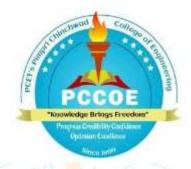
Pimpri Chinchwad Education Trust's PIMPRI CHINCHWAD COLLEGE OF ENGINEERING SECTOR NO. 26, PRADHIKARAN, NIGDI, PUNE 411044

SECTOR NO. 20, I RADIIIRARAN, NIGDI, I UNE 411044

An Autonomous Institute Approved by AICTE and Affiliated to SPPU, Pune

**DEPARTMENT OF MECHANICAL ENGINEERING** 



Curriculum Structure and Syllabus of M. Tech. Mechanical Design Engineering (Approved by BoS Mechanical Engineering) (Course 2020)

"Knowledge Brings Freedom"



Effective from Academic Year 2020-21 (Updated with minor changes from 2021-2022)

### **Institute Vision**

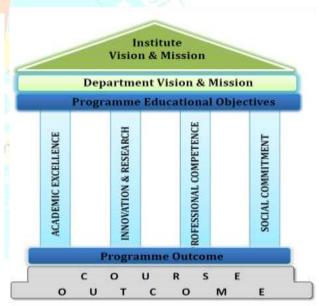
To Serve the Society, Industry and all the Stakeholders through the Value-Added Quality Education.

### **Institute Mission**

To serve the needs of society at large by establishing State-of-the-Art Engineering, Management and Research Institute and impart attitude, knowledge and skills with quality education to develop individuals and teams with ability to think and analyze right values and self-reliance.

### **Quality Policy**

We at PCCOE are committed to impart Value Added Quality Education to satisfy the applicable requirements, needs and expectations of the Students and Stakeholders. We shall strive for academic excellence. professional competence and social commitment in fine blend with innovation and research. We shall achieve this by establishing and strengthening state-ofthe-art Engineering and Management Institute through continual improvement in effective implementation of Quality Management System.



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### ABBREVIATION

Abbreviations	Course Full Name
PCC	Programme Core Course
PEC	Professional Elective Course
OEC#	Open Elective Course
PROJ	Project, Mini / Minor Projects, Integrated Projects
SEM	Seminar
INTR	Internship
LS	Life Skill
AUDIT*	Audit Course
MO	Massive Open Online Courses
19	

Note: \* Indicates that these courses are at institute level

# The Course offered by other departments

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Strace 10 99

# CURRICULUM STRUCTURE STRUCTURE FOR 1<sup>ST</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – I

M.Tech. Str	ucture	Sem-I	Tea	ching	g Sch	eme	Exam	ination S	Scheme			
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ЕТЕ	TW	OR	Total
MMD1401	PCC	Research Methodology & IPR	3	-	3	3	20	30	50	-	-	100
MMD1402	PCC	Stress Analysis	3	-	3	3	20	30	50	-	-	100
MMD1403	PCC	Finite Element Method	3	d.	3	3	20	30	50	-	-	100
MMD1404	PCC	Professional core Lab-I (SA, FEM)	-	2	2	1	-	-	-	50	50	100
MMD1405	PCC	Skill Development Lab - I (Software Skills)	-	2	2	1	-	-	-	50	-	50
MMD1501	PEC	Professional Elective-I	3	-	3	3	20	30	50	-	-	100
MMD1502	PEC	Professional Elective-II	3	-	3	3	20	30	50	-	-	100
MMD1503	PEC	Professional Elective Lab-I ( PE I , PE II)		2	2	1	-	-	6003	50	50	100
**	OEC	Open Elective-I	2	-	2	2	20	-	30	-	-	50
M_1961	Audit	Audit course – I	1	-	1	-	-	-	-	-	-	-
		Total "Know	18	6	24	20	120	150	280	150	100	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam \*\* Course code of the selected open elective by student

# STRUCTURE FOR 1<sup>ST</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – II

M.Tech. Str	ucture	Sem-II	Tea	ching	g Sch	eme	Exami	nation S	cheme			
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ETE	TW	OR	Total
MMD2406	PCC	Optimization Techniques in Design	3	-	3	3	20	30	50	-	-	100
MMD2407	PCC	Advanced Vibrations and Acoustics	3	-	3	3	20	30	50	-	-	100
MMD2408	PCC	Professional core Lab- II (OT, AVA)	N <sup>1</sup> O	2	2	10	olio	_	-	50	50	100
MMD2504	PEC	Professional Elective- III	3	-	3	3	20	30	50	-	-	100
MMD2505	PEC	Professional Elective- IV	3		3	3	20	30	50	-	-	100
MMD2506	PEC	Professional Elective Lab-II (EL III, EL IV)	-	2	2	1	-	-	-	50	50	100
MMD2701	PROJ	Integrated Mini- Project	1	6	6	3	-	50	010	-	50	100
**	OEC	Open Elective –II	2	-	2	2	20	-	30	-	-	50
M_2101	HSMC	Skill Development Lab – II (Written & Oral Communication)	led	2	2 Brii	1 nas I	Freed	om"	-	50	-	50
M_2962	Audit	Audit course – II	1	-	1	-	-	-	-	-	-	-
		Total	15	12	27	20	100	170	230	150	150	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam \*\* Course code of the selected open elective by student

# STRUCTURE FOR II<sup>ND</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-III

M. Tech. S	Structure	Sem – III	Т	TEACH	HING	SCHE	ME	EXAM	INATIO	N SCH	EME	
Abbr	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ЕТЕ	TW	OR	TOTAL
MMD3702	PROJ	Dissertation Phase - I [Company/ In-house project]	-	20	20	10	-	100	-	-	100	200
MMD3703	SEM	Seminar	-	04	04	02	-	-	-	50	50	100
MMD3801	INTR	Internship [Company/ In-house project] /	-	04	04	02	-	50	-	-	50	100
				C	)R							
MMD3981	MOOC	MOOC's / Entrepreneurship	5	04	04	02	-	50	<u>_</u>	-	50	100
		Total	-	28	28	14	-	150	-	50	200	400

\*Internship: -It may be in summer/winter vacation or within semester at least for three months, evaluation after fourth semester

# STRUCTURE FOR II<sup>ND</sup> YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-IV

M. Tech.	Structure	Sem – IV			CHIN HEMI		E	XAMINA	TION S	CHEMI	E	
Abbr	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ЕТЕ	TW	OR	TOTAL
MMD4704	PROJ	Dissertation Phase - II [Company/ In-house project]	-	24	24	12	-	200	-	-	200	400
MMD4982	MOOC	MOOC's	-	4	4	2	-	50	-	-	50	100
		Total	-	28	28	14	-	250	-	-	250	500

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam

### 2. A PROFESSIONAL ELECTIVE COURSES

	Elective-I		Elective-II
MMD1501A	Advanced Machine Design	MMD1502A	Mechanics of Composites
MMD1501B	Mechanical Behavior of Materials	MMD1502B	Tribology in Design
MMD1501C	Analysis and Synthesis of Mechanisms	MMD1502C	Vehicle Dynamics
MMD1501D	Mathematical Methods in Engineering	MMD1502D	Robotics

	Elective-III	Colle	Elective-IV
MMD2504A	Fatigue and Fracture Analysis	MMD2505A	Design of Material Handling Equipments
MMD2504B	Reliability in Engineering Design	MMD2505B	Computer Aided Design
MMD2504C	Mechatronics and Control Systems	MMD2505C	Multi-body Dynamics

### **2. B OPEN ELECTIVES**

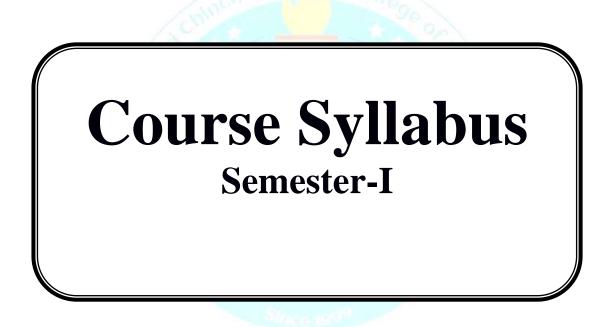
### OFFERED BY DESIGN ENGINEERING/ledge Brings Freedom"

	Open Elective – I Progress Cred	bility Conju	<b>Open Elective –II</b>
MMD1601A	Advanced Materials	MMD2602A	Room Acoustics
MMD1601B	Optimization Methods	MMD2602B	Design Thinking
MMD1601C	Modeling & Simulation of Dynamic Systems	MMD2602C	Reliability Engineering

### 2. C AUDIT COURSES (Common to all Programs)

	SEM-I		SEM-II
M_1961A	Constitution of India	M_2962A	Team Building & Leadership
M_1961B	Value Education	M_2962B	English for Research writing
M_1961C	Stress Management	M_2962C	Disaster Management

M. Tech. Mechanical (Design Engineering), PCCoE Pune



Program:	M. Tech. Mechanical	<u> </u>	ering)	Semester		
Course :	Research Methodolog		1	Code: M		
	Teaching Scheme/Wee	k		Evaluat	ion Scheme	[
Lecture	Credit	Hours	IE1	IE2	ЕТЕ	Total
3	3	3	20	30	50	100
Pre-requisite	Project and seminars in	n undergraduate				
<ol> <li>To un</li> <li>To un</li> <li>To le</li> <li></li></ol>	elect and define appropri- nderstand statistical tech ake predictions and deci- nderstand the mathemati- arn the various steps in r introduce fundamental as the course, the students are a research problem an nine data using different yze numerical data, usin lop a mathematical mod	niques for the spe sions for the data cal modeling and esearch writing a pects of Intellectur should be able to d use appropriate hypothesis tests g standard proced el and analyze the	cific perspective set using open- its predicting ca nd publication p lal property Right research metho and make conc ures of probabil	e data in an appr source software. pability. process hts dology clusions about a ity theory to pre	cceptance or rej	ection of samp
	e a research paper and re a concept note and prep			0		
	ription	1			93	Duration (Hrs)
Obje Rese Defin of Hy	arch Problem and Rese ctives, Motivation, Type arch Methods versus Me nition and Feasibility stu ypothesis, Characteristic ed of research design	es of Research, Re thodology, Criter dy of research pr	ia of Good Rese oblem, Sources	earch of research pro	blem, Meaning	6
2. App	ied Statistics					
Meas Infer	sures of Va <mark>riability: Stan</mark> ential Statistics: Statistic ANOVA (Analysis of va	cal Significance (				6
Samı Distr	ability bling, Types of Sampl ibution, Normal Distribution, Normal Distribution of for the data set using	ition, Case Study	: Develop a mo			6
4. Mat	nematical Modeling and	d prediction of p	erformance			
Type comp scale	s of Modeling, Types outer model to predict pe modeling and verifying asymptotic analysis, Sens	erformance of exp g performance of	erimental system	m, Validation of	results, Multi-	6
5. Rese	arch Report writing an	d Publication				
Rese differ refer Publi	arch Report: Disseminat rent steps and precautio encing. shing Research work: S	ns while writing election of suitab	research report	t, methods and ublishing resear	significance of ch work, Open	6
the j	ss Vs Subscription Journ ournal, structure of resea hission and review proce	arch paper, Checl				

5	Intellectual property Rights	
	Definition of IPR, Classification of IP, Patentable and non-patentable inventions, statutory exceptions, Persons entitled to apply for patents.	6
	Prior Art Search, Patentability Criteria, Patent Filing Procedure, Forms and Fees, Case Study of Patent, Copyright.	
	Total	36
<b>Fextbo</b>	ooks:	
l'extbo 1.	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec	
	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010.	
1.	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010. Ramakrishna B and Anil Kumar H S., Fundamentals of IPR, Notion Press, 2016	
1. 2.	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010.	
1. 2. 3. 4.	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010. Ramakrishna B and Anil Kumar H S., Fundamentals of IPR, Notion Press, 2016	
1. 2. 3. 4.	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010. Ramakrishna B and Anil Kumar H S., Fundamentals of IPR, Notion Press, 2016 Virendra Kumar Ahuja, IPR in India, LexisNexis Butterworths Wadhwa Nagpur, 2017 ence Books:	
1. 2. 3. 4. <b>Referen</b>	C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2 <sup>nd</sup> Ec Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010. Ramakrishna B and Anil Kumar H S., Fundamentals of IPR, Notion Press, 2016 Virendra Kumar Ahuja, IPR in India, LexisNexis Butterworths Wadhwa Nagpur, 2017 since Books: Stuart Melville and Wayne Goddard, Research methodology: An Introduction for Science & Er	

### **IE Activities:**

- 1. Write a review paper based on detailed literature survey and cheque for plagiarism.
- 2. Write a research proposal on your domain specific research problem.
- 3. Write a concept note and prepare to file an IP

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-WASSING P

		M. Tech. Mechanical (Design Engineering)				Semester : I		
Course	e: 8	Stress Analysis			Code: M			
		Teaching Scheme	1		Evaluat	ion Scheme		
L	ecture	Credit	Hours	IE1	IE2	ЕТЕ	Total	
	3	3	3	20	30	50	100	
Pre-ree Object		trength of Materials,	Machine Design					
1.	2. To 3. To 4. To mes: earning th Formula relation		approaches to obta mbers for bending lection due to line should be able to: ss Field equation:	in stresses, strai and torsion. or point contact s such as equili	ns and deforma in solids. brium equation	tions induced in		
2. 3. 4. 5. 6.	Apply I Analyse Analyse Underst techniq	ate and Analyse Stres Energy methods to eva e and Determine the T e and estimate contact cand experimental m ue and Photoelasticity	aluate stresses and orsion and Bendin stresses in confor ethods for stress	strains. ng of thin wall se min <mark>g and</mark> non-c	ection onforming shap		e strain gaugi	
	d Syllab					C X		
Unit	Descri					6	Duration, l	
1.	Analys	y of Elasticity is of Stresses and Ana ee dimensions, Airy's					6	
2.	Govern shrink f	rized Cylinders and ing equations, stress i it compound cylinder uniform strength,	n thick walled cyl				6	
3.	Energy	Methods method for analysis heorem of least work,			heorem's - theo	orem of virtual	4	
	-	all Members:			AND MEAN RE	/		
4.	Torsion Walled Concep wall be	of thin walled memb Sections t of shear centre in am cross section, ope	symmetrical and	unsymmetrical	bending, Shear		6	
	Geome	t stresses try of contact surfaces t contact, Stress for t	two bodies inline	-			7	
5.		rmal and tangent to co es like - gear contacts		a cam and follow	ver, ball bearing	contacts.		
5. <b>6.</b>	For cas Experi Dimens configu elasticit	es like - gear contacts mental stress analysis sional analysis, analysis ration, instrumentation ty, elements of polarisis soclinic and isochron	, contacts betweer is sis techniques, str. on, characteristics scope, simple and	ain gauges, typ of strain gauge circular polaris	bes of strain gau measurement, th cope, fringes in	iges, materials, neory of photo- dark and white	7	

#### **Text Books:**

- 1. Theory of Elasticity–Timoshenko and Goodier, McGrawHill
- 2. Advanced Strength and Applied Stress Analysis-Richard G. Budynas, McGrawHill
- 3. Advanced Mechanics of Materials–Boresi, Schmidt, Sidebottom, Willey

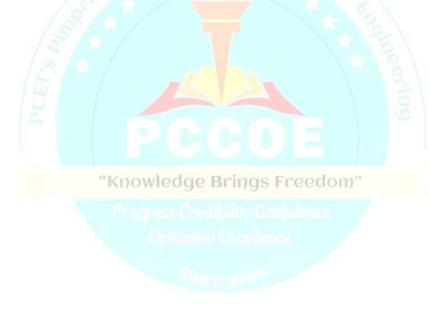
#### **Reference Books:**

- 1. Advanced Mechanics of Materials– Cook and Young, Prentice Hall
- 2. Advanced Mechanics of Solids, L S Shrinath, Tata McGrawHill
- 3. Advanced Strength of Materials, Vol.1, 2–Timoshenko, CBS
- 4. Advanced Strength of Materials–Den Hartog
- 5. Experimental Stress Analysis–Dally & Riley
- 6. Mechanics of Materials E J Hern, Buttorwoth
- 7. Strength of Materials, Singer Andrue Pytel, Pearson



<b>Course :</b>			(Design Enginee	ering)	Semester :			
Source .		Finite Element Method				Code: MMD1403		
		Teaching Scheme			Evaluati	on Scheme		
Lec	cture	Credit	Hours	IE1	IE2	ЕТЕ	Total	
	3	3	3	20	30	50	100	
Pre-requ		ering Mathematics, M	achine Design, Str	rength of Mater	ial			
2. 3. 4. 5.	To unde and the To fami and to i It provi numeric To stud It provi Ess: rning th Studen beam Studen Studen	erstand the philosophy mal analysis problem liarize students with t ntroduce related analy des a bridge between cal solutions for more y approximate nature des some experience e course, the students at will be able to apply element it will Understand the nt will be able to creat in plate element theor	ns. the displacement-by trical and compute hand calculations complex geometric of the finite element with a commercial should be able to: y different variation e Iso-parametric El the and solve the go	based finite eler er tools. based on mecha ies and loading ent method and FEM code and FEM code and on methods for o lements and For	nent method for anics of materials states. convergence of n some practical n deriving the stiffn rmulation of Plan	displacement and s and machine de results are examin nodeling exercise ness matrices of l ne Elasticity Prob	d stress analysis sign and ned. es bar and olems	
5. Detailed	Stude: vector	nt will be able to form s	ulate and solve the	e d <mark>ynamic</mark> prob	lems related to e	igen value and ei	gen	
	Syllab Descri					BUI	Duration, h	
Unit 1	Descrit One di Finite of formula method Variatio beam) elemen process	ption mensional problems element method, brie ttion, variational me of Weighted Residua onal formulation of – governing equation t connectivity, applii ing of the results. Auto	thods of approx ils. 1D bar and beam on, domain discre- ication of bound tomatic mesh gene	imation – Ray n elements (Eu etization, eleme ary condition,	vleigh-Ritzometh ler Bernoulli an ental equations, solution of ec	nods, Galerkin d Timoshenko assembly and juations, post-	Duration, h	
<b>Unit</b> 1	Descri One di Finite o formula method Variatio beam) elemen processs refinem Two D Introdu linear o functio parame matrix,	ption mensional problems element method, brie ation, variational me of Weighted Residua onal formulation of – governing equation t connectivity, appli	thods of approx ils. 1D bar and beam on, domain discre- ication of bound tomatic mesh gene g scheme etric Formulation lements (CST, La ement function – acement functions ameter relationshi oparametric elem	imation – Ray n elements (Eu etization, eleme ary condition, eration techniqu n ST, QST, Iso criteria for th s, displacemen ip, stress-strain ients, rate of	vleigh-Ritz meth ler Bernoulli an ental equations, solution of ec- nes, Mesh quality parametric), shap he choice of the t function in te relationship, ele convergence, p	hods, Galerkin d Timoshenko assembly and quations, post- v checks, h & p pe functions – e displacement erms of nodal ement stiffness		
Unit 1 2 3	Descri One di Finite o formula method Variatio beam) elemen process refinem <b>Two D</b> Introdu linear functio parame matrix, probler <b>Isopara</b> Isopara Numeri Quadra integrat	ption mensional problems element method, brie ation, variational me of Weighted Residua onal formulation of – governing equation t connectivity, appli- ing of the results. Au- ments, Node Numberin imensional Isoperim ction, types of 2D e & quadratic, displace n, polynomial displa- ters, strain-nodal par convergence of ison metric Formulation metric formulation of meetric Element cal Integration – Trap ture formula, Gauss	thods of approx ils. 1D bar and beam on, domain discre- ication of bound tomatic mesh gene getric Formulation lements (CST, Li ement function – acement functions ameter relationshi oparametric elem e stain and axisym and Numerical I of 1D and 2D El poezoidal rule, Simp	imation i - Ray a elements (Eu etization, eleme ary condition, eration techniqu n ST, QST, Iso criteria for th s, displacemen ip, stress-strain tents, rate of metric problen Integration ement, Subpar pson's 1/3 rule,	vleigh-Ritz meth ler Bernoulli an ental equations, solution of ec- nes, Mesh quality parametric), shap he choice of the t function in te relationship, ele convergence, p ns ametric , Superp Newton-Cotes F	d Timoshenko assembly and juations, post- checks, h & p pe functions – e displacement erms of nodal ement stiffness lane elasticity	6	

5	<b>Non-Linear Analysis</b> Introduction to non-linear analysis, formulation for geometrical, material and contact nonlinear problems, Nonlinear equation solving procedure - direct iteration, Newton- Raphson method, modified Newton-Raphson method, incremental techniques	6
6	<b>Dynamic Problems – Eigen value and Time Dependent Problems</b> Formulation of dynamic problems, consistent and lumped mass matrices Solution of eigenvalue problems – transformation methods, Jacobi method, Vector Iteration methods, subspace iteration method [Theoretical Treatment] Forced vibration – steady state and transient vibration analysis, modeling of damping, the mode superposition scheme, direct integration methods – implicit and explicit numerical integration	6
	Total	36
Text B	<ol> <li>Seshu P., "Text book of Finite Element Analysis", PHI Learning Private Ltd., New Delhi, 20</li> <li>Logan D, "First course in the Finite Element Method" Cengage Learning,2012</li> <li>nce Books:         <ol> <li>Bathe K. J., "Finite Element Procedures", Prentice-Hall of India (P) Ltd., New Delhi.</li> <li>Cook R. D., "Finite Element Modeling for Stress Analysis", John Wiley and Sons Inc, 1995</li> <li>Chandrupatla T. R. and Belegunda A. D., "Introduction to Finite Elements in Engineerir</li> <li>Hall India.</li> <li>Liu G. R. and Quek S. S. "The Finite Element Method – A Practical Course", Butterworth-</li> <li>2003.</li> <li>Reddy, J. N., "An Introduction to The Finite Element Method", Tata McGraw Hill, 2003.</li> </ol> </li> </ol>	g", Prentice



Program:	M. Tech. Mech	mester: I				
Course :	Professional Co	de: MMD1404				
	LAB Name : S	ion Scheme				
	Teaching Scheme			Evalua	lon Scheme	
Practica	actical Hours Credit		ТW	PR	OR	Total
2	2	1	50		50	100
2. T	otal experiments to be con otal : 6 experiments 12 h site: Engineering Design, s	ours		l Three from Pa	nrt B	
Outcomes	ing the course the students Simulate the problem a Understand the impact Obtain stresses and stra	and correlate with t of assumptions on ins using experime	heoretical concept the simulated rest	sults		
Detailed S	10	appropriate location			results.	
o cunica s	Jilabast				results.	
Expt.				analyse, interpret	results.	
	Description		ns, collect data,	analyse, interpret	results.	Duration
1.	Description Analytical and Numerica theoretical model develop	Part A: Stre	ns, <mark>collect</mark> data, a	analyse, interpret	Meerin	Duration 2
1. 2.	Analytical and Numerica	Part A: Street l Evaluation of Street for solution	ns, collect data, a	th hole and corre	late with	
	Analytical and Numerica theoretical model develop Contact stress analysis us	Part A: Stree l Evaluation of Stree ped for solution ing FEM software	ns, collect data, a ess Analysis ( AN esses for plate wi and correlate wit	th hole and correct h theoretical mo	late with	2
2.	Analytical and Numerica theoretical model develop Contact stress analysis us developed for solution.	Part A: Stree l Evaluation of Stree bed for solution sing FEM software thin section beam.	ns, collect data, a ess Analysis ( AN esses for plate wi and correlate wit ( Box, L-section,	th hole and correct C-section)	elate with del	2 2
2. 3.	Analytical and Numerica theoretical model develop Contact stress analysis us developed for solution. Shear Centre location for	Part A: Stree l Evaluation of Stree bed for solution sing FEM software thin section beam. d Measurement of	ns, collect data, a ess Analysis ( AN esses for plate wi and correlate wit ( Box, L-section,	th hole and correct C-section)	elate with del	2 2 2

Pre-requisite: Engineering Mathematics Machine Design, Strength of Material

**Objectives:** 

Total

- 1. To impart the philosophy and general procedure of Finite Element Method simulations as applied to solid mechanics and thermal analysis problems.
- 2. To describe and interpret Numerical solutions for more complex geometries and loading states.
- 3. To study approximate nature of the finite element method and convergence of results are examined.
- 4. Adequately describes a physical event and establishing or validating a relationship between obtained results and underlying physical principles.

(Any Three)

6

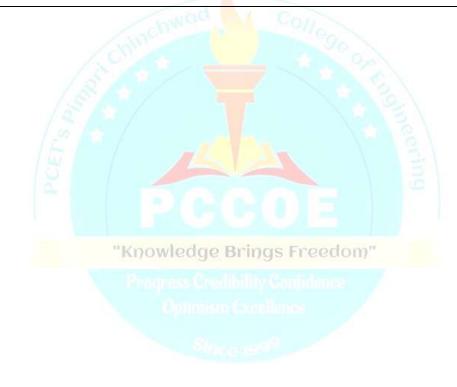
#### **Outcomes:**

After learning the course the students should be able to:

- 1. Apply General procedure and philosophy of finite element method to simulate complex engineering problems
- 2. Evaluate linear and non linear problems related to geometry, material and contact.
- 3. Understand and apply elements, mess sensitivity analysis and convergence study to real life problems.

Detailed	Syllabus:	
	Part B: Finite Element Method (ANY Three)	
Expt.	Description	Duration
1.	Stress analysis of 1D bar using linear and quadratic elements. Show the variation of stress and strain within the element for linear and quadratic bar element (Convergence Study)	2
2.	Modal analysis and stress analysis for 1-D beam (simply supported or cantilever beams) (Convergence Study)	2
3.	Static stress concentration factor calculation for a plate with center hole subjected to axial loading in tension using FEA software (Convergence Study)	2
4.	Stress, Strain and deflection analysis of any machine component consisting of 3-D elements using FEA software. (Convergence Study)	2
	Total (Any Three)	6
Text Boo	yks:	
1.	Advanced Strength and Applied Stress Analysis–Richard G. Budynas, McGrawHill	
2.	Seshu P., "Text book of Finite Element Analysis", PHI Learning Private Ltd., New Delhi, 2010.	
Reference	e Books:	
1.	Theory of Elasticity–Timoshenko and Goodier, McGrawHill	

2. Cook R. D., "Finite Element Modeling for Stress Analysis", John Wiley and Sons Inc, 1995



Program	M. Tech. Mech	anical (Design Eng		Semester : I			
Course :			Development Lab-I Code : MMD1			5	
	Teaching Scheme     Evaluation Scheme						
Practical	Hours	Credit	TW	PR	OR	Total	
2	2	1	50			50	
Pre-requisite:							
Objectives:							
То рі	ovide students with eering problems with				ods and the skills	required to analyz	
Outcomes:	eering problems with	in commerciality avai	IIADIE FEA SOILV	vale s			
	the course, the stude	ents with the aid of c	commercial FEA	software's sh	ould be able to pe	rform <sup>.</sup>	
inter rearing	the course, the stude			solution of solutions	oura de abre to pe		
1. The s	tatic and dynamic lir	near response for an	engineering cor	nponent			
	posite and fatigue and						
	near dynamic analys						
4. The s	hape and topological	l optimization for ar	1 engineering co	mponent			
Detailed Sylla	ibus:	chwit	30	C01100	<ul> <li></li></ul>		
List of Experin	ments/ Assignments:	( him		90			
Eschert lands	1			·a ·	20		
Each student s	hall complete any F	our of the following	g assignments, w	ith assignmen	t I compulsory.		
	mine static and dyna nation of loads	amic linear respons	se of <mark>a 3-di</mark> men	sional enginee	ering component	subjected to variou	
	igate effect of variou	is parameters (no. o	f lay-ups and fib	er orientation	) on laminated cor	nposite structures	
	m fatigue analysis u					1	
	mine frequency/Tran						
	m nonlinear dynam				ed to material not	nlinearity/Geometr	
	earity/Contact Nonli		mpact/Crash/Sho	ock problems			
6. Perfor	m topological/Shape	e optimization					
Students can p	erform above assign	ments using any of	the software me	ntioned below	:		
Ansys, ABAQ	US, 3D Exp <mark>erience,</mark>	Nastran, Hyper mes	shge Bring	s Freedo	m,		
Text Books:		Progress	Credibility C	Confidence	-		
		Onf	mism Excell	ende			
	Finite Element Meth im (Springer)	nod and Application	ns in Engineerii	ng Using ANS	SYS® by Maden	c1, Erdogan, Guve	
	P., "Text book of F	inite Element Analy	vsis" PHI Learn	ing Private I to	1 New Delhi 20	10	
		mite Liement / mary	, sis, i ili Louin	mg i nvaic Lu	$a_{1}, 1000$ Domin, $20$	10.	
	opadhyay M and Sh						

- 4. Nitin S. Gokhale, "Practical Finite Element Analysis", Finite to infinite, Pune
- 5. Ever J. Barbero," Finite element analysis of composite materials using Abaqus", CRC Press taylor Francis group.

Program:							
Course :							
	Teaching Scheme Evaluation Scheme						
Lecture	Lecture Credit Hours IE1 IE2 ETE						
3	50	100					
Pre-requisite	e:	•	•		•	•	
	anced Stress Analysis, E	ngineering Desigr	n, Manufacturing	Processes			
Objectives:							
	nake aware the students		0 1				
	enable the students to ide			engineering pro	blems.		
	After learning the course, lents will realize that creater			v maintainahili	t <del>.</del> .		
	tions, reliability are also					resses in the	
	ly competitive, dynamic			man muning uni	cusions and st		
	lents will demonstrate the			istomer and con-	vert them into t	echnical	
	cifications of a product.	e donity to identif	y needs of the ed	istomer and con	vert them into t	cennical	
-	lents will be able to gene	rate different idea	s after identifvin	g the need and d	letermining the	specifications	
	constraints of a product f				eterming the	specifications	
und		ior a particular pa					
4. Stud	lents will understand the	principals used w		r manufacture.	assembly, emot	tions and	
	lents will understand the ntenance.	principals used w		or manufacture, a	assembly, emot	tions and	
maii	ntenance.	- ACHV	hile <mark>de</mark> signing fo				
main 5. Stud		nethods of rapid p	hile designing for rototyping the pr	roducts to test a	nd modify the c		
main 5. Stud 6. Stud	ntenance. lents will know various r lents will be able to desig	nethods of rapid p	hile designing for rototyping the pr	roducts to test a	nd modify the c		
main 5. Stud 6. Stud Detailed Syll	ntenance. lents will know various r lents will be able to desig	nethods of rapid p	hile designing for rototyping the pr	roducts to test a	nd modify the c		
main 5. Stud 6. Stud Detailed Syll Unit De	ntenance. lents will know various r lents will be able to desig <b>labus:</b>	nethods of rapid p gn the components	hile designing for rototyping the pro- s considering stree	roducts to test an ength based relia	nd modify the c	lesigns.	
main 5. Stud 6. Stud Detailed Syll Unit Dev 1. Dev	ntenance. lents will know various n lents will be able to desig labus: scription	nethods of rapid p gn the components d organizations, I	hile designing for rototyping the pro- s considering stree Product Plannin	roducts to test at ength based relia	nd modify the c	lesigns.	
5. Stud 6. Stud Detailed Syll Unit Dev 1. Dev Intro cycl	ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering of les, organization for desig	nethods of rapid p gn the components d organizations, I design, Product de gn and product de	hile designing for rototyping the pro- s considering stree Product Plannin evelopment proc velopment, techn	roducts to test an ength based relia ng ess, Product and nological innova	nd modify the c ibility	lesigns. Duration, h	
5. Stud 6. Stud Detailed Syll Unit Dee 1. Dev Intro cycl 2. Nee	ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering of les, organization for desig d Identification and prob	nethods of rapid p gn the components d organizations, I design, Product de gn and product de plem definition, pr	hile designing for rototyping the pro- s considering strees Product Plannin evelopment proc velopment, technoduct specificati	roducts to test an ength based relia ng ess, Product and nological innova	nd modify the c ibility	lesigns. Duration, h	
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5. Stud 6. Stud Detailed Syll Unit Dev 1. Dev 1. Cycl 2. Nee and Ider	ntenance. lents will know various r lents will be able to designate labus: scription relopment processes and oduction to engineering of les, organization for designate d Identification and probiselection, evaluation, creatifying customer needs,	nethods of rapid p gn the components d organizations, I design, Product de gn and product de olem definition, pr eativity methods, ( requirements, esta	hile designing for rototyping the pro- s considering stree Product Plannin evelopment proc velopment, techn oduct specificati Concept testing blishing the eng	roducts to test an ength based relia g ess, Product and pological innova on, concept gene	nd modify the c ibility	lesigns. Duration, h	
5. Stud 6. Stud <b>Detailet Syll</b> <b>Unit Dev</b> <b>1. Dev</b> 1. Ceven 2. Nee and Ider qual	ntenance. lents will know various r lents will be able to designabus: scription relopment processes and oduction to engineering of les, organization for designable d Identification and prob selection, evaluation, creatifying customer needs, lity function deployment.	nethods of rapid p gn the components d organizations, I design, Product de gn and product de olem definition, pr eativity methods, ( requirements, esta , product design sj	hile designing for rototyping the pro- s considering stree Product Plannin evelopment proc velopment, technoduct specificati Concept testing blishing the eng pecification	roducts to test an ength based relia ng ess, Product and nological innova on, concept gene ineering charact	nd modify the c ibility	lesigns. <b>Duration, h</b> 6	
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Arrowski filozof (* 1997) Arrowski filozof (* 1	ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering of les, organization for desig d Identification and prob selection, evaluation, creatifying customer needs, lity function deployment, ign for manufacture, assessing ign for Reliability, streng	nethods of rapid p gn the components d organizations, I design, Product de gn and product de plem definition, pr eativity methods, C requirements, esta , product design sp embly, maintenance	hile designing for rototyping the pro- s considering stree Product Plannin evelopment proc velopment, technoduct specificati Concept testing blishing the engo pecification ce, casting, forgi	roducts to test an ength based relia ng ess, Product and nological innova on, concept gene ineering charact	nd modify the c ibility	lesigns. Duration, h 6	
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1. George E Dieter, "Engineering Design", McGraw Hill Company, 2000.

