas ent. To provide insi	0	d measures to be	e taken at diffe	rent stages of disaster rio of disaster manager	nent.	
After le 1.	Learn differ	ourse the students are the students of the students and n	neasures to reduce the for disaster manage	ement at nationa		obal level.		
			Detail	ed Syllabus:			Duration	
Unit	Description							
1.	<b>Introduction</b> – Hazard and Disaster. Concepts of Hazard, Vulnerability, Risks. Different Types of Disaster : A) Natural Disaster: such as Flood, Cyclone, Earthquakes, Landslides etc B) Man-made Disaster: such as Fire, Industrial Pollution, Nuclear Disaster, Biological Disasters, Accidents (Air, Sea, Rail & Road), Structural failures(Building and Bridge), War & Terrorism etc. Slow Disasters (famine, draught, epidemics) and Rapid Onset Disasters(Air Crash, tidal waves, Tsunami) Causes, effects and practical examples for all disasters.						6	
2.	Natural di eruptions. Disaster P and Rehab Models in I Disaster M	isasters- Earthqua Their case studies. revention and M ilitation issues du Disasters. Management : Re	kes, Tsunami, Floo Coastal disasters. C <b>litigation</b> . Refugee ring and after disa	coastal regulatio operations dur isters, Inter-sect	n Zone. ing disasters, toral coordinat and NGO Bo	clones and Volcanic Human Resettlement ion during disasters, dies. Role of IT in	6	
				U		Total	12	
<ol> <li>Pa</li> <li>Tr</li> <li>Ja</li> <li>Ja</li> <li>J.</li> <li>J.</li> <li>C</li> <li>Pr</li> </ol>	ushar Bhatta agbir Singh, I P. Singhal, C . K. Rajan, ublication	charya, Disaster So Disaster, Managen Disaster Manageme Navale Pandharin	varande a	nent, McGraw H ges and Opport ons nospheric Disas	Hill Education ( unities, K W Pr ster Managemo			
<ol> <li>D</li> <li>D</li> <li>D</li> <li>D</li> </ol>	isaster Admi isaster Mana isaster mana isaster Mana	gement- G.K Gho gement – S.K.Sing gement – Vinod K	sh-A.P.H. Publishin	g Corporation bha Singh A – 1 w Delhi,1995	119, William P	l Deep Publications ublications, New Delhi Jew Delhi, 2006.		

# **Course Syllabus**

# **Semester-III**

Program:	M. Tech. (Mech	anical) – Design I	Engineering	S	emester: III					
Course :		ase – I [Company			Code: MMD3702					
	<b>Teaching Scheme</b>				ation Scheme					
Practical	Hours	Credit	IE2	TW	OR	Total				
20	20	10		100	100	200				
Prior knowled 1. Basic 2. Mecha 3. Basics 4. MATI Course Object 1. To und 2. To pla 3. To ena 4. To inc Course Outcor After learning to 1. Under 2. To inte 3. To der 4. Prepar 5. Publis Guidelines : 1. Individ 2. Spons 3. The pl 4. Project 5. At lea and 40 6. Total studer	ge of: knowledge of Mecha unical system design, of Analysis software _AB programming ives: lerstand the product/p n for various activitie able students to apply ulcate research cultur	nism and Machine are essential process developments as of the major pro- the knowledge ab- the knowledge ab- te in students for the s should be able to te an original Projectice in relation to ills in the chosen and cal report based on in reputed journal lesign and demonsect the Internship is accounts are expected as the work should be counts are contact hours to requirements and	ent including budg ject and channeliz out research designeir technical grow ect work with app the identified area urea of study. In the project. and present their suftate project unde exptable considering sults is compulsor inpliance of term w research outcome ompleted for subm with guides and for d implementations	eting. e the work town n and method wth. reciable resea of study. work in repute ng postgraduat y. work associate of Project Stan ission of Diss for reviews; 12	wards product /proc s to develop their p rch outcomes. ed conferences. of allocated guide. a scope. d with subject. age-I ( Conference sertation Phase-I	ess development. roject. or reputed journal) ted to be spend by				
Sr. No.			Activity			Duration, H				
	eek 1, 2 and 3: G alization of topic and			isorship and	project internship,	40				
	eek 4 & 5: Literature view 1 for finalizatio			Finalization,		25				
3 W	eek 6, 7 & 8: understa	anding, analytical	/ numerical calcul	ations and des	ign of components,	40				
4 W	Review 2 to understand the progress of the project Week 9 & 10: preparation of the experimentation plan and measurement system for									
<b>4.</b> ex	perimentation									
5 W	eek 11 & 12: Project monstration of Project					20				

