Pimpri Chinchwad Education Trust's PIMPRI CHINCHWAD COLLEGE OF ENGINEERING SECTOR NO. 26, PRADHIKARAN, NIGDI, PUNE 411044

An Autonomous Institute Approved by AICTE and Affiliated to SPPU, Pune

DEPARTMENT OF MECHANICAL ENGINEERING



Curriculum Structure and Syllabus

of M. Tech. Mechanical Design Engineering (Approved by BoS Mechanical Engineering) (Course 2020)

"Knowledge Brings Freedom"



Effective from Academic Year 2020-21

Institute Vision

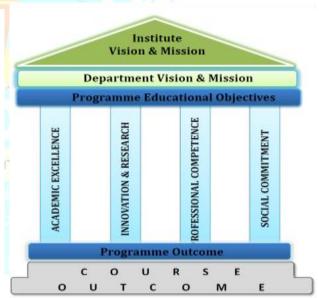
To Serve the Society, Industry and all the Stakeholders through the Value-Added Quality Education.

Institute Mission

To serve the needs of society at large by establishing State-of-the-Art Engineering, Management and Research Institute and impart attitude, knowledge and skills with quality education to develop individuals and teams with ability to think and analyze right values and self-reliance.

Quality Policy

We at PCCOE are committed to impart Value Added Quality Education to satisfy the applicable requirements, needs and expectations of the Students and Stakeholders. We shall strive for academic excellence. professional competence and social commitment in fine blend with innovation and research. We shall achieve this by establishing and strengthening state-ofthe-art Engineering and Management Institute through continual improvement in effective implementation of Quality Management System.



Index

Sr. No.		Content	Pg. No
1.		Abbreviations	4
2.		Curriculum Structure	5
	А	Professional Elective Courses	8
	В	Open Electives	8
	С	Audit Courses	8
3.		Course Syllabus (Semester-I)	9
4.		Course Syllabus (Semester-II)	31
5.		Course Syllabus (Semester-III)	49
6.		Course Syllabus (Semester-IV)	55
7.	/	Annexure-I Open Electives Syllabus	58
8.	16	Annexure-II Audit Courses Syllabus	95

PCCOE

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Progress Credibility Confidence Optimism Excellence

Since 1999

ABBREVIATION

Abbreviations	Course Full Name
PCC	Programme Core Course
PEC	Professional Elective Course
OEC#	Open Elective Course
PROJ	Project, Mini / Minor Projects, Integrated Projects
SEM	Seminar
INTR	Internship
LS	Life Skill
AUDIT*	Audit Course
МО	Massive Open Online Courses

Note: * Indicates that these courses are at institute level

The Course offered by other departments

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CURRICULUM STRUCTURE STRUCTURE FOR 1ST YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – I

M.Tech. Str	ucture	Sem-I	Tea	ching	g Sch	eme	Exam	ination (Scheme			
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ЕТЕ	TW	OR	Total
MMD1401	PCC	Research Methodology & IPR	3	-	3	3	20	30	50	-	-	100
MMD1402	PCC	Stress Analysis	3	-	3	3	20	30	50	-	-	100
MMD1403	PCC	Finite Element Method	3	<u>d</u>	3	3	20	30	50	-	-	100
MMD1404	PCC	Professional core Lab-I (SA, FEM)	-	2	2	1	-	-	-	50	50	100
MMD1405	PCC	Skill Development Lab - I (Software Skills)	-	2	2	1	-	-	-	50	-	50
MMD1501	PEC	Professional Elective-I	3	-	3	3	20	30	50	-	-	100
MMD1502	PEC	Professional Elective-II	3	-	3	3	20	30	50	-	-	100
MMD1503	PEC	Professional Elective Lab-I (PE I , PE II)	1	2	2	1	-	-	6013	50	50	100
**	OEC	Open Elective-I	2	-	2	2	20	-	30	-	-	50
M_1961	Audit	Audit course – I	1	-	1	-	-	-	-	-	-	-
		Total "Know	18	60	24	20	120	150	280	150	100	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam ** Course code of the selected open elective by student

STRUCTURE FOR 1ST YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER – II

M.Tech. Str	ucture	Sem-II	Tea	ching	g Sch	eme	Examination Scheme					
Course Code	Course Type	Course Name	L	Р	н	CR	IE1	IE2	ETE	тw	OR	Total
MMD2406	PCC	Optimization Techniques in Design	3	-	3	3	20	30	50	-	-	100
MMD2407	PCC	Advanced Vibrations and Acoustics	3	-	3	3	20	30	50	-	-	100
MMD2408	PCC	Professional core Lab- II (OT, AVA)	MO	2	2	10	oller	<u> </u>	-	50	50	100
MMD2504	PEC	Professional Elective- III	3	-	3	3	20	30	50	-	-	100
MMD2505	PEC	Professional Elective- IV	3		3	3	20	30	50	-	-	100
MMD2506	PEC	Professional Elective Lab-II (EL III, EL IV)	-	2	2	1	-	-	-	50	50	100
MMD2701	PROJ	Integrated Mini- Project	1	6	6	3	-	50	Cito (-	50	100
**	OEC	Open Elective –II	2	-	2	2	20	-	30	-	-	50
M_2101	HSMC	Skill Development Lab – II (Written & Oral Communication) M	led	2 ae	2 Bri	1 Das I	Freed	om"	-	50	-	50
M_2962	Audit	Audit course – II	1	-	1	-	-	-	-	-	-	-
		Total	15	12	27	20	100	170	230	150	150	800

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam ** Course code of the selected open elective by student

STRUCTURE FOR IIND YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-III

M. Tech. S	M. Tech. Structure Sem – III		Г	TEACH	HING	SCHE	ME	EXAM	INATIO	ON SCHEME		
Abbr	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ЕТЕ	TW	OR	TOTAL
MMD3702	PROJ	Dissertation Phase - I [Company/ In-house project]	-	20	20	10	-	100	-	-	100	200
MMD3703	SEM	Seminar	-	04	04	02	-	-	-	50	50	100
MMD3801	INTR	Internship [Company/ In-house project] /	-	04	04	02	-	50	-	-	50	100
				C)R							
MMD3981	MOOC	MOOC's / Entrepreneurship	E	04	04	02	-	50	-	-	50	100
		Total	-	28	28	14	-	150	-	50	200	400

*Internship: -It may be in summer/winter vacation or within semester at least for three months, evaluation after fourth semester

STRUCTURE FOR IIND YEAR M. TECH. MECHANICAL (DESIGN ENGINEERING) SEMESTER-IV

M. Tech.	M. Tech. Structure Sem – IV		TEACHING SCHEME			EXAMINATION SCHEME						
Abbr	Course Type	Courses	L	Р	Н	CR	IE1	IE2	ЕТЕ	TW	OR	TOTAL
MMD4704	PROJ	Dissertation Phase - II [Company/ In-house project]	-	24	24	12	-	200	-	-	200	400
MMD4982	MOOC	MOOC's	-	4	4	2	-	50	-	-	50	100
		Total	-	28	28	14	-	250	-	-	250	500

Abbr: Course Abbreviation; L- Lecture; P- Practical; H- Hours; CR- Credits; IE1 – Internal Evaluation-1; IE2 – Internal Evaluation-2; ETE – End Term Examination; TW – Term Work; OR – Oral Exam

2. A PROFESSIONAL ELECTIVE COURSES

	Elective-I		Elective-II
MMD1501A	Advanced Machine Design	MMD1502A	Mechanics of Composites
MMD1501B	Mechanical Behavior of Materials	MMD1502B	Tribology in Design
MMD1501C	Analysis and Synthesis of Mechanisms	MMD1502C	Vehicle Dynamics
MMD1501D	Mathematical Methods in Engineering	MMD1502D	Robotics

	Elective-III	Colle	Elective-IV
MMD2504A	Fatigue and Fracture Analysis	MMD2505A	Design of Material Handling Equipments
MMD2504B	Reliability in Engineering Design	MMD2505B	Computer Aided Design
MMD2504C	Mechatronics and Control Systems	MMD2505C	Multi-body Dynamics

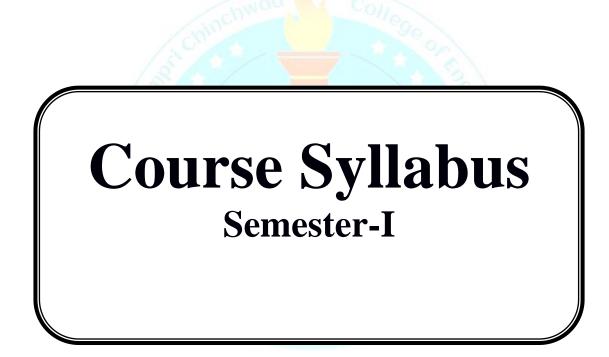
2. B OPEN ELECTIVES

OFFERED BY DESIGN ENGINEERING/ledge Brings Freedom"

	Open Elective – I Progress Cred		Open Elective –II
MMD1601A	Advanced Materials	MMD2602A	Room Acoustics
MMD1601B	Optimization Methods	MMD2602B	Design Thinking
MMD1601C	Modeling & Simulation of Dynamic Systems	MMD2602C	Reliability Engineering

2. C AUDIT COURSES (Common to all Programs)

	SEM-I		SEM-II
M_1961A	Constitution of India	M_2962A	Team Building & Leadership
M_1961B	Value Education	M_2962B	English for Research writing
M_1961C	Stress Management	M_2962C	Disaster Management



Program	n: M. 7	Fech. Mechanical	(Design Enginee	ering)	Semester	: I		
Course :	Res	earch Methodolog	gy and IPR	-	Code: M			
	Teac	hing Scheme/Wee	ek		Evaluat	ion Scheme		
Leo	ture	Credit	Hours	IE1	IE2	ETE	Total	
	3	3	3	20	30	50	100	
Pre-requ	isite: Proj	ect and seminars in	n undergraduate					
2. 3. 4. 5. 6. Outcome After lean 1. 2. 3. 4.	To select as To understa To make pro- To understa To learn th <u>To introdu</u> es: rning the co Define a re Examine d data. Analyze nu Develop a s	nd define appropri and statistical tech redictions and deci and the mathemati e various steps in r ce fundamental as purse, the students search problem an ata using different umerical data, usin mathematical mod	niques for the spe sions for the data cal modeling and research writing a pects of Intellectur should be able to d use appropriate t hypothesis tests g standard proced el and analyze the	cific perspectiv set using open- its predicting cand publication p al property Rig research methor and make con ures of probabi	e data in an appr source software apability. process hts dology clusions about a lity theory to pre	copriate manner.	ection of samp	
6.		earch paper and re neept note and prep		The second secon		22.		
	Descriptio	n (2 😒	1	1		3 6	Duration (Hrs)	
	Objectives Research M Definition of Hypothe	Problem and Reso , Motivation, Type Aethods versus Me and Feasibility stu esis, Characteristic research design	es of Research, Re ethodology, Criter ady of research pr	ia of Good Rest oblem, Sources Errors in selection	earch s of research pro ng a research pro	blem, Meaning oblem, Concept	6	
	Applied St		KI/Owieug	ge brings	rreedon/			
	Measures of Inferential	of Variability: Stan Statistics: Statistic VA (Analysis of va	cal Significance (-	-	6	
5.	Distributio	Types of Sampl n, Normal Distribu	ution, Case Study	: Develop a mo			6	
	Making for the data set using open-source software Mathematical Modeling and prediction of performance Types of Modeling, Types of solutions to mathematical models, Steps in Setting up a computer model to predict performance of experimental system, Validation of results, Multi-scale modeling and verifying performance of process system, Nonlinear analysis of system and asymptotic analysis, Sensitivity analysis.							
	Research Report writing and Publication Research Report: Dissemination of research findings, outline and structure of research report, different steps and precautions while writing research report, methods and significance of referencing. Publishing Research work: Selection of suitable journal for publishing research work, Open access Vs Subscription Journals, Identifying indexing of selected journals, Impact factor of the journal, structure of research paper, Check for plagiarism of the article, Research paper							

6	Intellectual property Rights	
	Definition of IPR, Classification of IP, Patentable and non-patentable inventions, statutory exceptions, Persons entitled to apply for patents.	6
	Prior Art Search, Patentability Criteria, Patent Filing Procedure, Forms and Fees, Case Study of Patent, Copyright.	
	Total	36

Textbooks:

- 1. C. R. Kothari, Research Methodology: Methods and Techniques, New Age International, 2nd Edition, 1985
- 2. Ranjit Kumar, Research Methodology: A Step-by-Step Guide for Beginners, 2nd Edition.,2010.
- 3. Ramakrishna B and Anil Kumar H S., Fundamentals of IPR, Notion Press, 2016
- 4. Virendra Kumar Ahuja, IPR in India, LexisNexis Butterworths Wadhwa Nagpur, 2017

Reference Books:

- 1. Stuart Melville and Wayne Goddard, Research methodology: An Introduction for Science & Engineering students
- 2. S.D. Sharma, Operational Research, Kadar Nath Ram Nath & Co.
- 3. Wayne Goddard and Stuart Melville, Research Methodology: An Introduction, Juta and Company Ltd, 2004

IE Activities:

- 1. Write a review paper based on detailed literature survey and cheque for plagiarism.
- 2. Write a research proposal on your domain specific research problem.
- 3. Write a concept note and prepare to file an IP

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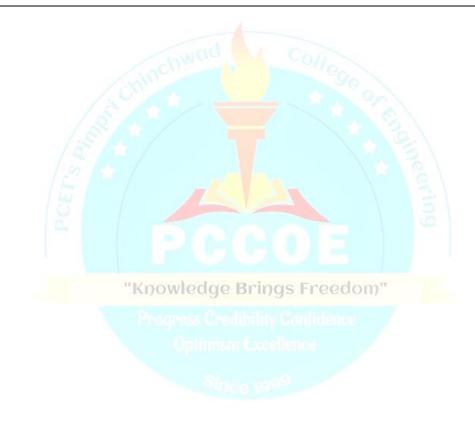
Progress Credibility Confidence