#### **Reference Books:**

- 1. Prashant Kumar, "Product Design, Creativity, Concepts and Usability", Eastern Economy Edition, PHI New Delhi. 2012
- 2. Woodson T.T., "Introduction to Engineering Design", McGraw Hill Book Company, 1966.
- 3. John J.C. "Design Methods", Wiley Inter science, 1970.
- 4. Averill M. Law and W. David Kelton "Simulation, modelling and analysis", McGraw Hill Book Company, 1991.
- 5. Pahl, G.andW.Beitz, Engineering Design–A Systematic Approach Springer, 2nd Ed., 1996.
- 6. Product Design and Development Karl T. Ulrich, Steven Eppinger

Program:	M. Tech. Mechanical (Design Engineering) Semester: I			I				
Course	Mechanical Behaviour of Materials (Elective) Code : MMD1501B		MD1501B					
	Teaching Scheme	Evaluation Scheme			e			
Lecture	Credit	Hours	IE1	IE2	ETE	Total		
3	3	3	20	30	50	100		
Pre-requisite:								
	ial science, Mechanics	of materials						
Objectives: 1 To ext	olore the modern mater	iale with their on	lications					
	ovide an ability to ident			or complex load	ing			
-	ke students able to inte	•		-	•			
	er learning the course,			visco-elastic illa	licitai			
	ply the mechanics of m			ring application	2			
	ve the basics problems		-			conditions		
	dy material behavior u	-		-	inpress ioucoing	conditions		
	entify and investigate er		U		n during strain	hardening.		
	lize the plastic and elas							
	mulate the mathematic							
	ioural study			11.5	5 6			
		danne -		20				
U.t. D.c.		Deta	ailed Syllabus	1		Deres from 1		
	cription	on En cin conin c			2	Duration, h		
	<b>lern Materials in Desi</b> l phase alloy, HSLA, li		mous allow and	their full range	trace strain			
	aviour subjected quasi			-	and the second se	06		
	otropic properties, Plas	-				00		
	its properties	dies, Smart mater	fiais, Nano-mai	enais – types, a	ppileations			
	ponse of metals and al	lovs under appli	ied loading					
	ss, strain transformation			city. Anisotropic	e elasticity.			
	sotropic thermal expan		-			06		
	d curve.		,,	,,	,			
	sile testing	"Knowled	an Prince	Eroodom	ri			
	axial and biaxial tens	ion test, Full ran	ige stress-strain	curves, True s	tress-strain			
	e, Bridgman correctior					06		
and	torsion test, Three poin	ts bend test, Elast	tic recovery		_			
4. Stre	ess- Strain relations for	r work hardenin	g materials					
Exp	erimental studies of pla	stic deformations	under simple a	nd complex load	ling, Strain	06		
hard	lening, Power law appr	oximations, Isoti	ropic, Kinemati	c and combined	hardening	00		
mod	els, Theory of plastic f	ow, Strain-rate a	nd temperature	dependence of f	ow stress			
	tic and Elastic-Plastic							
	ormation theory of plas	• •	•					
	rmations. Equations of		-			06		
		Plastic bending	and torsion, E	nd torsion, Elastic-Plastic bodies under				
	able loading							
	sto-Visco-Plasticity	1 1	11					
	co-elasticity, Rheologic							
	el, Natural decay, De					07		
	rmo-Elastic effect, I	-	-	-	-	06		
Craz	rmation models, Rub	ber elasticity, D	valuping, yieldi	ing, effect of s	su'am rate,			
Craz	sing.							
Ta	tal					36		
	LCI1					30		

#### **Text Books:**

- 1. Mechanical Behaviour of Materials, W.F.Hosford, Cambridge University Press, 2005
- 2. Theory of Plasticity and Metal Forming Processes, Sadhu Singh, Khanna Publishers

#### **Reference Books:**

- 1. Fundamentals of Materials Science and Engineering, William D. Callister, Jr., John Wiley & Sons,
- 2. Mechanical Metallurgy, George E. Dieter, McGraw Hill Book Company, 1988
- 3. Theory of Plasticity, J. Chakrabarty, Elsevier, 2006
- 4. Foundations of Theory of Plasticity, L. M. Kachanov, Dover Publications, 2004
- 5. Plasticity for Structural Engineers, W.F. Chen, Da-Jian Han, Springer
- 6.Mechanical Behavior of Materials, Meyers M A and Chawla K K



	: M. T	gram: M. Tech. Mechanical (Design Engineering) Semester : I						
						Code: MMD1501C		
	Teaching Scheme         Evaluation Scheme							
Lec	Lecture Credit Hours IE1 IE2 ETE						Total	
3 3 3 20 30 50								
Pre-requi	isite:		I			I		
		of Machines						
	. To stud		nalysis of simple ries to synthesize		chanisms			
1 2 3	ning the co Analyz Identif S. Synthe	e Simple and Con y the center of cu size mechanisms	should be able to nplex Mechanism rvature and design using graphical m s to synthesis of n	us n mechanism wit nethods	h dwell			
Detailed a	Syllabus		UNNO!		Qu			
	Descriptio		- nchi	1 2 Tona	100		Duration, h	
1.	Kinematic a	analysis of simp analysis of mecha analysis of simp	nisms, degree of	freedom, Graphi	cal method of v	elocity and	4	
2.	Гуреs of co	analysis of com mplex mechanisr	plex mechanisms			2		
t		Acceleration met	ns, velocity-accele hod and Auxiliary		of complex meet	hanisms by	6	
3.	Curvature Fixed and n vircle, Balls	theory noving centrodes,		Point Method.	-	2011	6	
3. [] 4. [5]	Fixed and n Ericle, Balls Synthesis o Fypes, num spacing, typ	theory noving centrodes, point. f planar mechan nber and dimen- pes of errors, bra	hod and Auxiliary	Point Method. Ire, cubic of stati II Accuracy (precent efects. Function	ionary curvature cision) points, generation and	, Inflection Chebychev rigid body		
3.    4.    5.    5.	Fixed and n circle, Balls Synthesis o Fypes, num pacing, typ guidance w nethod. Synthesis o Synthesis o	theory noving centrodes, point. f planar mechar nber and dimen- pes of errors, bra ith two and thre f planar mechar f four bar mechar	hod and Auxiliary Center of curvatu isms - Graphical sional synthesis, nch and order de	Point Method. Tre, cubic of station I I Accuracy (precent effects. Function s using Relative I II eration and rigid	cision) points, generation and pole method &	c, Inflection Chebychev rigid body t Inversion	6	
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#### **Text Books:**

- 1. Theory of Machines and Mechanisms, A. Ghosh and A.K. Mallik, Affiliated East-West Press.
- 3. Theory of Machines and Mechanisms, J. E. Shigley and J. J. Uicker, 2nd Ed. McGraw-Hill.
- 4. Design of Machinery: An Introduction to the Synthesis and Analysis of Mechanisms and Machines, Robert L. Norton, Tata McGraw-Hill,3rd Edition.
- 5. Theory of machines S. S. Rattan McGraw-Hill Publications.
- 6. Mechanisms and Machine Theory- A.G. Ambekar. PHI Learning Pvt. Ltd.

#### **Reference Books:**

- 1. Mechanism Design- Analysis and Synthesis (Vol.1and 2), A.G. Erdman and G.N. Sandor, Prentice Hall.
- 2. Kinematic Synthesis of Linkages, R.S. Hartenberg and J. Denavit, McGraw-Hill.

### M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program							
Course						IMD1501D ion Scheme	
		Teaching Scheme			Evaluat	ion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req 1.		rential and Integral Calc	ulus				
Objecti	ves:						
After co	omplet	ion of the course, stu	idents will have	adequate back	kground, concej	ptual clarity a	nd knowledge o
		principles related to:					
1.		Value and Eigen Vector			_		
2.		forms such as Laplace a			ations		
3.	-	al Functions and Numer					
4.	Calcu	lus of variation to optim	nze functional pro	blems.			
Outcom	nes.						
		the course, the students	should be able to:				
1.	-	the concept of Eigen V			nass spring syste	m.	
3.		problems related to Lap					
4.		the knowledge of serie					
5.	Find 1	numerical solution of PI	DE.				
6.		se the functional optimi	zation using diffe	rent <mark>me</mark> thodolo	ogy.	131	
Detailed	-				1	0	
Unit		ription			$\sim$	181	Duration, h
1.		concept of Laplace Tra	-			E	6
2.		ce transform of special cations to Differential H		step, Unit imp	ulse, Periodic a	nd Error.	6
3.		spring systems of mu ions in vibration theory		lution, Numeri	cal computation	of Eigen	6
4.		s Solution of differe ions. Least square solut	ntial equations,				6
5.	Calcu Probl	lus of Variation Intr em, Functional involv lary value problem, R	oduction, Functi ing higher order	derivative, A	Approximate sol	ution of	6
6.	Nume schen in bo	erical Analysis Finite d ne, Stability of finite dif undary value problem ce equation.	ference method, A	Applications of	finite difference	analysis	6
Total	Bapia						36
						I	
Text Bo							
1.		r Engineering Mathema					
2.		nced Engineering Mathe	ematics by Erwin	Kreyszig (Wile	y Eastern Ltd.)		
Referen					-		
1.		nced Engineering Math					
2.		nced Engineering Mathe					
3.	Highe	r Engineering Mathema	itics by B. S. Grev	vai (Khanna Pu	(blication, Delhi)		
<b>4.</b>	A	ed Mathematics (Volum					Calle David 1

Program: Course :			anical (Design E		Semester :		
		Mechanics of C iching Scheme	composites (Elect	live)	Code : MN	on Scheme	
	Iea	ichnig Scheme			Evaluati	on Scheme	
Lec	ture	Credit	Hours	IE1	IE2	ETE	Total
	3 3 3 20 30 50						
Pre-requi							
		ress Analysis, Ma	nufacturing Proce	esses			
Objective							
1			ts about various c	-	-	oplications.	
			analyze, design th		uctures.		
			he students shoul				
			se appropriate typ			plication.	
			macro-mechanics				
			of failure for the				
			ninate for the stre	esses and stiffne	ss.		
		he simple compos	site structures				
Detailed S							Duradian
<u>Unit</u> 1.	Descripti		Motoriala				Duration,
1.		ion to Composite	, Polymer Mat	riv Composites	Motal Matrix	Composites	
			es, Carbon–Carb				4
		es, Mechanics To		on composites	, Recyching I	iber-Reinföreeu	
2.		echanical Analys					
2.			Definitions, Str	ress Strain	Elastic Moduli	Strain Energy	
			Types of Materia				
			hogonally Anison				6
			ic Material, Rela				-
			nts of a Lamina,				
			and Compliance			3	
3.	Strength	Failure Theories	of an Angle Lan	nina:		22	
	Maximun	n Stress Failure T	heory, Strength	Ratio, Failure	e Envelopes, M	laximum Strain	
			ll Failure Theory				4
	-		Failure Theorie				-
	Lamina,		Stress-Strain F			ional Lamina,	
			Relationships for	r an Angle Lam	ina.		
4.		chanical Analysis		realibility Ca	minience		
			Mass Fractions,				-
			oid Content, Ev				8
			In-Plane Shear M		city, Ultimate, C	Coefficients of	
5		<u>.</u>	ients of Moisture	Expansion.			
5.		echanical Analys	ode, Stress–Stra	in Polotions for	a Laminata Or	Dimensional	
			in Relation, Strai				
			oment Resultants				6
			dulus of a Lami				
			ering Constants of			constants of a	
6.			ign of Laminate				
			s of Laminates,		inates . Cross-P	ly Laminates.	
			i-symmetric Lami				P
			on for a Laminate				8
	Mechanica	al Design Issues,	Sandwich Comp	osites, Long-T	erm Environmer	ntal Effects,	
	Inter-lamin	nar Stresses, Imp	act Resistance, F	racture Resistar	nce, Fatigue Res	istance.	
	Total						36
Reference	e Books:						
			rials, Robert M. J				
					el and OriIshai, (	Oxford University	Press.
		-	rials, Autar K. Ka				
4. N	Aechanics ar	nd Analysis of Co	mposite Material	s. Valerv V. Va	siliev and Evgen	v V. Morozov, El	sevier

Program		M. Tech. Mechanica		ring)	Semester :		
Course	:	Tribology in Design	(Elective)	. <u> </u>	Code : MN		
		Teaching Scheme			Evaluati	on Scheme	
Le	cture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req			·	•			
	Fluid	Mechanics, Engineerin	ig Metallurgy, Stre	ngth of Materia	als		
Objectiv	V0C.						
Objectiv		o provide necessary co	ncents, knowledge	and skills in F	ngineering Tribo	logy with design asr	ect
		To impart friction, wea					
	n	nachine components				-	
		o provide hands on trai	ining with design o	of bearing, frict	ion, wear test rig	for laboratory purpo	se
Outcom				11 .			
		learning the course, the oly theories of friction a			tions by analyzin	a the physics of the	
		ocess.	ind wear to various	s practical situa	tions by analyzin	g the physics of the	
		ect materials and lubric	ants to suggest a tr	ibological solu	tion to a particula	r situation.	
		sign a hydrodynamic be					harts.
		alyze the behavior of be					
		ermine the load carryin			•		
		lerstand the tribologica	l aspects in differe	nt applications	and understand th	ne solution to avoid	wear and
<b>D</b> 4 11		ction.				57	
Detailed	l Sylla	ibus:				0.	Duration
Unit			Des	scrip <mark>tio</mark> n			Duration h
	Frict	ion and wear			- Y -	8	
1.		on control and wear p	prevention, Bounda	ary lubrication	, Tribological pr	operties of bearing	7
		rials and lubricants, The	eories of friction ar	nd wear, Instab	ilities and stick-sl	ip motion	
		ication of bearings				- C2	
2.		anics of fluid flow, R					7
		plane pivoted and fixe ngs, Lightly loaded in					7
		ostatic, hydrodynamic a					
		ostatic squeeze film	nd undst on beam	igs, field in bee	unigs		
3.	•	lar and rectangular f	lat plates, variable	e and alternat	ing loads, pisto	n pin lubrications,	6
		cation to journal bearing			0 1	•	
4.		o-hydrodynamic lubri		nam Excerna	1998 <u>/</u>		
ч.		ure-viscosity term in R	eynold's equation,	hertz theory,	Ertel-Grubin equa	ation, lubrication of	6
	spher			there were			
5.		ubricated bearings	tatia hudrodunami	a and thrust ha	orings with sir lu	rightion	4
		ng pad bearings, hydrost blogical aspects of Rol		c and thrust be	arings with air iu	orication	
6.		anics of tire-road inter		nd rolling resi	stance tribologic	al aspects of wheel	6
0.		il contact, tribological a				ar aspects of wheel	Ū
	Tota	al	1	0, 0			36
Text Bo	oks:						
	1.	Principles of Lubric		-	en Co. Ltd.		
	2.	Tribology in Machi	ne Design, T. A. S	tolarski			
Referen							
		Fundamental of Friction					
		The Design of Aerostati Gas Bearings – Grassam		rowell			
	3 (						
				sh and Sterrolic	ht		
	4. Т	Theory Hydrodynamic I Principles of Lubrication	Lubrication, Pinkus				

Course :	M. Tech. Mechanical (D	Design Enginee	ring)	Semester	I	
course.	Vehicle Dynamics (Elec		-	Code : MI		
	Teaching Scheme			Evaluat	on Scheme	
Lect	ure Credit	Hours	IE1	IE2	ЕТЕ	Total
3	3	3	20	30	50	100
Pre-requis						
1.	Theory of Machine and					
2.	0 1	g,				
3.	Mechanical Vibration					
Objectives						
	acquaint with vehicle design p			behavior		
	o develop an ability to evaluate					
	o make aware the students about			2		
	After learning the course, the					
	investigate ISO and SAE veh		-			
	examine vehicle Tire model f	-				
	interpret Vibrational behavior				. <u> </u>	
	analyze the road holding and					nputs.
	o develop physical and mathem		-			
	analyze and calculate the ride	characteristic of	of <mark>quarter c</mark> ar m	odel of an auton	nobile with dif	ferent road
	citations.			0.		
Detailed S		12/				
Unit	Description			1	3	Duration, h
1	<b>Basics of Vehicle Dynamics</b>				19.1	
	Tyre mechanics, Vehicle tyre					
	information of Electric, Hybr					6
	software used for vehicle dyn	namics study, I	Different type o	f safety norms a	and Bharat	
	stage emission standards				3	
2	Performance characteristics			· C 1	22	
	Equation of motion and maxi					6
	Prediction of vehicle perfor					
	Introduction of Static V			1	Parameters	
2	Measurement Machine	Knowledg	ge Brings	Freedom'	r.	
3	Braking Characteristics Braking characteristics of a	stopping				
	distance, Braking characteristics of a				11 0	6
	Traction control systems, Stra				•	
	Handling characteristics of v		s event and Out	pat enalacteristi	<b>C</b> D	
4.			0			
4.	Steady-state handling charact					
4.	Steady-state handling charact steering input. Testing of har	eristics of a tw	wo-axle vehicle	, Steady-state re	esponse to	6
4.	steering input, Testing of har	eristics of a tw	wo-axle vehicle	, Steady-state re	esponse to	6
	steering input, Testing of har Directional stability	eristics of a tw	wo-axle vehicle	, Steady-state re	esponse to	6
4. 5.	steering input, Testing of har Directional stability Vehicle ride characteristics	eristics of a ty adling character	wo-axle vehicle ristics, Transie	e, Steady-state re nt response char	esponse to acteristics,	6
	steering input, Testing of har Directional stability	eristics of a two adling character , Vehicle ride	wo-axle vehicle ristics, Transier models - two-	, Steady-state ro nt response char degree-of-freedo	esponse to acteristics, om vehicle	6
	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration	eristics of a two ndling character , Vehicle ride prung mass, N	wo-axle vehicle ristics, Transier models - two- Numerical met	, Steady-state ro nt response char degree-of-freedo hods for detern	esponse to acteristics, om vehicle nining the	
	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-sp	veristics of a two ndling character , Vehicle ride prung mass, N lel to irregular	wo-axle vehicle ristics, Transier models - two- Numerical met surface profile	, Steady-state ro nt response char degree-of-freedo hods for detern excitation, Two-	esponse to acteristics, om vehicle nining the degree-of-	
	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-spresponse of a quarter-car mod freedom vehicle model for pite	veristics of a two ndling character , Vehicle ride prung mass, N lel to irregular ch and bounce,	wo-axle vehicle ristics, Transier models - two- Numerical met surface profile	, Steady-state ro nt response char degree-of-freedo hods for detern excitation, Two-	esponse to acteristics, om vehicle nining the degree-of-	
5.	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-s response of a quarter-car mod freedom vehicle model for pite Road and Suspension model	, Vehicle ride prung mass, N lel to irregular ch and bounce, ing	wo-axle vehicle ristics, Transier models - two- Numerical met surface profile Active and sen	e, Steady-state re nt response char degree-of-freedo hods for detern excitation, Two- ni-active suspens	esponse to acteristics, om vehicle nining the degree-of- ion,	
5.	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-spresponse of a quarter-car mod freedom vehicle model for pite	veristics of a two ndling character , Vehicle ride prung mass, N lel to irregular s ch and bounce, ing deterministic p	wo-axle vehicle ristics, Transien models - two- Numerical meth surface profile Active and sen profile, random	e, Steady-state re nt response char degree-of-freedo hods for detern excitation, Two- ni-active suspens n profile, auto-o	esponse to acteristics, om vehicle nining the degree-of- ion, correlation	
5.	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-s response of a quarter-car mod freedom vehicle model for pite Road and Suspension model Road – modeling aspects,	A vehicle ride prung mass, N lel to irregular s ch and bounce, <b>ing</b> deterministic p put and output,	wo-axle vehicle ristics, Transier models - two- Numerical mett surface profile Active and sen profile, random	e, Steady-state re nt response char degree-of-freedo hods for detern excitation, Two- ni-active suspens n profile, auto-o elbase, K&C ch	esponse to acteristics, om vehicle nining the degree-of- ion, correlation aracterizes	6
5.	steering input, Testing of har Directional stability Vehicle ride characteristics Human response to vibration model for sprung and un-sp response of a quarter-car mod freedom vehicle model for pite Road and Suspension model Road – modeling aspects, function, relation between inp	A vehicle ride prung mass, N lel to irregular s ch and bounce, <b>ing</b> deterministic p put and output,	wo-axle vehicle ristics, Transier models - two- Numerical mett surface profile Active and sen profile, random	e, Steady-state re nt response char degree-of-freedo hods for detern excitation, Two- ni-active suspens n profile, auto-o elbase, K&C ch	esponse to acteristics, om vehicle nining the degree-of- ion, correlation aracterizes	6

Te	xt Books:	
	1.	Vehicle Dynamics Theory and Application, Raza N. Jazar. Springer International Edition
	2.	Rajesh Rajamani, Vehicle Dynamics & control, Springer.
Re	eference Bool	KS:
	1.	Road Vehicle Dynamics – Problems & Solutions, Rao & Dukkipati, SAE,
	2.	Theory of Ground Vehicles, J.Y. Wong, John Wiley & Sons,
	3.	Fundamentals of Vehicle Dynamics, T.D. Gillespie, SAE
	4.	Garrett T K, Newton K and Steeds W, "Motor Vehicle", Butter Worths & Co., Publishers Ltd., New
		Delhi, 2001.

- Vittore Cossalter, Motorcycle Dynamics, 2nd Edition, Publisher: LULU.com Milliken W F and Milliken D L, Race car Vehicle Dynamics, SAE 5.
- 6.



Progr		M. Tech. Mechanica	al (Design Engine	ering)	Semester :		
Cours					MD1502D		
		Teaching Scheme			Evaluati	on Scheme	
]	Lecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-re	equisite:	I	1		1	1	
		hines, Mechatronics, B	asics of Electrical	and Electronics	Engineering		
Objec	tives:						
1.		t acquainted with basic	components of rol	botic systems.			
2.	-	derstand grippers, sense	-	•			
3.	To un	derstand statistics & kin	nematics of robots				
4.	To un	derstand dynamics of r	obot.				
Outco	mes:	÷					
After 1		the course, the students					
1.	Ident	ify different type of r	obot configuration	on and perform	n general transfo	ormations.	
2.	Apply	DH parameters to a ro	bot configuration	thus determine t	the kinematic par	ameters.	
3.	Deter	mine velocities and stat	ic forces in the ma	nipulator.			
4.		rm dynamic analysis of					
5.		suitable trajectory to		ot			
6.		necessary actuators, se			formance of the r	obot	
	ed Sylla	*		suisidetory per	formanee of the f	0001.	
Unit	-	ription	11			2	Duration, h
		luction				3	,
		are, classification and a	applications, robot	anatomy, dexte	erity and complia	ance of	
1.		Positions, orientation					6
		ormations.		or a ligit	eeeg, nomog	- III O UIS	
		oulator kinematics				61	
2.	-	sentation of joints and	link using Dena	vit-Hartenberg	parameters dire	ct and	6
	-	e kinematics of robots,	-	-	parameters, une	ot and	0
		ties and static forces					
3.		and angular velocity	of links velocity	v propagation	manipulator Jac	obians	6
		arity analysis, Static for	INTO AN ICOU.		manipulator sac	oolalis,	0
		nics of robots	rees in manipulato	13	and internet		
4.		and inertia of links, Acc	palaration of links	Lagrangian for	mulation for due	amics	6
		n-Euler dynamic formu		0 0	initiation for dyn	lannes,	0
			fration, Dynamic S				
5.		ctory generation	intion List and	a saharaa G	stanion cross	hamaa	C
		lerations in path description		ce schemes, Ca	mesian space sci	nemes,	6
		etric problems with path					
		tors, Sensors and Grip	-				
6.	Mecha	inical Hydraulic and Pr	neumatic actuators	, internal and ex	sternal state sense	ors	6
6.							
6.		or robots, types of gripp	bers.				36

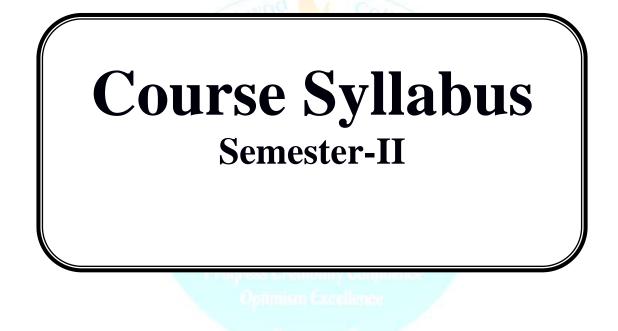
- 1. John Craig, Introduction to Robotics, Mechanics and Control, 3rd Edition, Pearson Education, 2009
- 2. K.S. Fu, R.C. Gonzales, C.S.G. Lee, Robotics: Control, Sensing, Vision and Intelligence, McGraw Hill, 1987.
- 3. S. K. Saha, Introduction to Robotics, Second Edition, McGraw Hill Education, 2014

#### **Reference Books:**

- 1. S B Niku, Introduction to Robotics, Analysis, Control, Applications, 2nd Edition, Wiley Publication, 2015.
- 2. Mathia, Robotics for Electronics Manufacturing, Cambridge Uni. Press, India
- 3. A Ghosal, *Robotics: Fundamental Concepts and Analysis*, Oxford University Press, 2013.
- 4. R K Mittal & I J Nagrath, *Robotics and Control*, McGraw Hill Publication, 2015.

		nical (Design Eng	ineering)	S	emester : I	
Course :	Professional Ele			6	Code : MMD15	03
course.		ctive I & Elective	II			05
	Teaching Schem	e	I	Evaluat	tion Scheme	
Practica	l Hours	Credit	TW	PR	OR	Total
2	2	1	50		50	100
Pre-requi		-	00		00	100
	es: This course is to provid stand the principles.	le students the tool	ls required for Sim	ulate correlat	e and validate th	eoretical concep
<b>Dutcome</b>		lants should be abi	la ta			
	ning the course the stud . Solve open ended I			on.		
2	2. Simulate the proble	em and correlate w	ith theoretical con	cepts		
3	3. Understand the imp			results		
4	. Collect data, Analy	se, interpret and re	eport th <mark>e r</mark> esults.			
a • • • •		chu		910		
Guideline		Dort A and Dort 1	R as por students a	lactive choice		
	Any one subject from					
	Fotal experiments to be		ree from Part A	and Three fi	rom Part B	
	Total : 6 experiments	12 hours			TQ.	
Ι	Detailed Syllabus:	Des /		1	M 131	
		art A: Elective 1-	Advanced Machi	ne Design ()	ANY Three)	
Expt.	Description				1151	Duration, h
1.	Case Studies Based of					2
2.	Case Studies Based of				10	2
3.	Case Studies Based of	on : Design for Ma	nufacturing and A	ssembly		2
4						2
4.		on : Design based of	on Quality and Rel			2
4. 5.	Case Studies Based of		on Quality and Rel			2 2
	Case Studies Based of <b>Total</b>	on : Design based of	on Quality and Rel on Cost	iability.		2
5.	Case Studies Based o Total Part A: E		on Quality and Rel on Cost	iability.	ANY Three)	2 2 06
5. Expt.	Case Studies Based of Total Part A: E	on : Design based of lective 1- Mechan	on Quality and Rel on Cost ical Behavior of I	iability. Materials ( 4	ANY Three)	2 2 06 Duration, h
5. Expt. 1.	Case Studies Based of Total Part A: E Description Elasto-plastic analysis	on : Design based of lective 1- Mechan is of a tensile test s	on Quality and Rel on Cost ical Behavior of I specimen using FE	iability. Materials (A M software		2 2 06
5. Expt. 1.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu	on : Design based of lective 1- Mechan is of a tensile test s ill range stress s	on Quality and Rel on Cost ical Behavior of I specimen using FE	iability. Materials (A M software		2 2 06 Duration, h
5. Expt. 1. 2.	Case Studies Based of Total Part A: Example Description Elasto-plastic analysis Determination of fur specimen as per AST	n : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M	on Quality and Rel on Cost <b>ical Behavior of</b> I specimen using FE strain curve for	iability. Materials (A M software		2 2 06 Duration, h 2 2
5. Expt. 1. 2. 3.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir	on Quality and Rel on Cost <b>Incomposition of Expectmen using FE</b> strain curve for at bending test	iability. Materials (A M software		2 2 06 Duration, h 2 2 2
5. Expt. 1. 2. 3. 4.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polym	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir ner and polymer co	on Quality and Rel on Cost <b>Incomposition of Expectmen using FE</b> strain curve for at bending test	iability. Materials (A M software		2 2 06 Duration, h 2 2 2 2 2
5. Expt. 1. 2. 3. 4.	Case Studies Based of Total Part A: El Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polym Impact test for plastic	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir ner and polymer co	on Quality and Rel on Cost <b>Incomposition of Expectmen using FE</b> strain curve for at bending test	iability. Materials (A M software		2 2 06 Duration, h 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4.	Case Studies Based of Total Part A: El Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verificat Tensile test for polym Impact test for plastic Total	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir ner and polymer co c	on Quality and Rel on Cost <b>ical Behavior of I</b> specimen using FE strain curve for nt bending test omposite	iability. Materials (4 M software mild steel a	nd aluminum	2 06 Duration, h 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polym Impact test for plastic Total Part A: Electric Case Studies Based of Case Studies	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir ner and polymer co	on Quality and Rel on Cost <b>ical Behavior of I</b> specimen using FE strain curve for nt bending test omposite	iability. Materials (4 M software mild steel a	nd aluminum	2 06 Duration, h 2 2 2 2 2 2 06
5. Expt. 1. 2. 3.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polyn Impact test for plastic Total Part A: Elec Description	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s M -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a	on Quality and Rel on Cost <b>ical Behavior of I</b> specimen using FE strain curve for at bending test omposite	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5. Expt. 1.	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verifica Tensile test for polym Impact test for plastic Total Part A: Elec Description Kinematic analysis o	en : Design based of lective 1- Mechan is of a tensile test s ill range stress s 'M -E8M ation of Three poir ner and polymer co c ctive 1- Analysis a f simple mechanis	on Quality and Rel on Cost <b>Idea Designed</b> <b>ical Behavior of I</b> specimen using FE strain curve for at bending test composite and Synthesis of M ms	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 2 06 Duration, h 2
5. Expt. 1. 2. 3. 4. 5. Expt.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polyn Impact test for plastic Total Part A: Elec Description	In : Design based of Interview 1- Mechan is of a tensile test shift range stress shift range stress shift range stress shift range of Three point inter and polymer construction of Three point inter and polymer construction of the stress shift range stress stress stress shift range stress s	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for at bending test omposite and Synthesis of M ms isms	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 2 06 Duration, h
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2.	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verifica Tensile test for polym Impact test for plastic Total Part A: Elec Description Kinematic analysis o Kinematic analysis o	In : Design based of Interview 1- Mechan is of a tensile test shall range stress shall range stress shall range stress shall range of Three point mer and polymer construction of Three point mer and polymer construction of the stress stress construction of the stress s	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for nt bending test omposite and Synthesis of M ms iisms anism	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 06 Duration, h 2 2 2 2 06
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2. 3. 3. 4. 5. 2. 3. 3. 4. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verificat Tensile test for polym Impact test for plastic Total Part A: Elect Description Kinematic analysis of Kinematic analysis of Curvature analysis si Graphical Synthesis of	In : Design based of Interview 1- Mechan is of a tensile test so ill range stress so M -E8M ation of Three poir mer and polymer co co ctive 1- Analysis a f simple mechanis f complex mechan mple planar mechan of path generating	on Quality and Rel on Cost <b>ical Behavior of I</b> specimen using FE strain curve for nt bending test omposite <b>and Synthesis of N</b> ms isms anism mechanism	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 4. 5. 4. 5. 4. 4. 5. 4. 4. 5. 4. 4. 5. 4. 4. 5. 4. 4. 5. 4. 4. 4. 5. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verifica Tensile test for polym Impact test for plastic Total Part A: Elec Description Kinematic analysis o Kinematic analysis o	In : Design based of Interview 1- Mechan is of a tensile test so ill range stress so M -E8M ation of Three poir mer and polymer co control of the polymer co control of the polymer co control of the polymer control control of the polymer control of the polymer control control of the polymer control of the polymer control of the polymer control control of the polymer control of	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for at bending test omposite and Synthesis of M ms isms anism mechanism ting mechanism	iability. Materials (4 M software mild steel a	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 5.	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verificat Tensile test for polym Impact test for plastic Total Part A: Elect Description Kinematic analysis of Kinematic analysis of Curvature analysis si Graphical Synthesis of Graphical Synthesis of	In : Design based of lective 1- Mechan is of a tensile test s ill range stress s M -E8M ation of Three poir mer and polymer co c ctive 1- Analysis a f simple mechanis f complex mechan mple planar mecha of path generating of function generating of rigid body guidi	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for at bending test omposite and Synthesis of M ms isms anism mechanism ing mechanism	iability. Materials (4 M software mild steel a Mechanisms	nd aluminum	2 2 06 Duration, h 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 6.	Case Studies Based of Total Part A: El Description Elasto-plastic analysis Determination of fu specimen as per AST Experimental verificat Tensile test for polynt Impact test for plastic Total Part A: Elect Description Kinematic analysis of Curvature analysis si Graphical Synthesis of Graphical Synthesis of Graphical Synthesis of Synthesis of Syn	In : Design based of lective 1- Mechan is of a tensile test s ill range stress s M -E8M ation of Three point ner and polymer co c ctive 1- Analysis a f simple mechanis f complex mechan mple planar mechan of path generating of rigid body guidi of path generating	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for at bending test composite and Synthesis of M ms isms anism mechanism ing mechanism mechanism, using	iability. Materials (7 M software mild steel a Mechanisms g MATLAB	nd aluminum (ANY Three)	2 2 06 Duration, h 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2
5. Expt. 1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 6. 7.	Case Studies Based of Total Part A: E Description Elasto-plastic analysi Determination of fu specimen as per AST Experimental verifica Tensile test for polyn Impact test for plastic Total Part A: Elec Description Kinematic analysis of Kinematic analysis of Curvature analysis of Graphical Synthesis of Analytical Synthesis	In : Design based of Interview 1- Mechan is of a tensile test so ill range stress so i'M -E8M ation of Three point ner and polymer co control of Three point ner and polymer co control of the polymer c	on Quality and Rel on Cost ical Behavior of I specimen using FE strain curve for at bending test omposite and Synthesis of M ms isms anism mechanism ting mechanism ism gechanism, using ting mechanism, using	iability. Materials (7 M software mild steel a Mechanisms g MATLAB using MATLAB	nd aluminum (ANY Three)	2 2 06 Duration, h 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2

Expt.	Description	Duration, h
1.	Solution using Matlab for Power Method	2
2.	Solution using Matlab for Mass spring system	2
3.	Solution using Matlab for Least square method	2
4.	Solution using Matlab for Numerical solution to Laplace Equation.	2
5.	Solution using Matlab for Numerical solution to Heat Equation.	2
	Total	06
	Part B: Elective 2- Mechanics of Composites (ANY Three)	
Expt.	Description	Duration, h
1.	Analytical determination of strength of lamina using properties of matrix and fibres.	2
2.	Compare the theories of failure for the composite lamina using analytical formulation	2
3.	Study of various test standards for behavior testing of composite laminates.	2
4.	Determination of the stress distribution across various layers of a laminate using Classical Laminate Theory.	2
	Total	06
	Part B: Elective 2- Tribology in Design (ANY Three)	
Expt.	Description	Duration, h
1.	Case study on Tribological aspects of rolling motion / Tribo-characteristics of different materials / Evaluation of friction & wear through experiments under	2
	influencing parameters. Coefficient of friction using pin-on-disc type friction monitor	
2.	Friction in Journal Bearings	2
3.	Four Ball Tester	2
4.	Study of Lubricating systems with example	2
5.	Journal Bearing Apparatus	2
6.	Tilting pad and thrust bearing apparatus	2
	Total	06
	Part B: Elective 2- Vehicle Dynamics (ANY Three)	00
Expt.	Description	Duration, h
1.	Assignment on Road holding characteristics of vehicle and its control	2
2.	Assignment on analysis and optimal control of car ride model	2
3.	Assignment on ABS or Power-steering for handling analysis - single lane event	2
4.	To simulate and understand behavior of sprung / un-sprung mass & lumped mass system MBD software.	2
	Total	06
	Part B: Elective 2- Robotics (ANY Three)	00
Expt.	Description	Duration, h
1.	Simulation of Cartesian/ cylindrical/ spherical robot.	2
2.	Simulation of Articulated/ SCARA robot.	2
3.	Virtual modelling for kinematic and dynamic verification of any one robotic structure using suitable software.	2
4.	Design, modeling and analysis of gripper	2
	Total	06



M. Tech. Mechanical (Design Engineering), PCCoE Pune

			(Design Enginee	ring)	Semester :	II	
Course	: Opt	imization Technic	ques in Design		Code : MM	ID2406	
		aching Scheme			Evaluatio	on Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req 1. Objectiv	Engineering	Mathematics					
<ol> <li>To</li> <li>Pro</li> <li>Pro</li> <li>Pro</li> </ol>	introduce stu ovide student ovide student	idents to the mode s with the basic ma s with the modellin s with the skills ne	athematical conce ng skills necessary	pts of optimiza y to describe an	tion. d formulate optin	nization proble	
Outcom			J		1	0	6
	<ol> <li>Interpret</li> <li>Obtain et</li> <li>Simulat</li> <li>Use soft</li> <li>Apply t</li> </ol>	ate mathematical p et the results of line optimum paramete e the optimized me tware to solve prol opology optimizat	ear programming f ers for non-linear j odel. blems using mode	model and pres problems.		assical optimiz	zation techniqu
	Syllabus:	12		<u> </u>	90	1	
Unit	Description					2	Duration, h
1.	Mathemati multi varia	<b>Description Tech</b> cal Modeling, Cla ble optimization, v	assification of mo	odels, single v	ariable optimizat	ion and	6
			with and without of	const <mark>rai</mark> nts.	<u> </u>	2	
2.		ogramming e simplex method		1 1 5	fethod, revised s	simplex	6
2. 3.	Two phase method. <b>Non-Linea</b> Elimination	ogramming	l, primal and du	ual Simplex N		20	6
	Two phase method. Non-Linea Elimination dimension Modern M	<b>pgramming</b> e simplex method or <b>Programming</b> n and iterative r minimization. <b>Iethods of Optimi</b> gorithms, Simulate	d, primal and du nethods for one zation	ual Simplex M	minimization an	d multi	
3.	Two phase method. Non-Linea Elimination dimension Modern M Genetic alg Optimization Simulation Introductio	<b>pgramming</b> e simplex method or <b>Programming</b> n and iterative r minimization. <b>Iethods of Optimi</b> gorithms, Simulate	d, primal and du nethods for one <b>zation</b> ed Annealing, Par types, limitation	ual Simplex M e-dimensional rticle Swarm O s, various pha	minimization an ptimization, Ant ses of modeling,	d multi Colony	6
3.	Two phase method. Non-Linea Elimination dimension Modern M Genetic alg Optimization Introductio Carlo meth Topology of Problem for	bgramming e simplex method ar Programming n and iterative minimization. Iethods of Optimi gorithms, Simulate on, etc. n Modeling n, definition and nod, applications, a Optimization ormulation and p on as a design	d, primal and du methods for one <b>zation</b> ed Annealing, Par types, limitation idvantages and lir arameterization of	ual Simplex M e-dimensional eticle Swarm O s, various pha nitations of sim	minimization an ptimization, Ant ses of modeling, nulation.	d multi Colony Monte ppology	6

- 1. Engineering Optimization: Theory and Practice, Singiresu S. Rao, John Wiley & Sons
- Practical Optimization Methods with Mathematical Applications, M. Asghar Bhatti, Springer
- 3. Optimization for engineering design, K. Deb, PHI

#### **Reference Books:**

- 1. Topology Optimization Theory, Methods and Applications, M. P. Bendse, Q. Sigmund
- 2. Evolutionary Topology Optimization of Continuum Structures, Methods and Applications, X. Huang, Y.M. Xie, Wiley
- 3. Structural Optimization, Raphael T. Haftka and Zafer Gurdal, Kluwer Academic Publishers
- 4. Mathematical Modelling, J N Kapur, New age international publication
- 5. Optimization concepts and applications in engineering, Belegundu, Chandrupatla, Pearson Education

M. Tech. Mechanical (Design Engineering), PCCoE Pune

	n: M	. Tech. Mechanical	(Design Enginee	ring)	Semester	: II	
Course		Ivanced Vibrations		<u> </u>	Code : MI		
		<b>Feaching Scheme</b>				ion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req							
Objectiv		1. Physics 2. E	ngineering Mather	matics 3. Dyn	amics of Machi	inery	
1. To res 2. Stu	enable stu ponse to di	udents to analyse n ifferent excitation co be able to acquir	onditions.	-		-	
Outcom	06.						
1. For 2. For 3. An 4. Un 5. Un cor	rmulate an rmulate th alyse Vibr derstand R derstand B npliance to	course, the students s ad <b>Evaluate</b> problem e mathematical mod ation in System and andom process para basic principles in a noise regulations. <b>Design</b> of Acoustic	ns of MDOF mech lels Transient Vibi <b>Design</b> a Vibratic meters and <b>analys</b> acoustics, measure	rations and study on Control Strate se vibration resp ement of sound	y its impact on o egies, onse of single d Power and <b>ap</b>	design of system. legree linear syst <b>oply to analyze</b>	em.
	Syllabus:		1		1200	0	
Unit	Descrip		1		1.1.1	2	Duration, h
1.	Free vil (ii) flex equations	egree Freedom Syst pration equation xibility coefficien s matrix method E s of un-damped syst	of motion, infl t generalized co ligen values <mark>Eig</mark> e	ordinates, coor en vector probl	dinate coupling	gs, Lagrange's	6
2.	Transien Response	t vibrations to an impulsive ar pulse and half sin	input, Response		Response to	a pulse input-	6
3.	Vibratio Balancin vibration	n Control g of rotating mach isolation and vibrat trained layer dampin	ine, in-situ balan ion absorbers, Pas				4
4.	<b>Random</b> Probabili	<b>Vibrations</b> ty, Auto and cross c vsis of narrow band s	correlation functio	n, spectral densi	ity, response of	linear systems,	6
5.	Acoustic Basics o number, density, s Directivit octave ba Sound P		ninologies speed and particle velo vity index, levels a d levels.	city, acoustic i and the decibel,	ntensity and a combination of	sound sources,	6
				and Mufflers			
6.	Transmis oblique in controlle Enclosure	s of Partitions, Enc sion of Sound: chan ncidence, sound tran d region- mass-contr es, Barriers, muffler ntrol strategies and A	ges in media with smission through rolled region - dan elements.	normal incidend a wall, transmis	sion loss for wa	alls - stiffness-	8

#### **Text Books:**

- 1. Mechanical Vibrations, S. S. Rao, Pearson Education, Delhi
- 2. Theory of Vibrations with Applications, W. T. Thomson, Pearson Education, Delhi
- 3. Industrial Noise Control, Randell Barron, Marcel Dekker, Inc.
- 4. Noise and Vibration Control, M L Munjal, World Scientific Publishing Co. Ltd.