	Program: M. Tech (Mechanical) – Design Course : Seminar			gn Engineering Semester : III Code : MMD3703					
Course :									
Teaching Scheme     Evaluation Scheme									
Practica	al Hours	Credit	IE2 TW		OR	Total			
4	4	2		50	50	100			
gu in 3. Tl fr 4. Se 5. A 6. Te Course C 1. T 2. T	es : dividual student needs hide. udents can choose to portance. he extensive Literature om seminar study. eminar Report should b t least 1 review paper p total Duration: 24 Conta quirements. Dutcomes 'o acquire the basic skil 'o provide students bett 'o describe the current f	pic related to des Survey, Mathema e submitted as a co ublication is expec- act Hours and 24 H ls to for performin er communication	sign of mechanic tical Modeling of ompliance of term eted as research ou Hours should be sp g literature survey skills	al system comparticular met work associat atcome of semi pent by studen	nsidering recent t thod and valuable red with subject. inar. ats on completion of esentation	rends and its societa			
	o be able to write a rep		in or study based (	ni recent publi	leations				
			Seminar Activi	ties					
Sr. No.			Activity			Duration, (H)			
1.	Week 1, 2 & 3: Guide Review-1 conduction		ation of <mark>topic</mark> , Pla	nning of the w	vork.	8			
2.	Week 4 & 5: Literatu					5			
3.	3.Week 6, 7 & 8 : Mathematical model and findings and its analysis Review-2 conduction8								
4.	Week 9 & 10 : Comp					5			
5.	Week 11 & 12: Semi Final Review conduct		and publication o	r copyright pla	anning	4			

# "Knowlettpi thisigs breatont"

Program:	M. Tech (Mech	anical) – Design I	Engineering		Semester : III			
Course :	Internship [Cor	npany / In-house	project]		Code :	MMD380	01	
	Teaching Scheme Evaluation Scheme							
Practical	Practical Hours Credit			TW	TW OR		Total	
4	4	2	-	100	-		100	
De 2. If 1 fro 3. Th 4. Int 5. To	i lividual student need sign under the guidan not get selected for a m PCCOE, related to e idea presentation is ernship report should tal Duration: 24 Con uirements.	nce of allocated gu ny internships, stu o Mechanical desig expected from the l be submitted as a	tide. dent can choose e gn considering rece e student based on a compliance of ter	xtension of ent trends a the topic. m work ass	mini-project / en nd its societal imj ociated with subj	trepreneur portance. ect.	ship opportunity	
			Detailed Syllab	us:				
		Internship / Internship / Internship / Internship	n-hous <mark>e / Entr</mark> epr	eneurship	activity			
Sr. No.	Activity	- Im			1000		Duration, (H)	
1. Week 1, 2 and 3: Guide allotment, Application of internships, finalization of topic, Planning of the work. Review-1 conduction						20	6	
2.	Week 4 & 5: Interns requirements	ship/ Mini-project	/Entrepreneurship	activity im	plementation as p	ber	4	
3.	Week 6, 7 & 8 : Rev	view-2 of Activiti	es			1	6	
4.	4. Week 9 & 10: Interaction of Guides with Industry, Poster Presentation							
5.	Week 11 & 12: Inte Final Review condu		ting and publication	n or copyri	ght planning		4	
	the second se					Total	24	

# "Reconduction the boilties Ferrenteene"

Program:	M. Tech. Mecha	anical (Design En	Semester :	III			
Course :	MOOCs		Code :	MMD3981			
	<b>Teaching Schem</b>	e	Evaluation Scheme				
Practical	Hours	Credit	IE2	TW	OR	Total	
4	4	2	-	100	-	100	

**Guidelines :** 

- 1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related trainings.
- 2. Weekly assignments need to be completed regularly as per requirement of course, which will be considered for internal assessment of course.
- 3. The certification of course or training is mandatory.
- 4. Oral presentation of course/ training will be taken at the end of semester
- 5. Total duration: 24 contact hours and 24 hours should be spent by students on completion of related activities and requirements.