Optimism Excellence

Program	n: M. T	ech. Mechanical	(Design Enginee	ring)	Semester		
Course :		ss Analysis		I	Code: M		
	Те	aching Scheme	r		Evaluati	on Scheme	
Leo	ture	Credit	Hours	IE1	IE2	ЕТЕ	Total
	3	3	3	20	30	50	100
		gth of Materials, l	Machine Design				
Outcom	1. To und 2. To und 3. To solv 4. To eval es:	erstand different a re thin section mer luate stresses, defl	se stress and strain approaches to obta mbers for bending ection due to line	in stresses, strai and torsion. or point contact	ins and deformat		the solids.
1. 2. 3. 4. 5. 6.	Formulate a relationship Formulate a Apply Ener Analyse and Analyse and Understand technique a	and Analyse Stress and Analyse Stress gy methods to eva d Determine the T d estimate contact	should be able to: ss Field equations ses in pressurised aluate stresses and orsion and Bendir stresses in confor ethods for stress technique.	s such as equil cylinder and rot strains, ng of thin wall s ming and non-c	ating disc. ection onforming shap	es.	
	Syllabus:	15 1	1			3	
Unit	Descriptio					101	Duration, h
1.	-	Stresses and Ana	lysis of Strain. Str stress functions ir				6
2.	Governing shrink fit co	-	Rotating Disks, n thick walled cyl s, stresses in rotati "Knowledg	ing flat solid dis	sk, flat disk with	central hole,	6
3.		thod for analysis	of stress, strain a Castiglioni's theo		heorem's - theo	orem of virtual	4
	Walled Sec Concept of	thin walled memb tions shear centre in s	ers of open cross s symmetrical and a section with one	unsymmetrical	bending, Shear		6
	Contact str				-		
5.	Geometry of in point colload normal	of contact surfaces ntact, Stress for t l and tangent to co	s, method of comp wo bodies inline ontact area, , contacts betweer	contact with lo	ad normal to co	ontact area and	7
6.	Experiment Dimensiona configuration elasticity, e	tal stress analysi al analysis, analysi on, instrumentatio lements of polaris		ain gauges, typ of strain gauge circular polaris	bes of strain gau measurement, th cope, fringes in	ges, materials, leory of photo- dark and white	7
	Total						36

- 1. Theory of Elasticity-Timoshenko and Goodier, McGrawHill
- 2. Advanced Strength and Applied Stress Analysis-Richard G. Budynas, McGrawHill
- 3. Advanced Mechanics of Materials–Boresi, Schmidt, Sidebottom, Willey

- 1. Advanced Mechanics of Materials- Cook and Young, Prentice Hall
- 2. Advanced Mechanics of Solids, L S Shrinath, Tata McGrawHill
- 3. Advanced Strength of Materials, Vol.1, 2–Timoshenko, CBS
- 4. Advanced Strength of Materials–Den Hartog
- 5. Experimental Stress Analysis–Dally & Riley
- 6. Mechanics of Materials E J Hern, Buttorwoth
- 7. Strength of Materials, Singer Andrue Pytel, Pearson



		hanical (Design I	Engineering)	Semester			
Course :					Code: MMD1403		
	Teaching Se	cheme		Evaluat	ion Scheme		
Lectu	ire Cre	dit Hou	ırs IE1	IE2	ETE	Total	
3	3	3	20	30	50	100	
Pre-requis		atics, Machine De	sign, Strength of Mate	erial			
Objectives		,					
ar 2. To ar 3. It 4. To 5. It Dutcomes	d thermal analysis o familiarize studen id to introduce relat provides a bridge b imerical solutions for o study approximate provides some expo ing the course, the s	problems. ts with the displace ed analytical and c etween hand calcu- or more complex g e nature of the fini- erience with a com- students should be	alations based on mech geometries and loading te element method and inmercial FEM code an	ement method for nanics of material g states. d convergence of d some practical	displacement and s and machine de results are examin modeling exercise	l stress analysi sign and ned. es	
2. 2 3. 2 4. 2 5. 2	Student will be able Mindlin plate eleme Student will be able Student will be able vectors	to create and solv nt theory to Evaluate non li	netric Elements and For re the governing equation inear problems related solve the dynamic pro	ions for plates usit	ing Kirchoff theorem terial and contact.	ory and	
Detailed S Unit I	Description					Duration, h	
O F fc m	ne dimensional pr nite element meth		hasic steps advanta			Durution, i	
be el pr re	ethod of Weighted ariational formulat eam) – governing ement connectivity occessing of the rest finements, Node N	nal methods of Residuals. ion of 1D bar an equation, domain y, application of ults. Automatic me umbering scheme	approximation – Ra nd beam elements (E n discretization, elem boundary condition esh generation techniq	ayleigh-Ritz met uler Bernoulli an nental equations, n, solution of e	hods, Galerkin nd Timoshenko assembly and quations, post-	6	
2 fu bu el pre T Ir li fu pre n re	ethod of Weighted ariational formulat eam) – governing ement connectivity occessing of the resu- finements, Node N wo Dimensional Is troduction, types of hear & quadratic, unction, polynomia arameters, strain-no atrix, convergence	nal methods of Residuals. ion of 1D bar an equation, domain y, application of ults. Automatic me umbering scheme operimetric Form of 2D elements ((displacement fun l displacement fun dal parameter rel e of isoparametri	approximation – Ra nd beam elements (E n discretization, elem boundary condition esh generation techniq	ayleigh-Ritz met uler Bernoulli an nental equations, a, solution of e jues, Mesh qualit oparametric), sha the choice of th nt function in t n relationship, el	hods, Galerkin nd Timoshenko assembly and quations, post- y checks, h & p pe functions – e displacement erms of nodal ement stiffness	6	
2 fr 3 Is 2 fr 1 Is 3 Is 1	ethod of Weighted ariational formulat eam) – governing ement connectivity rocessing of the resis finements, Node N wo Dimensional Is troduction, types of hear & quadratic, inction, polynomia arameters, strain-no atrix, convergence roblems – plane stree oparametric Form oparametric formu oparametric Elemo umerical Integratio	onal methods of Residuals. ion of 1D bar an equation, domain y, application of ults. Automatic me <u>umbering scheme</u> operimetric Forn of 2D elements (0 displacement fun 1 displacement fun 1 displacement fun 2 displacement fun 1 displacement fun 2 displacement f	approximation – Ra ad beam elements (E n discretization, elem boundary condition esh generation techniq nulation CST, LST, QST, Isa action – criteria for t unctions, displacement lationship, stress-strain ic elements, rate of	ayleigh-Ritz met uler Bernoulli an nental equations, a, solution of e jues, Mesh qualit oparametric), sha the choice of th nt function in t n relationship, el convergence, j ms rametric , Super e, Newton-Cotes	hods, Galerkin nd Timoshenko assembly and quations, post- y checks, h & p pe functions – e displacement erms of nodal ement stiffness plane elasticity parametric and Formula, Gauss		

5	Non-Linear Analysis Introduction to non-linear analysis, formulation for geometrical, material and contact nonlinear problems, Nonlinear equation solving procedure - direct iteration, Newton- Raphson method, modified Newton-Raphson method, incremental techniques	6
6	Dynamic Problems – Eigen value and Time Dependent Problems Formulation of dynamic problems, consistent and lumped mass matrices Solution of eigenvalue problems – transformation methods, Jacobi method, Vector Iteration methods, subspace iteration method [Theoretical Treatment] Forced vibration – steady state and transient vibration analysis, modeling of damping, the mode superpresentation exheme direct integration methods.	6
	mode superposition scheme, direct integration methods - implicit and explicit numerical	
	integration	
	Total	36
Text B	ooks:	
	1. Seshu P., "Text book of Finite Element Analysis", PHI Learning Private Ltd., New Delhi, 20	010.
	2. Logan D, "First course in the Finite Element Method" Cengage Learning, 2012	
Refere		
	 Bathe K. J., "Finite Element Procedures", Prentice-Hall of India (P) Ltd., New Delhi. Cook R. D., "Finite Element Modeling for Stress Analysis", John Wiley and Sons Inc, 1995 Chandrupatla T. R. and Belegunda A. D., "Introduction to Finite Elements in Engineerin Hall India. Liu G. R. and Quek S. S. "The Finite Element Method – A Practical Course", Butterworth- 2003. Reddy, J. N., "An Introduction to The Finite Element Method", Tata McGraw Hill, 2003. 	g", Prentice



Program:	M. Tech. Mecha	anical (Design En		Semester : I		
Course :	Professional Co LAB Name : SA		Code: MMD1404	4		
	Teaching Scheme			Eval	uation Scheme	
Practical			TW	TW PR OR Tot		
2	2	1	50		50	100
Guidelines : 1. Total	l experiments to be cond	ducted are Three	from Part A and	l Three from	Part B	

2. Total : 6 experiments 12 hours

Pre-requisite: Engineering Design, Strength of materials

Objectives:

This course is to provide students the tools required for Simulate, correlate and validate theoretical concepts and understand the basic principles.

Outcomes:

. . . .

After learning the course the students should be able to:

- 1. Simulate the problem and correlate with theoretical concepts
- 2. Understand the impact of assumptions on the simulated results
- 3. Obtain stresses and strains using experimental methods of stress analysis
- 4. Apply strain gauges at appropriate locations, collect data, analyse, interpret results.

	Part A: Stress Ana	lysis (ANY Three)	
Expt.	Description		Duration
1.	Analytical and Numerical Evaluation of Stresses for theoretical model developed for solution	r plate with hole and correlate with	2
2.	Contact stress analysis using FEM software and condeveloped for solution.	relate with theoretical model	2
3.	Shear Centre location for thin section beam.(Box, 1	L-section, C-section)	2
4.	Stain gauge mounting and Measurement of strain in	n cantilever beam using strain gauges	2
5.	Calibration of Photoelastic materials	Acellence	2
6.	Evaluation of Stresses using Polariscope	1999	2
	Total (Any Three)	6

Pre-requisite: Engineering Mathematics Machine Design, Strength of Material

Objectives:

- 1. To impart the philosophy and general procedure of Finite Element Method simulations as applied to solid mechanics and thermal analysis problems.
- 2. To describe and interpret Numerical solutions for more complex geometries and loading states.
- 3. To study approximate nature of the finite element method and convergence of results are examined.
- 4. Adequately describes a physical event and establishing or validating a relationship between obtained results and underlying physical principles.

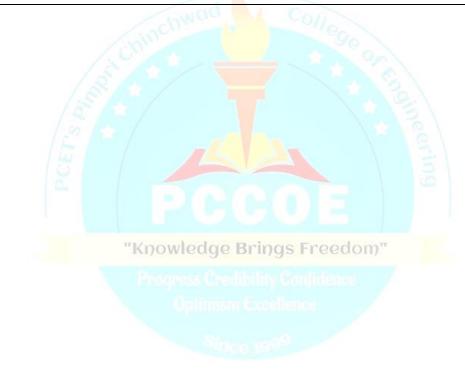
Outcomes:

After learning the course the students should be able to:

- 1. Apply General procedure and philosophy of finite element method to simulate complex engineering problems
- 2. Evaluate linear and non linear problems related to geometry, material and contact.
- **3.** Understand and apply elements, mess sensitivity analysis and convergence study to real life problems.

Detailed	Syllabus: Part B: Finite Element Method (ANY Three)	
Expt.	Description	Duration
1.	Stress analysis of 1D bar using linear and quadratic elements. Show the variation of stress and strain within the element for linear and quadratic bar element (Convergence Study)	2
2.	Modal analysis and stress analysis for 1-D beam (simply supported or cantilever beams) (Convergence Study)	2
3.	Static stress concentration factor calculation for a plate with center hole subjected to axial loading in tension using FEA software (Convergence Study)	2
4.	Stress, Strain and deflection analysis of any machine component consisting of 3-D elements using FEA software. (Convergence Study)	2
	Total (Any Three)	6
Text Boo		
	Advanced Strength and Applied Stress Analysis–Richard G. Budynas, McGrawHill	
2.	Seshu P., "Text book of Finite Element Analysis", PHI Learning Private Ltd., New Delhi, 2010.	
Reference	e Books:	
1. ′	Theory of Elasticity–Timoshenko and Goodier, McGrawHill	
_		

2. Cook R. D., "Finite Element Modeling for Stress Analysis", John Wiley and Sons Inc, 1995



Department of Mechanical Engineering

Program	M. Tech. Mech	anical (Design Eng	gineering)		Semester: I	
Course :	LAB Name : Sk	till Development L	ab-I	С	ode : MMD1405	5
	Teaching Scheme			Evalua	ation Scheme	
Practical	Hours	Credit	TW	PR	OR	Total
2	2	1	50			50
Pre-requisite:						
Objectives:						
To pr	ovide students with eering problems with				ods and the skills	required to analyz
Outcomes:	01	<u>_</u>				
After learning	the course, the stude	nts with the aid of	commercial FEA	software's sho	ould be able to per	rform:
		2				
	tatic and dynamic lir					
	posite and fatigue and near dynamic analys			I		
	hape and topological			mpopont		
4. 1110 S	hape and topological	opunitzation for a	il elignicering co	Inponent		
Detailed Sylla	bus:	-chw		0110		
List of Experin	ments/ Assignments:	(phi		90		
		64 611 3				
Each student s	hall complete any F	our of the following	g assignments, w	ith assignment	I compulsory.	
1. Detern	nine static and dyna	amic linear respon	se of a 3-dimen	sional enginee	ring component	subjected to variou
	nation of loads	/ 2 / · · · ·			8	j
2. Invest	igate effect of variou	is parameters (no. c	of lay-ups and fib	er orientation)	on laminated con	nposite structures
3. Perfor	m fatigue analysis u	sing stress and strai	n life approach o	o <mark>f a</mark> n engineerir	ng component	
4. Detern	nine frequency/Tran	sient/Random resp	onse for member	s subjected to f	orced vibration	
	m nonlinear dynam				l to material non	nlinearity/Geometri
	earity/Contact Nonli		mpact/Crash/Sho	ock problems		
6. Perfor	m topological/Shape	optimization				
Students con m	orform obout accien	manta vaina anv of	the software may	ntioned helowy		
	erform above assign US, 3D Experience,				n)"	
•			A M. to. A	Second Second		
Text Books:						
	Finite Element Meth	od and Applicatio	ns in Engineerir	ng Using ANS	YS® by Madend	ci, Erdogan, Guvei
	im (Springer)	inita Elamant Arral	voia" DLUI Las	ing Drivets I +1	Now Dalk: 201	0
	P., "Text book of F					
	opadhyay M and Sh .td., 2009.	сікіі А. п., Matrix	and rinne Elem	ient Analyses c	or structures , An	C DOOKS
	S Gokhale "Practic		1	· · · · D		

- 4. Nitin S. Gokhale, "Practical Finite Element Analysis", Finite to infinite, Pune
- 5. Ever J. Barbero," Finite element analysis of composite materials using Abaqus", CRC Press taylor Francis group.