#### **Reference Books:**

- 1. Mechanical Vibrations, G K Groover, Nem Chand & Bros, Roorkee, India
- 2. Fundamentals of Vibration, Leonard Meirovitch, McGraw Hill International Edison
- 3. Principles of Vibration Control: Ashok Kumar Mallik, Affiliated East-West Press, New Delhi.
- 4. Mechanical Vibrations, A H Church, John Wiley & Sons Inc
- 5. Mechanical Vibrations & Noise Engineering, A.G.Ambekar, Prentice Hall of India, New-Delhi.



Program:				Semester : II	er : II	
Course :	Professional	<u> </u>	Code : MMD2408			
	LAB Name :		Γ			
	Teaching Schem	e		Eva	luation Scheme	
Practical	l Hours	Credit	TW	PR	OR	Total
2	2	1	50		50	100
Guidelines			•			·
1.	1		e Three from Pa	rt A and Th	ree from Part I	3
2.	-	nts 12 hours				
Pre-requis						
	ngineering Mathematic	CS				
Dbjectives		the modelling stril	lla nagagami ta da	coribo and f	rmulata anti-	ation problems
	Provide students with Provide students with					
Δ.		the skins necessar		cipier optim	ization problems	in engineering.
Dutcomes	:					
		dents should be ab	ble to:			
After learn	ing the course, the stu			ems	<	
After learn 1. Fo		programs in vario	ous pract <mark>ical sy</mark> ste		ity)	
After learn 1. Fo 2. in 3. U	ing the course, the stu- ormulate mathematical atterpret the results of a se software to solve pr	programs in varie model and presen	ous pract <mark>ical sy</mark> ste		ity)	
After learn 1. Fo 2. in 3. U	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus:	programs in vario model and presen oblems	ous practical syste at the in <mark>sights (s</mark> er	sitivity, dual	ap	
After learn 1. Fo 2. in 3. U Detailed S	ing the course, the stu- ormulate mathematical atterpret the results of a (se software to solve pro- syllabus: Pa	programs in varie model and presen	ous practical syste at the in <mark>sights (s</mark> er	sitivity, dual	ap	
After learn 1. Fo 2. in 3. U	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus:	programs in vario model and presen oblems	ous practical syste at the in <mark>sights (s</mark> er	sitivity, dual	ap	Duration
After learn 1. Fo 2. in 3. U Detailed S	ing the course, the stu- ormulate mathematical atterpret the results of a (se software to solve pro- syllabus: Pa	l programs in varie model and presen oblems rt A: Optimizatio	ous practical syste at the insights (ser	sitivity, dual	ap	Duration 2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1.	ing the course, the stu- ormulate mathematical atterpret the results of a se software to solve pro- syllabus: Pa Description	l programs in varie model and presen oblems rt A: Optimizatio	ous practical syste at the insights (ser	sitivity, dual	ap	
1. Fo 2. in 3. U Detailed S Expt.	ing the course, the stu- ormulate mathematical atterpret the results of a se software to solve pro- syllabus: Pa Description	l programs in varie model and presen oblems rt A: Optimization ng of a real life p	ous practical syste at the insights (ser	sitivity, dual	ap	
After learn 1. Fo 2. in 3. U <b>Detailed S</b> <b>Expt.</b> 1. 2.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex 1	l programs in varie model and presen oblems rt A: Optimization ng of a real life p nethod	ous practical syste at the insights (ser	sitivity, dual	ap	2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli	l programs in varie model and presen oblems rt A: Optimization ng of a real life p nethod	ous practical syste at the insights (ser	sitivity, dual	ap	2
After learn 1. Fo 2. in 3. U <b>Detailed S</b> <b>Expt.</b> 1. 2.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex r Sensitivity analysis o	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem	ous practical system at the insights (ser on Techniques in roblem	sitivity, dual	ap	2 2 2
After learn 1. Fo 2. in 3. U <b>Detailed S</b> <b>Expt.</b> 1. 2. 3.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex 1	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem	ous practical system at the insights (ser on Techniques in roblem	sitivity, dual	ap	2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1. 2. 3.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex r Sensitivity analysis o	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem on-linear methods	ous practical system at the insights (ser on Techniques in roblem	a Design ( A	NY Three)	2 2 2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1. 2. 3. 4.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex r Sensitivity analysis o Optimization using n	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem on-linear methods	ous practical system it the insights (ser on Techniques in roblem	o Design ( A	NY Three)	2 2 2 2 2 2 2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1. 2. 3. 4. 5.	ing the course, the stu- ormulate mathematical interpret the results of a sesoftware to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex r Sensitivity analysis o Optimization using n Optimization using n Total	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem on-linear methods	ous practical system it the insights (ser on Techniques in roblem	a Design ( A	NY Three)	2 2 2 2 2
After learn 1. Fo 2. in 3. U Detailed S Expt. 1. 2. 3. 4.	ing the course, the stu- ormulate mathematical interpret the results of a se software to solve pro- syllabus: Pa Description Mathematical modeli Primal dual simplex r Sensitivity analysis o Optimization using n Optimization using n Total site:	l programs in varie model and presen oblems rt A: Optimization ng of a real life present nethod f linear problem on-linear methods	ous practical system it the insights (ser on Techniques in roblem	Design ( A Design ( A S Free Three)	NY Three)	2 2 2 2 2 2 2

#### **Outcomes:**

After learning the course, the students should be able to:

- 1. Apply Vibration measurement techniques and Analyse using modern tools and technique.
- 2. Understand Basic principals in acoustics, measurement of sound Power and apply to analyze effectiveness in compliance to noise regulations.

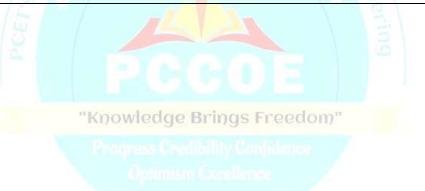
Expt.	Part B: Advanced Vibrations and Acoustics (ANY Three) Description	Duration
1.	Case Study on - Time domain and Frequency domain analysis of signals / experimental modal analysis / machine conditioning and monitoring / fault diagnosis	2
2.	Simulation study using finite element Analysis Tool on a. Modal analysis b. Harmonic analysis c. Transient analysis	2
3.	Modal Analysis with Impact Hammer Test	2
4.	Electro Dynamic Shaker to Obtain Natural Frequency and Dynamic Studies of a Cantilever Beam.	2
5.	Case study Analysis machine noise signature and analyze effectiveness in compliance to noise regulations.	2
	Total (Any Three)	6

3. Industrial Noise Control, Randell Barron, Marcel Dekker, Inc.

#### **Reference Books:**

- 1. Optimization Concepts and Applications in Engineering, Belegundu, Chandrupatla,
- 2. Machinery Condition Monitoring: Principles and Practices, A. R. Mohanty, CRC Press, 2014
- 3. Vibration and Acoustic: Measurement and Signal Analysis, C. Sujatha, Tata McGraw Hill
- Pvt. Ltd





Storeness

Program		M. Tech. Mechanica			Semester		
Course	:	Fatigue and Fractur	e Analysis (Electi	ive)	Code : M		
		Teaching Scheme			Evaluat	tion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req	uisite:		•				
	1.	Machine Design 2.	Engineering Meta	allurgy 3. Mater	rial Science		
Objecti	V06+						
1.		sess fatigue life at differ	ent loading condit	tions			
2.		ake aware about the ana			echanical compo	onents	
Outcon			•		<b>1</b>		
After lea	arning	the course, the students					
	1.	Identify the cycle co					lure.
	2.	Understand the use		0	0 1	1 standards.	
	3. 4.	Apply the fatigue fa Apply linear elastic				for brittle fracture	<b>x</b>
	4. 5.	Estimate crack resis					ו
	5. 6.	Examine the crack to					on.
			1 1 3 1	1	9		
Detaileo	l Sylla	bus 🧹	10				
Unit		cription	ALL A			2	Duration, h
		gue Mechanics				51	10
1.		varying uniaxial, biax					10
		ting, fatigue damage the gue Testing	eories of crack init	nation, stress ba	ised and strain b	ased approach	
2.		acquisition and instrum	nentation classica	1 methods of fa	tique testing A	STM standards	4
		cimen preparation, proc		i methous of h		STIT Standards	·
2		ial Cases in Fatigue					
3.		ue analysis in freque				lded structure,	5
		sion fatigue, high temp		mperature fatig	ue		
		ar Elastic Fracture M					
4.		nanisms of fracture, in risk in the second sec					6
		y of fracture, energy ba				icept – Grinnin	
		ss Intensity factors –				e crack double	
5.		crack, round hole with					5
	-	B) criterion	· 1 1				
		tic – Plastic Fracture I					
6.		duction, crack tip stres					6
	-	ing displacement, shape	e of the plastic zon	ie – von Mises	and Tresca yield	ing criteria,	2(
Text Bo	Tota	al					36
Text Du		atigue Testing and Ana	lysis – Theory and	Practice YUN	IG-LULEE Else	vier	
		atigue of Structures and				vier	
		fetal Fatigue in Enginee		-			
		lements of Fracture Me	-	-		n	
	2				<b></b>		
Referen	ce Boo	oks:					
	1. N	Ietal Fatigue Analysis I	Handbook, YUNG	-LI LEE, Elsev	ier		
	2. D	esign & Analysis of Fa	tigue Resistant We	elded Structure	, Dieter Radaj, V	Voodhead Publish	ning
		racture Mechanics And					
		racture Mechanics, Nes					
		racture Mechanics – An					
		Ionlinear Fracture Mech				D W/ Labor W/1	lor & Come To
	7. D	eformation and Fractur	e mechanics of Er	igineering Mate	mais, nertzberg	, к. w., Jonn Wi	iey & Sons, Inc

	n: N	A. Tech. Mechanical	(Design Engine	ering)	Semester	: II	
Course	: I	Reliability in Enginee	ering Design (Ele	ective)	Code : MI	MD2504B	
	•	<b>Teaching Scheme</b>			Evaluat	ion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req	uisite:						
	ring Math	ematics					
Objectiv							
1.		rm reliability enginee	ring analysis				
	To com	pute reliability engir	<b>U</b> .	ers and estimat	es for applicati	ons in mechani	cal devices a
	manulac	turing environments.					
Outcom	es:						
After lea		course, the students s					
1.		the possible faults in s					
		fault trees for a sub-s					
3.	Evaluate	maintenance schedul	es and assess the	corresponding	isk with appropr	iate techniques a	and tools
			es and assess the	conception ing i	isk with uppropi	inte teeninques t	ind tools.
Detailed	l Syllabu			conception			
Detailed Unit	l Syllabu Descri	s:					Duration, h
	Descri	s:					
	Descri Fundar	s: ption	chinchwa		ollege		
Unit	Descri Fundar Failure	s: ption nental concepts – I	hazard rate, MT	TF, MTBF, mai	ntainability, ava		Duration, h
Unit	Descri Fundar Failure cdf, Lif	s: ption nental concepts – I density, failure rate,	hazard rate, MT	TF, MTBF, mai	ntainability, ava		Duration, h
Unit 1.	Descri Fundar Failure cdf, Lif Fundar	s: ption nental concepts – I density, failure rate, e characteristic phases	hazard rate, MT s, modes of failur	TF, MTBF, mai	ntainability, ava bility.	ilability, pdf,	<b>Duration, h</b> 6
Unit	Descri Fundar Failure cdf, Lif Fundar Quality	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II	hazard rate, MT s, modes of failur nce rules, produc	TF, MTBF, mai re, Areas of relia	ntainability, ava bility. ability distributio	ilability, pdf,	Duration, h
Unit 1.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent.	hazard rate, MT s, modes of failur nce rules, produc	TF, MTBF, mai re, Areas of relia	ntainability, ava bility. ability distributio	ilability, pdf,	<b>Duration, h</b> 6
Unit 1. 2.	Descri Fundan Failure cdf, Lif Fundan Quality normal, coeffici System	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard o	ntainability, ava bility. ability distributio deviation, varian	ilability, pdf, ons binomial, ce, skewness	<b>Duration, h</b> 6
Unit 1.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series,	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard of of n structure, co	ntainability, ava bility. ability distribution deviation, varian omplex systems-	ilability, pdf, ons binomial, ce, skewness	<b>Duration, h</b> 6
Unit 1. 2.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabili	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard of of n structure, co	ntainability, ava bility. ability distribution deviation, varian omplex systems-	ilability, pdf, ons binomial, ce, skewness	<b>Duration, h</b> 6 6
Unit 1. 2. 3.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method Redund	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabilitancy	hazard rate, MT s, modes of failur ince rules, produc Weibull, expone guration, k- out o ity method, cut se	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard of of n structure, co et and tie set me	ntainability, ava bility. ability distributio deviation, varian omplex systems- thod,	ilability, pdf, ons binomial, ce, skewness enumeration	<b>Duration, h</b> 6 6
Unit 1. 2.	Descri Fundau Failure cdf, Lif Fundau Quality normal, coeffici System Series, method Redund Elemen	s: ption mental concepts – I density, failure rate, e characteristic phases mental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabilities lancy t redundancy, unit recomposite t redundancy, unit recomposite ption terms of the second	hazard rate, MT s, modes of failur ince rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard of of n structure, co et and tie set me by redundancy- t	ntainability, ava bility. ability distributio deviation, varian omplex systems- thod, ypes of stand by	ilability, pdf, ons binomial, ce, skewness enumeration	<b>Duration, h</b> 6 6
Unit 1. 2. 3.	Descri Fundan Failure cdf, Lif Fundan Quality normal, coeffici System Series, method Redund Elemen parallel	s: ption mental concepts – I density, failure rate, e characteristic phases mental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabili lancy t redundancy, unit red components single red	hazard rate, MT s, modes of failur ince rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb	TF, MTBF, mai re, Areas of relia ct liability, prob ential, standard of of n structure, co et and tie set me by redundancy- t	ntainability, ava bility. ability distributio deviation, varian omplex systems- thod, ypes of stand by	ilability, pdf, ons binomial, ce, skewness enumeration	<b>Duration, h</b> 6 6
Unit 1. 2. 3. 4.	Descri Fundan Failure cdf, Lif Fundan Quality normal, coeffici System Series, method Redund Elemen parallel System	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probability lancy t redundancy, unit rec components single refiability Analysis	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb	TF, MTBF, mai re, Areas of relia et liability, prob ential, standard of of n structure, co et and tie set me by redundancy- to ple redundancy.	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6
Unit 1. 2. 3.	Descri Fundan Failure cdf, Lif Fundan Quality normal, coeffici System Series, method Redund Elemen parallel System Reliabil	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabili lancy t redundancy, unit rec components single re reliability Analysis ity apportionment, F	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb dundancy, multip Reliability apport	TF, MTBF, mai re, Areas of relia et liability, prob ential, standard of of n structure, co et and tie set me by redundancy- to ole redundancy- to ole redundancy.	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6
Unit 1. 2. 3. 4.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method Redund Elemen parallel System Reliabii AGREI	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probabili lancy t redundancy, unit rec components single re reliability Analysis ity apportionment, F E, ARINC, feasibility	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb edundancy, multip Reliability apport of objectives app	TF, MTBF, mai re, Areas of relia et liability, prob ential, standard of of n structure, co et and tie set me by redundancy- to ole redundancy- to ole redundancy.	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6 6 6
Unit           1.           2.           3.           4.           5.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method Redund Elemen parallel System Reliabii AGREI Failure	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probability lancy t redundancy, unit red components single refiability Analysis ity apportionment, F E, ARINC, feasibility Mode, Effects and C	hazard rate, MT s, modes of failur nce rules, produc Weibull, expone guration, k- out o ity method, cut se dundancy, standb edundancy, multip Reliability apport of objectives app <b>Criticality Analy</b>	TF, MTBF, main re, Areas of reliant ct liability, prob cential, standard of of n structure, con- cent and tie set me may redundancy- to the redundancy- to the redundancy. cionment technic cortionment. rsis	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis ques – equal ap	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6 6 6 6
Unit 1. 2. 3. 4.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method Redund Elemen parallel System Reliabit AGREI Failure Failure	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probability lancy t redundancy, unit rec components single re reliability Analysis ity apportionment, F 2, ARINC, feasibility Mode, Effects and C mode effects analy	hazard rate, MT s, modes of failur ince rules, produc Weibull, expone guration, k- out of ity method, cut se dundancy, standb dundancy, multip Reliability apport of objectives app <b>Criticality Analy</b> vsis, severity/crit	TF, MTBF, main re, Areas of reliant ct liability, prob cential, standard of of n structure, control of the set me rest and tie	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis ques – equal ap , FMECA exam	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6 6 6
Unit           1.           2.           3.           4.           5.	Descri Fundar Failure cdf, Lif Fundar Quality normal, coeffici System Series, method Redund Elemen parallel System Reliabit AGREI Failure Failure	s: ption nental concepts – I density, failure rate, e characteristic phases nental concepts – II and reliability assura Poisson, lognormal, ent. reliability parallel, mixed config , conditional probability lancy t redundancy, unit red components single refiability Analysis ity apportionment, F E, ARINC, feasibility Mode, Effects and C	hazard rate, MT s, modes of failur ince rules, produc Weibull, expone guration, k- out of ity method, cut se dundancy, standb dundancy, multip Reliability apport of objectives app <b>Criticality Analy</b> vsis, severity/crit	TF, MTBF, main re, Areas of reliant ct liability, prob cential, standard of of n structure, control of the set me rest and tie	ntainability, ava bility. ability distribution deviation, varian omplex systems- thod, ypes of stand by Markov analysis ques – equal ap , FMECA exam	ilability, pdf, ons binomial, ce, skewness enumeration redundancy,	<b>Duration, h</b> 6 6 6 6 6

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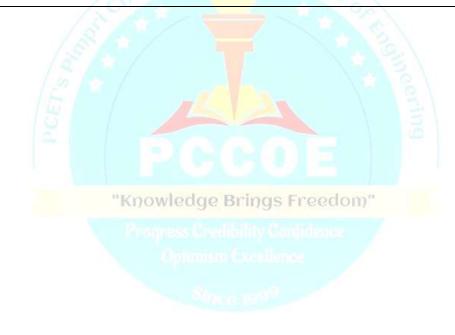
Program:	M. Tech. Mechanical (Design Engineering)Semester : IIMechatronics and Control Systems (Elective)Code : MMD2504C					
Course :		ontrol Systems (E	lective)			
	Teaching Scheme	1		Evaluat	ion Scheme	•
Lecture	Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisite:		-	-			
	athematics, Mechatron	nics				
Objectives:	·					
•	and Apply various sens	sors/transducers fo	r suitable applie	cation		
2. Select	sensors/transducers bas	sed on static and d	ynamic characte	eristics		
	stand and apply, interfa					
	l mechanical and electro	•				
	n controller in time and					
	stand control actions su	ich as Proportiona	l, derivative an	d integral and s	tudy its significa	ance in industria
applic	ation					
Outcomes:						
-	the course, the students					_
•	se static and dynamic cl		struments and S	select and Apply	sensors/ transdu	icers for
	rements of physical qua			00		
	interfacing techniques		em <mark>ent data</mark> from	n external enviro	nment and apply	/ filtering
	ques to attenuate measu				A	
	alate the mathematical n					oach.
•	ze system stability base	• / / ·				
-	n the control system for		•			-
6. Desig	n the control system i	n frequency dom	ain and Analy	to quatom stabil		1 1 1 1 1
-			ani and Analy.	ze system stadn	ity in open and	d closed loop i
freque	ency domain by Bode pl			ze system stadn	ity in open and	a closed loop i
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freque Detailed Sylla Unit Des 3. Fund	ency domain by Bode pl bus: cription lamentals of Instrume	ot.			60,25	-
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freque       Detailed Sylla       Unit     Des       3.     Fund       Class     Sense	ency domain by Bode pl bus: cription lamentals of Instruments sification of instruments ors and Transducers: Fo	ot. <b>ntation</b> ;; Characteristics of proce, Speed Measu	of Measurement urement, Strain	system: Static a Measurement, V	nd Dynamic; Vibration and	-
freque Detailed Sylla Unit Des 3. Func Class Sense Noise	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele	ot. <b>ntation</b> ;; Characteristics of prce, Speed Measure rometer, Laser De	of Measurement arement, Strain oppler Vibrome	system: Static a Measurement, V ter, Temperature	nd Dynamic; Vibration and e: Pyrometer,	Duration, h
freque Detailed Sylla Unit Des 3. Fund Class Sense Noise Vary	ency domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu	ot. <b>ntation</b> ;; Characteristics of prce, Speed Measure rometer, Laser De	of Measurement arement, Strain oppler Vibrome	system: Static a Measurement, V ter, Temperature	nd Dynamic; Vibration and e: Pyrometer,	Duration, h
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas	ency domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement.	ot. <b>ntation</b> ;; Characteristics o prce, Speed Measu rometer, Laser Do ure: Pirani, Mcle	of Measurement arement, Strain oppler Vibrome	system: Static a Measurement, V ter, Temperature	nd Dynamic; Vibration and e: Pyrometer,	Duration, h
freque       Detailed Sylla       Unit     Des       3.     Func       Class     Sense       Noise     Vary       mease     2.	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont	ot. <b>ntation</b> ;; Characteristics of prce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller	of Measurement prement, Strain poppler Vibrome cod; flow rate	system: Static a Measurement, V ter, Temperatura : Ultrasonic; a	nd Dynamic; Vibration and Pyrometer, nd humidity	Duration, h
freque       Detailed Sylla       Unit     Des       3.     Func       Class     Sense       Noise     Vary       meas     2.       Inter     Data	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A	ot. <b>ntation</b> ;; Characteristics of porce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit	of Measurement arement, Strain oppler Vibrome cod; flow rate al Signals, Ba	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl	nd Dynamic; Vibration and e: Pyrometer, nd humidity ing theorem,	Duration, h
freque       Detailed Sylla       Unit     Des       3.     Func       Class     Sense       Noise     Vary       meas     Data       2.     Inter       Data     ADC	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A	ot. <b>Intation</b> ;; Characteristics of porce, Speed Measure rometer, Laser Doure: Pirani, Mcle ure: Pirani, Mcle troller Analog and Digit ation, Dual slope,	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 2	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters:	Duration, h
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas 2. Inter Data ADC Low	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi	ot. <b>ntation</b> ; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacin	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ng of sensors/ac	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 2	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters:	Duration, h
freque       Detailed Sylla       Unit     Des       3.     Func       Class     Sense       Noise     Vary       meas     2.       Inter     Data       ADC     Low       3.     Math	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi pematical Modelling of	ot. <b>ntation</b> ; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacin f Dynamic System	of Measurement arement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b og of sensors/ac 15	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, i tuators with Ard	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino	Duration, h
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Treque Detailed Sylla Unit Des 3. Func Class Sensu Noise Vary meas 2. Inter Data ADC Low 3. Math Class funct	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelli	ot. <b>Intation</b> ;; Characteristics of porce, Speed Measure rometer, Laser Doure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f <b>Dynamic System</b> g, Modelling of ing, Block diagram	of Measurement arement, Strain oppler Vibrome od; flow rate al Signals, Ba DAC: R-2R, bi og of sensors/ac ns Mechanical, 1	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, T tuators with Ard Electro-mechanic	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino	Duration, h
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas 2. Inter Data ADC Low 3. Math Class funct 4. Stab	ncy domain by Bode pl bus: cription lamentals of Instruments of and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelli ility analysis of Dynam	ot. <b>intation</b> ;; Characteristics of porce, Speed Measure rometer, Laser Doure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, ba of sensors/ac s Mechanical, I n representation	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer	Duration, h
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas 2. Inter Data ADC Low 3. Matl Class funct 4. Stab Poles	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelli	ot. <b>ntation</b> ; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of s	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b og of sensors/ac ns Mechanical, In n representation econd order	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction system, Transic	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer	Duration, h
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas 2. Inter Data ADC Low 3. Matl Class funct 4. Stab Poles speci	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelli ility analysis of Dynam s and Zeros, System	ot. <b>ntation</b> s; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f <b>Dynamic System</b> g, Modelling of ing, Block diagram <b>nic Systems</b> a response of se and relative stability	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ag of sensors/ac ns Mechanical, In representation econd order y, System Stab	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, i tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and	Duration, h
freque         Detailed Sylla         Unit       Des         3.       Fund         3.       Fund         Class       Sense         Noise       Vary         meas       Vary         2.       Inter         Data       ADC         Low       Class         3.       Math         Class       funct         4.       Stab         Poles       speci         Zero       Zero	ncy domain by Bode pl bus: cription lamentals of Instruments of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelli ility analysis of Dynam s and Zeros, System fications, Absolute ar	ot. <b>ntation</b> s; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f <b>Dynamic System</b> g, Modelling of ing, Block diagram <b>nic Systems</b> a response of se and relative stability	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ag of sensors/ac ns Mechanical, In representation econd order y, System Stab	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, i tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and	Duration, h 6 6
freque Detailed Sylla Unit Des 3. Func Class Sense Noise Vary meas 2. Inter Data ADC Low 3. Matl Class funct 4. Stab Poles speci Zero on R 5. Cont	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling in, State space modelling in, State space modelling sifications, Absolute ar s and Zeros, System fications, Absolute ar s of System, Stability of outh Hurwitz criterion trol in Time Domain	ot. <b>Intation</b> S; Characteristics of orce, Speed Measure rometer, Laser Do ure: Pirani, Mcle <b>troller</b> Analog and Digit ation, Dual slope, gh Pass; Interfacing f <b>Dynamic System</b> g, Modelling of ing, Block diagram <b>nic Systems</b> a response of s and relative stability f system using Lystem	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b- ng of sensors/ac ns Mechanical, I n representation econd order y, System Stab- apunov's criteri	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction system, Transic ility analysis usi ion, Stability of	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based	Duration, h 6 6
frequeDetailed SyllaUnitDes3.Func3.FuncClassSensNoiseVarymeasVary2.InterDataADCLowLow3.MatlClassfunct4.StabPolesspeciZeronon R5.ContIntro	ncy domain by Bode pl bus: cription lamentals of Instruments of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu- urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling in Zeros, System fications, Absolute ar s of System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an	ot. <b>ntation</b> ; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of se ad relative stability f system using Lystem and closed loop con	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b og of sensors/ac ns Mechanical, I n representation econd order y, System Stabi apunov's criteri	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, T tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state	Duration, h 6 6 6 6
freque         Detailed Sylla         Unit       Des         3.       Fund         3.       Fund         Class       Sense         Noise       Vary         meas       Vary         2.       Inter         Data       ADC         Low       Low         3.       Matl         Class       funct         4.       Stab         Poles       speci         Zeros       on R         5.       Cont         Intro       space	ncy domain by Bode pl bus: cription lamentals of Instruments of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling ion, State space modelling is and Zeros, System fications, Absolute ar s of System, Stability of puth Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o	ot. <b>ntation</b> s; Characteristics of proce, Speed Measure rometer, Laser Do ure: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of se ad relative stability f system using Lya ad closed loop con bservability of sy	of Measurement arement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b og of sensors/ac ns Mechanical, In representation econd order y, System Stabi apunov's criteri trol, Conversio stem, Full state	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, i tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback contr	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state	Duration, h 6 6
frequeDetailed SyllaUnitDes3.Func3.FuncClassSenseNoiseVarymeasNoise2.InterDataADCLowLow3.MatlClassfunct4.StabPolesspeciZeroson R5.ContIntrospaceusing	ncy domain by Bode pl bus: cription lamentals of Instruments of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling in and Zeros, System fications, Absolute ar s of System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o g pole placement technic	ot. <b>ntation</b> ; Characteristics of proce, Speed Measures rometer, Laser Do prometer, Laser Do promet	of Measurement arement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b og of sensors/ac ns Mechanical, In representation econd order y, System Stabi apunov's criteri trol, Conversio stem, Full state	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, i tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback contr	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state	Duration, h 6 6 6 6
freque         Detailed Sylla         Unit       Des         Jane 1       Des         3.       Fund Class Sense         3.       Fund Class         Vary meas       Noise         2.       Inter         Data       ADC         Low       ADC         Jata       Math         Class       funct         4.       Stab         Poles       speci         Zeros       on R         5.       Cont         Intro       space         using       Cont         6.       Cont	ncy domain by Bode pl bus: cription lamentals of Instruments of instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu- urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi penatical Modelling of sification of modelling ion, State space modelli ility analysis of Dynam s and Zeros, System fications, Absolute ar s of System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o g pole placement technic trol in Frequency Dom	ot. ntation s; Characteristics of proce, Speed Measure rometer, Laser Do troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f <b>Dynamic System</b> g, Modelling of ing, Block diagram nic Systems a response of sind relative stability f system using Lyst and closed loop cond bservability of sy ue, Pole placement ain	of Measurement arement, Strain oppler Vibrome od; flow rate al Signals, Ba DAC: R-2R, bi og of sensors/ac <b>18</b> Mechanical, In representation econd order y, System Stabia apunov's criteri ttrol, Conversio stem, Full state it using Ackern	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, T tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback conti- nan's formula	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state rol of system	Duration, h 6 6 6 6
frequeDetailed SyllaUnitDes3.Fund3.FundClassSenseNoiseVarymeas2.InterDataADCLowLow3.MatlClassfunct4.StabPolesspeciZeroson R5.ContIntrospaceusing6.	ncy domain by Bode pl bus: cription lamentals of Instruments ors and Transducers: For e Measurement: Accele ing Resistance; pressu- urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling ility analysis of Dynamis and Zeros, System fications, Absolute ar s of System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o g pole placement technic rol in Frequency Dom uency response of system	ot. ntation s; Characteristics of proce, Speed Measure rometer, Laser Do are: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of sy a closed loop con bservability of sy pue, Pole placement ain m, Bode plot to de	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ing of sensors/ac IN Mechanical, In representation econd order y, System Stabi apunov's criteri ttrol, Conversio stem, Full state at using Ackern	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback contri nan's formula margin and gain	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state ol of system margin, PID	Duration, h 6 6 6 6 6
frequeDetailed SyllaUnitDes3.Func3.FuncClassSenseNoiseVarymeas2.InterDataADCLowLow3.MatlClassfunct4.StabPolesspeciZeroson R5.ContIntrospaceusing6.	ncy domain by Bode pl bus: cription lamentals of Instruments of an and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling ion, State space modelling in, State space modelling sof System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o g pole placement technic rol in Frequency Dom uency response of system of system design and	ot. ntation s; Characteristics of proce, Speed Measure rometer, Laser Do are: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of sy a response of sy a response of sy a response of sy a closed loop con bservability of sy pue, Pole placement ain m, Bode plot to de	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ing of sensors/ac IN Mechanical, In representation econd order y, System Stabi apunov's criteri ttrol, Conversio stem, Full state at using Ackern	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback contri nan's formula margin and gain	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state ol of system margin, PID	Duration, h 6 6 6 6
frequeDetailed SyllaUnitDes3.Fund3.FundClassSenseNoiseVarymeas2.InterDataADCLowLow3.MatlClassfunct4.StabPolesspeciZeroson R5.ContIntrospaceusing6.Cont	ncy domain by Bode pl bus: cription lamentals of Instruments of an and Transducers: For e Measurement: Accele ing Resistance; pressu urement. facing with Microcont Acquisition System, A : Successive Approxim Pass, Band Pass and Hi nematical Modelling of sification of modelling ion, State space modelling ion, State space modelling ion, State space modelling in, State space modelling sof System, Stability of outh Hurwitz criterion rol in Time Domain duction to open loop an e. Controllability and o g pole placement technic rol in Frequency Dom uency response of system of system design and	ot. ntation s; Characteristics of proce, Speed Measure rometer, Laser Do are: Pirani, Mcle troller Analog and Digit ation, Dual slope, gh Pass; Interfacing f Dynamic System g, Modelling of ing, Block diagram nic Systems a response of sy a response of sy a response of sy a response of sy a closed loop con bservability of sy pue, Pole placement ain m, Bode plot to de	of Measurement urement, Strain oppler Vibrome cod; flow rate al Signals, Ba DAC: R-2R, b ing of sensors/ac IN Mechanical, In representation econd order y, System Stabi apunov's criteri ttrol, Conversio stem, Full state at using Ackern	system: Static a Measurement, V ter, Temperature : Ultrasonic; a ndwidth, Sampl inary weighted, 1 tuators with Ard Electro-mechanic and reduction system, Transie ility analysis usi ion, Stability of n of transfer fun e feedback contri nan's formula margin and gain	nd Dynamic; Vibration and Pyrometer, nd humidity ing theorem, Noise Filters: uino cal, Transfer ent response ng Poles and system based ction to state ol of system margin, PID	Duration, h 6 6 6 6 6

### **Text Books:**

- 1. Measurement and Instrumentation Theory and Application, Alan Morris, Reza Langari, Elsevier
- 2. Alciatore & Histand, Introduction to Mechatronics and Measurement system, 4th Edition, McGraw Hill publication, 2011
- 3. Control System Engineering, Norman Nise, 6th Edition, John Wiley and Sons