Recordentages the boggs. For exclorer



Program: Course :	e: Entrepreneurship Code: MMD3981						
	Teaching Scheme Evaluation Scheme						
Practical	Hours	Credit	IE2	TW	OR	Total	
4	4	2	-	100	-	100	
	y Engineering Graduate						
	sign thinking knowledg	eare esse	ntial				
Course Ob							
	acquaint with Entrepre						
	apply entrepreneurship						
	imbibe Entrepreneurial	capabilities in en	gineering students				
Course Ou	ng the course, the stude	nto chould be oble	tot				
	otivate students to think			to omploymor	<b>.</b> +		
	gistering students for S				ιι.		
2. Kt	gistering students for 5		Detailed Syllabus				
Unit	Description		Jetaneu Synabus	•	1000	Duration	
	Description					<b>(H</b> )	
1.	Introduction to Entrepre	eneurship and its in	mportance			5	
2.	Achievement Motivation	n. Case Studies of	Indian Entrepren	eurs		5	
3.	Product Identification,	Market Survey				5	
4.	Whom to contact for w	hat? Financial Mar	nagement,			5	
5.	Business Planning					5	
6.	Project Report preparat	ion				5	
					To	tal 30	
<ol> <li>Entrep</li> <li><i>Entrep</i></li> <li>2005</li> <li><i>Dynam</i></li> </ol>	ence Books: preneurial Developmen preneurship Developmen nics of entrepreneurial gement, finances, progra	nt and Small Busin development and n ammes, and proble	ness Enterprise. I nanagement : Ent rms. by Vasant De	Poornima M. C repreneurship		on Education India	

dini thriens Friedom

4.

Course Material by EDII, Ahmedabad Experiment List: Project Report preparation for an Enterprise and Udyam Registration.2

# **Course Syllabus**

# **Semester-IV**

M. Tech Design Engineering (Mechanical Engineering), PCCoE Pune

Program:		anical) – Design I			emester : I			
Course :		ase – II [Compan	y/ In-house proje	-		/MD4704		
	Teaching Scheme			Evalu	ation Scheme			
Practical	Hours	Credit	IE2	TW	OR	Total		
24	24	12	-	200	200	400		
Prior know	8							
a.	Basic knowledge of M		chine Design,					
b.	Mechanical system des	•						
с.	Basics of Analysis soft							
d.	MATLAB programmin	ngare esse	ntial					
Course Ob	jectives:							
1.	To understand the Proc							
2.	To plan for various act					ct development.		
3.	To build, design and in				tforms.			
<u>4.</u>		culture in students	for their technical	growth.				
Course Ou After Jearni	ng the course the student	s should be able to	· ·					
	Understand, plan and e			appreciable r	research outcome	26		
2.								
3.	0 .			area or stady				
4.								
5.				heir work in re	eputed conferenc	es		
3. 4. 5.	Final Project Report is associated with subject Total 2 Paper publicati journal) and 100% of p Total Duration: 144 h by students to satisfy a	and permission to ons are expected planned project we ours are contact h	appear for exami as research outcor rk should be comp ours with guides a	nation. ne of Project S pleted for subr and for review	Stage-I and II ( C	Conference or reput rtation Phase-II		
Plan of Act		in project requirem	ients und impleme	intutions.				
Sr. No.	Activity			-		Duration, (H)		
1.	Week 1 & 2: 60 %	Work should be	completed, by fab	rication the se	tup	30		
2.	Week 3 & 4: exp Review 1 conduct	ion.		-		30		
3.	Week 5 & 6: Paper Publication should be in process or completed during this week, 80% work should be completed.30							
4.	Week 7 & 8: Cor Review -2 will be	conducted		d to alterate d	augliter of any in	<b>30</b>		
5.	Week 9 & 10: De and requirements	fulfillment to perr	nit project submis	sion.		30		
6.	Week 11 & 12: Demonstration of will be conducted	Project work and	Final Research Re	eview Commit				
	will be conducted for submission and term work compliances							

180

Total

Program:	M. Tech. (Desig	n Engineering)	Semester : IV				
Course :	MOOCs		Code : MMD498	32			
	<b>Teaching Scheme/w</b>	veek	Evaluation Scheme				
Practical	Hours	Credit	IE2	TW	OR	Total	
4	4	2	- 100 - 100				

#### Guidelines :

1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related training.

- 2. Week assignment needs to be regularly completed as per requirement of course, which will be considered for internal assessment of course.
- 3. The certification of course or training is mandatory.
- 4. Oral and Presentation of course/ training will be taken at the end of semester
- 5. Total Duration: 24 Contact Hours and 24 Hours should be spent by students on completion of related activities and requirements.