Program:						
Course :	Advanced Machine	Design (Elective)			IMD1501A	
	Teaching Scheme			Evaluati	ion Scheme	_
Lectur	Lecture Credit Hours IE1 IE2 ETE					Total
3	50	100				
Pre-requisit		•		•		
	anced Stress Analysis, E	ngineering Design	n, Manufacturing	g Processes		
Objectives:						
	nake aware the students				1.1	
	enable the students to ide After learning the course,			engineering pro	oblems.	
	lents will realize that cre			v maintainahili	tx7	
	tions, reliability are also					esses in the
	ly competitive, dynamic			than mang an	inclusions and su	
	lents will demonstrate th			stomer and con	vert them into te	echnical
	rifications of a product.		,			
	lents will be able to gene	erate different idea	s after identifvin	g the need and o	determining the	specifications
	constraints of a product					
and	constraints of a product a lents will understand the	for a particular pu	rpos <mark>e.</mark>		assembly, emoti	ions and
and 4. Stud mai	lents will understand the ntenance.	for a particular pur principals used wi	rpos <mark>e.</mark> hile designing fo	or manufacture, a	-	
and 4. Stud mai 5. Stud	lents will understand the ntenance. lents will know various r	for a particular pun principals used wh nethods of rapid p	rpose. hile designing for rototyping the pr	or manufacture, a	nd modify the d	
and 4. Stud mai 5. Stud 6. Stud	lents will understand the ntenance. lents will know various r lents will be able to desig	for a particular pun principals used wh nethods of rapid p	rpose. hile designing for rototyping the pr	or manufacture, a	nd modify the d	
and 4. Stud mai 5. Stud 6. Stud Detailed Syl	lents will understand the ntenance. lents will know various r lents will be able to desig labus:	for a particular pun principals used wh nethods of rapid p	rpose. hile designing for rototyping the pr	or manufacture, a	nd modify the d	esigns.
and 4. Stua mai 5. Stua 6. Stua Detailed Syl Unit De	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription	for a particular pur principals used wh nethods of rapid p gn the components	rpose. hile designing for rototyping the pro- s considering stree	or manufacture, a roducts to test a ength based relia	nd modify the d	
and 4. Stud mai 5. Stud 6. Stud 0. Stud 0. Detailed Syl 0. Detailed Syl 1. Detailed Syl	lents will understand the ntenance. lents will know various r lents will be able to designabus: scription relopment processes and	for a particular pun principals used wh nethods of rapid p gn the components d organizations, H	rpose. hile designing for rototyping the pro- s considering stree Product Plannin	or manufacture, a roducts to test as ength based relia	nd modify the d	esigns. Duration, h
and 4. Stud mai 5. Stud 6. Stud 0. Stud 0. Stud 0. Detailed Syl 0. Detailed Syl 0. Detailed Syl 0. Intr	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering	for a particular pun principals used wh nethods of rapid p gn the components d organizations, H design, Product de	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proc	or manufacture, a roducts to test at ength based relia eg ess, Product and	nd modify the d ability	esigns.
and 4. Stud mai 5. Stud 6. Stud 6. Stud Detailed Syl Unit Dev 1. Dev Intr cyc	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering les, organization for desig	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product dev	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techr	or manufacture, a roducts to test a ength based relia ng ess, Product and nological innova	nd modify the d ability	esigns. Duration, h
A. Stua mai 5. Stua 6. Stua 6. Stua Detailed Syl Unit Dev 1. Dev Intr cyc 2. Nee	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering les, organization for desig d Identification and prob	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product de plem definition, pro	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proch velopment, techr oduct specificati	or manufacture, a roducts to test a ength based relia ng ess, Product and nological innova	nd modify the d ability	esigns. Duration, h
A. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev Intr cyc 2. Nee and	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering les, organization for desi d Identification and prob selection, evaluation, cre	for a particular pur principals used wh methods of rapid p gn the components d organizations, H design, Product de gn and product de plem definition, pre eativity methods, C	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techro oduct specificati Concept testing	or manufacture, a roducts to test an ength based relia g ess, Product and nological innova on, concept gen	nd modify the d ability	esigns. Duration, h
A. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev 1. Dev 2. Nee and Iden	lents will understand the ntenance. lents will know various r lents will be able to designate labus: scription relopment processes and oduction to engineering les, organization for designate d Identification and prot- selection, evaluation, cro- ntifying customer needs,	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product de blem definition, pre eativity methods, C requirements, esta	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification Concept testing blishing the eng	or manufacture, a roducts to test an ength based relia g ess, Product and nological innova on, concept gen	nd modify the d ability	esigns. Duration, h 6
A. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev 1. Dev 2. Nee and Ideu qua	lents will understand the ntenance. lents will know various r lents will be able to designabus: scription relopment processes and oduction to engineering les, organization for designable d Identification and prot selection, evaluation, cro ntifying customer needs, lity function deployment	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification concept testing iblishing the eng- pecification	or manufacture, a roducts to test an ength based relia ag ess, Product and nological innova on, concept gen ineering charact	nd modify the d ability	esigns. Duration, h 6 6
A. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev 1. Dev 2. Nee and Ideu qua	lents will understand the ntenance. lents will know various r lents will be able to designate labus: scription relopment processes and oduction to engineering les, organization for designate d Identification and prot- selection, evaluation, cro- ntifying customer needs,	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification concept testing iblishing the eng- pecification	or manufacture, a roducts to test an ength based relia ag ess, Product and nological innova on, concept gen ineering charact	nd modify the d ability	esigns. Duration, h 6
A. Stue mai 5. Stue 6. Stue Detailed Syl Unit Detailed 1. Dev 1. Dev 1. Intr cycc 2. Nee and Ider qua 3. Des	lents will understand the ntenance. lents will know various r lents will be able to designabus: scription relopment processes and oduction to engineering les, organization for designable d Identification and prot selection, evaluation, cro ntifying customer needs, lity function deployment	for a particular pur principals used wh nethods of rapid p gn the components d organizations, H design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce velopment, techno oduct specification Concept testing iblishing the engo pecification ce, casting, forgin	or manufacture, a roducts to test an ength based relia ong ess, Product and nological innova on, concept gen ineering charact	nd modify the d ability	esigns. Duration, h 6 6 6
4. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev 1. Dev 2. Nea and Iden qua 3. Des 4. Des des	lents will understand the ntenance. lents will know various r lents will be able to design labus: scription relopment processes and oduction to engineering les, organization for desi d Identification and prot selection, evaluation, cro ntifying customer needs, lity function deployment ign for manufacture, asso ign for Reliability, streng gn	for a particular pur principals used wh methods of rapid p gn the components d organizations, F design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance gth based reliabilit	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification concept testing iblishing the engo pecification ce, casting, forgi y, parallel and se	or manufacture, a roducts to test an ength based relia ng ess, Product and nological innova on, concept gen ineering charact ng eries systems, ro	nd modify the d ability	esigns. Duration, h 6 6
4. Stua mai 5. Stua 6. Stua Detailed Syl Unit Det 1. Dev 1. Dev 2. Nea and Iden qua 3. Des des	lents will understand the ntenance. lents will know various r lents will be able to desig labus: scription relopment processes and oduction to engineering les, organization for desi d Identification and prot selection, evaluation, cro ntifying customer needs, lity function deployment ign for Reliability, streng	for a particular pur principals used wh methods of rapid p gn the components d organizations, F design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance gth based reliabilit	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification concept testing iblishing the engo pecification ce, casting, forgi y, parallel and se	or manufacture, a roducts to test an ength based relia ng ess, Product and nological innova on, concept gen ineering charact ng eries systems, ro	nd modify the d ability	esigns. Duration, h 6 6 6 6 6
and Stue mai5.Stue G.6.StueDetailed SylUnitUnitDev Intr cyc1.Dev Intr cyc2.Nee and Ider qua3.Des des4.Des des5.Des	lents will understand the ntenance. lents will know various r lents will be able to design labus: scription relopment processes and oduction to engineering les, organization for desi d Identification and prot selection, evaluation, cro ntifying customer needs, lity function deployment ign for manufacture, asso ign for Reliability, streng gn	for a particular pur principals used wh methods of rapid p gn the components d organizations, F design, Product de gn and product de plem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance gth based reliabilit	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification concept testing iblishing the engo pecification ce, casting, forgi y, parallel and se	or manufacture, a roducts to test an ength based relia ng ess, Product and nological innova on, concept gen ineering charact ng eries systems, ro	nd modify the d ability	esigns. Duration, h 6 6 6
and Stue mai5.Stue detailed6.Stue StueDetailedSylUnitDetailed1.Detailed2.Nee and Ider qua3.Des des4.Des des5.Des and 6.	lents will understand the ntenance. lents will know various r lents will be able to designate labus: scription relopment processes and oduction to engineering des, organization for designation des, organization for des, organization des, organization for des, organization for des, organization des, organization for des, organization des,	for a particular pur principals used wh methods of rapid p gn the components d organizations, H design, Product des gn and product des olem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance gth based reliabilit sign for reuse, Des	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification Concept testing blishing the eng- pecification ce, casting, forgi- y, parallel and so- ign for Environn	or manufacture, a roducts to test an ength based relia ag ess, Product and nological innova on, concept gen ineering charact ng eries systems, ro nent and Design	nd modify the d ability	esigns. Duration, h 6 6 6 6 6 6 6 6
and Stue mai5.Stue detailed6.Stue StueDetailedSylUnitDetailed1.Detailed2.Nee and Ider qua3.Des des4.Des des5.Des and 6.	lents will understand the ntenance. lents will know various r lents will be able to designate labus: scription relopment processes and oduction to engineering les, organization for designation designation of Identification and proti- selection, evaluation, creatifying customer needs, lity function deployment ign for Reliability, streng gn ign of dis-assembly, Des- Design for Quality	for a particular pur principals used wh methods of rapid p gn the components d organizations, H design, Product des gn and product des olem definition, pre eativity methods, C requirements, esta , product design sp embly, maintenance gth based reliabilit sign for reuse, Des	rpose. hile designing for rototyping the pro- s considering stree Product Plannin evelopment proce- velopment, techno oduct specification Concept testing blishing the eng- pecification ce, casting, forgi- y, parallel and so- ign for Environn	or manufacture, a roducts to test an ength based relia ag ess, Product and nological innova on, concept gen ineering charact ng eries systems, ro nent and Design	nd modify the d ability	esigns. Duration, h 6 6 6 6 6
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1. George E Dieter, "Engineering Design", McGraw Hill Company, 2000.

- Prashant Kumar, "Product Design, Creativity, Concepts and Usability", Eastern Economy Edition, PHI New Delhi. 2012
- 2. Woodson T.T., "Introduction to Engineering Design", McGraw Hill Book Company, 1966.
- 3. John J.C. "Design Methods", Wiley Inter science, 1970.
- 4. Averill M. Law and W. David Kelton "Simulation, modelling and analysis", McGraw Hill Book Company, 1991.
- 5. Pahl, G.andW.Beitz, Engineering Design–A Systematic Approach Springer, 2nd Ed., 1996.
- 6. Product Design and Development Karl T. Ulrich, Steven Eppinger