### **Reference Books:**

- 1. Mechanical Measurements, S.P. Venkateshan, Ane Books Pvt. Ltd.
- 2. Measurement Systems-Application and Design, Doebelin E.O, McGraw Hill Publication
- 3. Park & Mackay, Practical Data Acquisition for Instrumentation & Control System, Elsevier, 2003
- 4. Dorf& Bishop, Modern Control Systems, 12<sup>th</sup> Ed, Prentice Hall
- 5. Ogata, Modern Control Engineering, 4<sup>th</sup> Ed, Prentice Hall
- 6. Golnaraghi & Kuo, Automatic Control Systems, John Wiley publications, 2010
- 7. C. D. Johnson, Process Control Instrumentation Technology, Prentice Hall, New Delhi
- 8. Astrom & Hagglund, PID Controllers: Theory, Design & Tuning, Chapter 2, 2<sup>nd</sup> Ed, Instrument Society of America, 1995.
- 9. J. P. Holman; "Experimental Methods for Engineers" McGraw Hill International Editions, Mechanical Engineering Series. ISBN 0-07-113354-2



Program:	M. Tech. Mechanical			Semester :		
Course :	Design of Material H	andling Equipme	nt (Elective)	Code : MN		
	Teaching Scheme			Evaluat	ion Scheme	
Lecture	e Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisite	:					
	ry of Machines nine Design					
<ol> <li>Under</li> <li>Ident</li> </ol>	easilze the importance of erstand the benefit of an e ify and select various typ gn of material handling s	efficient material have been of material have been been been been been been been be	andling system dling equipmen	ts	acturing and se	ervice industry.
Jutcomes:	0.	<u> </u>		0	0	2
After learning	the course, the students	should be able to				
1. Idei	ntify the use and importat	nce of material han	ndling			
2. Ider	ntify different loads and c	classify material ha	indling based of	n application		
	ply the design procedures	of various materia	al h <mark>an</mark> dling equi	pment & compo	onents and desi	gn the
	erial handling system.	hwat		0/1		
	ign load lifting & load m		n <mark>ts with p</mark> roper	design consider	ation understa	nd the use
	utomation in material has					
	ign the auxiliary equipment	ent			0	
Detailed Sylla Unit D	abus: Description	100/		1	2	Duration, h
	aterial handling system				100	Duration, n
Pr	inciples and features		ling system	importance ter	minology	
	jectives and benefits of					6
	uipment	1 1	8,		8	
Sc	election of material hand	lling equipment				
	noice of material handling		rs affecting for	selection, gener	al analysis	6
	ocedures, basic analytica				·	
	esign of cranes		ACAC			
	and-propelled and travel					6
	nsiderations for structu					Ū
	verhead traveling cranes,	stability of stationa	ary rotary and the	caveling rotary c	ranes,	
	esign of cranes	a north rest of		anneres		
	ectric overhead travelling					6
	nsiderations, end carria lection, safety arrangeme			chamsms, brak	les, motor	
	oad lifting attachments	ins, cicculcal colli	ioi system			
	bad inting attachments and chains and types of re	opes used in mater	ial handling sv	stem, forged sta	indard and	
	amshorn hooks, crane					6
	eaves, sprockets	- 1	2	5		
	udy of bulk material ha	ndling systems				
De	esign consideration for co	onveyor belts, Obje				
	avity flow of solids thro					6
	nveyor, vibratory conve	yor, pneumatic &	hydraulic conv	eyor (classificat	ion, types,	
	inciples of operation)					24
	otal					36
<b>Text Books:</b>	1. N. Rudenko, 'Materi	al Handling Equin	ment' Dessa D.	ublishers		
	2. James M. Apple, 'Ma				Sons	
	3. John R. Immer, 'Mat			to in the participation	S 9115	
Reference Bo		The second secon				
	1. Colin Hardi, 'Materia	al Handling in Mad	chine Shops'. N	Iachinery Public	ation Co. Ltd.	
	2. M.P. Nexandrn, 'Ma					
	3. C. R. Cock and J. Ma	ason, 'Bulk Solid F	landling', Leor	ard Hill Publica		
4	4. Spivakovsy, A.O. and	d Dyachkov, V.K.,	, 'Conveying M	lachines', Volun	nes I and II, M	IR Publishers,
	5. Kulwiac R. A., 'Mate	erial Handling Han	d Book', John	Wiley Publicati	on	

Program:	M. Tech. Mechanica		ring)	Semester		
Course :	Computer Aided De	sign (Elective)			MD2505B	
	Teaching Scheme			Evalua	tion Scheme	
Lectu	re Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisi						
	ctors, Programming languations and the second structure of the second seco		omatria modal	ing coftwore		
Dbjectives:	s recommended to have ki	lowledge of any ge	ometric model	ing software.		
	intends to give students a	an insight into use	of computers	in various stage	es of the product of	levelopment li
	ation, geometric modellin				b of the product (	ae veropinent n
Outcomes:			1			
After learnii	ng the course, the students	should be able to:				
	aluate mathematical transf		ections of rigio	l bodies.		
	sign & model curves, surfa					
	velop codes to solve engin					
4. Imj Detailed Sy	plement various algorithm	s studied in Compu	iter Graphics			
Unit	Description		-			Duration, h
	Computer aided Design -	- An insight		COL		<u> </u>
	A typical product cycle, th		omputers for d	esign. CAD tool	s for the design	0
	process, Hardware requir					
	graphical memory, Concep					
2.	Geometric Transformati	ons			181	6
	Homogeneous representat			Reflection, Rot	ation, Shearing	
İ	in 2D and 3D; Orthograph	ic and perspective	proj <mark>ecti</mark> ons.		131	
	Curves and Surfaces					6
	Lines, scan conversion al					
	lines, distance of a point,	Intersection of line	s, Circle, Ellip	<mark>se</mark> and general c	urves (parabola	
	and hyperbola),	momenties and ble	nding Dagio	Cumula aquati	Concernation.	
	Cubic Spline: equation, Properties and advantages					
	their typical applications.	or D-Sprines and	NORDS. Vanc	has types of surf	aces along with	
	Computer Aided Geome	tric Design - Curv	es	The second second	77	6
	Plane Curves, Space Curv			icit, Parametric	curves. The de	
	Casteljau Algorithm, de					
	Geometric continuity, Pro	ojection Of Point (	On Curve, Cur	rve-Curve Inters	section, Hermit,	
	Bezier, B-Spline curves	le Ontim	ism Excelle	nee 🧭		
	Computer Aided Geome					6
	Trim Surfaces, Curve an Equation, Curve And Su					
	Surface-Surface Intersection					
	Surfaces			luces, 1 lojection	of Surface on	
	Solid Modelling and App	lications				6
	Introduction, solid repres		of Topology,	Boundary Repr	resentations (B-	
	Rep), Constructive Solid					
	Drawings, Extrusion, Re	volve, Shell, Dra	ft, Patterning	, Surface and	Solid Boolean	
(	Operations					•
	Total					36
Fext Books		Zlamanta fan Cama		Tata MaCasasa I	TH New Dalk: 2	
<ol> <li>Rogers</li> <li>Donald</li> </ol>	& Adams, Mathematical I Hearn and M. Pauline Bal	ker Computer Grav	uter graphics,	F ata MCOFaW – I	n. Prentice Hall 3	rd Edition 198
3. Compu	ter graphics, Schaum Serie	es. McGraw Hill 2 <sup>1</sup>	<sup>1d</sup> Ed. 2000	Leonomy Eunio		Luiuon, 170
	ter graphics- Foley Van Da			n, 1996		
Reference I	* * *		. , <u></u>	,		
	y, J. and Steadman, P., Pri	nciples of Compute	er Aided Desig	n, Design, Prent	ice Hall.	
	-Hua Chang, Product Dest eering Design Series, Else		, CAD/CAE -	The Computer A	lueu	

			(Design Enginee	ring)	Semester		
Cours		i-body Dynamics	(Elective)		Code : MI		
	Те	eaching Scheme			Evalua	tion Scheme	1
L	ecture	Credit	Hours	IE1	IE2	ЕТЕ	Total
	3	3	3	20	30	50	100
Pr	e-requisite:	Theory of Machi	nes, Engineering	g Mathematics	1		1
Object	1. To Kin <b>2.</b> To Kin	ematically and d mematically and d					
	earning the co 1. Deriv dimen 2. Imple 3. Write 4. Simu	burse, the students re equations of mo- sional motion. ement and analyze programs to solv late and analyze a	tion for interconn methods of form e constrained diff ll types of static a	nected bodies in ulating equation Perential equation	s of motion for ns for analyzing	interconnected multi-body sy	l bodies. stems.
Dotoil	includ ed Syllabus	ing the kineto-sta	tic analysis.				
Unit	Descriptio	n		d			Duration, h
Unit		iples for analysis	of multi-body s	vstems	0110		Duration, n
1.	The constra The automatic	ints for planar kin atic assembly of analysis. Iterative	ematic analysis. the systems of	Revolute, prism f equations for	position, velo		6
2.	<b>Computatio</b> Geometry o	on of Forces, plan f masses, compute forces for externa	nar ation and assembl	ly of mass matri	x. Computation	of planar	6
3.	Computation	on of Forces, spec n of spatial gener Lagrange's multi	alized forces for	external forces.	Computation o	f reaction	б
4.		of Planar Systems of planar systems		ations of invers	e and forward	dynamic	6
5.	Reference parameters.	of <b>rigid bodies i</b> frames for the l Screw motion between the an	ocation of a bo in space. Veloci	ity, acceleration	n and angular	velocity.	6
6.	Kinematic Basic kinen description	analysis of spatia natic constraints. in space of comr Equations of motio	Joint definition f non kinematic pa	airs (revolute, p			6
	Total			spatial systems.			36
	10141						50
<b>Text B</b> 1. 2. 3. 4. 5.	Wittenburg Kane, T.R, Nikravesh, 1988. Roberson, I	g, J., Dynamics of Levinson, D.A., P.E., Computer R.E., Schwertasse Computer-Aided	Dynamics: Theory Aided Analysis og k, R., Dynamics o	y and Applicatio f Mechanical S of Multibody Sys	ns, McGraw-Hi ystems, Prentice tems, Springer-	ill Book Co., 1 e-Hall Inc., Er Verlag, Berlin	nglewood Cliffs, 1 , 1988.

- 7. Schielen, W. ed., Multibody Systems Handbook, Springer-Verlag, Berlin, 1990.
- 8. de Jalo n, J.C., Bayo, E., *Kinematic and Dynamic Simulation of Multibody Systems*, Springer-Verlag, 1994.

9. Shabana, A.A., Computational Dynamics, John Wiley & Sons, 1994.

**Reference Books:** 

- 1. "Why Do Multi-Body System Simulation?" by Rajiv Rampalli, Gabriele Ferrarotti & Michael Hoffmann, Published NAFEMS Publications, January 12
- 2. "Principles of Dynamics" by Donald T. Greenwood, 2nd ed., Prentice Hall

	M.Tech. Mecha		gineering)	S	emester :	II
Course :	Professional Ele			C	ode : MMD2	2506
course.		ctive III & Electi	ve IV			
	Teaching Schem	e		Evalı	uation Schem	e
Practical	Hours	Credit	TW	PR	OR	Total
2	2	1	50		50	100
Pre-requis	ite:				1	
		de students the too	ols required for Sin	nulate, correla	ate and validate	te theoretical concepts an
Outcomes: After learn	<ol> <li>ing the course the stud</li> <li>Solve open end</li> <li>Simulate the prior</li> <li>Understand the</li> </ol>	led Design proble roblem and correla e impact of assum	m and report the se ate with theoretical ptions on the simu	concepts lated results		
<u>a</u>		nalyse, interpret ai	nd report the result	S.		
Guidelines	s : ny one subject from [	Dart A and Dart	R as per students a	lective choice	c	
	• •		-			
	otal experiments to be		nree from Part A	and Three fr	om Part B	
<b>3.</b> To	otal : 6 experiments	12 hours				
D	etailed Syllabus:	P.J.A			43	
		A: Elective 1- Fa	tigue and Fractu	e Analysis (	ANY Three)	
Expt.	Description	ni-an y		,	1	Duration
1.	Case Studies based o Rain Flow Counting		54	-		2
2.	Stress / Strain Based	Fatigue Analysis	1 . 1 . 1	0.0		2
3.	FEA Simulation of f		Problem			2
4.	Crack tip stresses usi	U				2
5.				1	Treat	
	Biress 7 mary 515 doing	Image Processing	odgo Bring	E FROOD		
	Total	g Image Processing	edge Bring	is Freedo	2117	2
	Total Part A					06
Exnt	Part A		gedge Bring iability in Engine			06
Expt.	Part A Description	A: Elective 1- Reli	iability in Engine			06 ) Duration
1.	Part A Description Characteristics of Bi	A: Elective 1- Reli	iability in Engine			06 ) Duration 2
1. 2.	Part A Description Characteristics of Bi Characteristics of No	A: Elective 1- Reling nomial and Poisson rmal and Log-Nor	iability in Engine on distributions rmal distributions			06 ) Duration 2 2 2
1. 2. 3.	Part A Description Characteristics of Bi Characteristics of No Determination of MT	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and	iability in Engine on distributions rmal distributions parallel systems	ering Design (		06 ) Duration 2 2 2 2
1. 2. 3. 4.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p	<b>Contract Series and Poisse and Poisse and Poisse and Log-Nor</b> TF for series and robability indices	iability in Engine on distributions rmal distributions parallel systems	ering Design (		06 ) Duration 2 2 2 2 2
1.           2.           3.           4.           5.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s	a: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system	iability in Engine on distributions rmal distributions parallel systems	ering Design (		06 ) Duration 2 2 2 2 2 2 2 2
1.           2.           3.           4.           5.           6.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation	A: Elective 1- Reli nomial and Poisso ormal and Log-Nor 'TF for series and robability indices system to system	iability in Engined on distributions rmal distributions parallel systems for series and para	ering Design (		06 ) Duration 2 2 2 2 2 2 2 2 2 2
1.           2.           3.           4.           5.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects	A: Elective 1- Reli nomial and Poisso ormal and Log-Nor 'TF for series and robability indices system to system	iability in Engined on distributions rmal distributions parallel systems for series and para	ering Design (		06 ) Duration 2 2 2 2 2 2 2 2 2 2 2 2
1.           2.           3.           4.           5.           6.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects <b>Total</b>	a: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity	iability in Engine on distributions rmal distributions parallel systems for series and para / criticality	ering Design (	(ANY Three	06           Duration           2           2           2           2           2           2           2           2           2           2           2           2           2           2           06
1. 2. 3. 4. 5. 6. 7.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A:	a: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity	iability in Engined on distributions rmal distributions parallel systems for series and para	ering Design (	(ANY Three	06 ) Duration 2 2 2 2 2 2 2 2 2 2 2 2 06 e)
1. 2. 3. 4. 5. 6. 7. Expt.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor 'TF for series and robability indices system to system analysis, severity Elective 1- Mech	iability in Engine on distributions rmal distributions parallel systems for series and para / criticality natronics and Cor	ering Design (	(ANY Three	06 ) Duration 2 2 2 2 2 2 2 2 2 06 e) Duration
1. 2. 3. 4. 5. 6. 7. Expt. 1.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description Interfacing of any set	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor 'TF for series and robability indices system to system analysis, severity Elective 1- Mech	iability in Engine on distributions rmal distributions parallel systems for series and para / criticality natronics and Cor	ering Design ( llel systems	( ANY Three ( ANY Three	06 ) Duration 2 2 2 2 2 2 2 2 2 2 2 2 06 e)
1.         2.         3.         4.         5.         6.         7.         Expt.         1.         2.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description Interfacing of any set Modelling and Analy System using MATL	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity Elective 1- Mech nsor / actuator wit rsis in Time Doma AB and Simulink	iability in Engine on distributions rmal distributions parallel systems for series and para / criticality hatronics and Cor h Arduino in: State Space Me	ering Design ( llel systems atrol Systems	( ANY Three ( ANY Three ( ANY Three MO/SISO	06 ) Duration 2 2 2 2 2 2 2 2 2 06 e) Duration
1.         2.         3.         4.         5.         6.         7.         Expt.         1.         2.         3.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description Interfacing of any set Modelling and Analy System using MATL Modelling and Analy MIMO/SISO System	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity Elective 1- Mech nsor / actuator wit assor / actuator wit AB and Simulink visi in Frequency I using MATLAB	iability in Engined on distributions rmal distributions parallel systems for series and para / criticality hatronics and Cor h Arduino hin: State Space Me Domain: Transfer and Simulink	ering Design ( llel systems atrol Systems odelling of MI Function Mod	(ANY Three (ANY Three (ANY Three MO/SISO lelling of	06           Duration           2           2           2           2           2           2           2           2           2           06           e)           Duration           2           2           2           2           2           2           2           2           2
1.         2.         3.         4.         5.         6.         7.         Expt.         1.         2.         3.         4.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description Interfacing of any set Modelling and Analy System using MATL Modelling and Analy MIMO/SISO System Mapping of pole- ze	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity Elective 1- Mech msor / actuator wit rsis in Time Doma AB and Simulink rsis in Frequency I a using MATLAB ro and analysis of	iability in Engined on distributions rmal distributions parallel systems for series and para / criticality hatronics and Cor h Arduino in: State Space Ma Domain: Transfer and Simulink system stability of	ering Design ( llel systems atrol Systems odelling of MI Function Mod	(ANY Three (ANY Three (ANY Three MO/SISO lelling of ystem	06           Duration           2           2           2           2           2           2           2           2           2           2           2           06           e)           Duration           2           2           2           2           2           2           2           2           2           2           2           2
1.         2.         3.         4.         5.         6.         7.         Expt.         1.         2.         3.	Part A Description Characteristics of Bi Characteristics of No Determination of MT Evaluation of basic p Markov Analysis of s Reliability allocation Failure mode effects Total Part A: Description Interfacing of any set Modelling and Analy System using MATL Modelling and Analy MIMO/SISO System	A: Elective 1- Reli nomial and Poisso rmal and Log-Nor TF for series and robability indices system to system analysis, severity Elective 1- Mech msor / actuator wit rsis in Time Doma AB and Simulink rsis in Frequency I a using MATLAB ro and analysis of	iability in Engined on distributions rmal distributions parallel systems for series and para / criticality hatronics and Cor h Arduino in: State Space Ma Domain: Transfer and Simulink system stability of	ering Design ( llel systems atrol Systems odelling of MI Function Mod	(ANY Three (ANY Three (ANY Three MO/SISO lelling of ystem	06           Duration           2           2           2           2           2           2           2           2           2           06           e)           Duration           2           2           2           2           2           2           2           2           2           2

Expt.	Description	Duration
1.	Case Studies Based on	
	Use and importance of different material handling equipment's.	2
2.	Safety in Material handling system.	2
3.	Design aspects and failures in the material handling system	2
4.	Design of any one material handling system based on Manufacturing assembly and cost consideration.	2
	Total	06
	Part B: Elective 2- Computer Aided Design (ANY Three)	
Expt.	Description	Duration
1.	Curves: Line DDA, Line Bresenham, Circle Bresenham	2
2.	Curves & Clipping: Mid-point ellipse, Window Clipping	2
3.	Transformations: Translation, Rotation, Scaling, Shear, Mirror	2
4.	Transformations: Combination of above	2
5.	Curves: Bezier curve, B-spline Curve, Hermite Curve,	2
6.	Surfaces: Lofted Surfaces, Bezier surface, B-spline Surface	2
	Total	06
	Part B: Elective 2- Multi-body Dynamics (ANY Three)	
Expt.	Description	Duration
1.	Velocity and acceleration analysis of planar systems	2
2.	Constraint analysis for planar kinematic analysis for revolute, prismatic, gear and cam pairs	2
3.	Dynamic analysis of planar systems	2
4.	Inverse and forward dynamic analysis	2
5.	Kinematic analysis of rigid bodies	2
6.	Kinematic analysis of spatial systems	2
7.	Reaction forces from actuator-spring-damper system	2
	Total	06

"Knowledge Brings Freedom"

Progress Credibility Confidence

Optimism Excellence

Since 1999

Program:	M. Tech Mecha	nical (Design Eng	gineering)	Semester	r:II	
Course :	Skill Developme		Skills and Englis			
	Aptitude) Teaching Schem	P			ion Scheme	
Practical	Hours	Credit	TW	PR	OR	Total
2	2	2	50		-	50
<b>Objectives</b> 1. To	s: o facilitate holistic gro	with				
2. To 3. To	o make the students av o develop the ability o o expose students to ri	ware about the sign f effective commu	inication through i	ndividual and	group activities	ious ostivitios
4. To	b expose students to h		enavioural aspects	and build the	same through val	nous activities
Outcomes			1			
	ing the course the stuc xpress effectively thro			c		
	repare for group discu	•				
	perate effectively in	•	-		gh the knowleds	ge of team wor
	ter personal relationsh	1 0	0		0	,
	-	achw	-	0110		
Guidelines		conducted and C'	out of sight			
	otal experiments to be otal : 6 experiments 1		out of eight			
Detailed S	-				12	
Detaileu B	ynabus.	Skill Deve	lopmen <mark>t L</mark> ab ( Al	NY Six)	181	
Expt.	Description	± /			6	Duration h
1.	Group Discussion: handle work, colleag one's opinion in a f	ues and clients. Dorum. Cultivate	evelop group com the habit of pres	munication skil	lls. Learn to speak	cup 2
2.	arguments making th	em contributors in	any team.		-	
2.	<b>Public Speaking:</b> Any one of the follo <b>1. Prepared speech</b> speech and 5 minu spontaneously for 5 r	(Topics are given tes to deliver.)	in advance, stude 2. Extempore sp			
3.	Writing An Article knowledge about how	On Any Social Is	sue: Build writing	skills, improv	e language and g	ain 2
4.	<b>Reading and Liste</b> given a article by th article one by one. <i>A</i> and needful correcti and listening skills.	ning skills: The ne facilitator. Eacl After reading by ea	batch can be divi h pair would come th pair, the other	e on the stage students would	and read aloud be asked questi	the ons 2
5.	<b>Debate On Current</b> forceful arguments w					. 2
6.	<b>Telephonic etiquett</b> phone. Students wil such as phone call members, phone call be given 10 min to p the telephone call.	l be divided into to enquire abou l for requesting of	pairs. Each pair w it job vacancy, so urgent leave from	vill be given d cheduling a m higher author	lifferent situation neeting with tea ities. Students w	ns, m ill 2
7.	Email etiquettes: T emails.	o provide student	s with an in-depth	understanding	g of writing form	al 2
8.	Mock interviews: C	Buide students and	conduct mock into	erviews		2
						-

### **Text Books:**

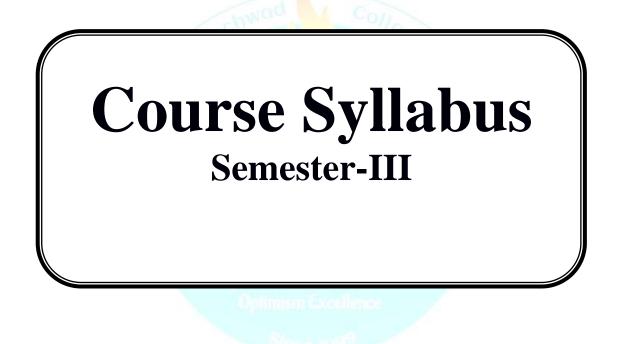
- 1. B. Mitra, Personality Development and Soft Skills
- 2. S. Lucas, The Art of Public Speaking

### **Reference Books:**

- 1. M. Weaver, Empowering Employees Through Basic Skills
- 2. G. Ratigan, Aced: Superior Interview Skills to Gain an Unfair Advantage to Land Your DREAM JOB!



		nical (Design Ei	ingineering)		Semester : II	
Course :	Integrated Mini				Code : MMD2	2701
	Teaching Schem	ie		Evalı	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
6	6	3	50		50	100
	e: cs of Design, Finite cs of MATLAB and			Acoustics, Cor	nposites	
2. Top 3. To	inderstand the 'Proc plan for various acti- build, design and forms.	vities of the proje	ect planning and e	execution.		ect. omain using availab
After learning 1. Und 2. Desi 3. Prep 4. Deli	g the course the stud erstand, plan and ex- ign real time applica- pare a technical repo- ver technical semin erstand publication	ecute a Mini Pro ation. ort based on the M ar based on the M	iject. Aini project. Aini Proj <mark>ect work</mark>			
Guidelines :	Total : 36 hours		1		and the	
<ol> <li>Indi</li> <li>Studi</li> <li>Studi</li> <li>The</li> </ol>	vidual student need ents can choose ementation in Majo hardware implement	area of project or Project in secon ntation on the boa	monstrate Mini-p in field of M nd year ard and software s	ulti-disciplinary	Designing compulsory.	nsidering their futu
<ol> <li>Indi</li> <li>Studi</li> <li>Studi</li> <li>The</li> <li>Min</li> <li>Pape</li> </ol>	vidual student need ents can choose ementation in Majo hardware implement i-Project Report sho er publication assoc	area of project or Project in secon ntation on the boa buld be submitted iated with mini-p	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research	ulti-disciplinary simulation is con of term work as noutcome is app	Designing co mpulsory. ssociated with su	nsidering their futu
<ol> <li>Indi</li> <li>Studi</li> <li>Studi</li> <li>The</li> <li>Min</li> <li>Pape</li> <li>Min</li> </ol>	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe	area of project or Project in secon ntation on the boa buld be submitted iated with mini-p	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research	ulti-disciplinary simulation is con of term work as noutcome is app	Designing co mpulsory. ssociated with su	nsidering their futur
<ol> <li>Indi</li> <li>Studi</li> <li>Studi</li> <li>The</li> <li>Min</li> <li>Pape</li> <li>Min</li> </ol>	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe	area of project or Project in secon ntation on the boa ould be submitted iated with mini-p erably should be o	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research	ulti-disciplinary simulation is con of term work as outcome is app ratory.	Designing co mpulsory. ssociated with su	nsidering their futur
<ol> <li>Indi</li> <li>Studi</li> <li>Studi</li> <li>The</li> <li>Min</li> <li>Pape</li> <li>Min</li> </ol>	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe	area of project or Project in secon ntation on the boa ould be submitted iated with mini-p erably should be o	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research completed in labo	ulti-disciplinary simulation is con of term work as outcome is app ratory.	Designing co mpulsory. ssociated with su	nsidering their futur
<ol> <li>Indi</li> <li>Studimpl</li> <li>The</li> <li>Min</li> <li>Pape</li> <li>Min</li> </ol> Detailed Syll	vidual student need ents can choose ementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe abus: Activity	area of project or Project in secon ntation on the boa build be submitted iated with mini-p erably should be on In Mini-project guid	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research completed in labo	ulti-disciplinary simulation is con of term work as noutcome is app ratory.	Designing compulsory. ssociated with subreciable.	nsidering their futu bject.
<ol> <li>Indi</li> <li>Studimpl</li> <li>The</li> <li>Min</li> <li>Pape</li> <li>Min</li> <li>Min</li> <li>Detailed Syll</li> <li>Sr. No.</li> </ol>	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefet abus: Activity Week 1 & 2 : M Planning of the w	area of project or Project in secon ntation on the boa ould be submitted iated with mini-p erably should be on In Aini-project guid work terature review as	monstrate Mini-p in field of M nd year ard and software s as a compliance project as research completed in labo	ulti-disciplinary simulation is con of term work as noutcome is appratory. Project ization of topic	Designing compulsory. ssociated with subreciable.	nsidering their futu bject. Duration, h
1. Indi 2. Stud impl 3. The 4. Min 5. Pape 6. Min Detailed Syll Sr. No. 1. 2. 3.	vidual student need ents can choose ementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Litt Review 1 for fin Week 5 & 6 : S of hardware plat	area of project or Project in secon ntation on the boa buld be submitted iated with mini-p erably should be on <u>In</u> Mini-project guid work terature review and alization of topic imulation of Idea form	monstrate Mini-p in field of M nd year ard and software s ard and software s roject as research completed in labo <b>ntegrated Mini-I</b> e allotment, final and specification a and specification a	ulti-disciplinary simulation is con of term work as noutcome is appratory. Project ization of topic and Methodolog	Designing compulsory. ssociated with subreciable. and platform, y Finalization, nd finalization	nsidering their futu bject. Duration, h
1. Indi 2. Stud impl 3. The 4. Min 5. Pape 6. Min Detailed Syll Sr. No. 1. 2.	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lin Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : ur and execute blo project	area of project or Project in secon ntation on the boa ould be submitted iated with mini-p erably should be of <u>In</u> Aini-project guid work terature review and alization of topic imulation of Idea form nderstanding plat ck level design	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research completed in labo <b>integrated Mini-I</b> e allotment, final and specification a and specification a and specification a and specification a a on appropriate s form implementa , Review 2 to u	ulti-disciplinary simulation is con- of term work as routcome is appratory. Project and Methodolog software tools a tion and related nderstand the p	y Designing compulsory. ssociated with subreciable. and platform, y Finalization, nd finalization software flow progress of the	nsidering their futu bject. Duration, h 6 6
1. Indi 2. Stud impl 3. The 4. Min 5. Pape 6. Min Detailed Syll Sr. No. 1. 2. 3.	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe labus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lit Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : un and execute blo project Week 9 & 10: M and execution.	area of project or Project in secon ntation on the boa build be submitted iated with mini-p erably should be or <u>In</u> Aini-project guid work terature review and alization of topic imulation of Idea form inderstanding plat ck level design	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research completed in labo <b>ntegrated Mini-I</b> e allotment, final nd specification a and specification a form implementa , Review 2 to u	ulti-disciplinary simulation is con- of term work as noutcome is appratory. Project ization of topic and Methodolog software tools a tion and related nderstand the p	v Designing co mpulsory. ssociated with sub preciable. and platform, ty Finalization, nd finalization software flow progress of the vright planning	nsidering their futu bject. Duration, h 6 6 6 6
1.       Indi         2.       Stud         3.       The         4.       Min         5.       Pape         6.       Min         Detailed Syll         Sr. No.         1.         2.         3.         4.	vidual student need lents can choose lementation in Majo hardware implement i-Project Report sho er publication assoc i-project work prefe labus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lit Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : un and execute blo project Week 9 & 10: M and execution.	area of project or Project in secon ntation on the boa build be submitted iated with mini-p erably should be of <b>In</b> Aini-project guid work terature review and alization of topic imulation of Idea form inderstanding plat ck level design Lini Project Repo	monstrate Mini-p in field of M nd year ard and software s l as a compliance roject as research completed in labo <b>integrated Mini-I</b> e allotment, final and specification a and specification a and specification a and specification a a on appropriate s form implementa , Review 2 to u	ulti-disciplinary simulation is con- of term work as noutcome is appratory. Project ization of topic and Methodolog software tools a tion and related nderstand the p	v Designing co mpulsory. ssociated with sub preciable. and platform, ty Finalization, nd finalization software flow progress of the vright planning	nsidering their futu bject. Duration, h 6 6 6 6 6



M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program:		anical) – Design			emester: III	
Course :			y/ In-house projec		ode: MMD3702	2
Т	eaching Scheme/we	ek		Evalua	tion Scheme	
Practical	Hours	Credit	IE2	PR	OR	Total
20	20	10	100		100	200
Pre-requisite:	e of Mechanism and	Machina Dasign	Machanical systa	m dasian Bas	ice of Applysic so	ftwara MATIAI
programming		Machine Design,	Mechanical syste	ili desigli, Das	ics of Allarysis so	itwale, MATLA
Objectives:						
	erstand the product/r	process developm	ent including budg	eting		
	n for various activ				e work towards	product /proces
develop		·	5 1 5			1 1
	ble students to apply				s to develop their	project.
	lcate research cultur	e in students for t	heir technical grov	wth.		
Outcomes:	· · · · · · · · · · · · · · · · · · ·					
0	ne course the student tand, plan and execu			raciable resear	rch outcomes	
	grate theory and prace				ren outcomes.	
	ionstrate research ski			e of study.		
	good quality techni					
5. Publish	good quality paper	in reputed journal	and present their	work in repute	d conferences.	
Guidelines :	1	0		10°0		
1. Individ	ual student need to c	lesign and demon	strate project unde	r the guidance	of allocated guid	e.
2. Sponso	ored Project or Project	et Internship is acc	ce <mark>ptable co</mark> nsiderin	ng postgraduat	e scope.	
3. The ph	ysical / soft model a	nd validation of re	esul <mark>ts is co</mark> mpulsoi	y.		
4. Project	Report-1 should be	submitted as a con	mplia <mark>nc</mark> e of term v	work associate	d with subject.	
5. At leas	st 2 paper publication	ons are expected	as research outco	ome of Projec	ct Stage-I ( Conf	erence or reput
journal	) and 40% of planne	d project work she	ould be completed	for submissio	n of Dissertation	Phase-I
	Duration: 120 hours a					
	s to satisfy all project				Star 1	Ĩ
Plan of Activiti	es					
Sr. No.	Activity					Duration, H
1.			lotment, applying c and platform, Pla			30
2.			v, objectives and n ppic and objectives		inalization,	20
3.	Week 6, 7 & of component		g, analytical / num	erical calculat	tions and design	30
	Review 2 to	understand the pr	ogress of the proje	ect		
4.	Week 9 &		of the experiment		nd measurement	20
5.	Week 11 & and executi	12: Project Report on. Demonstration	rt writing and pub on of Project w	-		20
	sudmission a	and term work con	nphances		Total	120
					Iual	140

Program:	M. Tech (Me	chanical) – Design	Engineering		mester : III	
Course :	Seminar			Со	de: MI	MD3703
Т	eaching Scheme/v	veek		Evaluati	on Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4 Guidelines :	4	2		50	50	100
allo 2. Stu imp 3. The exp 4. Ser 5. At 5. At 6. Tot acti 7. Course Outc 1. To ac 2. To pr 3. To de	becated guide. dents can choose to portance. e extensive Literature ected from seminar ninar Report should least 1 review pape al Duration: 24 C vities and requirem comes equire the basic skill rovide students bett	d be submitted as a c r publication is expe ontact Hours and 2 nents. Is to for performing er communication sh opics in the domain	n of mechanical atical Modeling ompliance of ter octed as research 4 Hours should literature survey kills	system conside of particular n m work associa outcome of ser be spent by s	ering recent trend nethod and valua ated with subject. ninar. tudents on comp sentation	ls and its societ
	1.00					
Sr. No.	Activity	Ser	ninar <mark>Ac</mark> tivities		2	
1		Ser	ninar <mark>Ac</mark> tivities		1990	Duration, H
1.	Week 1, 2 & 3: 0 Review-1 condu	Guide allotment, fina			e work.	Duration, H
2.	Review-1 condu	Guide allotment, fina	alization of topic	, Planning of th		
	Review-1 condu Week 4 & 5: Lit	Guide allotment, fina ction erature review and n Mathematical mode	alization of topic	, Planning of th		6
2.	Review-1 condu Week 4 & 5: Lit Week 6, 7 & 8 : Review-2 condu	Guide allotment, fina ction erature review and n Mathematical mode	alization of topic nethodology of t l and findings ar	, Planning of the selected topi d its analysis		6
2.	Review-1 condu Week 4 & 5: Lit Week 6, 7 & 8 : Review-2 condu Week 9 & 10 : C	Guide allotment, fina ction erature review and n Mathematical mode ction Comparison of findin Seminar Report writi	alization of topic methodology of t l and findings ar gs with findings	, Planning of the selected topi d its analysis in literature	c.	6 4 6

Program:	M. Tech (Mecha	ameal) Design I	ungineering		Semester : II	1
Course :	Internship [Con	npany / In-house	project]		Code :	MMD3801
r	<b>Teaching Scheme/v</b>	veek		Evalu	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100
<b>Guidelines :</b>					•	
1.	Individual student	need to attempt f	for internship wit	h the help of	of PCCOE T&	P cell in the field of
	Mechanical Design	under the guidance	ce of allocated gui	de.		
2.	If not get selected t	for any internships	s, student can cho	ose extensio	n of mini-proj	ect / entrepreneurshi
	•	•			1 0	ends and its societa
	importance.			51 <u>5</u> 11 € 01151 <b>0</b>		
3.	1					
	The idea precentation	on is avnacted from	m the student base	d on the ton	ic	
		-	m the student base	-		th subject
4.	Internship report sh	ould be submitted	l as a compliance	of term work	associated wi	
	Internship report sh Total Duration: 24	ould be submitted Contact Hours an	l as a compliance	of term work	associated wi	th subject. completion of relate
4. 5.	Internship report sh Total Duration: 24 activities and require	ould be submitted Contact Hours an	l as a compliance	of term work	associated wi	
4.	Internship report sh Total Duration: 24 activities and requin labus:	could be submitted Contact Hours an rements.	l as a compliance on 24 Hours shoul	of term work d be spent b	associated wi	
4. 5. Detailed Syl	Internship report sh Total Duration: 24 activities and requir <b>labus:</b>	ould be submitted Contact Hours an	l as a compliance on 24 Hours shoul	of term work d be spent b	associated wi	completion of relate
4. 5. Detailed Syl Sr. No.	Internship report sh Total Duration: 24 activities and requin <b>labus:</b>	could be submitted Contact Hours an rements.	l as a compliance on 24 Hours shoul	of term work d be spent b	associated wi	
4. 5. Detailed Syl	Internship report sh Total Duration: 24 activities and requir labus: Activity Week 1, 2 and	could be submitted Contact Hours an rements.	as a compliance of a compliance of a compliance of a complication of a complication of	of term work d be spent b eurship acti	associated wi by students on vity	Completion of relate
4. 5. Detailed Syl Sr. No. 1. 2.	Internship report sh Total Duration: 24 activities and requir labus: Activity Week 1, 2 and topic, Planning of Week 4 &	Contact Hours an rements. Internship / In-ho 3: Guide allotmer	as a compliance of ad 24 Hours shoul ouse / Entreprene nt, Application of w-1 conduction Mini-project/	of term work d be spent b eurship acti	x associated wi by students on vity , finalization o	Duration, H       of       6
4. 5. Detailed Syl Sr. No. 1.	Internship report sh Total Duration: 24 activities and requir labus: Activity Week 1, 2 and topic, Planning of Week 4 & implementation	Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revie 5: Internship/	as a compliance of ad 24 Hours shoul ouse / Entreprene nt, Application of w-1 conduction Mini-project/ ts	of term work d be spent b eurship acti	x associated wi by students on vity , finalization o	Duration, H       of       6
4. 5. Detailed Syl Sr. No. 1. 2.	Internship report sh Total Duration: 24 activities and requin labus: Activity Week 1, 2 and topic, Planning of Week 4 & implementation Week 6, 7 & 8 :	Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revier 5: Internship/ as per requirement	as a compliance of ad 24 Hours shoul ouse / Entreprene nt, Application of w-1 conduction Mini-project/ ts	of term work d be spent b eurship acti internships Entreprenet	x associated wi by students on vity , finalization of urship activit	Duration, H       of     6
4. 5. Detailed Syl Sr. No. 1. 2. 3.	Internship report sh Total Duration: 24 activities and requir <b>labus:</b> Activity Week 1, 2 and topic, Planning of Week 4 & implementation Week 6, 7 & 8 : Week 9 & 10: In	a contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revier 5: Internship/ as per requirement Review-2 of Action tteraction of Guide Internship Report	as a compliance of ad 24 Hours shoul ouse / Entreprene nt, Application of w-1 conduction Mini-project/ ts ivities es with Industry, F	of term work d be spent b eurship acti i internships Entrepreneu	tation	Duration of relate       Duration, H       of       6       4

"Knowledge Brings Freedom"

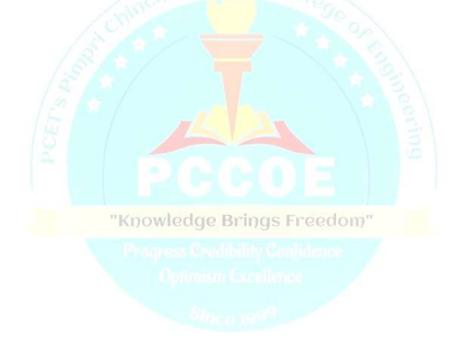
Progress Credibility Conjidence

Optimism Excellence

Program:	M. Tech. Mecha	anical (Design En	gineering)		Semester :	III
Course :	MOOCs				Code :	MMD3981
Т	eaching Scheme/v	veek		Evalu	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100

**Guidelines :** 

- 1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related trainings.
- 2. Weekly assignments need to be completed regularly as per requirement of course, which will be considered for internal assessment of course.
- 3. The certification of course or training is mandatory.
- 4. Oral presentation of course/ training will be taken at the end of semester
- 5. Total duration: 24 contact hours and 24 hours should be spent by students on completion of related activities and requirements.



Program:	M. Tech. (Desig	gn Engineering)			Semester : III	
Course :	Entrepreneurship				Code: MMD398	81
	Teaching Scheme/w	eek		Evaluat	ion Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100
Pre-requisit	te:		•	•	·	
	y Engineering Graduat	e with Innovation a	and Design thinki	ng knowledge		
Objectives:						
	acquaint with Entrepre					
	apply entrepreneurship	0 0				
	imbibe Entrepreneuria	l capabilities in eng	gineering students			
<b>Outcomes:</b>						
A.C. 1 .						
	ig the course, the stude			1		
1. Mo	tivate students to think	about Entreprenet	urship alternative	• •		
<ol> <li>Mo</li> <li>Reg</li> </ol>	tivate students to think gistering students for S	about Entreprenet	urship alternative	• •		
1. Mo 2. Reg Detailed Sy	tivate students to think gistering students for S llabus:	about Entreprenet	urship alternative	• •		Desertion II
1. Mo 2. Reg Detailed Sy	tivate students to think gistering students for S	about Entreprenet	urship alternative	• •		Duration, H
1. Mo 2. Reg Detailed Sy Unit	tivate students to think gistering students for S llabus:	about Entreprenet tartup / Udyam reg	urship alternative gistration of MSM	• •		Duration, H 04
1. Mo 2. Reg Detailed Sy Unit 1. 1	tivate students to think gistering students for S llabus: Description	about Entreprenet tartup / Udyam reg	urship alternative gistration of MSM its importance	E		
1. Mo           2. Reg           Detailed Sy           Unit           1.           2.           3	tivate students to think gistering students for S llabus: Description Introduction to Entre	about Entrepreneu tartup / Udyam reg preneurship and i ion. Case Studies	urship alternative gistration of MSM its importance	E		04
1. Mo       2. Reg       Detailed Sy       Unit       1.       2.       3.       1	tivate students to think gistering students for S llabus: Description Introduction to Entre Achievement Motivat	about Entrepreneu tartup / Udyam reg preneurship and i ion. Case Studies h, Market Survey	urship alternative gistration of MSM its importance of Indian Entrep	E		04 04
1. Mo         2. Reg         Detailed Sy         Unit         1.         2.         3.         1.         4.         5.	tivate students to think gistering students for S llabus: Description Introduction to Entre Achievement Motivat Product Identification	about Entrepreneu tartup / Udyam reg preneurship and i ion. Case Studies h, Market Survey	urship alternative gistration of MSM its importance of Indian Entrep	E		04 04 04
1. Mo         2. Reg         Detailed Sy         Unit         1.         2.         3.         1.         4.         5.         1.	tivate students to think gistering students for S llabus: Description Introduction to Entre Achievement Motivat Product Identification Whom to contact for	about Entrepreneu tartup / Udyam reg preneurship and i ion. Case Studies h, Market Survey what? Financial N	urship alternative gistration of MSM its importance of Indian Entrep	E		04 04 04 04

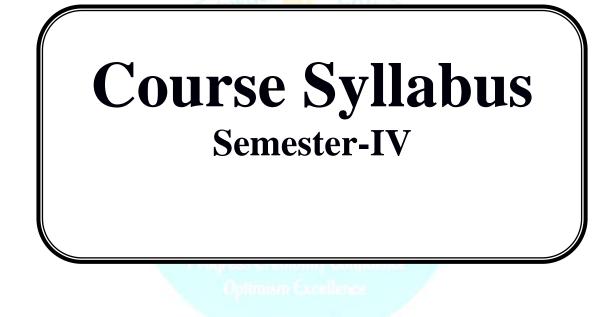
1. Entrepreneurial Development by Vasant Desai, Himalaya publication

2. Entrepreneurship Development and Small Business Enterprise. Poornima M. Charantimath. Pearson Education India, 2005

3. Dynamics of entrepreneurial development and management : Entrepreneurship, project management, finances, programmes, and problems. by Vasant Desai.

4. Course Material by EDII, Ahmedabad

**Experiment List:** Project Report preparation for an Enterprise and Udyam Registration.



Program: Course :	M. Tech (Mecha	anical) – Design I	Engineering		Semester :	IV
	Dissertation Pha	ase – II [Compan	y/ In-house proje	ct] (	Code:	MMD4704
	<b>Teaching Scheme/we</b>	ek		Evalua	tion Scheme	
Practical	Hours	Credit	IE2	PR	OR	Total
24	24	12	200		200	400
Pre-requisit						
	Basic knowledge of M	Mechanism and M	Machine Design, 1	Mechanical s	ystem design, E	Basics of Analysi
	software, MATLAB pi	ogramming				
Objectives:	· •	0 0				
1.	To understand the Prod	luct Development	Process including	budgeting.		
2.	To plan for various act				rk towards produ	uct development.
3.	To build, design and in					
4.	To inculcate research c	ulture in students	for their technical	growth.		
Outcomes:						
After learning	g the course the student					
1.	Understand, plan and e					les.
	To integrate theory and			area of study		
	To demonstrate research					
	Prepare good quality to					
	Publish good quality p	aper in reputed joi	urnal and present t	heir work in i	eputed conferen	ces
Guidelines :	о . щ :				.1	• • • •
1.	Semester III major pro	-				
2.	Students need to imple	ment the project u	ising <mark>su</mark> itable com	outational too	ls and /or experi-	mental setups.
3.	Final Project Report in	1 1' 11				-
	j	ncluding all proce	ess of project shou	ld be submit	ted as a complia	ance of term wor
	associated with subject				ted as a complia	ance of term wor
	•	and permission to	o appear for exami	nation.	3	
	associated with subject Total 2 Paper publica	t and permission to	o appear for examination of a strand of the	nation. ome of Proje	ct Stage-I and I	II ( Conference of
	associated with subject Total 2 Paper publicat reputed journal) and 1	t and permission to	o appear for examination of a strand of the	nation. ome of Proje	ct Stage-I and I	II ( Conference of
4.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II	and permission to tions are expected 00% of planned p	o appear for examination of a provident of a series of	nation. ome of Proje ld be comple	ct Stage-I and I ted for submissi	II ( Conference of on of Dissertatio
4.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 h	and permission to tions are expected 00% of planned p nours are contact	o appear for examination of a project work shout the project work shout the project work shout the project with guides the pro	nation. ome of Proje ld be comple and for revio	ct Stage-I and I ted for submissi	II ( Conference of on of Dissertatio
4. 5.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 H spend by students to sa	and permission to tions are expected 00% of planned p nours are contact	o appear for examination of a project work shout the project work shout the project work shout the project with guides the pro	nation. ome of Proje ld be comple and for revio	ct Stage-I and I ted for submissi	II ( Conference of on of Dissertatio
4. 5. <b>Plan of Acti</b> v	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 h spend by students to sa vities	and permission to tions are expected 00% of planned p nours are contact	o appear for examination of a project work shout the project work shout the project work shout the project with guides the pro	nation. ome of Proje ld be comple and for revio	ct Stage-I and I ted for submissi	II ( Conference of on of Dissertation are expected to b
4. 5. <u>Plan of Activ</u> Sr. No.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 H spend by students to sa	and permission to tions are expected 00% of planned p nours are contact	o appear for examination of a project work shout the project work shout the project work shout the project with guides the pro	nation. ome of Proje ld be comple and for revio	ct Stage-I and I ted for submissi	II ( Conference of on of Dissertatio
4. 5. <b>Plan of Acti</b>	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 h spend by students to sa vities Activity	and permission to tions are expected 00% of planned p nours are contact ttisfy all project re	o appear for examination of a project work shout the project work shout the project work shout the project with guides the pro	nation. ome of Proje d be comple and for revie plementation	ct Stage-I and I ted for submissi ews; 144 hours a s.	II ( Conference of on of Dissertation are expected to b
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 h spend by students to sa vities Activity Week 1 & 2	and permission to tions are expected 00% of planned p nours are contact tisfy all project re : 60 % Work shou	o appear for examination of a several of the severa	nation. ome of Proje d be comple and for revie plementation by fabrication	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup	II ( Conference of on of Dissertation are expected to b Duration, H 24
4. 5. <u>Plan of Activ</u> Sr. No.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 &	and permission to tions are expected 00% of planned p nours are contact tisfy all project re : 60 % Work shou	o appear for examination of a project work should be appeared by the project work should be appe	nation. ome of Proje d be comple and for revie plementation by fabrication	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup	II ( Conference of on of Dissertation are expected to be Duration, H
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 & results.	and permission to tions are expected 00% of planned p nours are contact in this fy all project re : 60 % Work shou 4: experimentation	o appear for examination of a several of the severa	nation. ome of Proje d be comple and for revie plementation by fabrication	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup	II ( Conference of on of Dissertation are expected to b Duration, H 24
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1. 2.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 &	and permission to tions are expected 00% of planned p nours are contact in this fy all project re : 60 % Work shou 4: experimentation	o appear for examination of a several of the severa	nation. ome of Proje d be comple and for revie plementation by fabrication	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup	II ( Conference of on of Dissertation are expected to b Duration, H 24 24
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co	and permission to tions are expected 00% of planned p nours are contact i tisfy all project re : 60 % Work shou 4: experimentation onduction.	o appear for examination of a several of the severa	nation. ome of Proje ld be comple and for revie plementation by fabrication generate and	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup I compile the	II ( Conference of on of Dissertation are expected to b Duration, H 24
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1. 2.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co Week 5 & 6	and permission to tions are expected 00% of planned p nours are contact i tisfy all project re : 60 % Work shou 4: experimentation onduction.	o appear for examination of a several control of the several control	nation. ome of Proje ld be comple and for revie plementation by fabrication generate and	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup I compile the	II ( Conference of on of Dissertation are expected to b Duration, H 24 24
4. 5. <u>Plan of Activ</u> <u>Sr. No.</u> 1. 2.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co Week 5 & 6 this week, 8	and permission to tions are expected 00% of planned p nours are contact in thisfy all project re 60 % Work shou 4: experimentation onduction. 6: Paper Publication 0% work should b	o appear for examination of a project work should be completed, the formation of the setup, on should be in project.	nation. ome of Proje ld be comple and for revie plementation by fabrication generate and	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup I compile the	II ( Conference of on of Dissertation are expected to b Duration, H 24 24
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4. 5. Plan of Activ Sr. No. 1. 2. 3. 4.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 f spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co Week 5 & 6 this week, 8 Week 7 & 8 Review -2 w	and permission to tions are expected 00% of planned p nours are contact in thisfy all project re : 60 % Work shou 4: experimentation onduction. 5: Paper Publication 0% work should b : Compliance of in vill be conducted	o appear for examination of a several of the severa	nation. ome of Projection Id be completed and for revie plementation by fabrication generate and roccess or con	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup I compile the apleted during	II ( Conference of on of Dissertation are expected to b Duration, H 24 24 24 24 24 24
4. 5. Plan of Activ Sr. No. 1. 2. 3.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 H spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co Week 5 & 6 this week, 8 Week 7 & 8 Review -2 w	and permission to tions are expected 00% of planned p nours are contact in tisfy all project re : 60 % Work shou 4: experimentation onduction. 5: Paper Publication 0% work should b : Compliance of p vill be conducted 0: Department Re	o appear for examination of a several of the severa of the several of the severa of the several of the several	nation. ome of Proje ld be comple and for revie plementation by fabrication generate and rocess or con	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup 1 compile the opleted during	II ( Conference of on of Dissertation are expected to b Duration, H 24 24 24 24
4. 5. Plan of Activ Sr. No. 1. 2. 3. 4. 5.	associated with subject Total 2 Paper publicat reputed journal) and 1 Phase-II Total Duration: 144 H spend by students to sa vities Activity Week 1 & 2 Week 3 & results. Review 1 co Week 5 & 6 this week, 8 Week 7 & 8 Review -2 w Week 9 & 1 of project ar	and permission to tions are expected 00% of planned p nours are contact atisfy all project re contact of the contact of the contaction. Compliance of the conducted of conducted of conducted of conducted of conducted for the conducted	b appear for examination of a project work should be completed, the formation of the setup, and the setup, and the setup, and the setup of the setup	nation. ome of Projection and for revie plementation by fabrication generate and rocess or con ducted to che project subn	ct Stage-I and I ted for submissi ews; 144 hours a s. the setup I compile the apleted during ck the quality ission.	II ( Conference of on of Dissertation are expected to be Duration, H 24 24 24 24 24 24 24 24 24
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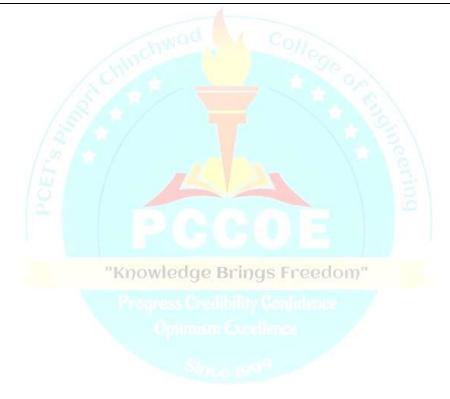
Program:	M. Tech. (Desig	n Engineering)		S	emester : IV	
Course :	MOOCs			C	ode : MMD498	32
	<b>Teaching Scheme/w</b>	reek		Evaluat	ion Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100

**Guidelines :** 

1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related training.

2. Week assignment needs to be regularly completed as per requirement of course, which will be considered for internal assessment of course.

- 3. The certification of course or training is mandatory.
- 4. Oral and Presentation of course/ training will be taken at the end of semester
- 5. Total Duration: 24 Contact Hours and 24 Hours should be spent by students on completion of related activities and requirements.



# Annexure-I Open Electives Syllabus

Progress Credibility Confidence Optimism Excellence

Store was

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program	n:	M. Tech. Mechanical	(Heat Power Engineering)	Semeste	er:I		
Course	:	Electronic Cooling (	Open Elective)	Code :	MMH1601	lA	
		Teaching Scl	heme		Eval	uation Sche	me
Lect	ure	Hours	Credit	IE1	IE2	ETE	Total
2		2	2	20		30	50
Pre-req		mics, Fluid Mechanics, I	Joot Transfor				
Object	-	inics, Fluid Mechanics, I					
	To est To sel To inc	ect a suitable cooling proceeding proceeding the capabilities in	erstanding of heat transfer in el ocesses for electronic compon- design and analysis of cooling for electronic components and	ents and sy g of electro	vstems.	es.	
2. 3. 4.	After I Under Analy Assign Design	stand Heat transfer proc ze thermal failure for ele n the best cooling metho n cooling system for any	students should be able to esses involved in electronics c ectronic components and defin d for each individual application electronic device and select E	e the solut on.		ach for any d	esign.
Detaile Unit		abus: scription			- 2		Duration, I
		- / -	Casling	-			
1.	Intro Conc Natu	duction Heat Transfer, M	nds and Thermal Management Multi-Dimensional Conduction onic Devices, Forced Convec	n, Transiei	nt Conduct	ion,	06
2.	Ther Heat Imm	Sinks, Heat Pipes in Ele	ds in Industry change materials, passive and ectronics Cooling, Thermoele and Two-phase), Cooling Tech	ctric Cooli	ng, Liquid		06
3.	Pack Com	<b>Exaging of Electronic Eq</b> ponents of Electronic Syling for Chassis and Circ	uipments ystems, Packaging of Electroni uit Boards, Chip/circuit mater				06
4.	Con Tem	trol Parameters Measu	rement and simulation uirement, CFD analysis for A	irflow & to	emperature		06
	To						24
Text B							
1. I	Dave S	S. Steinberg," Cooling 7	Techniques for Electronic Equ	upment ",	Second E	dition, John	Wiley & Sons
2. I 3. S		<b>1</b>	on to Heat Transfer ", Fourth E Lee, "Air cooling Technology				press, Londor
4. 1			ooling of Electronic Devices b	y Single-I	Phase Conv	vection", Joh	n Wiley& son
Refere							
	Belady	C., "Standardizing Heat	kaging of Electronic Equipment Sink Performance for Forced				
	Septem	lber, 1997.					
3. I	Biber (		ing, Wakefield, Massachusett	s, "Charac	terization	of the Perfor	rmance of Hea

0	m:   M. Tech. (Mecha	nical)- Heat Powe	r Engineering		Semester: I		
Course		gs (Open Elective			Code: MMH16	01B	
	Teaching Schen			Evalua	ation Scheme		
Lectu	re Hours	Credit	IE1	IE2	ETE	То	otal
2	2	2	20		30	5	0
Ba	<b>quisite:</b> sics of air conditioning sics of building construc	tion					
Objecti							
2. 3. 4.	To develop a multidisc To develop knowledg buildings in an environ To create awareness of	e and understandir mentally and cost-	ng of system solu effective way				onment i
Outcon							
After le	arning the course, the st	udents should be ab	ole to:				
1.		-					
2.				ildings to perf	form energy calc	culations, ev	valuate
	the relationship betwe						
3.			istif <mark>y energy</mark> -savi	ng measures in	n existing buildir	ng on the ba	asis of
	engineering and econ						
4.		e to apply the princ	ciples of energy m	anagement to	obtain buildings	s that can be	•
<b>D</b> / 1	certified				19.		
	d Syllabus:			<u></u>	12		D 4 <sup>1</sup>
Unit	Description					1	Duratior h
	XX71 / ' 1 '1 1'		ding rating syste				
	What is green buildi comparison of USGBC Conducting feasibility credit categories, under	ng, conventional LEED, IGBC, GR studies, reference	building practice IHA, EDGE and o standards, key do	s versus inte other green bu efinitions, syn	ilding rating sys ergies between	tems,	6
2.	comparison of USGBC Conducting feasibility	ng, conventional LEED, IGBC, GR studies, reference standing building f uiddings, oor water use, rainw reducing water consource reduction, red	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> vater harvesting, in sumption duce – recycle – r	s versus inter other green bu efinitions, syn atures, microco Freedom rrigation water	ilding rating sys ergies between climate features	tems, various	6
	comparison of USGBC Conducting feasibility credit categories, under <b>Resource Efficiency</b> Energy efficiency in bu Water efficiency – indo systems, strategies for Waste management – s	ng, conventional LEED, IGBC, GR studies, reference estanding building f hildings, oor water use, rainw reducing water cons ource reduction, re- ion waste managen air quality, ASHRA parameters affectir ategies to enhance	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> vater harvesting, in sumption duce – recycle – r ment plan &E 62.1 overview ag indoor environt daylight availabili	s versus interestion of the system of the sy	ilding rating sys ergies between ilimate features use, wastewate s for waste nts, ventilation r nagement plan	tems, various r	
3	comparison of USGBC Conducting feasibility credit categories, under <b>Resource Efficiency</b> Energy efficiency in bu Water efficiency – indo systems, strategies for f Waste management – s management, construct <b>Health and Wellness</b> Introduction to indoor a procedure method, key Daylight and views, str Overview of WELL sta health <b>Site features</b> Erosion and sedimentat microclimate, heat islan	ng, conventional LEED, IGBC, GR studies, reference estanding building f hildings, oor water use, rainw reducing water cons ource reduction, rea ion waste managen air quality, ASHRA parameters affectin ategies to enhance indard for buildings	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> vater harvesting, in sumption duce – recycle – r ment plan AE 62.1 overview ing indoor environing daylight availabilities, impact of VOCs efficient landscapi ighting pollution,	s versus inter other green bu efinitions, syn atures, microor Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou	ilding rating sys ergies between limate features ruse, wastewate s for waste nts, ventilation r nagement plan is chemicals on l	tems, various r	6
3	comparison of USGBC Conducting feasibility credit categories, under <b>Resource Efficiency</b> Energy efficiency in bu Water efficiency – indo systems, strategies for 1 Waste management – s management, construct <b>Health and Wellness</b> Introduction to indoor a procedure method, key Daylight and views, str Overview of WELL sta health <b>Site features</b> Erosion and sedimentat	ng, conventional LEED, IGBC, GR studies, reference estanding building f hildings, oor water use, rainw reducing water cons ource reduction, rea ion waste managen air quality, ASHRA parameters affectin ategies to enhance and ard for buildings	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> vater harvesting, in sumption duce – recycle – r ment plan AE 62.1 overview ing indoor environing daylight availabilities, impact of VOCs efficient landscapi ighting pollution,	s versus inter other green bu efinitions, syn atures, microor Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou	ilding rating sys ergies between limate features ruse, wastewate s for waste nts, ventilation r nagement plan is chemicals on l	tems, various r	6
3 4 5	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in bu Water efficiency – indo systems, strategies for to Waste management – s management, construct Health and Wellness Introduction to indoor a procedure method, key Daylight and views, str Overview of WELL sta health Site features Erosion and sedimentate microclimate, heat islan transportation manager Materials and resource Low-embodied energy material categories of L	ng, conventional LEED, IGBC, GR studies, reference standing building f iddings, reference at a construction of the standard oor water use, rainw reducing water construction, rea- ource reduction, rea- ion waste managen air quality, ASHRA parameters affecting at egies to enhance and ard for buildings tion control, water of an effect, exterior li- nent strategies and res- materials, environn GBC, LEED & GR CA,	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> vater harvesting, in sumption duce – recycle – r ment plan E 62.1 overview ing indoor environ daylight availabilities, impact of VOCs efficient landscapi ighting pollution, planning mental product dec IHA, life cycle ar	s versus interestions, syn atures, microco Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou ing and irrigati Location and to clarations (EPI	ilding rating systergies between ergies between elimate features ruse, wastewate s for waste nts, ventilation r nagement plan is chemicals on l ion practices, transportation, Ds), overview of	tems, various r r rate human	6
2. 3 4 5 6	comparison of USGBC Conducting feasibility credit categories, under <b>Resource Efficiency</b> Energy efficiency in bu Water efficiency – indo systems, strategies for r Waste management – s management, construct <b>Health and Wellness</b> Introduction to indoor a procedure method, key Daylight and views, str Overview of WELL sta health <b>Site features</b> Erosion and sedimentat microclimate, heat islan transportation manager <b>Materials and resource</b> Low-embodied energy material categories of I	ng, conventional LEED, IGBC, GR studies, reference standing building f iddings, oor water use, rainw reducing water con- ource reduction, red ion waste managen air quality, ASHRA parameters affectin ategies to enhance indard for buildings tion control, water end effect, exterior linent strategies and ces materials, environn GBC, LEED & GR CA, and incentive pro- for green building	building practice IHA, EDGE and o standards, key do forms, site level fe <b>Ige Brings</b> water harvesting, in sumption duce – recycle – r ment plan AE 62.1 overview ing indoor environing daylight availabilities, impact of VOCs efficient landscapi ighting pollution, planning mental product dea EIHA, life cycle ar <b>grams</b> rating programs,	s versus inter other green bur efinitions, syn atures, microor <b>Freedom</b> rrigation water euse, strategie and requirement, IAQ ma ity, s and hazardou ing and irrigati Location and the clarations (EPI nalysis and its	ilding rating sys ergies between limate features ruse, wastewate s for waste nts, ventilation r nagement plan is chemicals on l ton practices, transportation, Ds), overview of application, ove	tems, various r r rate human f rview	6 4 2

### **Text Books:**

- 1.
- Shahane, V. S, "Planning and Designing Building", Poona, Allies Book Stall, 2004. Michael Bauer, Peter Mösle and Michael Schwarz "Green Building Guidebook for Sustainable 2. Architecture" Springer, 2010.
- Tom Woolley, Sam Kimmins, Paul Harrison and Rob Harrison "Green Building Handbook" Volume I, Spon 3. Press, 2001.

### **Reference Books:**

- Mili Majumdar, "Energy-efficient buildings in India" Tata Energy Research Institute, 2002. 1.
- TERI "Sustainable Building Design Manual- Volume I & II" Tata Energy Research Institute, 2009 2.
- 3. Reference manuals of green building rating programs (LEED, WELL, IGBC, GRIHA)
- 4. ASHRAE Standard 62.1, Standard 55, Standard 90.1, and other standards referred by green building programs
- 5. EDGE App user manual
- National Building Code of India 2016 6.
- 7. ECBC 2017



Program:	M. Tech. Mechanic	al (Heat Power B	Engineering)		Seme	ster : I	
Course :	System Modellin	ng and Simulation	n (Open Elective)		Code	: MMH1601C	
	<b>Teaching Scheme</b>				Evalua	ation Scheme	
Lecture	Hours	Credit	IE1	II	22	ЕТЕ	Total
2	2	2	20	-	-	30	50
Pre-requisite:							
	nts able to model any p nts able to simulate any						
<ol> <li>Develo</li> <li>Develo</li> <li>Apply</li> </ol>	he course, the students op mathematical model op Bond Graph model transfer function and S ate the system using su	for practical prob for system State space model	lem techniques	ters by	optimi	zation	
Detailed Syllal			dun				
	scription	china	~	$21_{\odot}$			Duration
Ma	oduction to Modelling, I thematical modelling, I	Basic building blo	cks Mechanical, E	lectrica	l, Ther	mal systems.	6
	nd Graph Modelling of tiports Causality, App tem						6
	namic Response and Sy ck diagram/Signal flow				uency	response	6
	ulation and Simulation ameter Estimation, Sys		and Optimization				6
То	tal		100				24
<b>Reference Boo</b> Brown, Forbes	<b>ks:</b> T. Engineering System		ge Brings F York, NY: CRC, 2				

Onimism Excellence

Progra	am: M. Tech	n Mechanic	al (Heat Power E	ngineering)		Semester: II		
Cours	e: Waste M	Managemer	it for Smart Citie	s (Open Elec	tive)	Course: MMH2	2602A	
	Teach	ing Scheme	•		E	valuation Scheme		
Lectu	re Hou	irs	Credit	IE1	IE2	ЕТЕ	Т	otal
2	2		2	20		30		50
Course	Objective:							
1. 2. 3. 4. 5. C <b>ourse</b> 1. 2.	To provides an To make aware To equip with to To provide an i To be able to d <b>Outcomes:</b> The learners w Identify and ev municipal wast Evaluate and an effects.	e about regu the methods in-depth und lesign the la vill be valuate the s te treatment nalysis the n	lations in the area of environment ri derstanding of Phy nd-fields for the sr ources; compositio isk and methods o	municipal wa sk assessment siochemical a nart cities. on; generation f handling the	ste manageme of waste. nd biological rates, method hazardous an	treatment of Munic s of separation and d radioactive waste	ipal waste collectior	n methods of
3.	Evaluate the Pl	hysiochemio	cal and biological	waste for its tr	reatment and d	lisposal		
4.		d field for so	olid and hazardous	wastes collec	tion and remo	oval.		
Detaile	d Syllabus							
Unit	Description						Du	ration, h
1.	and transport handling rules usage and batt	Sources; co of waste, to s for solid wastes	omposition, genera creatment and disp vaste, hazardous v	posal options vaste, biomed	. Municipal v	ste, separation, tran vaste management y ash, recycled pla	and	6
2.	Fundamentals Fundamentals	Characteriz sources, me	we Waste Managen ation of waste, fat easures and health clear power plants;	e and transpor effects; nucle	ear power plan	s, health effects, hts and fuel produc	tion;	6
3.	Physicochemic MSW (combu processes for	cal Treatme ustion, stab hazardous	ilization and solid	lification of our extraction	hazardous wa	treatment processe (stes); physicochen g, chemical oxidat	nical	6
4.	Biological Tr decomposition metabolism; o	eatment of 1 of solid v xidative and gn Landfill	waste; principles l reductive process design for solid	dous Waste of biodegrada ses; slurry pha	tion of toxic se bioreactor.	bioreactors; anaer waste; inhibition; eachate collection	, co-	6
	Total							24
	<b>References:</b> John Pichtel W							

Course		nanical (Heat Power			Semester : II	
Course :		gement for Electric V	ehicle (Open		Code : MMH2602B	
	Teaching Schen	ne		Eva	luation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
	ite: Basics of Electrical	Engineering,				
2. To 3. To 4. To 5. To 6. To <b>Dutcomes:</b> After learni 1. the 2. the 3. Th 4. the 5. the	o understand the various o understand the requirer o make the learners conv o make the learners conv o make the learners conv o make the learners awar	nents of battery managersant with Equivaler ersant with SOC estim ersant with Battery Pa e of thermal issues of select battery for EV estimate available endo simulate charge disc estimate SOC and SC understand various m	gement system nt Circuit Cell nation ick Balancing a Lithium ion ba application ar ergy and powe harge characte DH of battery iethods of batter	Modeling of and Power Eattery and the attery and the d design bat r of battery p ristics of a bat ery pack bala	Battery stimation rmal management syste ery pack ack attery using equivalent ncing	em circuit mode
	ck. y <b>llabus</b>				se cooning strategy for	Duratio
e III e	Description					h
1.	Introduction to batter Battery terminology a Cells components, prin BMS design requirer Primary functions of H estimation of cell SOC and battery pack	nd performance paran mary functions and co nents BMS, sensing voltage,	neters, Types of Emponents of E current and te	BMS mperature of		6
					energy and power of ce.	11
2.	Equivalent Circuit C Modeling OCV and S Model parameter valu of OCV, modeling hys	OC, Modeling voltage es: OCV, Columbic E steresis, using the ECI	fficiency, total	Warburg imp	edance, Estimation of nperature dependence	5
	Equivalent Circuit C Modeling OCV and Se Model parameter valu of OCV, modeling hys discharge characteristi State-of-Charge (SO Different approaches t linear Kalman filter, e Reasons of battery pack	OC, Modeling voltage es: OCV, Columbic E steresis, using the ECI ics C) Estimation and B to estimating battery c extended Kalman filte ck unbalancing, criter c, Passive balancing m acitor-based circuits,	fficiency, total M to simulate of attery Pack B cell SOC, Kaln r ia for specifyin ethods for batt	Warburg imp capacity, ter constant volta alancing man-filter me ng a balancir rery packs, A	edance, Estimation of nperature dependence	5 n: ls 7
2. 3. 4.	Equivalent Circuit C Modeling OCV and Se Model parameter valu of OCV, modeling hys discharge characteristi State-of-Charge (SO Different approaches t linear Kalman filter, e Reasons of battery pack for battery packs: cap battery power using a Battery Thermal Ma	OC, Modeling voltage es: OCV, Columbic E steresis, using the ECI ics <b>C) Estimation and B</b> to estimating battery c extended Kalman filte ck unbalancing, criter t, Passive balancing m acitor-based circuits, simplified cell model <b>nagement</b> e battery , Thermal iss s and Thermal modelin ling, liquid cooling, P	fficiency, total M to simulate of attery Pack B cell SOC, Kaln r ia for specifyin ethods for batt transformer-batt sues of Lithiun ng of LIB, Coc	Warburg imp capacity, ter constant volta alancing nan-filter me ng a balancir rery packs, A ased circuits, n Ion Battery pling strategio	edance, Estimation of nperature dependence age/ power charge/ thod of SOC estimation ag set point and when t ctive balancing method Estimation of availabl	5 n: o s e 7

 Gregory L. Plett, Battery Management Systems Volume II, Equivalent-Circuit Methods, Artech House, Lond
 Gianfranco Pistoia, Boryann Liaw (eds.), Behaviour of Lithium-Ion Batteries in Electric Vehicles\_ Battery Health, Performance, Safety, and Cost, Springer International Publication

4. Reiner\_Korthauer, Li-I Batteries Basics and Applications, Springer International Publication

Program:		anical (Heat Pow		)	Semester : II	
Course:		nergy Sources (C	Dpen Elective)		Code: MMH2602C	
	Teaching Scheme	2		Eva	aluation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
<u>Pre-requisite:</u> Objectives:	Thermodynamics;	Fluid Mechanics;	Heat Transfer; H	Elements of E	lectrical Engineering; E	conomics
<ol> <li>Demo utiliza</li> <li>Expos</li> <li>Enabl</li> <li>Devel deploy</li> </ol> Course Outco <ol> <li>To be energy</li> </ol>	ation se them to conceptu e them to independence op a research insight yment <b>mes:</b> e able to determine y systems	of analysis solar alize and design re ently analyze, imp nt about renewable the fundamental	enewable energy lement and asse e technologies so performance of	appliances a s the real-life as to motiva characteristic		ir enhanced
<ol> <li>To be therm</li> <li>To be</li> </ol>	al energy conversio able to determine t	d the fundamentation systems	als of energy co	onversion fro	m biomass, geotherma hnologies	ıl, tidal and ocea
Detailed Sylla						
	escription ar energy					Duration, h
inst Sol esti Sol Flat per: Sol	alled capacity ar- Earth Geomet mation, instruments <b>ar thermal collecto</b> t plate collectors formance. Solar con	ry_for assessme s for measurement ors – General deso – Heat transfer acentrators – Aspe vstems– Working,	nt of available cription and char processes – Sh ects of Design, a Constructional	solar radia acteristics: ort term and nd performar	scenario of worldwide tion,_Solar radiation d long-term collector ace evaluation. formance Assessment	6
2. Win reso Win des		ples of wind energ ntial measuremen gn – <i>Aerodynamic</i> eeling and banking	gy conversion – 5 t, wind electric g es and performan g concepts.	generator com <i>ice</i> , vertical v	s. Horizontal axis	6
3. End Sou ferr con Pro Bio cha Bio	ergy from biomass irces of biomass – I mentation – Pyrolys iversion, perties of biomass ogas plants – Types racteristics of bioga	Different species, of is, gasification an of plants – Designation	Conversion of bi d combustion – and operation –	omass into fu Aerobic and a - Properties an	els – Energy through maerobic bio-	5
4 Gee Geo eco Ava Wa	othermal, Tidal a othermal energy: ho nomics. Environme ailability, system de	ot springs and stea ental impacts, Eco evelopment and lin –Scope and econo	m ejection site se nomic and social mitations, omics, Introduct	l consideratio	ns, red energy systems.	7
	otal			*		24

### Text Books

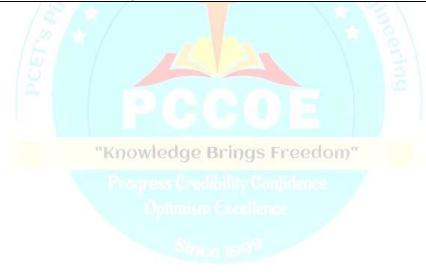
- 1. S.P. Sukhatme, Solar Energy Principles of thermal collection and storage, II edition, Tata McGraw Hill, New Delhi, 1996.
- 2. Garg H.P., Prakash J., Solar energy Fundamentals and Applications, Tata Mc Graw Hill Publishing Company, New-Delhi, Latest Edition
- 3. V.V. N. Kishore, Editor, Renewable Energy Engineering and Technology, A knowledge Compendium, The Energy and Resources Institute, New Delhi, 2008

### **Reference Books:**

- 1. J.A.Duffie and W.A.Beckman, Solar engineering of Thermal processes, II edition,
- 2. John Wiley, New York, 1991.
- 3. D.Y.Goswami, F.Kreith and J.F.Kreider, Principles of Solar Engineering, Taylor and
- **4.** Francis, Philadelphia, 2000.
- 5. D.D.Hall and R.P.Grover, Biomass Regenerable Energy, John Wiley, New York, 1987.
- 6. Mukund R Patel, Wind and Solar Power Systems, CRC Press, 1999.
- 7. J F Manwell, J.G.McGowan, A.L.Rogers, Wind Energy Explained: Theory, Design and Application, John Wiley and Sons, May 2002.
- 8. R D Begamudre, Energy Conversion Systems, New Age International (P) Ltd., Publishers, New Delhi ,2000.
- **9.** Bureau of Energy Efficiency Volume 1

### List of Assignments

- 1. Visit to a biogas / Bio-engine plant and its report (Energy Capacity assessment).
- 2. Visit to photovoltaic plant for agricultural / Village / Stand-alone applications.
- 3. Economic Analysis of a Renewable Energy system.
- 4. Visit to a Hybrid System & it's assessment system.