Program:	M. Tech. Mechanical (Design Engineering) Semester: I			Ι		
Course	Mechanical Behaviour of Materials (Elective)Code : MMD1501B			MD1501B		
	Teaching Scheme			Evaluat	ion Scheme	
.				11.4		
Lectur	e Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisit		c i 1				
Ma Objectives:	erial science, Mechanics of	t materials				
v	explore the modern materia	ls with their ann	lications			
	provide an ability to identif			complex loadi	nσ	
	nake students able to inter	• •		-	-	
	After learning the course, the					
	apply the mechanics of mo			ing applications		
	solve the basics problems of		-	~		conditions
	study material behavior und				1 0	
4. To	dentify and investigate eng	gineering problem	ns involving pla	stic deformation		
	ealize the plastic and elasti	1			0	
	formulate the mathematical	modelling of V	isco <mark>-Elast</mark> ic mate	erials and apply	to engineering	g materials for
beh	avioural study					
		Doto	ilad Syllaburg	0,		
Unit D	escription	Deta	iled Syllabus		0	Duration, h
	odern Materials in Desig	n Engineering			2	Duration, II
	ual phase alloy, HSLA, lig		rous alloy and th	eir full range s	tress strain	
	haviour subjected quasi-	-		-		06
	thotropic properties, Plasti	-		•		
	id its properties			inais of post, a	ppirounous	
	esponse of metals and allo	ovs under appli	ed loading		0	
	ress, strain transformations			ity, Anisotropic	elasticity,	0.6
	nisotropic thermal expansi		-			06
	ield curve.					
3. T	ensile testin <mark>g</mark>	"Knowledg	ae Brings	Freedom'	19 -	
U	ni-axial and biaxial tension	on test, Full ran	ge stress-strain	curves, True st	tress-strain	07
C	rve, Bridgman correction,	Temperature ris	se, Bauschinger	effect, Combine	ed bending	06
	d torsion test, Three points					
	ress- Strain relations for		•	88 / I		
	xperimental studies of plas		-	-	-	06
	rdening, Power law appro					00
n	odels, Theory of plastic flo		nd temperature d	ependence of fl	ow stress	
	astic and Elastic-Plastic l	Behaviour				
5. P						
5. P D	eformation theory of plast	• •	•			
5. P D d	formations. Equations of	Elastic-Plastic E	Equilibrium, Res	idual stresses a	nd strains,	06
5. P D d P	formations. Equations of astic-rigid body, Elastic-H	Elastic-Plastic E	Equilibrium, Res	idual stresses a	nd strains,	06
5. P D d P v	formations. Equations of astic-rigid body, Elastic-H riable loading	Elastic-Plastic E	Equilibrium, Res	idual stresses a	nd strains,	06
5. P D d P v 6. E	formations. Equations of astic-rigid body, Elastic-H riable loading asto-Visco-Plasticity	Elastic-Plastic E Plastic bending	Equilibrium, Res and torsion, Ela	idual stresses a astic-Plastic bo	nd strains, dies under	06
5. P D d P v 6. E	formations. Equations of astic-rigid body, Elastic-I riable loading asto-Visco-Plasticity isco-elasticity, Rheologica	Elastic-Plastic E Plastic bending 1 models, Maxv	Equilibrium, Res and torsion, Ela vell model, Voig	idual stresses a astic-Plastic bo gt model, Voig	nd strains, dies under t–Maxwell	06
5. P D d P v 6. E V n	formations. Equations of astic-rigid body, Elastic-H riable loading asto-Visco-Plasticity isco-elasticity, Rheologica odel, Natural decay, Dep	Elastic-Plastic E Plastic bending 1 models, Maxw endence of dam	Equilibrium, Res and torsion, Ela vell model, Voig pping and elastic	idual stresses a astic-Plastic bo gt model, Voig c modulus on	nd strains, dies under t–Maxwell frequency,	
5. P D d P v 6. E V m T	eformations. Equations of astic-rigid body, Elastic-H riable loading asto-Visco-Plasticity isco-elasticity, Rheologica odel, Natural decay, Dep nermo-Elastic effect, Lo	Elastic-Plastic E Plastic bending 1 models, Maxv endence of dam ow temperature	Equilibrium, Res and torsion, Ela well model, Voig aping and elastic and high te	idual stresses a astic-Plastic bo gt model, Voig c modulus on emperature Vi	nd strains, dies under t–Maxwell frequency, sco-plastic	06
5. P D d P v 6. E V n T d	formations. Equations of astic-rigid body, Elastic-H riable loading asto-Visco-Plasticity isco-elasticity, Rheologica odel, Natural decay, Dep nermo-Elastic effect, Lo formation models, Rubb	Elastic-Plastic E Plastic bending 1 models, Maxv endence of dam ow temperature	Equilibrium, Res and torsion, Ela well model, Voig aping and elastic and high te	idual stresses a astic-Plastic bo gt model, Voig c modulus on emperature Vi	nd strains, dies under t–Maxwell frequency, sco-plastic	
5. P D d P v 6. E V n T d	eformations. Equations of astic-rigid body, Elastic-H riable loading asto-Visco-Plasticity isco-elasticity, Rheologica odel, Natural decay, Dep nermo-Elastic effect, Lo	Elastic-Plastic E Plastic bending 1 models, Maxv endence of dam ow temperature	Equilibrium, Res and torsion, Ela well model, Voig aping and elastic and high te	idual stresses a astic-Plastic bo gt model, Voig c modulus on emperature Vi	nd strains, dies under t–Maxwell frequency, sco-plastic	

- 1. Mechanical Behaviour of Materials, W.F.Hosford, Cambridge University Press, 2005
- 2. Theory of Plasticity and Metal Forming Processes, Sadhu Singh, Khanna Publishers

- 1. Fundamentals of Materials Science and Engineering, William D. Callister, Jr., John Wiley & Sons,
- 2. Mechanical Metallurgy, George E. Dieter, McGraw Hill Book Company, 1988
- 3. Theory of Plasticity, J. Chakrabarty, Elsevier, 2006
- 4. Foundations of Theory of Plasticity, L. M. Kachanov, Dover Publications, 2004
- 5. Plasticity for Structural Engineers, W.F. Chen, Da-Jian Han, Springer
- 6.Mechanical Behavior of Materials, Meyers M A and Chawla K K



Program:	M. Tech. Mechanica	l (Design Engine	ering)	Semester :	Ι		
Course :	Analysis and Synthe			Code: M	MD1501C		
	Teaching Scheme Evaluation Scheme						
Lectur	Lecture Credit Hours IE1 IE2 ETE					Total	
3 3 3 20 30 50							
Pre-requisit				•			
	Theory of Machines						
Objectives: 1. 2.	To study the kinematic a To apply kinematic theo			echanisms			
0.4		-					
Outcomes:	g the course, the students	should be able to					
After learnin 1.	Analyze Simple and Co						
	Identify the center of cu			th dwell			
	Synthesize mechanisms						
	Apply kinematic theorie	001					
Detailed Syl		inw()	a	011			
	scription	(m)Chi		100		Duration, h	
	ematic analysis of simp						
1 .	ematic analysis of mecha		freedom, Graph	ical method of v	elocity and	4	
acc	eleration analysis of simp	ole mechanism.			3		
, Kir	ematics analysis of com	plex mechanism	S S		1931		
2. Typ	es of complex mechanis	ms, velocity-accel	eration analysis	of complex mec	hanisms by	6	
the	Normal Acceleration me	thod and Auxiliar	y Point Method.				
2 Cu	rvature theory		2 27		E		
3. Fixe	ed and moving centrodes	Contor of ourvet					
	le, Balls point.	, Center of curvat	are, cubic of stat	ionary curvature	, Inflection	6	
circ	·, · · · ·	, Center of curvat	are, cubic of stat	ionary curvature	, Inflection	6	
	thesis of planar mecha			ionary curvature	, Inflection	6	
Syn Tyr	*	nisms - Graphica	11		2	6	
Syn Typ	thesis of planar mechai	nisms - Graphica sional synthesis,	II Accuracy (pred	cision) points,	Chebychev	6	
4. Syn Typ space	thesis of planar mechan bes, number and dimen	nisms - Graphica sional synthesis, anch and order de	II Accuracy (pre- efects. Function	cision) points, generation and	Chebychev rigid body		
4. Syr guid	thesis of planar mechan bes, number and dimen cing, types of errors, bra	nisms - Graphica sional synthesis, anch and order de	II Accuracy (pre- efects. Function	cision) points, generation and	Chebychev rigid body		
4. Syr space guid met Syr	thesis of planar mechan bes, number and dimen cing, types of errors, bra dance with two and thre hod. thesis of planar mechan	nisms - Graphica sional synthesis, anch and order do be accuracy point nisms - Graphica	II Accuracy (pre- efects, Function s using Relative	cision) points, generation and pole method &	Chebychev rigid body t Inversion		
4. Syn space guid met 5. Syn	thesis of planar mechan bes, number and dimen cing, types of errors, bra dance with two and thre hod. thesis of planar mechan thesis of four bar mechan	nisms - Graphica sional synthesis, anch and order de ee accuracy point nisms - Graphica nism for path gen	II Accuracy (pre- efects, Function s using Relative III eration and rigid	cision) points, generation and pole method &	Chebychev rigid body t Inversion		
4. Syr space guid met 5. Syr three	thesis of planar mechan bes, number and dimen- cing, types of errors, bra- dance with two and three hod. thesis of planar mechan thesis of four bar mechan e and four position) for v	nisms - Graphica sional synthesis, anch and order de ce accuracy point nisms - Graphica nism for path gen with and without ti	II Accuracy (predefects, Function s using Relative III eration and rigid ming.	cision) points, generation and pole method &	Chebychev rigid body t Inversion	8	
4. Syr spaa guid met 5. Syr Syr three Syr	thesis of planar mechan bes, number and dimen- cing, types of errors, bra- dance with two and three hod. thesis of planar mechan thesis of four bar mechan e and four position) for y thesis of Planar Mecha	nisms - Graphica sional synthesis, anch and order do be accuracy point nisms - Graphica nism for path gen with and without ti nisms - Analytica	II Accuracy (pre- efects, Function s using Relative s using nelative III eration and rigid iming.	cision) points, generation and pole method &	Chebychev rigid body 2 Inversion tasks (two,	8	
4. Syn spa guid met 5. Syn three 6 Free	thesis of planar mechan bes, number and dimen cing, types of errors, bra dance with two and thre hod. thesis of planar mechan thesis of four bar mechan e and four position) for v athesis of Planar Mechan udenstein equation for s	nisms - Graphica sional synthesis, anch and order do be accuracy point nisms - Graphica nism for path gen with and without the nisms - Analytica ynthesis of four 1	II Accuracy (predefects, Function s using Relative III eration and rigid iming. I Dar mechanism.	cision) points, generation and pole method & body guidance Four position s	Chebychev rigid body 2 Inversion tasks (two, ynthesis of	8	
4. Syn spa guid met 5. Syn three 6. Fre slid	thesis of planar mechan bes, number and dimen cing, types of errors, bra dance with two and thre hod. thesis of planar mechan thesis of four bar mechan e and four position) for v thesis of Planar Mechan udenstein equation for s er crank mechanism, Co	nisms - Graphica sional synthesis, anch and order de e accuracy point nisms - Graphica nism for path gen with and without ti nisms - Analytica ynthesis of four l pomplex numbers of	II Accuracy (predefects, Function s using Relative III eration and rigid iming. I Dar mechanism.	cision) points, generation and pole method & body guidance Four position s	Chebychev rigid body 2 Inversion tasks (two, ynthesis of	8	
4. Syr spa guid met 5. Syr 5. Syr three 6. Fre slid	thesis of planar mechan bes, number and dimen cing, types of errors, bra dance with two and thre hod. thesis of planar mechan thesis of four bar mechan e and four position) for v athesis of Planar Mechan udenstein equation for s	nisms - Graphica sional synthesis, anch and order de e accuracy point nisms - Graphica nism for path gen with and without ti nisms - Analytica ynthesis of four l pomplex numbers of	II Accuracy (pre- efects, Function s using Relative III eration and rigid iming. I ar mechanism.	cision) points, generation and pole method & body guidance Four position s	Chebychev rigid body 2 Inversion tasks (two, ynthesis of	8	

- 1. Theory of Machines and Mechanisms, A. Ghosh and A.K. Mallik, Affiliated East-West Press.
- 3. Theory of Machines and Mechanisms, J. E. Shigley and J. J. Uicker, 2nd Ed. McGraw-Hill.
- 4. Design of Machinery: An Introduction to the Synthesis and Analysis of Mechanisms and Machines, Robert L. Norton, Tata McGraw-Hill,3rd Edition.
- 5. Theory of machines S. S. Rattan McGraw-Hill Publications.
- 6. Mechanisms and Machine Theory- A.G. Ambekar. PHI Learning Pvt. Ltd.

Reference Books:

- 1. Mechanism Design- Analysis and Synthesis (Vol.1and 2), A.G. Erdman and G.N. Sandor, Prentice Hall.
- 2. Kinematic Synthesis of Linkages, R.S. Hartenberg and J. Denavit, McGraw-Hill.

Program:	M. Tech. Mechanic			Semester		
Course :	Mathematical Met		g (Elective)		IMD1501D	
	Teaching Scheme	e		Evaluati	ion Scheme	-
Lectu	re Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requis 1. Di	ite: fferential and Integral Ca	alculus				
nathematic	: pletion of the course, al principles related to: gen Value and Eigen Veo		-	cground, concep	ptual clarity a	nd knowledge (
2. Tr	ansforms such as Laplac	e and Fourier transfo	orm and applica	tions		
	ecial Functions and Nun					
4. Ca	lculus of variation to opt	timize functional pro	oblems.			
1. Aj 3. Sc 4. Aj 5. Fi	ng the course, the studen oply the concept of Eiger live problems related to I oply the knowledge of se and numerical solution of nalyse the functional opti	a Value and Eigen V Laplace transform ar ries solution in spec PDE.	Tector to solve m ad applications t ial functions	o Design Engine		
Detailed S				6).	0	
	escription		-		0	Duration, h
	asic concept of Laplace 7	Fransforms, Laplace	transforms and	its inverse.	3	6
2. La	aplace transform of spec	eial functions: Unit			nd Error.	6
3. M eq	ass spring systems of mutations in vibration theo luations in vibration theo	multi degree freedo	olution, Numeric	cal computation	of Eigen	6
4. Se	eries Solution of diffe uations. Least square sol	erential equations,				6
5. Ca Pr bo	alculus of Variation I oblem, Functional invo oundary value problem, incipal.	ntroduction, Function	r derivative, A	pproximate sol	ution of	6
sc in	umerical Analysis Finite heme, Stability of finite boundary value proble aplace equation.	difference method, A	Applications of	finite difference	analysis	6
Total						36
Text Book 1. Hi	gher Engineering Mathe					
2. Ac Reference	lvanced Engineering Ma	memaucs by Erwin	Kieyszig (wile	y Lastern Ltu.)		
1. A 2. Ac 3. Hi	dvanced Engineering Ma lvanced Engineering Ma gher Engineering Mathe	thematics, 2e, by M matics by B. S. Grev	. D. Greenberg (wal (Khanna Pu	(Pearson Educati blication, Delhi)	ion).	Caiba Dast - 1
-	oplied Mathematics (Volume).	umes I and II) by P.	N. Wartikar & .	J. N. Wartikar (H	Pune Vidyarthi	Griha Prakash

Program:			anical (Design E		Semester :					
Course :			Iechanics of Composites (Elective)Code : MMD1502Aing SchemeEvaluation Scheme							
	Te	aching Scheme			Evaluati	on Scheme	1			
Leo	ture	Credit	Hours	IE1	IE2	ETE	Total			
	3	3	3	20	30	50	100			
Pre-requ	isite:	•		•	•	•	1			
		tress Analysis, Ma	nufacturing Proc	esses						
Objectiv										
		e aware the studer		-	-	oplications.				
		ble the students to			uctures.					
		arning the course, t			6	1				
		the ability to choo				plication.				
		tand and apply the appropriate theory								
		e the composite la								
		the simple composite full		coses and summe						
	Syllabus:	F F								
Unit	Descrip	tion					Duration,			
1.		tion to Composit	e Materials	a	011					
	Introduct	ion ,Classification	, Polymer Mat	trix Composites	, Metal Matrix	c Composites,	4			
		Matrix Composite		bon Composites	, Recycling F	iber-Reinforced	-			
		tes, Mechanics To								
2.		nechanical Analys				81				
		ion, Review of								
		Law for Different					(
		bic Material (Ort					6			
		Material, Isotrop ing Elastic Consta								
		Form of Stiffness				Aligie Laillia,				
3.		Failure Theories			Angle Lamma.	0				
5.		m Stress Failure T			e Envelopes - M	faximum Strain				
		heory, Tsai–Hi			- · ·					
		ental Results with					4			
	Lamina,		Stress-Strain							
		rmal Stress-Strain		or an Angle Lam	ina.					
4.		echanical Analysis				10				
		tion, Volume and								
		ctions, Density, V					8			
		Poisson's Ratio,			city, Ultimate, O	Coefficients of				
-		Expansion Coeffic		e Expansion.						
5.		nechanical Analyst tion, Laminate C		in Polations f	a Lominata	Dimonsional				
		Beam Stress–Stra								
		ite, Force and M					6			
		and Flexural Mo								
		, Flexural Engine				or u				
6.		Analysis, and Des								
		ion, Special Case			ninates, Cross-P	Ply Laminates,				
		y Laminates, Ant								
		s, Failure Criterio					0			
		cal Design Issues,								
		inar Stresses, Imp	act Resistance, I	Fracture Resistar	nce, Fatigue Res	istance.				
-	Total						36			
Referenc		. ~ .								
		of Composite Mate					D			
		Mechanics of Con			el and Orilshai, (Jxford University	Press.			
		of Composite Mate			ailion on I Farra	W Morrer P	laarian			
4. 1	viechames a	and Analysis of Co	mposite Materia	is, valery v. va	sinev and Evgen	\mathbf{y} v. wiorozov, E	isevier			

Program			l (Design Enginee	ring)	Semester :		
Course :		bology in Design ((Elective)	I	Code : MN		
	Т	eaching Scheme			Evaluati	on Scheme	
Lec	ure	Credit	Hours	IE1	IE2	ETE	Total
		3	3	20	30	50	100
Pre-requ							
I	luid Mecl	nanics, Engineerin	g Metallurgy, Stre	ngth of Materia	als		
Objective	·C•						
•		vide necessary co	ncents knowledge	and skills in F	ngineering Tribo	logy with design asp	ect
						e in design and mai	
		ne components		5		C	
		ovide hands on trai	ning with design of	of bearing, frict	ion ,wear test rig	for laboratory purpo	se
Outcome							
			students will be a		4	- 41 1:	
1	process		nd wear to various	s practical situa	tions by analyzin	g the physics of the	
			ants to suggest a tr	ibological solu	tion to a particula	r situation.	
						ng various bearing c	harts.
			aring in different l			0 0	
			g capacity in air lu		0		
6		nd the tribological	aspects in different	nt applications	and understand th	ne solution to avoid	wear and
Detelled	friction.	18	A			2	
Detailed Unit	Synabus:	15				2.	Duration
Unit			Des	scrip <mark>tio</mark> n			h
]	Friction a	nd wear	/	200		0	
			revention, Bounda	ary lubrication	, Tribological pro	operties of bearing	7
			ories of friction ar	nd wear, Instab	ilities and stick-sl	ip motion	
		on of bearings					
			* I			bearings, Infinitely	7
						rt (narrow) journal , Finite bearings -	7
			nd thrust oil bearing				
1		ic squeeze film		. <u></u>			
4	•	-	at plates, variable	e and alternat	ing loads, pistor	n pin lubrications,	6
:	pplicatior	n to journal bearing	gs		1		
4	•	drodynamic lubri					
1		iscosity term in Re	eynold's equation,	, hertz theory, l	Ertel-Grubin equa	tion, lubrication of	6
	pheres	ated bearings		thice toole			
			atic, hydrodynami	c and thrust be	arings with air lul	prication	4
		cal aspects of Roll					
				nd rolling resi	stance, tribologic	al aspects of wheel	6
	on rail con		spects of metal rol				
	Total						36
Text Boo		· · 1 . CT 1 ·	d a t		0 1/1		
			ation, Camaron, L		en Co. Ltd.		
Referenc		inology in Machin	ne Design, T. A. S	101415K1			
		mental of Friction	and Wear of Meta	uls – ASM			
			c Bearings – J. W.				
3	. Gas B	earings – Grassam	and Powell				
			ubrication, Pinkus				
,	. Princi	ples of Lubrication	Camaron Longr	non's Groon C	5 T + J		
			esign, T. A. Stolar		5. Ltd.		

Program:	M. Tech. Mechanical	(Design Engine	ering)	Semester	: I		
Course :	Vehicle Dynamics (E			Code : M	MD1502C		
	Teaching Scheme			Evaluat	ion Scheme		
_					_		
Lecture	Credit	Hours	IE1	IE2	ETE	Total	
3	3	3	20	30	50	100	
Pre-requisite:							
1.	Theory of Machine a						
2.	Automobile Engineer						
3. Objectives:	Mechanical Vibratio	n					
-	quaint with vehicle desig	n narameters & s	vehicle dynamic	behavior			
	evelop an ability to evalu			bellavioi			
	ake aware the students a			e			
	fter learning the course, t			-			
	vestigate ISO and SAE v						
	amine vehicle Tire mode		-				
	terpret Vibrational behav	-		response			
4. To an	alyze the road holding a	nd directional sta	bilit <mark>y of tw</mark> o axe	el vehicles at diff	ferent steering	inputs.	
5. To de	evelop physical and math	ematical models	to predict the dy	namic response	of vehicles	-	
6. To an	alyze and calculate the r	de characteristic	of quarter car m	nodel of an autor	nobile with dif	ferent road	
	ations.						
Detailed Sylla	bus:	27/			2		
Unit D	escription	5 1			13	Duration, h	
1 Ba	sics of Vehicle Dynamic	es			201		
	re mechanics, Vehicle ty						
	formation of Electric, Hy					6	
	ftware used for vehicle of	lynamics study,	Different type of	of safety norms a	and Bharat		
	ge emission standards				<u> </u>		
	rformance characterist						
	uation of motion and m					6	
	Prediction of vehicle performance, acceleration time and distance, gradeability, Introduction of Static Vehicle Characteristics and Suspension Parameters						
	easurement Machine	venicie chara	cicilistics and	Suspension	rarameters		
	aking Characteristics	Deserver	the state the P	to C. Januara			
	Braking characteristics of a two-axle vehicle, Braking efficiency and stopping						
	distance, Braking characteristics of a Tractor-Semitrailer, Antilock brake systems,						
	action control systems, S						
	andling characteristics of		81-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-				
	eady-state handling char					6	
	ering input, Testing of I	nandling characte	eristics, Transie	nt response char	acteristics,	Ū	
	rectional stability						
	hicle ride characteristic		11 .	1	,.,		
	iman response to vibration					-	
	odel for sprung and un					6	
	ponse of a quarter-car medom vehicle model for						
	ad and Suspension mo		, Active and sen	m-active suspens			
	ad – modeling aspects	-	profile randon	n profile auto-	correlation		
	nction, relation between					6	
	d different type of roads					~	
	CV, and Agricultural)	,	J				
	otal					36	
Т							

Text	Books:
IUAL	DOORS.

- 1. Vehicle Dynamics Theory and Application, Raza N. Jazar. Springer International Edition
- 2. Rajesh Rajamani, Vehicle Dynamics & control, Springer.

- 1. Road Vehicle Dynamics Problems & Solutions, Rao & Dukkipati, SAE,
- 2. Theory of Ground Vehicles, J.Y. Wong, John Wiley & Sons,
- 3. Fundamentals of Vehicle Dynamics, T.D. Gillespie, SAE
- 4. Garrett T K, Newton K and Steeds W, "Motor Vehicle", Butter Worths & Co., Publishers Ltd., New Delhi, 2001.
- 5. Vittore Cossalter, Motorcycle Dynamics, 2nd Edition, Publisher: LULU.com
- 6. Milliken W F and Milliken D L, Race car Vehicle Dynamics, SAE



	am: M	I. Tech. Mechanical	(Design Enginee	ering)	Semester :	Ι	
Cours		obotics (Elective)		<u>C</u> .	Code : MN		
		Teaching Scheme			Evaluati	on Scheme	
I	Lecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
	equisite:	es, Mechatronics, Ba					
Objec 1. 2.	To get ac	quainted with basic c stand grippers, senso	-	ootic systems.			
3.	To under	stand statistics & kine	ematics of robots				
4.	To under	stand dynamics of ro	bot.				
After I 1. 2. 3. 4. 5. 6.	Identify Apply DF Determin Perform o Plan suit	course, the students s different type of ro I parameters to a rob e velocities and static lynamic analysis of t able trajectory to t cessary actuators, ser	bot configuratio ot configuration t c forces in the man he manipulator. he designed rob	hus determine t nipulator. ot	he kinematic par	ameters.	
Dotail	od Syllobus			satisfactory per	formance of the r	obot.	
	ed Syllabus	a A		satisfactory per	formance of the r	3	
Detaile Unit	Descript	ion		satisfactory per	formance of the r	3	Duration, h
	Descript Introduct Structure,	ion ion classification and ap positions, orientation	oplications, robot	anatomy, dexte	erity and complia	ince of	Duration, h
Unit	Descript Introduct Structure, robot. Po transforma Manipula Represent	ion ion classification and ap ositions, orientation ations. tor kinematics ation of joints and	oplications, robot as and frames link using Denav	anatomy, dexte of a rigid vit-Hartenberg	erity and complia body, homog parameters, dire	unce of eneous ct and	¢
Unit 1.	Descript Introduct Structure, robot. Petransforma Manipula Represent inverse kin Velocities Linear an	ion ion classification and ap ositions, orientation ations. tor kinematics	oplications, robot as and frames link using Denav rames with standa	anatomy, dexte of a rigid vit-Hartenberg ard names.	erity and complia body, homog parameters, dire	unce of eneous ct and	6
Unit 1. 2.	Descript Introduct Structure, robot. Petransforma Manipula Represent inverse kii Velocities Linear an Singularit Dynamics Mass and	ion ion classification and ap ositions, orientation ations. tor kinematics ation of joints and nematics of robots, F and static forces d angular velocity of	oplications, robot as and frames link using Denav rames with standa of links, velocity ces in manipulator eleration of links,	anatomy, dexte of a rigid vit-Hartenberg ard names. y propagation, rs Lagrangian for	erity and complia body, homog parameters, dire Freedom manipulator Jaco	ct and bians,	6
Unit 1. 2. 3.	Descript Introduct Structure, robot. Petransforma Manipula Represent inverse kii Velocities Linear an Singularit Dynamics Mass and Newton-E Trajector Considera	ion ion classification and ap ositions, orientation ations. itor kinematics ation of joints and mematics of robots, F and static forces d angular velocity of y analysis, Static forces of robots inertia of links, Access	oplications, robot as and frames link using Denay rames with standa of links, velocity ces in manipulator eleration of links, ation, Dynamic Si ption, Joint space	anatomy, dexte of a rigid vit-Hartenberg ard names. propagation, rs Lagrangian for imulation.	erity and complia body, homog parameters, dire Freedom manipulator Jaco	ct and bians, amics,	6 6 6
Unit 1. 2. 3. 4.	Descript Introduct Structure, robot. Petransforma Manipula Represent inverse kin Velocities Linear an Singularit Dynamics Mass and Newton-E Trajector Considera Geometric Actuators Mechanic	ion ion classification and ap ositions, orientation ations. itor kinematics ation of joints and nematics of robots, F and static forces d angular velocity of y analysis, Static forces of robots inertia of links, Acce uler dynamic formul y generation tions in path descri	oplications, robot as and frames link using Denav rames with standa of links, velocity ces in manipulator eleration of links, ation, Dynamic Si ption, Joint space s. pers eumatic actuators,	anatomy, dexte of a rigid vit-Hartenberg ard names. propagation, rs Lagrangian for imulation. e schemes, Ca	erity and complia body, homog parameters, dire Freedom manipulator Jaco mulation for dyn rtesian space sci	amics, america, and a second s	6 6 6 6

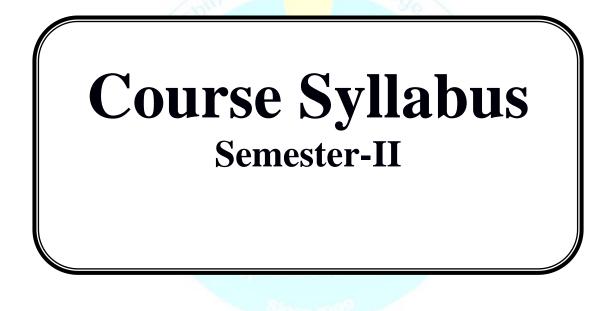
- 1. John Craig, Introduction to Robotics, Mechanics and Control, 3rd Edition, Pearson Education, 2009
- 2. K.S. Fu, R.C. Gonzales, C.S.G. Lee, Robotics: Control, Sensing, Vision and Intelligence, McGraw Hill, 1987.
- 3. S. K. Saha, Introduction to Robotics, Second Edition, McGraw Hill Education, 2014

Reference Books:

- 1. S B Niku, Introduction to Robotics, Analysis, Control, Applications, 2nd Edition, Wiley Publication, 2015.
- 2. Mathia, Robotics for Electronics Manufacturing, Cambridge Uni. Press, India
- 3. A Ghosal, Robotics: Fundamental Concepts and Analysis, Oxford University Press, 2013.
- 4. R K Mittal & I J Nagrath, *Robotics and Control*, McGraw Hill Publication, 2015.