		TC (VLSI and Em	*		Semester:	Ι	
Course		Electronics and its	Applications (O		Code:	MET16	01A
	Teaching Scher	ne		Evaluat	tion Scheme	1	
Lectu	ire Hours	Credit	IE1	IE2	ETE		Total
2	2	2	20		30		50
	quisite: Knowledge of el	ectronics & electric	al, instrumentatio	on, control system	s, and IC engir	ne operatio	on, etc.
<b>Objecti</b> 1. 2. 3.	To learn and understan To learn and understan To learn and understan To learn and understan	d principles and app	plications of sens	ors and actuators i			s systems.
Outcon		d various control sy	stems in automo	live			
After le 1. 2.	earning the course, the str Acquire an overview automotive industry. Use and apply availab automotive system des	of automotive co le automotive senso ign.	omponents, subs	in various electro			-
3.	Apply knowledge of m	odern technologies	in automotive de	sign.			
Detaile	d Syllabus:	(by	NOG V	Coll		I	
Unit	Description						Duration
1.	Automotive Systems with emphasis on incr						
	subsystems and compo	onents, Body, Chass	is, and Powertrai	n Electronics			6
2.		nents, Body, Chass rs: Basic sensor ar sensors, Fuel meter	is, and Powertrai rrangement, Type ing/ vehicle spec	n Electronics es of sensors sucl ed sensors, Flow	h as oxygen s sensor, Tempe	ensors, erature,	6
2.	subsystems and compo Sensors and Actuato Crank angle position EGO, Air mass flow se Engine Control System control system, Electro Need of maps, Procedu	onents, Body, Chass rs: Basic sensor ar sensors, Fuel meter ensors, Throttle posi em: Algorithms for ponic ignition, EGR to ure to generate m	is, and Powertrai rrangement, Type ing/ vehicle spec ition sensor, Sole r engine control for exhaust emiss naps, Engine ca	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mo including open 1 sion control. Look libration, Torque	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam	ensors, erature, etc., ed loop 1 maps,	
	subsystems and compo Sensors and Actuato Crank angle position a EGO, Air mass flow se Engine Control Syste control system, Electro Need of maps, Procedu testing Active and passive sa entry, Immobilizers e	onents, Body, Chass rs: Basic sensor ar sensors, Fuel meter ensors, Throttle posi- em: Algorithms for onic ignition, EGR i ure to generate m <u>Knowle</u> fety systems: Body etc., Electronic inst	is, and Powertrai	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mo including open 1 sion control. Look libration, Torque IS Freedom uding lighting cor and dashboard	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam munor, Remote f electronics, A	ensors, erature, etc., ed loop 1 maps, oometer keyless	6
3.	subsystems and compo Sensors and Actuato Crank angle position a EGO, Air mass flow se Engine Control Syste control system, Electro Need of maps, Procedu testing Active and passive sa	onents, Body, Chass rs: Basic sensor ar sensors, Fuel meter ensors, Throttle posi- em: Algorithms for onic ignition, EGR i ure to generate m <u>Knowle</u> fety systems: Body etc., Electronic inst	is, and Powertrai	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mo including open 1 sion control. Look libration, Torque IS Freedom uding lighting cor and dashboard	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam munor, Remote f electronics, A	ensors, erature, etc., ed loop 1 maps, oometer keyless	6
3.	subsystems and composition Sensors and Actuato Crank angle position EGO, Air mass flow se Engine Control Syste control system, Electro Need of maps, Procedu testing Active and passive sa entry, Immobilizers en braking system, Electro	onents, Body, Chass ors: Basic sensor and sensors, Fuel meter ensors, Throttle posi- em: Algorithms for onic ignition, EGR is ure to generate m onic stability program Understanding Auto in Publications.	is, and Powertrai rrangement, Type ing/ vehicle spec ition sensor, Sole r engine control for exhaust emiss haps, Engine ca edge Brind y electronics incl trument clusters im, Air bags, Cor Total	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mo including open 1 sion control. Look libration, Torque <b>IS Freedom</b> uding lighting cor and dashboard nputer vision base	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam htrol, Remote f electronics, A ed ADAS	ensors, erature, etc., ed loop l maps, oometer keyless ntilock	6 6 6 24
3. 4. Text Bo 1. 2.	subsystems and compo Sensors and Actuato Crank angle position = EGO, Air mass flow se Engine Control Syste control system, Electro Need of maps, Procedu testing Active and passive sa entry, Immobilizers en braking system, Electro ooks: William B. Ribbens, "T Butterworth-Heineman	onents, Body, Chass ors: Basic sensor and sensors, Fuel meter ensors, Throttle posi- em: Algorithms for onic ignition, EGR is ure to generate m onic stability program Understanding Auto in Publications.	is, and Powertrai rrangement, Type ing/ vehicle spec ition sensor, Sole r engine control for exhaust emiss haps, Engine ca edge Brind y electronics incl trument clusters im, Air bags, Cor Total	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mo including open 1 sion control. Look libration, Torque <b>IS Freedom</b> uding lighting cor and dashboard nputer vision base	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam htrol, Remote f electronics, A ed ADAS	ensors, erature, etc., ed loop l maps, oometer keyless ntilock	6 6 6 24
3. 4. Text Bo 1. 2. Referen	subsystems and compo Sensors and Actuato Crank angle position = EGO, Air mass flow se Engine Control Syste control system, Electro Need of maps, Procedu testing Active and passive sa entry, Immobilizers end braking system, Electro ooks: William B. Ribbens, "T Butterworth-Heineman Ronald K. Jurgen, "Au	onents, Body, Chass ors: Basic sensor and sensors, Fuel meter ensors, Throttle posi em: Algorithms for onic ignition, EGR ure to generate m fety systems: Body etc., Electronic inst onic stability progra Understanding Auto an Publications. tomotive Electronic	is, and Powertrai rrangement, Type ing/ vehicle spec- ition sensor, Sole r engine control for exhaust emiss haps, Engine ca ca doe Brind y electronics incl trument clusters im, Air bags, Cor Total	n Electronics es of sensors sucl ed sensors, Flow noids, Stepper Mc including open 1 sion control. Look libration, Torque <b>IS Freedom</b> uding lighting cor and dashboard nputer vision base cs- An Engineerin c-Graw Hill.	h as oxygen s sensor, Tempe otors, Relays, e oop and close c-up tables and table, Dynam htrol, Remote f electronics, A ed ADAS	ensors, erature, etc., ed loop l maps, oometer keyless ntilock	6 6 6 24
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Course:		TC (VLSI and Embe	edded Systems	)	Semester: I	
		ives (Open Elective)			Code: MET	601B
	Teaching Scher	ne		Ev	aluation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisi						
	-	ectrical drives, Contro	ol Systems			
2. To	define electric drive, explain dynamics and	its parts, advantages a l modes of operation of	of electric drive	s.		
		notor power ratings ar nce of induction moto				
		induction motor, syn				
		ations electrical drive				
		ents should be able to and choice of electric				
		lifferent modes of ope		ic drives.		
		rive and control of dc				
		ce of induction motor			tions.	
		r, synchronous motor				
6. Si Detailed Sy		rical drive for specific		the muustry	181	
	escription				a C.	Duration
		ver Ratings: Thermal	Model of Mot	or for Heatin	g and Cooling, Classes	
Re Mo Ph Co Sej	ctifier Fed dc Drives, otor, Single Phase Ha ase Fully Controlled ntrolled Rectifier Co	Single Phase Fully Collification of Rectifier Control of	ontrolled Rectif er Control of c dc Separately	fier Control o lc Separately Excited Mo	tor Drives: Controlled f dc Separately Excited Excited Motor, Three otor, Three Phase Half	6
	otor, Supply Harmon	or Fed Form Fully C ics, Power Factor ar	Controlled Rect nd Ripple in N	ifier, Rectifie Iotor Curren	adrant Operation of dc er Control of dc Series t, Chopper Control of	
2. In Op Ro Sta	otor, Supply Harmon parately Excited dc M <b>luction Motor Dri</b> eration with Unbalan tor Impedances, Ana rting, Braking, Tran	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage ilysis of Induction M nsient Analysis. Spe	Controlled Rect ad Ripple in M l of Series Moto Performance o and Single Pl Motor Fed from ted Control T	ifier, Rectifie Aotor Curren or. f Three Pha nasing, Oper n Non-Sinus	er Control of dc Series	6
2. Ind Op Ro Sta Va 3. Vo Co Co	otor, Supply Harmon barately Excited dc M duction Motor Dri- eration with Unbalan tor Impedances, Ana rting, Braking, Tran- riable Voltage Freque ltage Source Inverter nverter Rating for V ntrol from a Current	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage alysis of Induction M nsient Analysis. Spe ncy Control from Vol (VSI) Control, Cyclo- 'SI and Cyclo-conve Source, Current Sour	Controlled Rect ad Ripple in M l of Series Mote Performance of and Single Pl Motor Fed from eed Control T ltage Sources. -converter Cont rter Induction rce (CSI) Control	ifier, Rectifie Aotor Curren or. f Three Pha hasing, Oper- n Non-Sinus echniques-St trol, Closed I Motor Drive ol, current re	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply,	6
Set2.IncOpRoStaVa3.VaCoCoCoCoCoCoStaPMStaMa	btor, Supply Harmon barately Excited dc M luction Motor Driver eration with Unbalant tor Impedances, Anarting, Braking, Tran- riable Voltage Freque ltage Source Inverter nverter Rating for V ntrol from a Current erter control, speed con nchronous Motor I tor. Self-controlled so rting Large Synchron IAC Motor Drives, Bar pper Motor Drives: otors, Torque Versus S	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage ilysis of Induction M nsient Analysis. Spe ncy Control from Vol (VSI) Control, Cyclo (VSI) Contr	Controlled Rect ad Ripple in M l of Series Mote Performance o and Single Pl Aotor Fed from ed Control T ltage Sources. -converter Control rter Induction rter Induction rce (CSI) Contri induction mote om fixed frequive employing unent Magnet ad ves. Permanent Magnet of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of	ifier, Rectifie Aotor Curren or. f Three Pha- nasing, Oper- n Non-Sinus echniques-St cechniques-St trol, Closed I Motor Drive rol, current re- ors. uency supply load commu c (PMAC) M agnet, Import Circuits for S	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply, ator Voltage Control, Loop Speed Control and es, Variable Frequency egulated voltage source 7-starting, synchronous tated thruster inverter, otor Drives, Sinusoidal ant Features of Stepper tepper Motor.	6
2. Ind Op Ro Sta Va 3. Vo Co Co inv 4. Sy Mo Sta Mo Ind	botor, Supply Harmon barately Excited dc M duction Motor Dri- eration with Unbalar tor Impedances, Ana rting, Braking, Tran- riable Voltage Freque ltage Source Inverter nverter Rating for V ntrol from a Current erter control, speed co- nchronous Motor I tor. Self-controlled so rting Large Synchron IAC Motor Drives, Bi- pper Motor Drives; So tors, Torque Versus S lustrial Drives: Text otal	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage alysis of Induction M maient Analysis. Spency Control from Vol (VSI) Control, Cyclo (VSI) Control (VSI)	Controlled Rect ad Ripple in M l of Series Mote Performance o and Single Pl Aotor Fed from ed Control T ltage Sources. -converter Control rter Induction rter Induction rce (CSI) Contri induction mote om fixed frequive employing unent Magnet ad ves. Permanent Magnet of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of the sector of	ifier, Rectifie Aotor Curren or. f Three Pha- nasing, Oper- n Non-Sinus echniques-St cechniques-St trol, Closed I Motor Drive rol, current re- ors. uency supply load commu c (PMAC) M agnet, Import Circuits for S	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply, ator Voltage Control, Loop Speed Control and es, Variable Frequency egulated voltage source 7-starting, synchronous tated thruster inverter, otor Drives, Sinusoidal ant Features of Stepper tepper Motor.	6
2. Ind Op Ro Sta Va 3. Vo Co Co inv 4. Sy Mo Sta PM Sta Ind Text Books	botor, Supply Harmon barately Excited dc M luction Motor Driver eration with Unbalant tor Impedances, Anarting, Braking, Trans- riable Voltage Freque Itage Source Inverter nverter Rating for V ntrol from a Current erter control, speed con- nection Motor I tor. Self-controlled synchron IAC Motor Drives, Bustrial Drives: Text otal	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage lysis of Induction M nsient Analysis. Spe ncy Control from Vol (VSI) Control, Cyclo (VSI) Contro	Controlled Rect ad Ripple in M l of Series Moto Performance o and Single Pl Aotor Fed from ted Control T ltage Sources. -converter Control rece (CSI) Contri- induction moto om fixed frequ- ive employing unent Magnet ad- ves. Permanent Ma- eristics, Drive of g Mills, Cranes	ifier, Rectifie Actor Curren or. f Three Pha- nasing, Oper- n Non-Sinus echniques-St trol, Closed I Motor Drive rol, current re- ors. Jency supply load commu- c (PMAC) M agnet, Import Circuits for S and Hoists, N	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply, ator Voltage Control, Loop Speed Control and es, Variable Frequency egulated voltage source 7-starting, synchronous tated thruster inverter, otor Drives, Sinusoidal ant Features of Stepper tepper Motor.	6 6 6
2. Ind Op Ro Sta Va 3. Vo Co Co inv 4. Sy mo Sta PM Sta Ma Ind Text Books 1. Go 2. N. 3. Ve	botor, Supply Harmon barately Excited dc M luction Motor Driver eration with Unbalant tor Impedances, Anarting, Braking, Trans- riable Voltage Freque Itage Source Inverter nverter Rating for V ntrol from a Current erter control, speed con- nchronous Motor I tor. Self-controlled synchron IAC Motor Drives, Bis spper Motor Drives; Bis stors, Torque Versus S lustrial Drives: Text otal pal K Dubey , Fundar Mohan T.M. udeland dam Suryavanshi, Ele	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage alysis of Induction M insient Analysis. Spe incy Control from Vol (VSI) Control, Cyclo (VSI) Control, Cyclo (SI and Cyclo-conve Source, Current Sour pontrol of single phase (Note: Operation from ynchronous motor dra ous Machines, Perma rushless dc Motor Dri Variable Reluctance, Stepping Rate Charact ile Mills, Steel Rolling nentals of the electric & W.P.Robbins , Pov ctrical Drives Concep	Controlled Rect ad Ripple in M l of Series Moto Performance of and Single Pl Aotor Fed from eed Control T ltage Sources. -converter Control rece (CSI) Contri- induction moto free (CSI) Contri- free (CSI) Contri-	ifier, Rectifie Aotor Curren or. f Three Pha- nasing, Oper- n Non-Sinus echniques-St bechniques-St trol, Closed I Motor Driver rol, current re- ors. Jency supply load commu- c (PMAC) M agnet, Import Circuits for S and Hoists, M a publication converter app	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply, ator Voltage Control, Loop Speed Control and es, Variable Frequency egulated voltage source 7-starting, synchronous tated thruster inverter, otor Drives, Sinusoidal ant Features of Stepper tepper Motor.	6 6 6 24
Se Se Op Ro Sta Va Sta Va Sta Co Co Co Co Co Co Sta PM Sta PM Sta PM Sta PM Sta PM Sta PM Sta A Sub Sta Sub Sub Sub Sub Sub Sub Sub Sub	boor, Supply Harmon barately Excited dc M luction Motor Driver eration with Unbalant tor Impedances, Anarting, Braking, Tran- riable Voltage Freque Itage Source Inverter nverter Rating for V ntrol from a Current erter control, speed con- nchronous Motor I tor. Self-controlled synthesis tors, Torque Versus S supper Motor Drives; Bar pal K Dubey , Fundar Mohan T.M. udeland dam Suryavanshi, Ele K. Bose, Advanced po	or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro ves: Analysis and I need Source Voltage alysis of Induction M msient Analysis. Spe ncy Control from Vol (VSI) Control, Cyclo (VSI) Contr	Controlled Rect ad Ripple in M l of Series Moto Performance o and Single Pl Aotor Fed from ed Control T ltage Sources. -converter Com- rter Induction rce (CSI) Contri- induction moto om fixed frequ- ive employing ment Magnet ad- ves. Permanent Ma- teristics, Drive of g Mills, Cranes al drives Naross ver Electronics ot and application C. Drives	ifier, Rectifie Aotor Curren or. f Three Pha- nasing, Oper- n Non-Sinus echniques-St bechniques-St trol, Closed I Motor Driver rol, current re- ors. Jency supply load commu- c (PMAC) M agnet, Import Circuits for S and Hoists, M a publication converter app	er Control of dc Series t, Chopper Control of ase Induction Motors, ation with Unbalanced soidal Voltage Supply, ator Voltage Control, coop Speed Control and es, Variable Frequency egulated voltage source 7-starting, synchronous attated thruster inverter, fotor Drives, Sinusoidal ant Features of Stepper tepper Motor. Machine Tools.	6 6 6 24

### **Reference Books:**

- 1. N.K De, P.K. Sen, Electric Drives PHI Learning 1 st Edition, 2009
- 2. Gobal K.Dubey, Fundamentals of Electrical Drives- Alpha Science Int. Ltd.,
- 3. Shepherd Hullay & Liag, Power Electronics & Motor Control -, Cambridge Univ. Press
- 4. Gopal K Dubey, Power Semiconductor controlled Drives, Prentice Hall pub.
- 5. R. Krishnan, Electric Motor Drives-Modelling, Analysis and Control, Pearson Education, 2003
- 6. P.C. Sen, Thyristorised DC Drives -, Krieger pub.
- 7. S.B.Dewan, G.R.Slemon & A.Stranghan; Power Semi conductor controlled Drives John-Willey pub.



Program:		TC (VLSI and E		ns)	Semester : I	
Course :		A and CPLD (Op	oen Elective)			ET1601C
	Teaching Schen	ne		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requi	site: Fundamentals of	digital electronics	, Knowledge of o	ne hardware de	escription language	
Objective	5:	-				
1. T	o make students famil	iar with programn	nable logic device	es and its archit	ectures.	
2. T	o understand the archi	tecture and feature	es of FPGA and C	CPLD.		
<b>3.</b> T	o make the students f	amiliar with the d	esign process and	how the desig	n is mapped to the ex	sisting hardwa
	FPGA and CPLD.		8 1	2	, TI	8
11						
Outcomes	•					
	• ing the course the stu	dents should be ab	le to:			
	o understand the dept					
	o design a system usir					
	e .	0	facing of differen	t external devic	es with FPGA/CPLD	
	o apply the complete					•
	11 0 1	design flow of FPG	GA and CPLD 10	or the specific a	application.	
Detailed S	•	1.00		20		
	Description		D : .: 1	N. 1 6	D 11 1 1	Duration
d	ntroduction: Introduce evices, PLA PAL, overview, specification	CPLD, FPGA: C	General Architect	ure, features	CPLD Architecture:	6
	1.50				12121	
X P ca	<b>PGA Architecture:</b> (ilinx Logic Cell Arra rogramming methods apacity, Utilization an Design Guidelines.	, Advanced featur	es of Xilinx 4000	) series Techno	ology Trends: Device	6
3. In st	nterfacing with FPG	Bluetooth Modul			g of external devices e, Different types of	
	Case Studies-FPGA/C		ex-6. Spartan-6. Z	Z-board Advan	ced features in FPGA	
b	ased on Case studies.					6
	ogical Design by FI			any combination	onal circuit by gates,	0
	oolean Algebra, Desi	gn of sequential ci	rcuits			
	Fotal			in the		24
2. R pi	.K.Chan& S. Mourad,	rew G. Schmidt, Ifmann, 2010.	"Embedded syst		array, Prentice Hall (P ith platform FPGAs:	
Reference	Books					
Reference		ld Programmable	Gata Arrow Tash	ology Kluwer	Academic Publication	ns 1004
2. R					inciples & Application	
3. J 4. S. E		Rose, Z. Vransic, F	Field Programmab	le Gate Array,		t 2008.
Test 6. Step	of Computers, Vol. 1 hen Brown Zvonko V Graw Hill – 2000	3, No. 2, pp. 42-5'	7, 1996.		-	

Program:		&TC (VLSI and E			Semester: II	
Course:	Drone Prog	ramming for Begi	inners (Open E	lective)	Code: MET2602A	
	Teaching Scheme			Evalua	tion Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisite:				1		
1.	Basic understanding of		-			
2.	Understanding of sen		•			
3.	Modelling Basics –M	ATLB & SIMULI	NK, Programmi	ng in python		
2. To ci	nderstand the physics b reate the mathematical m nplement model into Si	nodel of quadcopt			ics & Experimental da	ata
<ol> <li>Ident</li> <li>Estat</li> </ol>	he course, the students ify & select different ac olish the mathematical r gn Simulink model simu	ccessories of Drone nodel & the Physic	es behind Quade	opter drone	e.	
Detailed Syllal	ous:	125/				
Unit	Description				9	Duration (H)
1.	<b>Introduction to drom</b> to Drones programmi owning and operatin issues	ng and Developm	ent Tools, Curre	ent rules and reg	gulations governing	6
2.	<b>Drone accessories a</b> propulsion, Forces w Stable, unstable and drones.	orking on a Flig	nt, Principal ax	es and rotation	of aerial systems,	6
3.	<b>Drone control sys</b> Quadcopter with ac functionality block, functionality block	tuator & propell	ers functionalit	ty block, Sens	sing & estimation	6
4.	Modelling, Simulati flight control design, Applicable software f	3D visualization	, testing & Tur	ning the model		6
	Total		<b>.</b>			24
<ol> <li>Quad</li> <li>Mod</li> </ol>	ling your own drones, a leopter modelling and c el based design of a qua btics control, sensing, vi	ontrol with Matlab adcopter by Ryan C	/Simulink imple Gordon	ementation by M	Iuhammad Usman	
2. Dro	ks: otics and control- R.K.I nes (The ultimate guide lab and Simulink for en	), Ben Rupert, Cre	ateSpace Indepe		-	

3. Matlab and Simulink for engineers, Agam Kumar Tyagi, Oxford University Press, 2012

	M. Tech. E&TC (	VLSI and Embedded	l Systems)	Semes	ster: II	
Course :	Instrumentation a	and Measurements (C	<b>Open Elective</b> )	Code:	MET2602B	
	Teaching Scher		Î î	Evaluat	ion Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requi	site: Basics of sensors and	d Actuators, Basic of I	Electronics, Analo	og and Digita	l Systems	
bjective	s:				-	
To impart	knowledge on the followi	ing Topics -				
	Basic functional elements of					
2. F	Fundamentals of electrical	and electronic instrun	nents			
3. 0	Comparison between vario	us measurement techn	iques			
	arious storage and display					
	arious transducers and the	e data acquisition syst	ems			
Outcome						
	ning the course, the studer					
	Analyse different measurin			-		
2. I	Design and evaluate charac	cteristics of different ty	ypes of mechatron	nics/ electrica	l/ electronic sys	tem
3. U	Jnderstand different types	of wave/spectrum ana	lyzer.			
4 T	nterface various system co					
4. I		omponents and analyse	e it <mark>s data using d</mark> a	ta acquisition	i system.	
Detailed S	Syllabus:	omponents and analyse	e its data using da	ta acquisition	i system.	Duration
Detailed S Unit	Syllabus: Description	chinchwice		llegeo		Duration
Detailed S Unit H	Syllabus: Description Basics of Measurements: A	Accuracy, Precision, 1	resolution, reliabi	lity, repeatab	ility, validity,	Duration
Detailed S Unit I I	Syllabus: Description Basics of Measurements: A Errors and their analysis,	Accuracy, Precision, 1 Standards of measu	resolution, reliabi	lity, repeatab Aeasurement:	ility, validity, DC bridges-	
Detailed S Unit H H	Syllabus: Description Basics of Measurements: A Errors and their analysis, vheatstone bridge, AC b	Accuracy, Precision, 1 Standards of measu pridges – Kelvin, Ha	resolution, reliabi rement. Bridge M ry, Maxwell, Sci	lity, repeatab Aeasurement: hering and V	ility, validity, DC bridges- Vien bridges,	Duration
Detailed S Unit I 1.	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect	Accuracy, Precision, 1 Standards of measu pridges – Kelvin, Ha ion. Electronic Instr	resolution, reliabi rement. Bridge M by, Maxwell, Sch uments for Mea	lity, repeatab Aeasurement: hering and V ssuring Basic	ility, validity, DC bridges- Vien bridges, Parameters:	
Detailed S Unit I 1.	Syllabus: Description Basics of Measurements: A Errors and their analysis, vheatstone bridge, AC b	Accuracy, Precision, 1 Standards of measur oridges – Kelvin, Ha ion. Electronic Instr Voltmeter, True- RN	resolution, reliabi rement. Bridge M by, Maxwell, Sch uments for Mea	lity, repeatab Aeasurement: hering and V ssuring Basic	ility, validity, DC bridges- Vien bridges, Parameters:	
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Detailed S Unit I. Y Z P	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC neter, Digital voltmeter, V Dscilloscopes: Cathode Ra Probes and Transducers,	Accuracy, Precision, 1 Standards of measur oridges – Kelvin, Ha ion. Electronic Instr Voltmeter, True- RM Vector Voltmeter. ay Tube, Vertical and Specification of an	resolution, reliabi rement. Bridge M ay, Maxwell, Scl uments for Mea 1S responding V Horizontal Deflet Oscilloscope.	lity, repeatab Aeasurement: hering and V isuring Basic oltmeter, Elec ction Systems Dscilloscope	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement	
Detailed S Unit 1. 2.	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC neter, Digital voltmeter, V Dscilloscopes: Cathode Ra Probes and Transducers, Fechniques, Special Oscil	Accuracy, Precision, 1 Standards of measur oridges – Kelvin, Ha ion. Electronic Instr Voltmeter, True- RM Vector Voltmeter. ay Tube, Vertical and Specification of an loscopes – Storage O	resolution, reliabi rement. Bridge M ay, Maxwell, Scl uments for Mea IS responding V Horizontal Defle Oscilloscope, Sam	lity, repeatab Aeasurement: hering and V suring Basic oltmeter, Elec- ction Systems Dscilloscope pling Oscillo	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement scope. Signal	
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Detailed S           Unit           I           <	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC neter, Digital voltmeter, V Dscilloscopes: Cathode Ra Probes and Transducers, Fechniques, Special Oscil Generators: Sine wave g requency Generator. Pulse Signal Analysis: Wave Frequency Counter; Me Fransducers: Types, Strain Digital Data Acquisition	Accuracy, Precision, 1 Standards of measur oridges – Kelvin, Ha ion. Electronic Instr Voltmeter, True- RM vector Voltmeter. any Tube, Vertical and Specification of an loscopes – Storage O generator, Frequency and square wave gen Analyzer, Spectrum easurement errors; of Gages, Displacement System: Interfacing umentation Amplifier	resolution, reliabi rement. Bridge M ay, Maxwell, Scl uments for Mea 1S responding V Horizontal Defler Oscilloscope, Sam – Synthesized erators. Function Analyzer. Frequent extending frequent transducers to , Isolation Amp	lity, repeatab Aeasurement: hering and V isuring Basic oltmeter, Election Systems Oscilloscope pling Oscillo Signal Gene Generators. juency Cour ency range Electronics	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement scope. Signal erator, Sweep nters: Simple of counters Control and	6 6 6

**Text Books:** 

1. Modern Electronics Instrumentation & Measurement Techniques, by Albert D.Helstrick and William D.Cooper, Pearson Education. Selected portion from Ch.1, 5-13.

2. Elements of Electronics Instrumentation and Measurement-3rd Edition by Joshph J.Carr.Pearson Education. Selected portion from Ch.1,2,4,7,8,9,13,14,18,23 and 25.

### **Reference Books:**

1. Electronics Instruments and Instrumentation Technology - Anand, PHI

2. Doebelin, E.O., Measurement systems, McGraw Hill, Fourth edition, Singapore, 1990.

- 0	m: M. Tech. E&TC (VLSI and Embedded Systems) Semester : II						
Course	Microcontrollers and M	Aicroprocessors	Applications	5	Code : I	MET2602	С
	(Open Elective)           Teaching Scheme					ion Schen	
					Evaluat	ion Schen	
Lectur	re Hours	Hours Credit IE1 IE2 ETE		Total			
2	2 2 2 20 30						
Pre-req	uisite: Digital Electronics						
Objectiv		· · · · · ·	<b>Ъ</b> С (	11			
1.	To understand architecture and f	• •					
2.	To understand need of microcon			5.			
3.	To learn interfacing of real-worl						
4.	To study various hardware and s						
5.	To learn the architecture and pro	0		1			
6.	To acquaint the learner with app	lication instruction	on set and log	ic to buil	d assembl	y languag	e programs.
Outcom			4				
	rning the course, the students sho			Cour			
	Learn importance of microcontro					application	1
2.	To apply the programming skills		ife embedde	d applica	tion.		
3.	Learn use of hardware and softw	are tools.					
4.	Develop interfacing to real work	d devices.					
	1.5		100		1.000	9.1	
Detailed	l Syllabus:						
	-					21	
Unit	Description					18	Duration, h
Unit 1.	-	anguage prograr					-
Unit 1.	Description           Introduction to single chip M architecture, 8051 assembly 1	anguage programunication design: Assemb ment: assembler	nming, addr ly vs High-I <sup>.</sup> , compiler	essing n Level lan and inte	nodes, Pro guage pro egrated de	ogrammin ogrammin	- 6
Unit 1. 2.	Description Introduction to single chip M architecture, 8051 assembly 1 interrupts, timers and serial com Microcontrollers and system System Development Environ	anguage program munication design: Assemble ment: assemble mulation, system ign; Advanced C processors; A	nming, addr ly vs High-I ;, compiler design with Microproces RM microco	essing n Level lan and inte 8051. sor Arch ontrollers	nodes, Pro- guage pro- egrated de edom'' nitectures- ; Embedo	ogrammin ogrammin evelopmer 286, 480 led system	<b>6</b> <b>6</b> <b>6</b>
Unit 1. 2. 3.	Description Introduction to single chip M architecture, 8051 assembly I interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RIS	anguage program munication design: Assembler mulation, system ign; Advanced C processors; A d controller desig s Applications: Case Study on re	nming, addr ly vs High-I ;, compiler design with Microproces RM microco n for commu Interfacing v al time embe	essing r Level lan and inte 3051. sor Arch ontrollers nication, vith disp	nodes, Pro- guage pro- egrated de dominitectures- itectures- i; Embedo digital co lay device	ogrammin ogrammin evelopmer 286, 480 led system ntrol.	g     6       g, nt     6       5, n     6       s, 6
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Unit 1. 2. 3. 4. Text Bo 1. 2. Referen	Description Introduction to single chip M architecture, 8051 assembly 1 interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RISC design methodologies, embedde Microcontroller & Processors actuators, and memory devices. oks: Barry B Brey, The intel micropr Delhi, 2003.ISBN-0138027455, Mohammad Ali Mazidi and Jani Pearson education, 2003, ISBN- ce Books:	anguage program munication design: Assemble ment: assembler mulation, system ign; Advanced C processors; A d controller desig s Applications: Case Study on re Total occessor: architect 4th Edition ce Gillispie Masz 9788131710265,	nming, addr ly vs High-I c, compiler design with Microproces RM microco n for commu Interfacing v al time embe l ure, program cidi "The 805 . 2 <sup>nd</sup> Edition	essing r Level lar and inte 3051. sor Arch ontrollers nication, vith disp dded syst ming and 1 Microo	nodes, Pro- guage pro- egrated de communitectures- ; Embedo digital co lay device tem. I interfacin controller a	ogrammin ogrammin evelopmen 286, 480 led system ntrol. es, Sensor ng, Prentic and Embed	$\begin{array}{c c} g & 6 \\ g & 6 \\ \hline g & 6 \\ \hline g & 6 \\ \hline 5, & 6 \\ \hline s, & 6 \\ \hline s, & 6 \\ \hline 24 \\ \hline e \text{ hall of India, New } \\ \hline dded Systems'' \\ \hline \end{array}$
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Unit 1. 2. 3. 4. Text Bo 1. 2. Referen 1. 3.	Description Introduction to single chip M architecture, 8051 assembly 1 interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RISC design methodologies, embedde Microcontroller & Processors actuators, and memory devices. oks: Barry B Brey, The intel micropr Delhi, 2003.ISBN-0138027455, Mohammad Ali Mazidi and Jani Pearson education, 2003, ISBN- ce Books: Chris H. Pappas, William H. Mu	anguage program munication design: Assemble mulation, system ign; Advanced C processors; A d controller desig s Applications: Case Study on re- Total ocessor: architect 4th Edition ce Gillispie Masz 9788131710265, urray, —80386 M 0078812422. Dx Microprocess 7300.	nming, addr ly vs High-I ;, compiler <u>design with</u> Microproces RM microco n for commu Interfacing v al time embe ure, program tidi "The 805 2 <sup>nd</sup> Edition icroprocesso or: Hardware	essing r and into 3051. sor Arch ontrollers nication, with disp dded syst ming and 1 Microo r Handbo	nodes, Pro- guage pro- egrated do dom'' nitectures- ; Embedo digital co lay device tem. l interfacir controller a poksl, McC are, and Int	ogrammin ogrammin evelopmen 286, 480 led system ntrol. es, Sensor ng, Prentic and Embed Graw-Hill terfacing,	g       6         g, nt       6         5, 6       6         ss, 6       24         e hall of India, New       1         ided Systems"       0         Osborne Media,       Pearson Education,