0	M.Tech Mecha	nical (Design Engi	ineering)	S	emester :	Ι
Course :	Professional El			C	ode : MMD1	503
course.		ctive I & Elective	II			505
	Teaching Schem	ne		Evaluati	on Scheme	
Practica	l Hours	Credit	TW	PR	OR	Total
Tacuca		Creuit	1 **		UK	Total
2	2	1	50		50	100
Pre-requi	site:					
Objective	s:					
	This course is to provid	le students the tool	s required for Sin	nulate correlate	e and validate t	heoretical concep
and under	stand the principles.					
Outcomes	X•					
	ning the course the stu	dents should be abl	le to:			
	. Solve open ended l			ion.		
	. Simulate the proble					
3	. Understand the imp					
4	. Collect data, Analy	se, interpret and re	port <mark>the resul</mark> ts.			
a					2	
Guideline		D		1	81	
	ny one subject from					
	otal experiments to be		iree fro <mark>m P</mark> art A	and Three fr	om Part B	
	Cotal : 6 experiments	12 hours			2 0	
Ľ	Detailed Syllabus:					
		art A: Elective 1-	Advanced Mach	<mark>ine Design (</mark> A	NY Three)	
Expt.	Description				0	Duration, h
1.	Case Studies Based					2
2.	Case Studies Based					2
3.	Case Studies Based					2
<u>4.</u> 5.	Case Studies Based			eliability.	ŋ"	2 2
5.	Case Studies Based of Total	on : Design based (Dir Cost		_	2
		lective 1- Mechan				06
Expt.	Description		ical Rehavior of	Matarials (A	NV Three)	06
LAPO	-	icenve 1- ivicentan	ical Behavior of	Materials (A	NY Three)	
			ilmsm cell	auce /	NY Three)	Duration, h
1.		is of a tensile test s	pecimen using F	EM software		Duration, h
	Determination of f specimen as per AST	is of a tensile test s ull range stress s	pecimen using F	EM software		Duration, h
1.	Determination of f	is of a tensile test s ull range stress s TM -E8M	pecimen using F. strain curve for	EM software		Duration, h
1. 2.	Determination of f specimen as per AST	is of a tensile test s ull range stress s TM -E8M ation of Three poir	specimen using F strain curve for nt bending test	EM software		Duration, h 2 2
1. 2. 3. 4.	Determination of f specimen as per AST Experimental verific	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co	specimen using F strain curve for nt bending test	EM software		Duration, h 2 2 2
1. 2. 3. 4.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c	specimen using F strain curve for at bending test composite	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2
1. 2. 3. 4. 5.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co	specimen using F strain curve for at bending test composite	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06
1. 2. 3. 4. 5. Expt.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description	is of a tensile test s ull range stress s TM -E8M ation of Three poir mer and polymer co c c ctive 1- Analysis a	specimen using F strain curve for nt bending test composite and Synthesis of	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h
1. 2. 3. 4. 5. Expt. 1.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of	is of a tensile test s ull range stress s CM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a f simple mechanis	specimen using F strain curve for at bending test composite and Synthesis of ms	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2
1. 2. 3. 4. 5. 5. Expt. 1. 2.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Kinematic analysis of	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c ctive 1- Analysis a of simple mechanis f complex mechan	specimen using F strain curve for at bending test composite and Synthesis of ms isms	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. 5. Expt. 1. 2. 3.	Determination of f specimen as per AST Experimental verific Tensile test for polyr Impact test for plasti Total Part A: Ele Description Kinematic analysis of Curvature analysis si	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a of simple mechanis of complex mechan imple planar mecha	specimen using F strain curve for at bending test composite and Synthesis of ms isms anism	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. Expt. 1. 2. 3. 4.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Curvature analysis si Graphical Synthesis	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a f simple mechanis f complex mechan imple planar mecha of path generating	specimen using F strain curve for at bending test omposite and Synthesis of ms isms anism mechanism	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. 5. <u>Expt.</u> 1. 2. 3. 4. 5.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Curvature analysis si Graphical Synthesis	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c c c c c c c c c c c c c c c c c c	specimen using F strain curve for at bending test omposite and Synthesis of ms isms anism mechanism ting mechanism	EM software mild steel ar	ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 6.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Curvature analysis of Graphical Synthesis Graphical Synthesis	is of a tensile test s ull range stress s TM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a f simple mechaniss of complex mechan mple planar mecha of path generating of function generat of rigid body guidi	specimen using F strain curve for at bending test composite and Synthesis of ms isms anism mechanism ting mechanism ng mechanism	EM software mild steel ar Mechanisms (ad aluminum	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 6. 7.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Kinematic analysis of Curvature analysis of Graphical Synthesis Graphical Synthesis Analytical Synthesis	is of a tensile test s ull range stress s CM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a of simple mechaniss of complex mechan imple planar mecha of path generating of rigid body guidi of path generating	pecimen using F strain curve for at bending test omposite and Synthesis of ms isms anism mechanism ting mechanism mechanism mechanism	EM software mild steel ar Mechanisms (ANY Three)	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. 5. Expt. 1. 2. 3. 4. 5. 6. 7. 8.	Determination of f specimen as per AST Experimental verific Tensile test for polyr Impact test for plasti Total Part A: Ele Description Kinematic analysis of Kinematic analysis of Curvature analysis of Graphical Synthesis Graphical Synthesis Analytical Synthesis Analytical Synthesis	is of a tensile test s ull range stress s CM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a f simple mechaniss f complex mechan imple planar mecha of path generating of function generat of rigid body guidi of path generating of function generating of function generating	pecimen using F strain curve for at bending test composite and Synthesis of ms isms anism mechanism ting mechanism mechanism mechanism, usin ting mechanism, usin	EM software mild steel ar Mechanisms (ag MATLAB using MATLA	ANY Three)	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2
1. 2. 3. 4. 5. Expt. 1. 2. 3. 4. 5. 6. 7.	Determination of f specimen as per AST Experimental verific Tensile test for polyn Impact test for plasti Total Part A: Ele Description Kinematic analysis of Kinematic analysis of Curvature analysis of Graphical Synthesis Graphical Synthesis Analytical Synthesis	is of a tensile test s ull range stress s CM -E8M ation of Three poir ner and polymer co c c ctive 1- Analysis a f simple mechaniss f complex mechan imple planar mecha of path generating of function generat of rigid body guidi of path generating of function generating of function generating	pecimen using F strain curve for at bending test composite and Synthesis of ms isms anism mechanism ting mechanism mechanism mechanism, usin ting mechanism, usin	EM software mild steel ar Mechanisms (ag MATLAB using MATLA	ANY Three)	Duration, h 2 2 2 2 2 2 06 Duration, h 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2

	Part A: Elective 1- Mathematical Methods in Engineering (ANY Three)	
Expt.	Description	Duration, h
1.	Solution using Matlab for Power Method	2
2.	Solution using Matlab for Mass spring system	2
3.	Solution using Matlab for Least square method	2
4.	Solution using Matlab for Numerical solution to Laplace Equation.	2
5.	Solution using Matlab for Numerical solution to Heat Equation.	2
	Total	06
	Part B: Elective 2- Mechanics of Composites (ANY Three)	
Expt.	Description	Duration, h
1.	Analytical determination of strength of lamina using properties of matrix and fibres.	2
2.	Compare the theories of failure for the composite lamina using analytical formulation	2
3.	Study of various test standards for behavior testing of composite laminates.	2
4.	Determination of the stress distribution across various layers of a laminate using Classical Laminate Theory.	2
	Total	06
	Part B: Elective 2- Tribology in Design (ANY Three)	
Expt.	Description	Duration, h
1.	Case study on Tribological aspects of rolling motion / Tribo-characteristics of different materials / Evaluation of friction & wear through experiments under influencing parameters. Coefficient of friction using pin-on-disc type friction monitor	2
2.	Friction in Journal Bearings	2
3.	Four Ball Tester	2
4.	Study of Lubricating systems with example	2
5.	Journal Bearing Apparatus	2
6.	Tilting pad and thrust bearing apparatus	2
	Total	06
	Part B: Elective 2- Vehicle Dynamics (ANY Three)	00
Expt.	Description	Duration, h
<u>1.</u>	Assignment on Road holding characteristics of vehicle and its control	2
2.	Assignment on analysis and optimal control of car ride model	2
3.	Assignment on ABS or Power-steering for handling analysis - single lane event	2
4.	To simulate and understand behavior of sprung / un-sprung mass & lumped mass	2
	system MBD software.	
	Total Part B: Elective 2- Robotics (ANY Three)	06
Fynt	Description	Duration, h
Expt. 1.	Simulation of Cartesian/ cylindrical/ spherical robot.	2
2.	Simulation of Catestal/ cymuncal/ spherical robot.	
<u> </u>	Virtual modelling for kinematic and dynamic verification of any one robotic	2 2 2
4.	structure using suitable software. Design, modeling and analysis of gripper	2
	Total	06



Program:	M. Tech. Mechanical ((Design Engineer	ring)	Semester :	II	
Course :	Optimization Techniq			Code : MN		
	Teaching Scheme			Evaluati	on Scheme	
Lecture	Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisite	I I					_
	neering Mathematics					
Objectives:						
	luce students to the model				l optimization.	
	students with the basic mat					
	students with the modellin					
	students with the skills nec	cessary to solve a	nd interpret op	timization proble	ms in engineer	ing.
Outcomes: After learning	the course, the students sh	hould be able to				
	Formulate mathematical pr		s practical syst	ems and apply c	lassical optimiz	vation techniqu
	nterpret the results of lines				ussieur opuiniz	auton teeninqu
	Obtain optimum parameter			and the mongines		
	Simulate the optimized mo					
	Jse software to solve prob		rn methods.			
6. 4	Apply topology optimization	on for design.				
	0				2	
Detailed Sylla					0	
	scription	S./			3	Duration, h
	ssical Optimization Tech	/ -				~
	hematical Modeling, Clas			ariable optimizat	ion and	6
		ith and without c	constraints.		3	
· · · ·		multi variable optimization, with and without constraints. Linear Programming				
			1.0.1.1		0	C.
		, primal and du	al Simplex M	fethod, revised	simplex	6
met		, primal and du	al Simplex M	fethod, revised	simplex	6
a Non	-Linear Programming	1.20				
3. Non Elin	-Linear Programming nination and iterative m	1.20				6
3. Non Elin dime	-Linear Programming nination and iterative mension minimization.	nethods for one				
3. Non Elin dime	-Linear Programming nination and iterative m ension minimization. lern Methods of Optimiz	nethods for one zation	-dimensional	minimization ar	id multi	6
3. Non Elin dim 4. Moo Gen	-Linear Programming nination and iterative m ension minimization. lern Methods of Optimiz etic algorithms, Simulated	nethods for one zation	-dimensional	minimization ar	id multi	
3.Non Elin dim4.Moo Gen Opti	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc.	nethods for one zation	-dimensional	minimization ar	id multi	6
3. Non Elin dim 4. Moo Gen Opti Sim	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling	nethods for one zation d Annealing, Par	-dimensional ticle Swarm O	minimization ar	d multi Colony	6 6
3. Non Elin dim 4. Moo Gen Opti 5. Intro	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and t	nethods for one zation d Annealing, Par types, limitations	-dimensional ticle Swarm O s, various pha	minimization ar ptimization, Ant ses of modeling.	d multi Colony	6
3. Non Elin dim 4. Moo Gen Opti 5. Intro Carl	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and to o method, applications, ac	nethods for one zation d Annealing, Par types, limitations	-dimensional ticle Swarm O s, various pha	minimization ar ptimization, Ant ses of modeling.	d multi Colony	6 6
3. Non Elin dim 4. Moo Gen Opti 5. Intro Carl Top	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and to o method, applications, ac ology Optimization	nethods for one zation d Annealing, Par types, limitations dvantages and lin	-dimensional ticle Swarm O s, various pha nitations of sin	minimization ar ptimization, Ant ses of modeling. pulation.	d multi Colony Monte	6
3. Non Elin dim 4. Moo Gen Opti 5. Intro Carl Top Prot	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and to o method, applications, ac ology Optimization olem formulation and pa	nethods for one zation d Annealing, Par types, limitations dvantages and lin grameterization of	-dimensional ticle Swarm O s, various pha nitations of sin of design, solu	minimization ar ptimization, Ant ses of modeling, nulation.	d multi Colony Monte	6 6
3. Non Elin dim 4. Moo Gen Opti 5. Intro Carl 6. Prot opti	-Linear Programming nination and iterative mension minimization. Itern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and to o method, applications, ac ology Optimization olem formulation and pa mization as a design to	nethods for one zation d Annealing, Par types, limitations dvantages and lin grameterization of	-dimensional ticle Swarm O s, various pha nitations of sin of design, solu	minimization ar ptimization, Ant ses of modeling, nulation.	d multi Colony Monte	6 6 6
3. Non Elin dim 4. Moo Gen Opti 5. Intro Carl 6. Prot opti	-Linear Programming nination and iterative mension minimization. Iern Methods of Optimiz etic algorithms, Simulated mization, etc. ulation Modeling oduction, definition and to o method, applications, act ology Optimization olem formulation and patimization as a design to mization.	nethods for one zation d Annealing, Par types, limitations dvantages and lin grameterization of	-dimensional ticle Swarm O s, various pha nitations of sin of design, solu	minimization ar ptimization, Ant ses of modeling, nulation.	d multi Colony Monte	6 6 6

- 1. Engineering Optimization: Theory and Practice, Singiresu S. Rao, John Wiley & Sons
- 2. Practical Optimization Methods with Mathematical Applications, M. Asghar Bhatti, Springer
- 3. Optimization for engineering design, K. Deb, PHI

Reference Books:

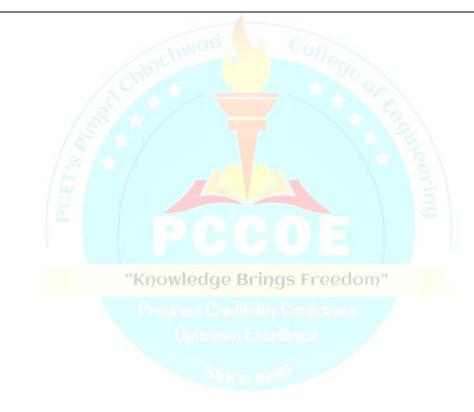
- 1. Topology Optimization Theory, Methods and Applications, M. P. Bendse, Q. Sigmund
- 2. Evolutionary Topology Optimization of Continuum Structures, Methods and Applications, X. Huang, Y.M. Xie, Wiley
- 3. Structural Optimization, Raphael T. Haftka and Zafer Gurdal, Kluwer Academic Publishers
- 4. Mathematical Modelling, J N Kapur, New age international publication

5. Optimization concepts and applications in engineering, Belegundu, Chandrupatla, Pearson Education

Program:	мт	ach Machanical	(Design Enginee	ring)	Semester :	Π	
Course :		anced Vibrations		i iiig)	Code : MN		
course.		aching Scheme	and moustics			on Scheme	
	10	senting sentenit			Evaluati		
Lect	ture	Credit	Hours	IE1	IE2	ETE	Total
3	3	3	3	20	30	50	100
Pre-requi	site: 1.	Physics 2. E	ngineering Mathe	matics 3. Dyn	amics of Machi	nery	
respo 2. Stud	enable stude	ents to analyse n erent excitation co	nodel physical sy	stems, categoriz	e and apply pr	inciples of Vib	
 Form Form Form Form Anal Under Under 	ning the cou nulate and nulate the r nulate the r yse Vibratio erstand Ran erstand Bas	nathematical mod nathematical mod on in System and dom process para	should be able to: ns of MDOF mech lel for continuous lels Transient Vibr Design a Vibratio meters and analys acoustics, measur	systems and An rations and study n Control Strate e vibration respo	alyse the effects y its impact on d gies, onse of single de	s of vibrations. lesign of system egree linear syste	em.
Detailed S	Syllahus					2	
Unit	Descriptio	n	/			0	Duration, h
		ree Freedom Syst	om			12	
1.	Free vibra (ii) flexib equations i	ation equation bility coefficien matrix method E	of motion, infl t generalized co ligen values Eige em and modal ana	ordinates, coord en vector probl	dinate coupling	s, Lagrange's	6
2.	Continuou Transverse	s System vibrations of St	ring, Longitudina mply supported a	l vibration of I		vibrations of	6
3.			input, Response usoidal pulse.	to step input,	Response to a	a pulse input-	4
4.	Vibration Balancing vibration is	Control of rotating mach	ine, in-situ balan ion absorbers, Pas				5
5.	Random V Probability, and analysi	ibrations	orrelation functio	n, spectral densi	ty, response of	linear systems,	6
6.	number, ac density, sph Directivity octave banc Sound Pow anechoic, se Transmissio oblique inc	coustic pressure a nerical wave, factor and directiv ls, weighted sound ver measurement ound power surve on of Sound: cha idence, sound tran	in a reverberar	city, acoustic is and the decibel, nt room, Sound ith normal incic a wall, transmis	ntensity and ac combination of l power measu lence, changes ssion loss for wa	sound sources, rement in an in media with	9
	Total	<u> </u>			0 1		36
	10001						

- 1. Mechanical Vibrations, S. S. Rao, Pearson Education, Delhi
- 2. Theory of Vibrations with Applications, W. T. Thomson, Pearson Education, Delhi
- 3. Industrial Noise Control, Randell Barron, Marcel Dekker, Inc.

- 1. Mechanical Vibrations, G K Groover, Nem Chand & Bros, Roorkee, India
- 2. Fundamentals of Vibration, Leonard Meirovitch, McGraw Hill International Edison
- 3. Principles of Vibration Control: Ashok Kumar Mallik, Affiliated East-West Press, New Delhi.
- 4. Mechanical Vibrations, A H Church, John Wiley & Sons Inc
- 5. Mechanical Vibrations & Noise Engineering, A.G.Ambekar, Prentice Hall of India, New-Delhi.



Course :	am: M. Tech. Mechanical (Design Engineering) Semester :							
course .	Professional		Code : MMD2408					
	LAB Name	/		Evaluation Scheme				
	Teaching Schem	e						
Practical	Hours	Credit	TW	PR	OR	Total		
2	2	1	50		50	100		
Guidelines 1.	Total experiments t		e Three from P	art A and Thre	e from Part B			
2.	Total : 6 experime	ents 12 hours						
Pre-requisi								
	gineering Mathemati	cs						
Objectives:								
1. P	rovide students with	the modelling ski	lls necessary to d	escribe and form	nulate optimizatio	on problems.		
	rovide students with							
2. 1	rovide students with	the skins neeessa	ly to solve and h	terpret optimize	aton problems m	engineering.		
<u> </u>			ad the					
Outcomes:								
After learnin	ng the course, the stu	dents should be al	ole to:					
	rmulate mathematica			ems				
			it the insights (se	nsitivity, duality	7)			
Dotailad Sr	e software to solve p		it the insights (se	nsitivity, duality	7)			
Detalled Sy	e software to solve pi illabus:		at the insights (se	nsitivity, duality	7)			
Detalled Sy	llabus:	roblems			3			
-	llabus: Pa				3	Duration		
Expt.	llabus: Pa Description	roblems rt A: Optimizati	on Techn <mark>iqu</mark> es i		3	Duration		
Expt.	llabus: Pa	roblems rt A: Optimizati	on Techn <mark>iqu</mark> es i		3	Duration 2		
Expt. 1.	llabus: Pa Description	roblems rt A: Optimizati	on Techn <mark>iqu</mark> es i		3			
Expt. 1. 2	llabus: Pa Description Mathematical modeli	roblems	on Techn <mark>iqu</mark> es i		3	2		
Expt. 1. 2	llabus: Pa Description	roblems	on Techn <mark>iqu</mark> es i		3			
Expt. 1. 1 2. 1 3 3	Illabus: Pa Description Mathematical modeli Primal dual simplex	roblems rt A: Optimizati ng of a real life p method	on Techn <mark>iqu</mark> es i		3	2		
Expt. 1. 1 2. 1 3 3	llabus: Pa Description Mathematical modeli	roblems rt A: Optimizati ng of a real life p method	on Techn <mark>iqu</mark> es i		3	2		
Expt. 1. 1 2. 1 3. 2	Illabus: Pa Description Mathematical modeli Primal dual simplex a Sensitivity analysis o	roblems art A: Optimizati ng of a real life p method f linear problem	on Techniques i	n Design (ANY	Z Three)	2		
Expt. 1. 1 2. 1 3. 2	Illabus: Pa Description Mathematical modeli Primal dual simplex a Sensitivity analysis o	roblems art A: Optimizati ng of a real life p method f linear problem	on Techniques i	n Design (ANY	Z Three)	2		
Expt. 1. 1 2. 1 3. 2 4. 0	Illabus: Pa Description Mathematical modeli Primal dual simplex	roblems art A: Optimizati ng of a real life p method f linear problem	on Techniques i	n Design (ANY	Z Three)	2 2 2		
Expt. 1.] 2.] 3. 3. 4. 0 5. 1	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods	on Techniques i	n Design (ANY	Z Three)	2 2 2 2 2		
Expt. 1.] 2.] 3. 3. 4. 0	Illabus: Pa Description Mathematical modeli Primal dual simplex a Sensitivity analysis o	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods	on Techniques i	n Design (ANY	Z Three)	2 2 2		
Expt. 1.] 2.] 3. 3. 4. 0	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods	on Techniques i roblem	n Design (ANY	Z Three)	2 2 2 2 2		
Expt. 1. 2. 3. 4. 5.	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n Optimization using n Total	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods	on Techniques i roblem	n Design (ANY	Z Three)	2 2 2 2 2 2 2		
Expt. 1. 1 2. 1 3. 3 4. 0	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n Optimization using n Total te:	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods nodern methods	on Techniques i problem	n Design (ANY gs Freedo y Three)	7 Three)	2 2 2 2 2 2 2		
Expt. 1.] 2.] 3. 3 4. 6 5. 6 Pre-requisi	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n Optimization using n Total te: Physics	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods	on Techniques i problem	n Design (ANY gs Freedo y Three)	7 Three)	2 2 2 2 2 2 2		
Expt. 1. 1 2. 1 3. 3 4. 6 5. 6 Pre-requisi 0 Objectives: 0	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n Optimization using n Total te: Physics	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods nodern methods Engineering Mat	on Techniques i roblem	n Design (ANY gs Freedo y Three) mics of Machin	Z Three)	2 2 2 2 2 2 6		
Expt. 1. 1 2. 1 3. 2 4. 6 5. 6 Pre-requisi 0 Objectives: To in	Ilabus: Pa Description Mathematical modeli Mathematical modeli Primal dual simplex is Primal dual simplex is Optimization using n Optimization using n Optimization using n Total Physics mpart students with v Physics	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods nodern methods <u>Engineering Mat</u> various Vibration	on Techniques i roblem edge Brin (An hematics Dyna and Noise Analy	n Design (ANY gs Freedo y Three) mics of Machin	Z Three)	2 2 2 2 2 2 6		
Expt. 1. 1 2. 1 3. 2 4. 6 5. 6 Pre-requisi 0 Objectives: To in	Ilabus: Pa Description Mathematical modeli Primal dual simplex Sensitivity analysis o Optimization using n Optimization using n Total te: Physics	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods nodern methods <u>Engineering Mat</u> various Vibration	on Techniques i roblem edge Brin (An hematics Dyna and Noise Analy	n Design (ANY gs Freedo y Three) mics of Machin	Z Three)	2 2 2 2 2 2 6		
Expt. 1. 1 2. 1 3. 2 4. 6 5. 6 Pre-requisi 0 Objectives: To in	Ilabus: Pa Description Mathematical modeli Mathematical modeli Primal dual simplex is Primal dual simplex is Optimization using n Optimization using n Optimization using n Total Physics mpart students with v Physics	roblems art A: Optimizati ng of a real life p method f linear problem on-linear methods nodern methods <u>Engineering Mat</u> various Vibration	on Techniques i roblem edge Brin (An hematics Dyna and Noise Analy	n Design (ANY gs Freedo y Three) mics of Machin	Z Three)	2 2 2 2 2 2 6		

After learning the course, the students should be able to:

- 1. Apply Vibration measurement techniques and Analyse using modern tools and technique.
 - 2. Understand Basic principals in acoustics, measurement of sound Power and apply to analyze effectiveness in compliance to noise regulations.

<u>o etuneu</u>	Syllabus: Part B: Advanced Vibrations and Acoustics (ANY Three)	
Expt.	Description	Duration
1.	Case Study on - Time domain and Frequency domain analysis of signals / experimental modal analysis / machine conditioning and monitoring / fault diagnosis	2
2.	Simulation study using finite element Analysis Tool on a. Modal analysis b. Harmonic analysis c. Transient analysis	2
3.	Modal Analysis with Impact Hammer Test	2
4.	Electro Dynamic Shaker to Obtain Natural Frequency and Dynamic Studies of a Cantilever Beam.	2
5.	Case study Analysis machine noise signature and analyze effectiveness in compliance to noise regulations.	2
	Total (Any Three)	6
Fext Boo	oks:	
2.	Engineering Optimization: Theory and Practice, Singiresu S. Rao, John Wiley & Sons Mechanical Vibrations, S. S. Rao, Pearson Education, Delhi Industrial Noise Control, Randell Barron, Marcel Dekker, Inc.	
Referen	ze Books:	
2. 3.	Optimization Concepts and Applications in Engineering, Belegundu, Chandrupatla, Machinery Condition Monitoring: Principles and Practices, A. R. Mohanty, CRC Press, 20 Vibration and Acoustic: Measurement and Signal Analysis, C. Sujatha, Tata McGraw Hill Pvt. Ltd	14 Education

"Knowledge Brings Freedom"



Program	n:	M. Tech. Mechanica	al (Design Engine	ering)	Semester	: II	
Course	:	Fatigue and Fractur	re Analysis (Electi	ive)		MD2504A	
		Teaching Scheme			Evalua	tion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
Pre-req	uisite:				-		
	1.	Machine Design 2	. Engineering Meta	allurgy 3. Mater	ial Science		
Objecti	ves:						
1.		sess fatigue life at diffe					
2.		ake aware about the an	alysis of Fracture N	Mechanics of m	echanical compo	onents	
Outcom		the course, the students	should be able to:				
Allerie	1.	Identify the cycle c			rain based appro	oach in fatique fa	ilure
	2.	Understand the use					
	3.	Apply the fatigue fa					
	4.	Apply linear elastic					2.
	5.	Estimate crack resis					
	6.	Examine the crack	ip opening displac	ement and shap	be by using differ	rent approximatio	on.
Detailed	l Svlla	bus				0	
Unit		cription	1			0	Duration, h
		gue Mechanics	S. /		12	3	
1.		e varying uniaxial, bia					10
		ting, fatigue damage th	eories of crack init	tiation, stress ba	used and strain b	ased approach	
2.		gue Testing acquisition and instru	montation classica	l mathods of f	tique testing A	STM standards	4
		cimen preparation, pro		ii methous of 1a	lingue testing, A	STIVI Standards	4
-		ial Cases in Fatigue	courre				
3.		ue analysis in frequ	ency domain, vib	ration fatigue,	fatigue of we	lded structure,	5
		osion fatigue, high temp				12	
		ar Elastic <mark>Fracture</mark> M					
4.		nanisms of fracture, i ria and fracture - effec					6
		ry of fracture, energy b				icept – Offittur	
		s Intensity factors –				e crack, double	
5.		crack, round hole with	. .				5
		3) criterion		Vince 199°			
(tic – Plastic Fracture		i (i F	11,	· 1	~
6.		duction, crack tip streating displacement, shap					6
	Tota		e of the plastic zon		and Tresea yield	ing criteria,	36
Text Bo							
	1. F	atigue Testing and Ana	alysis – Theory and	l Practice, YUN	IG-LI LEE, Else	vier	
	2. F	atigue of Structures an	d Materials, Japp S	Schijve, Kluwer	Academic		
	3. N	Ietal Fatigue in Engine	ering, Ali Fatemi,	Wiley-Interscie	ence		
	4. E	lements of Fracture M	echanics, Prashant	Kumar, Mc Gra	aw Hill Education	on	
Referen	ce Boo	oks:					
		Ietal Fatigue Analysis	Handbook, YUNG	-LI LEE, Elsev	ier		
		esign & Analysis of F				Voodhead Publis	hing
		racture Mechanics And	-		2		
		racture Mechanics, Ne					
		racture Mechanics – A					
		Ionlinear Fracture Mec Deformation and Fractu				R W John W:	lev & Sone Inc
	7. D	erormation and Fractu	ie micenanies of El	ing incoming width	mais, mentzuelg	, IX. 11. , JUIII 111	icy & Sons, me.