Program:						
Course :						
Teaching Scheme Evaluation Scheme						
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisit	e: . Basics of Progra	mming				
2.To dev 3.Acquin Outcomes: After learnin 1.Describe 2.Interpret	uire knowledge in P velop Python program re skills to apply data g the course the stud the Numbers, Math f Object oriented prog solution clearly and a	ms with conditiona a analysis method lents should be ab functions, Strings, ramming in Pytho	als and loops and s to a problem le to: List, Tuples and n	Dictionaries in		
Detailed Syl	labus:	-01	Mile	-0110	×	
	escription	1011		9	0	Duration
Pyti pyti if	roduction to Pytho hon environment in hon program, Editor else, for, while, r rations, String Meth	Windows and Lin for Python code, ange() function,	ux, basics of Pyt syntax, variable	hon interpreter, , Data types. F	Execution of low control if	6
and	ts: Basic Operations dictionaries, dicti- actions: Definition, C	onaries & lists.	Tuples and F	iles : reading		6
3. Ob Inh		Programming f	eatures in F	ython: Class		6
4. Nui Nui Fig Par Har	mpy and Matplotli mpy Basic Statistics. ures, Subplots. Idling NaN values relation, Histograms	Matplotlib: Intro Gelections and In , Mapping, Data	duction, Simple dexing, Filling a Frames, Rea	plots, Line API, Methods, Seri	Legend API, es operation,	6
	tal	J	Stewart			24
2. Peng, Rog	owney, —Think PY ger D and Elizabeth onsulting 200 (2015)	n Matsui, —The				

**Reference Books:** 1. Zed A. Shaw,Learn Python the Hard Way

Course :		uter Engineering		Semester :		
	Software Engineering Basics (Open Elective)         Code : MCE1601B					
	Teaching Schem	e		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
Pre-requisi	ite:-					
Dbjectives:           1.         To           2.         To           3.         To           4.         To           5.         To           Dutcomes:         After learni           1.         De           2.         Classical Clasclassical Classical Clasclassical Classical Clascla		ethods of capturin sting principles to anagement through quality attributes. ents should be able lel for a developin ations and Identify ftware system.	g, specifying, visu S/W project devel h life cycle of the e to: g a software proje unique features o	nalizing and an opment. project. ct		requirements.
6. Ap Detailed Sy Unit	an, schedule and execuply quality attributes in a schedule and executive in a schedule and executive in a schedule attribute attribute attribute in a schedule attribute attribute in a schedule attribute in a schedule attribute a			nagement.	900	Duration
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En So Pr Pr	troduction to Softw agineering Fundament ftware Process, Soft escriptive Process Mo ocess, Unified Proce ftware development: A	als: Nature of Sof ware Myths. Pro- odels: The Waterfa ss, Concurrent.	tware, Software E ocess Models :A all, Incremental P Advanced Process	Engineering Pr Generic Pro rocess(RAD), s Models &	inciples, The ocess Model, Evolutionary Tools: Agile	6
2. So an M Sp of	ftware Requirement d system requirement etrics, A spiral view o pecification (SRS): Th SRS, Ways of write equirements validation	s Engineering an its, Functional a f the requirements e software require ting a SRS, Req	d Analysis: Requ nd non-functiona engineering proce ments Specification uirements elicitation	irements Engi I requiremen ess. Software I on document,	neering: User ts, Types & Requirements The structure	6
3. De	<b>esign Engineering:</b> D ttern-based Software tterns, Application A esigning class based co	esign Process & c Design. Archite rchitectures, Mod omponents, condu	quality, Design Co ectural Design : eling Component	Design Decis level Design level design, U	ions, Views, component, Jser Interface	6
Pa De De	esign: The golden rule					
Pa De De 4. Pr Ri Ri Ri	esign: The golden rule roject Risk Managem sk Strategies, Softwar sk Mitigation, Risks I oject	ent: Risk Analysi e Risks, Risk Ider	is & Management tification, Risk P	: Reactive ver rojection, Risk	sus Proactive Refinement,	6
Pa De 4. Pr Ri Ri pro	oject Risk Managem sk Strategies, Softwar sk Mitigation, Risks N	ent: Risk Analysi e Risks, Risk Ider	is & Management tification, Risk P	: Reactive ver rojection, Risk	sus Proactive Refinement,	6

4. S K Chang, —Handbook of Software Engineering and Knowledge Engineering, World Scientific, Vol I, II, ISBN: 978-981-02-4973-1

5. Tom Halt, —Handbook of Software Engineeringl, Clanye International, ISBN10: 1632402939

6. Christine Bresnahan, Richard Blum - Linux command line and Shell Scripting Bible - Weilly, ISBN-978-0-470-25128-

### M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program:	M.Tech (Comp	uter Engineering)		Seme	ester : I	
Course :	Basics of Machi	e : MCE1601C				
	Teaching Schem	e		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
Pre-requisi						
	lgebra, Statistics, Pro	bability and Calcul	lus			
	ogramming Skills					
Objectives:			. 1	1	1.0	·
	master the concepts deling	s of supervised a	nd unsupervised	learning, reco	mmendation eng	gine, and time serie
on mo 3. To the 4. 4.T	gain practical knowle approach and to vali dels using another ser acquire thorough kno theoretical concepts o implement models dom forest classifier,	date Machine Lea t of optimization al owledge of the stat and how they relat s such as support	rning models an lgorithms, which tistical and heuri e to the practical vector machines	d decode variou include Boostin stic aspects of I aspects of Mac , kernel SVM,	us accuracy metr ng & Bagging tec Machine Learning hine Learning.	ics. Improve the fina hniques g and To comprehen
Outcomes:			Naa	Coll		
<ol> <li>Un cor</li> <li>Sol din</li> <li>De</li> </ol>	ng the course the stud derstand machine lean isideration. Ive problems associate mensionality, dynamic velop scaling up matious applications.	rning techniques a ed with batch lear cally growing data	nd computing en ning and online and in particular	learning, and th scalability issue	ne big data charac	cteristics such as hig
	plement various ways	of selecting suitab	ole model parame	eters for differen	nt machine learni	ng techniques.
Detailed Sy		or servering surray				ing too initiation
Unit	escription					Duration,
Un Va		forcement Lea Reduction/Dimens	rning,Validation ionality reduc	Technique tion;Principal	components	<u>h</u> 6
2. Ch Hie val	ustering: Distance erarchical); Iterative ues in K-Means; C nsity-based clustering	measures;Differer distance-based clu constructing a hie	nt clustering m stering; Dealing rarchical cluster	ethods (Distan with continuou	s, categorical	6
Re inf <b>K</b> - des	assification: Naïve B quired data pr ormation;Classifier Nearest Neighbors: signing K-Nearest Neression problems.	ocessing; M-es K-Nearest Neigl	timates;, Fea hbor algorithm;	ture selectio Aspects to co	n: Mutual onsider while	6
4. As Ba ana mi exa	sociation Rule min sket, Recommendati alysis; Large item se ni sup by iterations; amples; Association a	on Engines, etc. ts; Association Ru Interestingness c nalysis vs. classifie	; A mathemat les; Apriori: Co of discovered as cation; FP-trees	ical model for nstructs large it sociation rules;	r association tem sets with ; Application	6
Pu Im	search Aspects: A blication in Quali plementation of Indus	ty Indexed Inte	ernational Jour			
	otal					24
Text Books	: R. Tibshirani, J. Frie	dman The Flore	nts of Statistical	earning 20 20	008	
	er Bishop. Pattern Re			-		
			Louining, 2			
Reference I	SOOKS:					

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program	n: M.Tech (Comp									
Course :	0									
	Course :     Image Processing with WATLAD (Open Elective)     Code : MCE2602A       Teaching Scheme     Evaluation Scheme									
Lectur	re Hours	Credit	IE1	IE2	ETE	Total				
2	2	2	20		30	50				
Pre-requ	re-requisite: Programming Basics									
2. Cover 3. Develo 4. Famili Outcome After lea 1: Under 2: Learn 3: Under con 4: Learn	op an overview of the field the basic theory and algor op hands-on experience in arize with MATLAB Ima es: rning the course the studen stand the need for image t different techniques employ rstand the need for image pression. different feature extraction	ithms that are wide using computers to ge Processing Tool nts should be able t ransforms different oyed for the enhance e compression and n techniques for im	ely used in digital o process images. <u>box Course</u> o: : types of image tr cement of images. I to learn the sp	ansforms and t	heir properties.	echniques of imag				
	op any image processing a Syllabus: Description		T			Duration h				
	Introduction: What is image processin perception? Image sam MATLAB orientations. Image Transformations Discrete Fourier transfor Discrete cosine transform	pling and quantiz	zation, Basic rel	ationship betw	ween pixels,	6				
			transform		Correlation,					
	Image Enhancement Te Spatial Domain Techniq Image subtraction, Imag filters. Frequency Domain Tech	c <b>hniques</b> ues: Basic gray le e averaging, Spat nniques: Frequenc	ial filtering, Smo y domain filteri	ons, Histogram pothing filters,	processing, Sharpening	6				
3.	Spatial Domain Techniq Image subtraction, Imag filters. Frequency Domain Tecl Image sharpening using fi Color image processing: Color fundamentals, Colo Image Compression: Fundamentals, Encoder-1 compression, Huffman co transform coding, Run-le	chniques ues: Basic gray le e averaging, Spat miques: Frequenc requency domain fi r models, Color tra Decoder model, T oding, Arithmetic c	evel transformatio ial filtering, Smo y domain filteri ilters. unsformation, Smo ypes of redunda coding, Golomb c	ons, Histogram oothing filters, ng, Image sm oothing and Sha ncies, Lossy a oding, LZW c	a processing, Sharpening woothing and arpening and Lossless oding, Block	6				
3.	Spatial Domain Techniq Image subtraction, Imag filters. Frequency Domain Tech Image sharpening using fi Color image processing: Color fundamentals, Color Image Compression: Fundamentals, Encoder-1 compression, Huffman co transform coding, Run-le coding, Wavelet coding. Morphological Image pr Basics, Erosion, Dilation, Hole filling, Connected Pruning.	chniques ues: Basic gray le e averaging, Spat anniques: Frequenc requency domain fi r models, Color tra Decoder model, T oding, Arithmetic c ngth coding, JPEG rocessing: Opening, Closing, components, Con	evel transformatio ial filtering, Smo y domain filteri ilters. unsformation, Smo ypes of redunda coding, Golomb c Lossless predicti , Hit-or-Miss tran- vex hull, Thinnin	ons, Histogram oothing filters, ng, Image sm oothing and Sha ncies, Lossy a oding, LZW c ve coding, Los	arpening and Lossless oding, Block sy predictive					
3.	Spatial Domain Techniq Image subtraction, Imag filters. Frequency Domain Tech Image sharpening using fi Color image processing: Color fundamentals, Color Image Compression: Fundamentals, Encoder-1 compression, Huffman co transform coding, Run-le coding, Wavelet coding. Morphological Image pr Basics, Erosion, Dilation, Hole filling, Connected	chniques ues: Basic gray le e averaging, Spat aniques: Frequenc requency domain fi r models, Color tra Decoder model, T oding, Arithmetic c ngth coding, JPEG rocessing: Opening, Closing, components, Con d Representation: etection, Edge link	evel transformation ial filtering, Smo y domain filteri ilters. unsformation, Smo cypes of redunda coding, Golomb c Lossless predicti , Hit-or-Miss trans vex hull, Thinnin cing and Boundar	s Freedon ons, Histogram oothing filters, ng, Image sm oothing and Sha ncies, Lossy a oding, LZW c ve coding, LZW c sform, Bounda ng, Thickening	n processing, Sharpening noothing and arpening and Lossless oding, Block sy predictive ry Detection, g, Skeletons, Chresholding,	6				

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Text Books:

- 1. R. C.Gonzalez, R.E.Woods," Digital Image processing", Pearson edition, Inc3/e,2008.
- 2. A.K.Jain," Fundamentals of Digital Image Processing", PHI,1995

### **Reference Books:**

1. J.C. Russ," The Image Processing Handbook", (5/e), CRC, 2006

- 2. R.C.Gonzalez & R.E. Woods; "Digital Image Processing with MATLAB", Prentice Hall, 2003
- 3.W. K. Pratt, *Digital Image Processing*, John Wiley & Sons, 2006.
- 4.S. Ahmed, Image Processing, McGraw -Hill, 1994.
- 5.S. J. Solari, Digital Video and Audio Compression, McGraw-Hill, 1997



Program:	M.Tech (Computer Engineering) Semester : II					
Course :		s (Open Elective)		Code : MC		
	Teaching Scheme			Evalua	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
Pre-requisite	2:					
2.To dev	uire knowledge of bas elop programs using S	Shell scripting	nands, and terr	ninologies		
	uire skills related to I	Linux file system				
1. 1.Us 2. Dem 3. 3.De 4. App	g the course the studer the common and simple constrate programming evelop collaboratively by a solution clearly an	e Linux commands g ability using Unix using GIT and writ	s Shell te research-pap			
Detailed Syll	abus:					
Unit Des	scription					Duration h
Und Insta prog	oduction to Linux erstanding Software allation of Linux OS grams: Linux desktop erstanding and manag	Licensing and Linu (direct and using environment, wo	ux Distribution g virtual macl rking with dit	s; Architecture nine); Using co fferent productiv	of Linux OS; mmon Linux vity software;	6
shel Vari exar Shel Awl arra	ic Commands and S I, shell variables,getc ables declaration & nples, for I functions, pipe and a c script: Environment ys, control flows, loop	wd() and pwd; Ir scope,test, return and wh redirection, wildcar andworkflow, synt s,functions, output	ntroduction to value of a ile loo ds, escape cha ax, variables, o	shell programn program, if-els p, switch racters;	ning features: e and useful n case;	6
File Usir Mar Netv	<b>ux File System and N</b> System - Manipulat ag absolute and rela aging; Basic File and working - Understan ing a network connec	ing Files: creating tive path; Manipu Directory comman ding network fear	lating Directo ds; Understand	ries: Creating, ling Linux file s	Deleting and ystem;	6
4. Esse User Dele grou Proo man iden Or Intr LaT secti refer	ential System Admin rs and Group Managetion of user and group pmod, groupdeletc; N cess and PackageM agement commands tifying running procest roduction to GIT and EX:Basic syntax, cont ions and paragraphs; A rences, and Bibliograp	istration gement: Users and p; Commands – shad Managing ownership Management: Und like rpm, yum, a sses; Log files. LaTEX: npiling and creating Adding Images, Tai oby; Installation and	dow, useradd, o and permissio derstanding pa apt; Understan g documents; ble ofcontents, d Hands-on of	usermod, userde on. ackage manage ading Process h Document struct Source code, gr LaTEX.	l, groupadd, ment,package hierarchy and ture including raphs; Adding	6
reme Han	: Creating a project u ote repo, working wit ds-on of GIT.					
Tot Toxt Books:	lai					24
2. Sumitava I Reference B	Bresnahan, Richard Bl Das, Unix Concepts ar Doks: resnahan, Richard Blu	nd Applications, Ta	ta-McGraw Hi	11, ISBN 0-07-06	53546-3	978-0-470-25

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program	: M.Tech (Comp	uter Engineering)	Semester : II			
Course :	Design with UML (Open Elective) Code : MCE2602C				E2602C	
	Teaching Scheme Evaluation					
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
Pre-requ	isite:				•	
.Basic un	lerstanding of computer	programming and	l related program	ming paradigm	s.	
Objectiv	es:					
5.	To introduce the concept	t of Object-oriente	d design			
6. '	To understand and differ	entiate Unified Pro	ocess from other	approaches		
	To design static and dyn					
Outcome		<u> </u>				
After lear	ning the course the stud	ents should be able	e to:			
1.	<b>Understand Basic feature</b>	es and elements of	the object-orient	ed approach		
2.	dentify, analyse, and me	adal structural and	hahavioural con	onte of the even	om	
<i>2</i> .		Juci siluctulai allu	benavioural con	cepts of the syst	Lenn.	
	Apply the concepts of ar					
3.	Apply the concepts of ar					
3. J	Apply the concepts of ar Syllabus:					Duration. (H)
3. <u>Detailed</u> Unit	Apply the concepts of ar Syllabus: Description	chitectural design	for deploying the	code for softw	are.	Duration, (H)
3. J Detailed Unit 4.	Apply the concepts of ar Syllabus: Description Introduction to UML: In	chitectural design	for deploying the	code for softw	are.	
3.DetailedUnit4.	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n	chitectural design	for deploying the	code for softw	are.	Duration, (H)
3. 2 Detailed Unit 4.	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle	chitectural design nportance of mode nodel of the UMI	for deploying the eling, principles	of modeling, ob Software Deve	are. pject-oriented lopment Life	
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod	chitectural design nportance of mode nodel of the UMI	for deploying the eling, principles	of modeling, ob Software Deve	are. pject-oriented lopment Life	
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams.	nportance of mode nodel of the UMI eling: Classes, I	for deploying the eling, principles 2, Architecture, Relationships, c	of modeling, ob Software Deve	are. oject-oriented lopment Life anisms, and	
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod diagrams. Advanced Structural M	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance	of modeling, ob Software Deve	are. oject-oriented lopment Life anisms, and	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Fypes and Roles, Packag	chitectural design mportance of mode nodel of the UMI eling: Classes, l odeling: Advanced ges. Class & Objec	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance t Diagrams	of modeling, ob Software Deve ommon Mech	are. bject-oriented lopment Life anisms, and s, Interfaces,	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Fypes and Roles, Packag Basic and Advanced E	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Objec Behavioral Modeli	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions,	of modeling, ob Software Deve ommon Mech	are. bject-oriented lopment Life anisms, and s, Interfaces,	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod diagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli ns, Activity Diagra	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions, ms.	of modeling, ob Software Deve ommon Mech red relationship	are. bject-oriented lopment Life anisms, and s, Interfaces, agrams. Use	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram Advanced Behavioral N	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli ns, Activity Diagra Modeling Events	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions, ms. and signals, star	of modeling, ob Software Deve ommon Mech red relationship	are. bject-oriented lopment Life anisms, and s, Interfaces, agrams. Use	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram Advanced Behavioral I Fhreads, time and space	chitectural design nportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli ns, Activity Diagra Modeling Events , state chart diagra	for deploying the eling, principles 2, Architecture, Relationships, c d classes, advance of Diagrams ng: Interactions, ms. and signals, star ms.	code for softwork of modeling, ob Software Deve ommon Mech red relationship Interaction di e machines, p	are. oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use rocesses and	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram Advanced Behavioral I Fhreads, time and space Architectural Modelin	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli as, Activity Diagra Modeling Events , state chart diagra g: Component,	for deploying the eling, principles , Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions, ms. and signals, star ms. Deployment, C	code for softwork of modeling, ob Software Deve ommon Mech red relationship Interaction di e machines, p Component di	are. oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use rocesses and agrams and	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram Advanced Behavioral I Fhreads, time and space	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli as, Activity Diagra Modeling Events , state chart diagra g: Component,	for deploying the eling, principles , Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions, ms. and signals, star ms. Deployment, C	code for softwork of modeling, ob Software Deve ommon Mech red relationship Interaction di e machines, p Component di	are. oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use rocesses and agrams and	6
3	Apply the concepts of ar Syllabus: Description Introduction to UML: In nodeling, conceptual n Cycle Basic Structural Mod liagrams. Advanced Structural M Gypes and Roles, Packag Basic and Advanced E cases, Use case Diagram Advanced Behavioral I Fhreads, time and space Architectural Modelin	chitectural design mportance of mode nodel of the UMI eling: Classes, I odeling: Advanced ges. Class & Object Behavioral Modeli as, Activity Diagra Modeling Events , state chart diagra g: Component,	for deploying the eling, principles , Architecture, Relationships, c d classes, advance t Diagrams ng: Interactions, ms. and signals, star ms. Deployment, C	code for softwork of modeling, ob Software Deve ommon Mech red relationship Interaction di e machines, p Component di	are. oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use rocesses and agrams and	6 6 6

1. Grady Booch, - The unified modeling language user guide. Pearson Education India, ISBN: 0-201-57168

2. James Rumbaugh. Micheal Blaha- Object-Oriented Modeling and Design with UML: Pearson Education India, ISBN-13: 978-0130159205

#### **Reference Books:**

- 2. Charles Ritcher Designing Flexible Object-Oriented systems with UML. New Riders Publishing.
- 3. Jackson, Burd Thomson Object Oriented Analysis & Design. Thomson Course Technology.
- 4. Mike O'Docherty Object-Oriented Analysis and Design: using UML. Wiley Publication
- 5. Joseph Schmuilers Teach Yourself UML in 24 Hours. Sams publishing.

Program:	M. Tech. Civil		0		nester : I	
Course :	•	0	Finance (Open H		de: MCI160	1A
	<b>Teaching Scheme</b>			Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisi	te:					
	anagement, Basics of					
problem inv 1. Ou 2. To 3. To 4. To		followed in car edge and under as an individu of finance and	rying out a project standing of engine al, and as a memb accounts carried o	t. eering and mana er or leader in di ut in project mar	iverse teams.	nd and solve th
1. Acce	ss current market tre	ends and choos	e projects.			
2. Prep	are project feasibilit	y reports.	1 0			
	ity to implement the				nd conditions.	
	ity to select projects	which benefit	the society and or	ganization.		
Detailed Sy		/	hus	- U0/1_		1
	escription	1			20	Duration, h
Wh Dif		It's Need ,Imp approaches to			lanagements thought, Quantitative, Systems,	6
	ject Implementation		g and Control		1231	
Pro pre allo	ject representation: liminary manipula	Role of proje tions, Basic base line, Pro	ect managers, rele Scheduling con- oject managemen	cepts: Resource t information s	ective of organization, e levelling, Resource system: Importance of Effortive torms	6
	ganizing		loject Managemen	I. FOIMATION OF	Effective terms.	
Org org Cha Pro Dec	ganizing as a Mana anizations such as aracteristics, Featur prietorship, Partner	line, Line es, their Mer ship, Private I oup Decision	& Staff, Functio its and Limitatio td., Public Ltd., Making, Staffing:	nal, Matrix or n, Ownerships Introduction to What is Staffi	Different Structures of project Organization: of Organization: Sole Organizational climate, ng? Steps involved in	6
	ancial Statements			veellenee		
					ce Sheet, Profit & Loss	6
Ace	count, Ratio Analysi	s, Fund Flow	Analysis, Statemer	nt of Changes In	Financial Position.	
	otal		Street	101974		24
1. 2. 3. 4.	Assignment based of Assignment based of Assignment based of Assignment based of Assignment based of Ratio Analysis, Fur Yext Books:	on Need, Impo on Project Impl on Managemen on Financial S	lementation, Moni at process, Principl tatements and The	toring and Contr les of Organization		& Loss Accour
1. 2. 3.	Project Managemer (Sixth Edition), Sep James C.Van Horne Khanna, R.B.,Proje	ot 2017. e, Fundamental	ls of Financial Ma		nt Body of Knowledge n Education 2004.	PMBOK Guid
Reference 1 1. 2. 3. 4.	Kuster J., Huber, Handbook, 2015. Prasanna Chandra	, Financial Mar mes M. Reeve	nagement, Tata M , Jonathan Duchac	cGraw-Hill, 200 . Financial and M	Managerial Accounting,	

Program			n Managemen	t)	Semester : I	
Course :		hnology (Open	Elective)		Code : MCI1601B	
	Teaching	Scheme			Evaluation Scheme	
Lectu	ire Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
	isite: Environmental st					
	es: After Completing thi			equate backgrour	nd to:-	
	<ol> <li>Evaluate Global warn</li> <li>Demonstrate knowled</li> </ol>			warming		
	3. Apply control measu	-	-	-		
	4. Apply high tech mea					
	es: After learning the con					
	1. Analyse effects of C					
	2. Implement the conc					
	3. Apply remedial acti					
	4. Apply high tech me	asures for Redu	acing Carbon E	missions.		
	Syllabus:					Duration, I
Unit	Description Clobal Warming and	its effect. Int	roduction and r	hysical definitio	n of global warming, the	
					ential, Carbon Emission	
					on and its effect in India,	
	The Kyoto and Other P					
					aken to Control Carbon	
	Emissions universally,	Use of Promot	ional and Punit	tive Mechanisms	for Reducing Carbon in	6
					Developing Countrywide	
	-		-		ive Measures for Global	
					ange (NAPCC) till date,	
	National Mission for a				inne Econtial Store for	
					ion:- Essential Steps for velop own Priorities and	
					d accumulation, Needs a	
					al Approach for Carbon	
					ment rates procedure for	
	controlling carbon emis					6
	0		THE COLOR		es Available for Energy	
					Generation, Sources of	
			Iternative Meth	hods Ready for	Use, Green Technologies	
	Needing some Prior R&		nd Citywide	Application • N	Aleasures to be taken for	.+
					Emission Reduction at	
	Local Authority and Cit					
	•	•		-	n' Buildings, Guidelines,	
					s and Hospitals, Green	
					lustries, Carbon, Carbon	
					enario in Cities, Need for	
					ment Projects ,'Green	
	Crematoria, Spreading 1			ip mutan vinag	ges, Green Services for	
				Emissions ·- I	Jse of Solar Power with	+
					tration), Microorganisms,	
	A Quick SWOT Analys				, ,	
			ia's National Ac	ction Plan Take U	Js to a Low-Carbon Path	6
				tudies on Project	s undertaken by Various	
	Countries Adaptive Ma		al for Indian Da	-		
	Countries, Adaptive Mic	easures Essentia	al for indian Pe	ople to Cope wit	n Climate Change	-
	Countries, Adaptive Me	easures Essentia	ai ior indian Pe	ople to Cope wit	n Climate Change	24

#### **Assignments :**

- 1. Assignment based on Global Warming and its effect and reduction measures.
- 2. Assignment based on Control of Carbon Emissions and Accumulation
- 3. Assignment based on Applications of green technologies.
- 4. Assignment based on High-tech measure for carbon emission reduction/ action plan

#### **Text Books:**

1. Green Technologies, Soli J. Arceivala, Mc Graw Hill Education.

#### **Reference Books**

- 1. Green Technologies and Environmental Sustainability edited by Ritu Singh, Sanjeev Kumar 2. http://cpcbenvis.nic.in/greentechnology.html



Program:	M. Tech. Civil (Construction Management)     Semester : II       Contract Tendering and Arbitration     Contract MCI2(024)					
Course :						
course .		n Elective)	1	Code: M		
	Teaching S	scheme		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2 2 2 20 30					
Pre-requis	ite:		•			
Objectives	:					
1. To equip	ped with knowl	edge of contracts system	l <b>.</b>			
		specifications for making				
	· ·	of Arbitration in the con	ntext of various c	onstruction asp	ects.	
Outcomes						
		he students should be abl				
		ical knowledge for maki			ders.	
		ng documents as per cond				
	· · ·	of Arbitration to resolution	on of disputes in	construction pr	ojects.	
Detailed S		61	ad l	Con		
Unit	Description	<u> </u>		100		Duration
1.	Construction		f. th	an man the ACT	Walid Waidahla	
		ct Act (1872): Definition				6
		s, Objectives of the act.				
		cture & Working of Con	istruction Organi	Zation Firms, L	aws of Toft.	
2.		<b>Contract Documents:</b>	16 1			
		contract documents, need				
		ontract documents, types	s of construction	contracts, roles	and functions of	6
	parties to the c					
3.	Contract Form Stages in Con					
5.	0	tender documents estimation	ating pro quali	fication bid ava	lustion sward of	
	contract,	tender documents estima	ating, pre - quan	fication, old eva	indation, award of	6
		ing and contract payment	ts contracts clos	e out and comp	letion	
4.	Arbitration:	ing and contract payment		as Freedo		
т.		f Actions and Laws - Ag				6
		-Conditions of Arbitratic			ions rippointment	U
	Total					24
Text Book			<del>olimian Exce</del>	Nerrise		27
1.		ring Contracts and Estim	nates - B S Patil	– Universities P	ress- 2006 Edition	reprinted in 2009
2.		ontract Act (9 of 1872), 1				
3.		on and Conciliation Act,				
Reference				,	,	
1. La	aw of contract Pa	art I and Part II, Dr. R.K.	. Bangia- 2005 E	dition, Allahaba	ad Law Agency.	
2. A	rbitration, Conci	liation and Alternative D	Dispute Resolution	on Systems- Dr.	S.R. Myneni-	
		inted in 2005- Asia Law				
		Compensation Act, 1923				
		Conditions for Domestic		Ministry Of St	atistics and Progra	m Implementation,
		dia. FIDIC Document (1				
	<u>.</u>	n Board foundation man	ual-www.drbf.or	g. 30 Edition		
List of Ass						
•	ignments on:					
		ditions of Contract relate			Defects in construe	ction work.
		nission and necessary Ter	nder Documents			
3. Pr	ocedure of Bid	Opening				

Program:		ech. Civil (Construct			ter : II	
Course :		l Quality Managemen	nt (Open Elective)		MCI2602B	
	Teaching S	cheme		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
	: TQM & N	AIS at UG Level, Awa	areness of Quality	Construction As	spects	
<ol> <li>To a</li> <li>To a</li> </ol>	pply necess pply effection	the need of QM in cor sary trainings for the en- ively the eight principl igma tool for TQM in	ffective utilization es of ISO for quali	of resources ty processes in o		
<ol> <li>Unde</li> <li>Able</li> <li>Appl</li> <li>Able</li> <li>Able</li> </ol>	erstand and to use effe y ISO princ to apply Si	, the engineers should apply the TQM phylo ctively QC tools. ciples for effective Qua x Sigma effectively.	sophy in construct			
Detailed Syll Unit D	abus: escription					Duration, h
	ncepts of Q	hality				Duration, n
A) cor 1. Ma imj ma	Definition ntrol, Qual nagement plementatio	of quality as given ity Assurance (QA/C (TQM), Need for TC n of quality, Quality r oring for quality- PDC	QC). Total qualit M in construction nanual-Contents, d	y control (TQ n industry. Org ata required, pr	C) and Total Qu anization necessary eparation, responsib	ality for <b>6</b> bility
2. His qua Tes	ality control st (NDT).	rol Tools areto diagram, Fish-ba l of construction mate lity Control-Necessity	rial used in RCC			
3. Put for 3. the cor <b>De</b>	pose of ISC ISO 9001. se principle nmitment n velopment	<b>9004-</b> Quality System O Standards. Difference Certification bodies in es for an effective qua ecessary for achieving of quality circles, qua eedback for quality.	the between ISO 90 nvolved. Eight Prin lity process in the minimum formation for	nciples of ISO-E organization. Nor quality system	Basic meaning, appl lanagement support n standards.	ying and <b>6</b>
4. (ii) 4. (ii)	Six Sigma finition of ngs, Six sig Applicatio RCC Work	six sigma, evolution gma training, six sigma <b>n of Six Sigma</b>	a as an effective too	ol in TQM.		6
	otal					24
2.Total En 3.Total Pro Reference Bo 1. In 2. M 3. Ju	gineering Q oject Manag ooks: ternational antri Handt ran's Quali	l Total Quality Manag Quality Management – gement – The Indian C Standards Organizatio pook – A to Z of Const ty Handbook – Joseph	Sunil Sharma – M ontext - P.K.Joy M n – ISO 9001 and cruction – Mantri P	acmillan India I Iacmillan India ISO 9004 ublications	.td. Ltd.	
	dition (1998 anagement	8) Information Systems -	- Gordon B. Davis	, Margrethe H.	Olson – Tata McGr	aw Hill Publ. Co.

#### List of Experiments/ Assignments:

- 1. One Assignment on Each Unit
- Activity: Posters / Flex / Flow Charts / Presentation etc. Per students on any one Topic of the Syllabus
   Quality Circle Team for Problem Solving.



Program:		(Civil Engin			Semester : 1		
Course :			Open Elective	e)	Code : MCI		
	Teaching	Scheme			Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Tota	al
2	2	2	20		30	50	
2. Calcul <b>Objectives:</b> This course	d Mathematic us-Based Prol aims at enab	bability/Statis	3,		nlinear Program	ming Problems	
<ol> <li>To der</li> <li>To app</li> </ol>	ive feasible and a state of the second se	nd optimal sol thods to selec	ution for Tran	sportation and various optim	l Assignment Pro al strategies usin		viect
Outcomes:		k ulagrafilis w	tui single and			es involved in the pre	Jeet.
<ol> <li>Model</li> <li>Model</li> <li>Model</li> <li>Apply</li> </ol>	and solve Lir & Solve prof various metho ate Project scl	near and Nonlinear and Nonlinear and Nonlinear and Nonlinear and States and S		ming Problem tion and Assig rious optimal	nment Problem. strategies using o	lecision theory.	
Unit	Description	l					Duration, h
1.	Introduction, operations r Methodology Linear Prog Introduction, Assumptions Formulation, Simplex Met Transportat	esearch, Adv of operations ramming Structure of and Appli Solving Lin hod ion and Assig	search approa antages, Met s research, Ad of Linear pr cations of I near program	hods for sol vantages. rogramming Linear progr ming problem	ving operations Model, Advant amming, Guide ns using Grap	s and Modelling in research models, ages, Limitations, elines for Model hical Method and	6
2.	Methods for Assignment l	Finding Init Problem, Solu	ial Solution, tion Methods	Test for Op	timality. Mather	rtation Algorithm, matical Models of	6
3.	Steps of Dec Making Und Pure Strategi Strategies: G	er Uncertainty ies (Minimax	g Process, Ty y, Games The and Maximit Saddle Point	ory: Introduct n Principles):	ion, Two Person Games with Sa	ironment, Decision Zero Sum Games, addle Point, Mixed olution Methods of	6
4.	PERT/CPM	Basic Differe Network Com	ponents and l	Precedence Re	elationships, Crit	oject Management, ical Path Analysis. completion time.	6
	Total						24
9789 2. Fred	9350593363.		-		·	s 5th Edition ISBN N h, McGraw Hill", 6tl	
Reference B 1. Gera 2. Gup 3. Way No.	ooks: ald Lieberman ta Prem Kuma yne L. Winston 978-8131501	ar and Hira D n, "Operations 900.	S, "Problems S Research Ap	in Operations plications and	Research", S. Cl Algorithms", Co	n, ISBN No. 978- 93 hand, ISBN No.978- engage Learning, 4th BN No.978-0070669	8121909686. Edition, ISBN

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Progra			nation Technology)	)		ester : I	
Course	: 1		ics (Open Elective)	1	Cod		IT1601A
		<b>Teaching Scher</b>	ne		Evalua	ation Scheme	
Lec	ture	Hours	Credit	IE1	IE2	ETE	Total
/	2	2	2	20	-	30	50
. Mach <u>. Data</u> <b>)bjecti</b> 1. Un 2. Un 3. Un	nderstand nderstand	the different bas the concept of P	ic concept / fundame robability and its usa pplication of Descrip	age in various bus	iness application		ir uses for Busine
		fferent data analy	tics tools.				
<ol> <li>Ga</li> <li>Ev</li> <li>To</li> <li>An</li> <li>Ev</li> </ol>	uining Kn valuating perform nalytics. valuate di	owledge of basic basic concepts of practical applie fferent tools.	dents should be able c concept / fundamen f probability and perf cation by taking ma	ntals of <mark>bu</mark> siness a form pr <mark>obabil</mark> ity t	heoretical distr		of Business
	d Syllab	us:	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1				<u> </u>
Unit		1		scripti <mark>on</mark>		6	Duration, h
1.	What is model	building, Deploy	<b>n</b> tics?, Business Analyment, Different type , roles within data ar	es of business an			6
2.	UNIT Optimi Non –1 predict	• II: Analytics T zation technique inear programmi ive analysis, le		ing, Goal Progra ling :- regression linear discrimin	, multiple linea ant analysis,	ar regression for	6
3.	UNIT Probab Probab Norma Concep	<b>III: Probability</b> ility: Theory of ility Theoretical distributions. ot of Business A	Theory & Distribut Probability, Additi Distributions: Conc nalytics- Meaning ty yze data-Descriptive	tion and Multipli cept and applicat	s Freedo cation Law, E ion of Binomi	al; Poisson and s Analytics, Use	6
4.	UNIT	IV : Data analy	tics tools	Sterner			6
				Total			24
Text Bo 1. R.N. Referen	ooks: . Prasad , nce Book	Seema Acharya	g Tableau/Python/R/	Total			24

Program:		mation Technology)			ester: I	
Course :		g (Open Elective)	I	Code		IT1601B
	Teaching Scher	ne		Evalua	tion Scheme	
Lectur	re Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20	-	30	50
2. Prior Kı Dbjective . To use I	dge of Statistics in Ma nowledge of any progra s: R and R Studio Environ	amming				
8. To inter	erstand different data ty face R with other lang erstand the use of R for	lages.	ctures in R			
After learn 1. Understa 2. Apply th 3. Learn to 4. Able to a	ing the course, the stu- and the basics in R pro- ne use of R for Big Dat apply R programming appreciate and apply the	gramming in terms o a analytics. for Text processing.	f constructs, cont		string functions.	
Detailed S	Syllabus:	1.9			a la	
1. II	JNIT – I: Getting Sta ntroduction to the R- ceading data into R, Su	rted with R Program		ands, Data Str	ructures in R,	Duration, h
2. A R	<b>INIT - II: Matrices, A</b> Creating matrices ,Mat Adding and deleting ro Reduction, Higher Dir Accessing list compone	rrays And Lists rix operations ,Appl ws and columns, Ve nensional arrays, Li	ector/Matrix Dist ists, Creating lis	inction, Avoidi ts, General lis	ng Dimension t operations,–	6
3. w R J	<b>INIT III : Data Frame</b> Creating Data Frames, unctions to Data frame vith factors, Working tatements: Arithmetic Returning Boolean value Replacement functions	Matrix-like operation es, Factors and Table with tables, Other and Boolean operato ues, Environment an	es: factors and le factors and tab ors and values, I d Scope issues:	vels, Common e related func Default values f Writing Upstain	functions used tions, Control for arguments, rs - Recursion	6
4. II	JNIT IV : Interfacing nterfacing R to other 1 inear models, Non-line					6
			Total		G	24
2. Norman Reference 1. Jared P. 2. Robert	ardener, "Beginning R Matloff, "The Art of	R Programming: A T one: Advanced Analy : A Beginner's Guide	Cour of Statistical	Software Desig ", Addison-We	gn", No Starch F sley Data & An	alytics Series, 201

Program:		nation Technology)				ester: I		
Course :		nt of Engineering P	roject (Open Elec		Code		EIT1601C	
	Teaching Scher	ne		F	lvaluat	tion Scheme		
Lecture	Hours	Credit	IE1	II	22	ETE	Total	
2	2	2	20		- 30		50	
2. Identifying <b>Outcomes:</b>	ngineering nagement e the parties concerr g "best value" proje	ed with a most favor ct option selection an dents should be able	nd developing reali		-	oject.		
1. Prepare fa	vorable financial or	atcome to the project	-					
Detailed Syll	abus:	D					Duration, h	
Unit	Description Introduction and Purpose of Project Cost Management							
1. Clies (Mar actir	nt, Engineering contractor	nsultant supporting carrying out EPCM lient, Material Sup	Client in Develop role for project in	npleme	ntation	, Consultant	6	
2. Proj	e Project Cost Mar ect Concept &				Definiti	on, Project	6	
3. Estin Estin fund Loca Proj- finan Cust	mating and Projec nate Categories, E nate Scope, Study ing, Estimate qua ation factors, Escala ect Financing: Inter acing, Banks & Ver omers	t Financing stimate Quality, Pro / Development Esti lity required for pr tion ,Currency fluctu nal financing, Finan ture Funds, Governm	oject Schedule inf mates, Estimates oject authorizatio lations, Contingend cing of project dev	luence for pro n, Esti cy, Casl velopmons, Con	vision mating n flow ent wo: ntractor	of advanced techniques, rks, External rs, Suppliers,	6	
4. Meg exter in e requ	nsions to existing f merging markets	s with value >€21 acilities), New Tech (e.g. E Europe, As gulatory validation (o	Bn), Retrofit pro nology projects, S ia), Projects in r	ojects ( ub-surf remote	Modifi ace wo locatio	cations and rks, Projects ons, Projects	6	
		Te	otal				24	
Marcel Dekka	ar Inc., New York B	M. English, "Projec asel.	t and cost engined	er's hai	ndbook	", third editio	n, Ace Internatior	
		M. English, "Projec asel.	t and cost engined	er's har	ndbook	", third edition	n, Ace Internation	

Program:		nation Technology)		S		II
Course :	Cryptography (					MEIT2602A
	Teaching Scher	ne		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	1	20	-	30	50
Pre-requisite	:					
1. Basic Math	ematics					
	outer Network.					
		ork and information s	security.			
		urity and malwares.				
	curity issues in inte					
	twork defense tool	S.				
Outcomes:	а а.					
		dents should be able		•		
		elated to cryptograph			ility of these m	athods
		cryptography and refl sophy of modern sym				emous
		he various categories			113	
Learn uses	and minitations of t	ne various categories	or cryptographic	angoriumis		
Detailed Sylla	abus:	1 All		90		
Unit		Desc	ription		and and	Duration,
1. Com servi	mation Security, S ces, Modular Arith	on: oncepts, Terminolog Security Policy, Typ metic, GCD, Euclide ded Euclidean Algori	es of Security a a security security a secur	ttacks , Se rmat's Littl	curity Goals a le Theorem, Eu	and <b>b</b>
2. UNI Sym Subs	<b>T – II : Classical I</b> metric Cipher M	Encryption Technique odel, Encryption M ransposition Ciphers	ues : Methods, Classic	al Encryp	tion Techniqu	
3. Bloc Encr		es, Data Encryption AES), RC5, Interna				
4. Publ	e Hellman Key E	<b>cryptosystems:</b> hy, Key Manageme xchange, Elliptic Cu				U
		Т	'otal			24
2. V. K. Pachg	ghare, "Cryptograp atz, Yehuda Lindel	ecurity : Principles a ny and Information S I, "Introduction to Mo	ecurity", PHI Lear	ming 3rd ed	dition	13-335469-0
1. Oded Golda	reich, "Foundations	of Cryptography Bas systems Security", W		-	•	2-6

		formation Technology)			ester : II	
Course		uting and Security (Op	pen Elective)	Code		EIT2602B
	Teaching Sc	heme		Evaluation	on Scheme	
Lect	ure Hours	Credit	IE1	IE2	ETE	Total
2		1	20	-	30	50
Pre-requ						
	ating Systems					
	mentals of Computer	Networks.				
<b>Objectiv</b>		loud Computing and its	acosystam			
		ation and its importance				
		of Cloud Programming				
-		ies in cloud computing.				
Outcom	es:					
		students should be able	to:			
		Cloud based solutions.		1' '		
		chanisms and issues in		lications		
		ques to program Cloud lenges and trade-offs in				
10 uli	acrotuna current ella	lenges and trade offs in	Cioud Computing	110		
Detailed	Syllabus:	( mini		20	e	
Unit	-	Des	cription	07	1	Duration, l
		nentals of cloud compu			2.1	
		ces, Basic Concepts and				
		enges, Roles and Boundaries, Cloud Characteristics, Cloud Delivery Models, Cloud				
1	Daulasumant Madal	Enderstad Claud/In				
1.		s, Federated Cloud/In	terclo <mark>ud</mark> , Types (	of Clouds. C	loud-Enabling	0
1.	Technology: Broadt	oand Networks and In-	terclo <mark>ud</mark> , Types ( t <mark>ernet Archit</mark> ecture	of Clouds. C , Data Cente	loud-Enabling r Technology,	0
1.	Technology: Broadb Virtualization Tech		terclo <mark>ud</mark> , Types ( t <mark>ernet Archit</mark> ecture	of Clouds. C , Data Cente	loud-Enabling r Technology,	0
1.	Technology: Broad Virtualization Technology.	oand Networks and In-	terclo <mark>ud</mark> , Types of ternet Architecture nology, Multiten	of Clouds. C e, Data Cente ant Technol	loud-Enabling r Technology,	0
1.	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Leve	and Networks and Im hnology, Web Tech ization and common st els of Virtualization, Vi	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct	of Clouds. Control of Clouds. Control of Clouds. Control of the computing: computing: ures/Tools and	loud-Enabling r Technology, ogy, Service I Mechanisms,	0
1.	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor	and Networks and Im hnology, Web Tech ization and common st els of Virtualization, Virtualization of CP	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L	of Clouds. C c, Data Cente ant Technol computing: ures/Tools and O Devices, V	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters	0
	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Levy Types of Hypervisor and Resource Mat	and Networks and Im hnology, Web Tech ization and common st els of Virtualization, Vi rs, Virtualization of CP nagement, Virtualizati	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen	of Clouds. Co c, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common	6
1. 2.	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Levy Types of Hypervisor and Resource Mar Standards: The Op	and Networks and Im hnology, Web Tech ization and common st els of Virtualization, Vi rs, Virtualization of CP nagement, Virtualizati en Cloud Consortium,	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualization	of Clouds. C e, Data Cente ant Technol computing: ures/Tools and O Devices, V ter Automati tion Format,	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on, Commor Standards for	6
	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop	and Networks and Imphology, Web Tech ization and common st els of Virtualization, Virtualization of CP nagement, Virtualizati en Cloud Consortium, pers: Browsers (Ajax),	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSO	of Clouds. C e, Data Cente ant Technol computing: ures/Tools and O Devices, V ter Automati tion Format, N), Solution S	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Stacks (LAMP	6
	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica	and Networks and Im hnology, Web Tech ization and common st els of Virtualization, Vi rs, Virtualization of CP nagement, Virtualizati en Cloud Consortium,	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSO	of Clouds. C e, Data Cente ant Technol computing: ures/Tools and O Devices, V ter Automati tion Format, N), Solution S	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Stacks (LAMP	6
	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security	and Networks and Imphology, Web Tech ization and common st els of Virtualization, Virtualization of CP nagement, Virtualizati en Cloud Consortium, pers: Browsers (Ajax),	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSOI iblishing Protocol	of Clouds. Construction Format, N, Solution S, and RSS),	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Stacks (LAMP	6
	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Leve Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP nagement, Virtualization en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO iblishing Protocol nents and applica	of Clouds. Co of Clouds. Co of Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: :	loud-Enabling r Technology, ogy, Service I Mechanisms, irtual Clusters on, Commor Standards for Stacks (LAMF Standards for	6
2.	Technology: Broadt Virtualization Technology. UNIT – II : Virtual Implementation Leve Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP- nagement, Virtualizati en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pu Amazon AWS and M	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSOI iblishing Protocol nents and applica rogramming Suppo ficrosoft Azure,	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : port of Google Emerging Cl	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Commor Standards for Standards for Standards for Standards for App Engine, oud Software	6
	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Unit	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP- nagement, Virtualizati en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu- rogramming, environr and Grid Platforms, Pi- Amazon AWS and M- lerstanding Core Op	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO iblishing Protocol nents and applica rogramming Supp ficrosoft Azure, enStack Ecosyste	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving	6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Und application to cloud	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vi rs, Virtualization of CP nagement, Virtualization en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pr Amazon AWS and M lerstanding Core Op l, Microsoft Cloud Se	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO iblishing Protocol blishing Protocol nents and applica rogramming Suppo ficrosoft Azure, enStack Ecosyste ervices, Google C	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving ions, Amazon	6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Leve Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Und application to cloud Cloud Services, Clo	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vi rs, Virtualization of CP nagement, Virtualization en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pr Amazon AWS and M lerstanding Core Op l, Microsoft Cloud Se ud Applications (Social	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSOI iblishing Protocol bilishing Protocol ments and applica rogramming Supp ficrosoft Azure, enStack Ecosyste rvices, Google C I Networking, E-m	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving ions, Amazon	6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Leve Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Und application to cloud Cloud Services, Clo Apps, Customer Rela	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP nagement, Virtualization en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pr Amazon AWS and M lerstanding Core Op I, Microsoft Cloud Se ud Applications (Social ationship Management)	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSOI iblishing Protocol bilishing Protocol ments and applica rogramming Supp ficrosoft Azure, enStack Ecosyste rvices, Google C I Networking, E-m	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving ions, Amazon	6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Leve Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud Programming on A Environments, Und application to cloud Cloud Services, Clo Apps, Customer Rela	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP nagement, Virtualizati- en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pr Amazon AWS and M lerstanding Core Op l, Microsoft Cloud Se ud Applications (Social ationship Management) curity and issues:	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and I on for Data-Cen Open Virtualiza Data (XML, JSO ablishing Protocol nents and applica rogramming Suppo ficrosoft Azure, enStack Ecosyste ervices, Google C I Networking, E-m	of Clouds. Co e, Data Cente ant Technol computing: ures/Tools and O Devices, V ter Automati ion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati oud Applicat ail, Office Set	loud-Enabling r Technology, ogy, Service I Mechanisms, irtual Clusters on, Commor Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving ions, Amazon rvices, Google	6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Und application to cloud Cloud Services, Clo Apps, Customer Rela UNIT IV : Cloud se Basic Terms and Co	pand Networks and Im- hnology, Web Tech ization and common st els of Virtualization, Vir- rs, Virtualization of CP- nagement, Virtualizati en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pu Amazon AWS and M derstanding Core Op l, Microsoft Cloud Se ud Applications (Social ationship Management) ceurity and issues: ncepts, Threat Agents, 0	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO) iblishing Protocol. nents and applica rogramming Suppo ficrosoft Azure, enStack Ecosyste ervices, Google C I Networking, E-m	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat ail, Office Ses	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Commor Standards for Standards for Stan	6 6
2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud a Programming on A Environments, Und application to cloud Cloud Services, Clo Apps, Customer Rela UNIT IV : Cloud se Basic Terms and Co Considerations, Cloud	and Networks and Imphology, Web Tech ization and common stells of Virtualization, Virtualization of CP nagement, Virtualization, Virtualization en Cloud Consortium, pers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pr Amazon AWS and M lerstanding Core Op d, Microsoft Cloud Se ud Applications (Social ationship Management) courity and issues: ncepts, Threat Agents, of ud Security Mechanis	tercloud, Types of ternet Architecture nology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO iblishing Protocol blishing Protocol nents and applica rogramming Supp ficrosoft Azure, enStack Ecosyste ervices, Google C I Networking, E-m	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat ail, Office Ser- reats and Attac Hashing, Digi	loud-Enabling r Technology, ogy, Service l Mechanisms, irtual Clusters on. Common Standards for Standards for Stan	6
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2.	Technology: Broadt Virtualization Tech Technology. UNIT – II : Virtual Implementation Lev Types of Hypervisor and Resource Mar Standards: The Op Application Develop and LAPP),Syndica Security UNIT III : Cloud p Features of Cloud Programming on A Environments, Und application to cloud Cloud Services, Clo Apps, Customer Rela UNIT IV : Cloud se Basic Terms and Co Considerations, Clo Public Key Infrastru (SSO), Hardened	and Networks and Impology, Web Tech ization and common stels of Virtualization of CP nagement, Virtualizati en Cloud Consortium, bers: Browsers (Ajax), tion (Atom, Atom Pu rogramming, environr and Grid Platforms, Pu Amazon AWS and M derstanding Core Op 1, Microsoft Cloud Se ud Applications (Social ationship Management) courity and issues: ncepts, Threat Agents, O ud Security Mechanis cture (PKI), Identity an Virtual Server Images	tercloud, Types of ternet Architecture mology, Multiten tandards in cloud irtualization Struct U, Memory, and L on for Data-Cen Open Virtualiza Data (XML, JSO) ablishing Protocol. nents and applica rogramming Suppo ficrosoft Azure, enStack Ecosyste ervices, Google C. I Networking, E-m Cloud Security Thi ms: Encryption, I ad Access Manager s. Cloud Issues:	of Clouds. Co e, Data Center ant Technol computing: ures/Tools and O Devices, V ter Automati- tion Format, N), Solution S and RSS), tions: : ort of Google Emerging Cl m. Applicati- oud Applicat ail, Office Ser- eats and Attack Hashing, Digi- nent (IAM), S Stability, Pa	loud-Enabling r Technology, ogy, Service I Mechanisms, irtual Clusters on. Commor Standards for Standards for Standards for Standards for App Engine, oud Software ons: Moving ions, Amazon rvices, Google eks, Additional ital Signature, Single Sign-Or rtner Quality,	6 6 6
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#### **Text Books:**

- 1. Jack J. Dongarra, Kai Hwang, Geoffrey C. Fox, Distributed and Cloud Computing: From Parallel Processing to the Internet of Things, Elsevier, ISBN :9789381269237, 9381269238, 1st Edition.
- 2. Thomas Erl, Zaigham Mahmood and Ricardo Puttini, Cloud Computing: Concepts, Technology & Architecture, Pearson, ISBN :978 9332535923, 9332535922, 1 st Edition.

#### **Reference Books:**

- 1. Srinivasan, J. Suresh, Cloud Computing: A practical approach for learning and implementation, Pearson, ISBN :9788131776513.
- 2. Brian J.S. Chee and Curtis Franklin, Jr., Cloud Computing: Technologies and Strategies of the Ubiquitous Data Center, CRC Press, ISBN :9781439806128.
- 3. Kris Jamsa, Cloud Computing: Saas, Paas, Iaas, Virtualization, Business Models, Mobile, Security, and More, Jones and Bartlett, ISBN :9789380853772.
- John W. Ritting house, James F. Ransome, Cloud Computing Implementation, Management, and Security, CRC Press, ISBN : 978 1439806807, 1439806802.
- 5. Karl Matthias, Sean P. Kane, Docker: Up and Running, OReilly, ISBN:9781491917572, 1491917571.



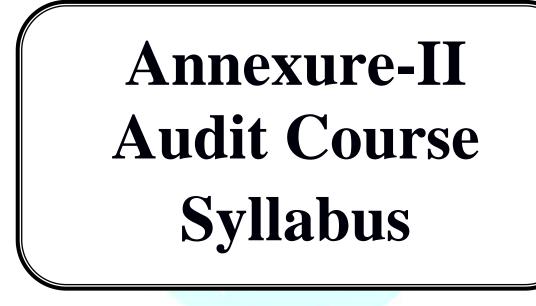
Program:		mation Technology			Semes	ter :	II	
Course :	Bit coin : Funda (Open Elective)	amentals of Crypto	Currencies		Code :		MEIT26	602C
	Teaching Sche	me		E	valuatio	on Scheme	e	
Lectur	re Hours	Credit	IE1	IE	2	ETE		Total
2	2	1	20	-		30		50
2. Basic of Objective 1. To unde 2. To unde 3. To unde 4. To unde Outcomes After learr	rstand the basic conce rstand the different Co rstand the concepts of rstand the Mechanics	epts behind Cryptogra onsensus approaches blockchain technolo of bit coin. dents should be able	for Bit coin. gy. to:					
2. Learn	and apply different con the block chain model of	nsensus mechanisms	for real time proj		l on digi	tal current	cy.	
2. Learn 3. Analyz	and apply different cost the block chain model of	nsensus mechanisms come from a differen	for real time proj t case studies.		l on digi	tal current		
2. Learn 3. Analyz Detailed S Unit 1. F T	and apply different corrections of the second secon	nsensus mechanisms come from a differen Des o currencies : Nodes larket Tradability Cu	for real time proj t case studies. cription , Transaction , W rypto Trading Stu	allets, Co	in Minii	ng ,Basics	of	Duration, h
2. Learn 3. Analyz Detailed S Unit 1. F 1. T P 2. H V	and apply different corrections of a sector and apply different corrections of a sector a	nsensus mechanisms come from a differen Des o currencies : Nodes larket Tradability Cr us Methods Genesis I Bit coins Bit coins, Hot and C	for real time proj t case studies. cription , Transaction , W rypto Trading Sta Block old Storage, Split	fallets, Co rategies,	in Minin Blockcl	ng ,Basics nain: Nod Keys, Onli	of les,	
2. Learn 3. Analyz Detailed S Unit 1. F 1. F 2. H V 3. C	and apply different corrections of the second secon	nsensus mechanisms come from a differen Des o currencies : Nodes larket Tradability Cr is Methods Genesis I Bit coins Bit coins, Hot and C , Payment Services, unctions: Hashing ar	for real time proj t case studies. cription , Transaction , W rypto Trading Stu Block old Storage, Split Transaction Fees,	fallets, Co rategies, ting and S Currency	in Minin Blockcl Sharing I	ng ,Basics nain: Nod Keys, Onli ge Marke	of les, ine t	6
2. Learn 3. Analyz Detailed S Unit 1. F 1. F 2. F V 3. C 3. C P 4. E T C	and apply different corrections of the second secon	nsensus mechanisms come from a differen Des o currencies : Nodes larket Tradability Cr is Methods Genesis I Bit coins Bit coins, Hot and C , Payment Services, unctions: Hashing ar crypto currency Bit coin Scripts, App How Bit coin Achiev buted Consensus : C	for real time proj t case studies. cription , Transaction , W rypto Trading Str Block old Storage, Split Transaction Fees, ad SHA 256, Dig clications of Bit co res Decentralization onsensus without	allets, Co rategies, ting and S Currency dial Signation on, Centra Identity, <sup>7</sup>	in Minin Blockcl Sharing l Exchan tures, P , Bit coi alization The Blo	ng ,Basics nain: Nod Keys, Onli ge Marke ublic Key n Blocks, vs.	of les, ine t	6

 Martin Quest, "Block chain Dynamics: A Quick Beginner's Guide on Understanding the Foundations of Bit coin and Other Crypto currencies", Create Space Independent Publishing Platform, 15-May-2018
 Daniel Drescher, "Block chain Basics", A Non -Technical Introduction in 25 Steps.

#### **Reference Books:**

1. Bikramaditya Singhal, Gautam Dhameja, Priyansu Sekhar Panda, "Beginning Block chain A Beginner's Guide to Building Block chain Solutions", 2018

2. Chris Dannen , "Introducing Ethereum and Solidity", Foundations of Crypto currency and Block chain Programming for Beginners



Program:	M.Tech. (Design Engin	eering)		Semeste	Semester : I and II		
Course :	Audit Courses (Semest	er I and II)		Code :	M_1961 M_2962		
	Teaching Scheme			Evalua	tion Scheme		
Lecture	Hours	Credit	IE1	IE2	ETE	Total	
1	1						
<b>Guidelines:</b>							
1. The	audit courses are commo	on to all M.Tech	Courses.				
2. Stu	dents can select any audi	t course from lis	st of audit co	ourses for semeste	r I and II		
3. <b>The</b>	se are non-credit courses	but mandatory	to comply th	he submission of t	he semester.		

### LIST OF AUDIT COURSES

## (Common to M.Tech and MCA programs)

	SEM-I	A	SEM-II
M_1961A	Constitution of India	M_2962A	Team Building & Leadership
M_1961B	Value Education "Knowledge	M_2962B	English for Research writing
M_1961C	Stress Management	M_2962C	Disaster Management

Program	M.Tech(Design Eng				Semester: I	
Course	Constitution of Ind				Code : M_1962	1A
	Teaching Schem	e		Evalua	tion Scheme	
Lecture	Hours	Credit	IE 1	IE 2	ETE	Total
1	1	-				
4. To	understand the constituti understand the rules and understand E-governanc	regulations under wl	hich public and	private sector v	vork	
Outcome	s:					
<ol> <li>Unders constitution</li> <li>Different</li> <li>rights and</li> </ol>	ning the course, the stud tand the functions of the on and assessment of the ntiate the functioning of abide the rules of the In	Indian government a Parliamentary Syste Indian Political syste	nd identify and m in India.	-		
Detailed Syl Unit De	llabus: escription	chwad		llo		Duration
	oduction to Constitution	& System of Gover	ament	00		h
and Prin Stru Cal dist	eaning of the constitution characteristics of the nciples of State Policy, F acture and Function of pinet, Parliament, Support cribution of legislative a vernment	Constitution of Ind Fundamental Duties a Central Governmen reme Court of Ind	ia, Preamble, F nd it's legal stat t, President, Vi ia, Judicial Re	Fundamental R tus, Citizenship ice President, eview, Federal	ights, Directive Prime Minister, structure and	6
Go and Co Re	iciary and Constitution I overnor, Chief Minister, I other Subordinate Cour onstitution Functions: I elations, President's R nctionaries, Emergency dia.	Cabinet, State Legis ts, Parliamentary For Indian Federal Syst Rule, Constitutional	m of Governme em and it's c Amendments	ent in India. characteristics, and powers,	Center& State Constitutional	6
		Opinii	an Excellenc	* _A	Total	12
ISBN-10938 2. Clarendor Law", NBT, <b>Reference B</b> 1. <b>Dr J N P</b> a 2. <u>https://w</u>	s Basu, "Introduction to 8548868 a Press, Subhash C, Kash 5th edition, 2014, ISBN Books: andey : Constitutional I ww.meity.gov.in/divisio	nyap, "Our Constituti [-9781107034624 Law of India	on: An Introduc	tion to India's (	Constitution and co	

Value Education	M.Tech(All Branches)/MCA Semester: I					
				Code : M_1961E	<u>1961B</u>	
eaching Schem	e	<u> </u>	Evaluat	ion Scheme		
Hours	Credit	IE 1	IE 2	ETE	Total	
1	-					
students to Familitudent to unders tudent to unders tudents to under course the stude n awareness leve n attitudes / beha nal leadership an	ly Relations tand Creative Think stand Humanistic Ed nts should be able to els, knowledge and u iviour of students wi d other life skills	ing and Problem ducation.	student	proved teamwork,		
:	alth and attitude.	d	ollege o		Duration	
anding Behaviou ception, Attitude	r, Human Relations es, Self-Concept, N				6	
r Humanistic E	ducation, Humanist	ic Constitution a	nd Humanistic	Universal Order,	6	
	N/OWIEU	ge prings	(Leeuoli)	Total	12	
	1 and develop Att students to Fami student to unders students to under course the stude n awareness leve n attitudes / beha nal leadership an nent in social he <b>:</b> <b>:</b> <b>ption</b> man Relations a anding Behaviou ception, Attitude with Conflict, L n Humankind, N or Humanistic Educe	1     - and develop Attitude and Core Faith students to Family Relations student to understand Creative Think students to understand Humanistic Ed course the students should be able to n awareness levels, knowledge and u n attitudes / behaviour of students wi nal leadership and other life skills nent in social health and attitude.	1       -          and develop Attitude and Core Faith values       students to Family Relations       student to understand Creative Thinking and Problem         attudent to understand Creative Thinking and Problem       students to understand Humanistic Education.          course the students should be able to:       n       awareness levels, knowledge and understanding of so          n attitudes / behaviour of students with regards to their            nal leadership and other life skills            man Relations are so important?            anding Behaviour, Human Relations, and Performanception, Attitudes, Self-Concept, Natural acceptance with Conflict, Leading and Trust           n Humankind, Nurturing and Exploitation, Definitive or Humanistic Education, Humanistic Constitution a ence in professional ethics	1       -          and develop Attitude and Core Faith values         students to Family Relations         student to understand Creative Thinking and Problem solving         student to understand Creative Thinking and Problem solving         students to understand Creative Thinking and Problem solving         students to understand Creative Thinking and Problem solving         students to understand Humanistic Education.         course the students should be able to:         n awareness levels, knowledge and understanding of student         n attitudes / behaviour of students with regards to their education imp         nal leadership and other life skills         nent in social health and attitude.         g:         ption         uman Relations are so important?         anding Behaviour, Human Relations, and Performance, Personality, ception, Attitudes, Self-Concept, Natural acceptance of human va with Conflict, Leading and Trust         n Humankind, Nurturing and Exploitation, Definitiveness of Ethical or Humanistic Education, Humanistic Constitution and Humanistic ence in professional ethics	1       -           and develop Attitude and Core Faith values students to Family Relations tudents to Family Relations tudents to understand Creative Thinking and Problem solving students to understand Creative Thinking and Problem solving students to understand Humanistic Education.         course the students should be able to: n awareness levels, knowledge and understanding of student n attitudes / behaviour of students with regards to their education improved teamwork, nal leadership and other life skills ment in social health and attitude.         s:         ption         uman Relations are so important?         anding Behaviour, Human Relations, and Performance, Personality, Stress, Learning, ception, Attitudes, Self-Concept, Natural acceptance of human values, and Ethics, with Conflict, Leading and Trust         n Humankind, Nurturing and Exploitation, Definitiveness of Ethical Human Conduct, r Humanistic Education, Humanistic Constitution and Humanistic Universal Order, ence in professional ethics	

(2014).
 Atkinson and Hilgard's, "Introduction to psychology" Nolen-Hoeksema, S., Fredrickson, B. L., Loftus, G. R., & Lutz, C., Cengage Learning EME.

Progra	m	M.Tech(All Branches)	)/MCA			Semester: I	
Course	:	Stress Management				Code : M_1961C	
		Teaching Scheme			Eva	aluation Scheme	
Lect	ture	Hours	Credit	IE 1	IE 2	ETE	Total
1	l	1	-				
<b>Object</b> i 1. 2. 3. 4.	To ove To ach To lear	ercome stress ieve overall health of bo rn to achieve the highest come a person with stable	goal happily	onality and d	eterminatio	n	
1. Deve	ts will be lop heal	e able to: thy mind in a healthy bo king efficiency	dy thus improving so	ocial health al	SO		
Detaile	d Syllat	ous:	bou	10			
Unit	Descri	iption	hinchus		1000		Duration hr
1	Yam ar	ions of Eight parts of Yo nd Niyam. nd Don't's in life.	g. (Ashtanga )			E.	6
2.	Types of	am rization of breathing tech of pranayama ch to day to day work an		s-		neering	6
		~			-	Total	12
<b>Text B</b> 1. Y		anas for Group Tarining-	Part-I" : Janardan Sv				
Referen	nce Boo		13	11.111			
. K 2. W	olkata /endelin	vekananda, Rajayoga or Küpers, David J. Paulee Practice, 2016					

 A Foundation Course in Human Values and Professional Ethics Presenting a Universal Approach to Value Education - Through Self-exploration

Progran	1	M.Tech(All Branc	hes)/MCA			Semester: II	[	
Course:		Team Building & Leadership     Code: N					/I_2962A	
		Teaching Scheme			Evaluatio	n Scheme		
Lect	ure	Hours	Credit	IE 1	IE 2	ЕТЕ	Total	
1		1	-					
2. 3. Outcom After lea	Develop Become Familia	e and strengthen inter e familiar with and di rize students with the e course, the students Use leadership and To develop the capa	scuss different lea characteristics of s should be able to teamwork knowle	f team building.				
Detailed			acity to work cona		am			
Unit	Description						Duration h	
4.	using future What leader.	rship: Will and mo power responsibly a actions and transmit the word "leader" r Categories: autocra rial, etc.	nd respectfully: that vision to oth neans, Types of	the leader as a t ers. Taking the in leadership, Trad	eam-builder, A hitiative and stin itional, legal, a	bility to plan mulate others. nd legitimate	6	
2.	Advan Traditi within Strateg vs. pe	work s teamwork importa tages and disadvanta onal vs. virtuoso tea the organization. Cre gies to develop the to rsonal motivation. I pation. Creating team	ges of teamwork. ms, forming effec eating a friendly a cam's mission, vi Distinguishing pu	How to determine ctive and balanced nd collaborative e sion, values, and urpose and tasks	e roles in a team l teams, Strengt nvironment. objectives. Shar in the team.	thening teams red objectives	6	
	Total		Орни	төн Схоейст	8 <u>/</u>		12	
2. Ro 3. Mi	ephen Conald A. Chael E. Ce Book		vithout Easy Ansy Strategy, Free Pre	wers, Belknap Pre ess, 1980.				
2. Iku	jiro Nor	r, Leading Change: V naka, The Knowledge est, The Secrets of S	e-Creating Compa	ny	. 2, "Self-Mana	gement," pgs. 32	2-61	

Program		M.Tech(All Bran	nches)/MCA	Semester: II			
Course :		English For Research Paper Writing			Code : M_2962B		
Teachi	aching Scheme Evaluation Scheme					Scheme	
Leo	cture	Hours	Credit	IE1	IE2	ETE	Total
	1	1	-				
Objecti							
			ve your writing skills	and level of read	lability		
		it what to write in e	when writing a Title				
			per at very first-time s	submission			
Outcon		good quanty of par	ber at very mist time s	500111351011			
		course the students	s should be able to:				
	U						
2.	effective		eview article, thesis o	chapter and oth		enne researen u	CAI
D 4 11	10 11 1						
Detaile	d Syllabu	s:	hwad	1 00			Duration
Detaile Unit	d Syllabu	s:	Descri	ption	llego		Duration h
	Planning Structuri Redunda Clarifyir Criticizi Writing Conclus	g and Preparation, V ing Paragraphs and ancy, Avoiding Aml ng Who Did What, I ng, Paraphrasing an the Introduction, ions, The Final Che	Vord Order, Breaking Sentences, Being Cor biguity and Vaguenes Highlighting Your Fin ad Plagiarism, Section , Review of the eck.	up long sentence ncise and Remov ss, ndings, Hedging ss of a Paper, Abs Literature, Met	ing and stracts. hods, Results,	a construction	
Unit	Planning Structuri Redunda Clarifyir Criticizi Writing Conclus Key skil Discussi	g and Preparation, V ing Paragraphs and ancy, Avoiding Aml ng Who Did What, J ng, Paraphrasing an the Introduction, ions, The Final Che Is needed: Title, A	Word Order, Breaking Sentences, Being Con biguity and Vaguenes Highlighting Your Fin d Plagiarism, Section , Review of the eck. Abstract, Introduction, Iseful phrases, how to	up long sentence ncise and Remov ss, ndings, Hedging los of a Paper, Abs Literature, Met	ing and stracts. hods, Results, Literature, Meth	ods, Results,	h
Unit 1	Planning Structuri Redunda Clarifyir Criticizi Writing Conclus Key skil Discussi	and Preparation, V ing Paragraphs and ancy, Avoiding Aml ng Who Did What, J ng, Paraphrasing an the Introduction, ions, The Final Che Is needed: Title, A on, Conclusions, U	Word Order, Breaking Sentences, Being Con biguity and Vaguenes Highlighting Your Fin d Plagiarism, Section , Review of the eck. Abstract, Introduction, Iseful phrases, how to	up long sentence ncise and Remov ss, ndings, Hedging los of a Paper, Abs Literature, Met	ing and stracts. hods, Results, Literature, Meth	ods, Results,	<u>h</u> 6
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Course	rogram M.Tech(All Branches)/MCA			Semester: II					
Course : Disaster Management			Code : M_2962C						
	7	<b>Feaching Scheme</b>	Γ		Evaluation Scheme				
Lecture		Hours	Credit	IE-1	IE2	ETE	Total		
1 1 -									
<ol> <li>To te managem</li> <li>To prov</li> <li>Outcome</li> <li>After lear</li> <li>Learn</li> </ol>	nt enginee each the c ent. vide insigh s: ning the co different o	concept of Disast at about global, nat ourse the students disasters and meas	sures to reduce the ri	d measures to evel scenario of sk due to these of	disaster manag disasters.	gement.	es of disaste		
Detailed			disaster managemen	nt at national as	well as global	level.			
Unit	Description					Duration h			
1.	<b>Introduction</b> – Hazard and Disaster. Concepts of Hazard, Vulnerability, Risks. Different Types of Disaster : A) Natural Disaster: such as Flood, Cyclone, Earthquakes, Landslides etc B) Man-made Disaster: such as Fire, Industrial Pollution, Nuclear Disaster, Biological Disasters, Accidents (Air, Sea, Rail & Road), Structural failures(Building and Bridge), War & Terrorism etc. Slow Disasters (famine, draught, epidemics) and Rapid Onset Disasters(Air Crash, tidal waves, Tsunami) Causes, effects and practical examples for all disasters.					6			
2.	Volcanio Disaster Resettler coordina Disaster	c eruptions. Their Prevention and ment and Rehab ation during disaster Management : I saster Preparednes	uakes, Tsunami, Fle case studies. Coastal I Mitigation. Refu iilitation issues du ers, Models in Disas Role of Government as Role of Engineers	disasters. Coas gee operations ring and after ters. t, International a on Disaster Ma	tal regulation 2 during disaste disasters, In and NGO Bod nagement.	Zone. ers, Human nter-sectoral	6		
	"Knowledge Brings Freedom" Total								
<ol> <li>Pandey</li> <li>Tushar</li> </ol>	Bhattacha Singh, Dis	rya, Disaster Scier aster, Managemen	ement, Wiley India P nce and Managemen t: Future Challenges Laxmi Publications	it, McGraw Hill and Opportuni			d.		

- 4. Disaster Management Vinod K Sharma- IIPA, New Delhi, 1995
- 5. Encyclopedia of Disaster Management- Goel S.L. Deep and Deep Publications, New Delhi, 2006.

### VISION AND MISSION OF MECHANICAL DEPARTMENT

### Vision

• To recognize for an academic excellence through skill development, innovation fine blend with quality work culture

### Mission

• To impart quality education, innovation culture, necessary skill sets and social commitment among the students to build professional carrier by establishing state-of-the-art Mechanical Engineering infrastructure and conducive learning environment

### Programme outcomes:

- 1. An ability to independently carry out research /investigation and development work to solve practical problems
- 2. An ability to write and present a substantial technical report/document
- 3. Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program

### **Programme Specific Outcomes:**

"Knowledge Brings Freedom"

- 1. Students will be able to critically analyze / synthesize, simulate and optimize mechanical systems, components and processes by applying the principles of design engineering.
- 2. Student will be able to investigate and provide solutions to complex interdisciplinary problems using modern tools of design engineering.

# Higher Study Scope: Ph.D. Research Centre at PCCOE.





"There are no secrets to success. It is the result of preparation, hard work, learning from failure." - Colin Powell



Pimpri Chinchwad College of Engineering (PCCoE),

Pradhikaran, Nigdi, Pune – 411 044

M. Tech. Mechanical (Design Engineering), PCCoE Pune