Program	:			l (Design Engine		Semester		
Course :				ering Design (El	ective)	Code : M		
		Tea	ching Scheme	1		Evaluat	ion Scheme	
Leo	cture		Credit	Hours	IE1	IE2	ETE	Total
	3		3	3	20	30	50	100
Pre-requ								
Engineer	ing Ma	athema	tics					
Objectiv	es:							
2.	Го со	mpute	eliability enginee reliability engi g environments.	ering analysis. neering paramete	ers and estimat	tes for applicati	ons in mechan	ical devices a
Outcome	s:							
After lean 1. 2. 1 3. 1	rning ti Identif Develo Evalua	y the p p faul te mai	oossible faults in t trees for a sub-s	should be able to: systems and their system and apply les and assess the	[·] imp <mark>ac</mark> ts to the overload to the overload to the overlaphic tensor of tensor	ity models on fau	lt analysis.	and tools.
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Unit		riptio					2	Duration, h
1.	Failu	re dens		hazard rate, MT s, modes of failu			ilability, pdf,	6
2.	Fund Quali	ament ty and al, Poi	cal concepts – II reliability assura		ct liability, prob	ability distribution		6
3.	Syste Series	m reli s, paral	llel, mixed confi	guration, k- out of ity method, cut so			enumeration	6
4.	Redu Eleme	ndanc ent red	y undancy, unit re		y redundancy-	types of stand by		6
5.	Syste Relia	m reli a bility a	ability Analysis apportionment, 1	Reliability apport of objectives app	tionment techni			6
6.	Failu Failu	re Mo re mo	de, Effects and de effects analy	Criticality Analy ysis, severity/crit representation, fa	v sis ticality analysis		mples, RPN,	6
	Tota		0	i ,				36
Text Boo	ks:							
				eliability Engg., 2 7 Engineering, Ta				
Reference	e Boo	ks:						
	2. B.S. 3. M.L	Dhilli Shoo	on, C. Singh, En man, Probabilist	ineering, Tata M gineering Reliabi ic, Reliability, M jability Engg., Jo	lity, John Wiley cGraw-Hill Boo	v & Sons, 1980. ok Co., 1968.	1983.	

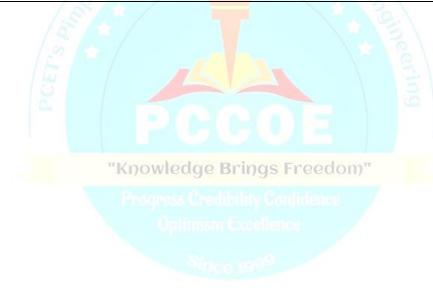
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Program:	M. Tech. Mechanical (Design Engineering) Semester : II				: 11	
Course :	Mechatronics and Co			Code : M	MD2504C	
	Teaching Scheme	v	,	Evaluat	ion Scheme	
Lecture	Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisite:						
	athematics, Mechatron	nics				
Objectives: 1. Select	and Apply various sens	ore/transducars fo	or suitable appli	cation		
	sensors/transducers bas					
	stand and apply, interface		•	ensues		
	l mechanical and electro	-				
	n controller in time and	•				
	stand control actions su			nd integral and s	tudy its signific:	ance in industria
applic		ion us rroportion	ai, deili aire ai	la integrar ana s	ludy no biginne	
Outcomes:	-		d la la			
	the course, the students	should be able to:				
-	se static and dynamic ch		struments and S	Select and Apply	sensors/ transdu	cers for
	rements of physical qua					
	interfacing techniques		ement data from	n external enviro	nment and apply	y filtering
	ques to attenuate measu					U
3. Form	late the mathematical m	nodel in by using	trans <mark>fer</mark> function	n and state space	modelling appr	oach.
4. Analy	ze system stability base	d on pole location		Hurwitz criterion		
	ze system stability base n the control system for		and by Routh-		ı. S	esponse.
5. Desig	n the control system for	meeting desired s	and by Routh-	time domain bas	n. ed on transient r	•
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 Desig Desig freque Detailed Sylla Unit Desig Junit Desig 3. Fund Class Sens Nois Vary meas 2. Inter Data ADC Low 3. Mati Class funct ADC Low 3. Mati Class Sens Nois Vary meas 2. Inter Data ADC Low 3. Mati Class funct Spect Zeroo on R 5. Con Intro space using 6. Con 	n the control system for n the control system in ency domain by Bode pla bus: cription damentals of Instruments ors and Transducers: For e Measurement: Acceler ing Resistance; pressu- surement. cracing with Microcont Acquisition System, A crucessive Approxime Pass, Band Pass and High hematical Modelling of sification of modelling tion, State space modelli ility analysis of Dynam s and Zeros, System fications, Absolute an s of System, Stability of outh Hurwitz criterion trol in Time Domain duction to open loop an e. Controllability and of g pole placement techning	meeting desired s n frequency dom ot. ntation ; Characteristics of orce, Speed Meas rometer, Laser Do ure: Pirani, Mcle roller Analog and Digination, Dual slope, gh Pass; Interfacin c Dynamic System g, Modelling of ing, Block diagram nic Systems response of s ind relative stabilit f system using Ly d closed loop cor bservability of sy pue, Pole placemeet ain	and by Routh- pecification in ain and Analy of Measurement urement, Strain oppler Vibrome eod; flow rate tal Signals, Ba DAC: R-2R, b ng of sensors/ac ns Mechanical, in representation second order y, System Stab apunov's criter ntrol, Conversice ystem, Full stat nt using Ackerr	time domain bas ze system stabi t system: Static a Measurement, Y eter, Temperatur e: Ultrasonic; a ndwidth, Samp inary weighted, tuators with Ard Electro-mechani and reduction system, Transie ility analysis usi ion, Stability of on of transfer fur e feedback cont nan's formula	n. ed on transient relity in open and and Dynamic; Vibration and e: Pyrometer, and humidity ling theorem, Noise Filters: luino cal, Transfer ent response ing Poles and system based action to state rol of system	Closed loop in Duration, h 6 6 6 6 6

	response.	
	Total	36
2. A	ooks: leasurement and Instrumentation – Theory and Application, Alan Morris, Reza Langari, Elsevie lciatore & Histand, Introduction to Mechatronics and Measurement system, 4th Edition, McGra 011	
3. C	ontrol System Engineering, Norman Nise, 6th Edition, John Wiley and Sons	

Reference Books:

- 1. Mechanical Measurements, S.P. Venkateshan, Ane Books Pvt. Ltd.
- 2. Measurement Systems-Application and Design, Doebelin E.O, McGraw Hill Publication
- 3. Park & Mackay, Practical Data Acquisition for Instrumentation & Control System, Elsevier, 2003
- 4. Dorf& Bishop, Modern Control Systems, 12th Ed, Prentice Hall
- 5. Ogata, Modern Control Engineering, 4th Ed, Prentice Hall
- 6. Golnaraghi & Kuo, Automatic Control Systems, John Wiley publications, 2010
- 7. C. D. Johnson, Process Control Instrumentation Technology, Prentice Hall, New Delhi
- 8. Astrom & Hagglund, PID Controllers: Theory, Design & Tuning, Chapter 2, 2nd Ed, Instrument Society of America, 1995.
- 9. J. P. Holman; "Experimental Methods for Engineers" McGraw Hill International Editions, Mechanical Engineering Series. ISBN 0-07-113354-2



Program: Course :	M. Tech. Mechanica Design of Material H			Semester Code : M		
Course :	Teaching Scheme		ent (Elective)		tion Scheme	
				Evalua	lion Scheme	
Lectu	re Credit	Hours	IE1	IE2	ETE	Total
3	3	3	20	30	50	100
Pre-requisi						
	eory of Machines					
	achine Design					
Objectives:			1 1 .	•		
	reasilze the importance of derstand the benefit of an e			ervice		
	entify and select various type			te		
	sign of material handling s				facturing and se	ervice industry.
Outcomes:	sign of material nanding s	jstems for variety	of section per		uoturing und se	strice maasay.
	ng the course, the students	should be able to				
1. Ic	lentify the use and importa	nce of material ha	ndling			
	lentify different loads and		0	application		
	pply the design procedures				onents and desi	gn the
n	naterial handling system.					
	esign load lifting & load m		en <mark>ts with p</mark> roper	design consider	ration understa	nd the use
	f automation in material ha					
	esign the auxiliary equipm	ent			-	
Detailed Sy					2	Daras 4 1
Unit	Description				6.	Duration, h
	Material handling system		lling system	mortanco to	minology	
	Principles and features of material handling system, importance, terminology, objectives and benefits of better material handling, classification of material handling					
	equipment	better material na	numig, classific		a nanding	
	Selection of material han	dling equipment			2	
	Choice of material handlin		ors affecting for	selection, gener	al analysis	6
	procedures, basic analytica	l techniques, the u	nit load concept			
	Design of cranes					
	Hand-propelled and travel					6
	considerations for structu					Ŭ
	overhead traveling cranes,	stability of station	ary rotary and tr	aveling rotary of	cranes,	
	Design of cranes		tial manta dagi	an nananatana	atmu atumal	
	Electric overhead travelli					6
	considerations, end carriages, long and cross travel mechanisms, brakes, motor selection, safety arrangements, electrical control system					
	Load lifting attachments					
	Load chains and types of r	opes used in mate	rial handling sv	stem, forged, sta	andard and	
	Ramshorn hooks, crane					6
	sheaves, sprockets		-			
	Study of bulk material ha	0.				
	Design consideration for co					-
	gravity flow of solids through					6
	conveyor, vibratory conve	yor, pneumatic &	hydraulic conve	eyor (classificat	tion, types,	
	principles of operation)					26
Text Books	<u>Total</u>					36
IEXT DOOKS	 N. Rudenko, 'Materi 	al Handling Fauin	ment' Peace Di	hlishers		
	 N. Kudeliko, Materi James M. Apple, 'M 				Sons	
	3. John R. Immer, 'Mat			and they are		
Reference 1		111				
	1. Colin Hardi, 'Materi	al Handling in Ma	chine Shops'. M	lachinery Public	cation Co. Ltd.,	
	2. M.P. Nexandrn, 'Ma	aterial Handling E	quipment', MIR	Publication,		
	3. C. R. Cock and J. M.	ason, 'Bulk Solid I	Handling', Leon	ard Hill Publica		
	4. Spivakovsy, A.O. an					IR Publishers,
	5. Kulwiac R. A., 'Mat	erial Handling Ha	nd Book'. John	Wilev Publicati	ion	

Program:	M. Tech. Mechanical		ering)	Semester				
Course :	Computer Aided Des	ign (Elective)	1		MD2505B			
	Teaching Scheme	1		Evalua	tion Scheme			
Lecture	Credit	Hours	IE1	IE2	ETE	Total		
3	3	3	20	30	50	100		
Pre-requisite:	:							
	ors, Programming langua							
	ecommended to have know	owledge of any ge	cometric modelin	ng software.				
Objectives:			6	•		1 . 11		
	tends to give students a				es of the product d	evelopment Iil		
Outcomes:	ion, geometric modelling	g, design and grap	nical representat	1011.				
	the course, the students	hould be able to:						
	ate mathematical transfo		iections of rigid	hodies				
	gn & model curves, surfa		eetions of fight	boules.				
	lop codes to solve engine							
	ement various algorithms		uter Graphics					
Detailed Sylla								
Unit D	escription		1 1 2			Duration, h		
1. Co	mputer aided Design –	An insight		0/1		6		
	typical product cycle, the	01	1	0	0			
	ocess, Hardware require							
	aphical memory, Concep		y <mark>stems, Software</mark>	requirements i	in CAD			
	eometric Transformation				2	6		
	omogeneous representati			Reflection, Rot	ation, Shearing			
	2D and 3D; Orthographi	c and perspective	projections.	$\sim \sqrt{2}$	121			
	irves and Surfaces					6		
	Lines, scan conversion algorithms for lines, point on a line, parallel lines, perpendicular							
	lines, distance of a point, Intersection of lines, Circle, Ellipse and general curves (parabola							
	d hyperbola),		I' D '	a ii	9			
	bic Spline: equation, p							
	operties and advantages eir typical applications.	of B-Splines and	NURBS. Variou	is types of surf	aces along with			
	mputer Aided Geomet	rie Design Curr	206			6		
	ane Curves, Space Curv			rit Parametric	curves The de	U		
	steljau Algorithm, de E							
				urve-Curve Intersection, Hermit,				
	zier, B-Spline curves		ism Exceller	ice /	, , , , ,			
	mputer Aided Geomet	ric Design - Surfa	aces			6		
	im Surfaces, Curve and			And Surface F	From Algebraic			
	uation, Curve And Sur							
	rface-Surface Intersection	n, Projection Of C	Curves On Surfa	ces, Projection	Of Surface On			
	rfaces	•				-		
	lid Modelling and Appl		. C. T. 1			6		
	roduction, solid represe							
	p), Constructive Solid C	•		-				
	awings, Extrusion, Revocations	volve, silell, Dra	an, ratterning,	Surface and	Solid Dooleall			
	otal					36		
Fext Books:	Utul					50		
	Adams, Mathematical E	lements for Comp	uter graphics T	ata McGraw –	Hill, New Delhi 2 ^r	d Edition 2007		
	earn and M. Pauline Bak							
	graphics, Schaum Series				inter i i i i i i i i i i i i i i i i i i i			
	graphics- Foley Van Da			1996				
Reference Bo			-					
	J. and Steadman, P., Prin							
	Iua Chang, Product Desig		g CAD/CAE - T	he Computer A	lided			
3. Engineer	ring Design Series, Elsev	ier Inc., 2014						

Progra		Tech. Mechanical		ering)	II		
Course	: Mul	ti-body Dynamics	(Elective)		Code : MN	AD2505C	
	T	eaching Scheme			Evaluat	ion Scheme	
Le	ecture	Credit	Hours	IE1	IE2	ETE	Total
	3	3	3	20	30	50	100
		Theory of Machi	nes, Engineerin	g Mathematics			
Objecti				1 1 1'			
		nematically and d			6		
Outcon		nematically and d	ynanneany anarys	se figia boales			
	arning the c 1. Deriv dimer 2. Imple	ourse, the students we equations of mo- nsional motion. ement and analyze	tion for interconr methods of form	nected bodies in mulating equation	ns of motion for i	interconnected	
	4. Simu	e programs to solv late and analyze a ling the kineto-sta	ll types of static a	-			
Detaila	d Syllabus	ang the kineto-sta	ue analysis.	-			
Unit	Descriptio)n	1.110	d	Court		Duration, h
		n ciples for analysis	of multi-body s	vstems	100		2 ai ativily li
1.	The constra The autom	aints for planar kir natic assembly of n analysis. Iterative	nematic analysis. the systems o	Revolute, prisr f equations fo	r position, velo		6
2.	Geometry of generalized	on of Forces, plan of masses, compute forces for externa	ation and assemb 1 forces and for a			of planar	6
3.	Computatio	ion of Forces, spectrum on of spatial gener a Lagrange's multi-	alized forces for	external forces	. Computation of	f reaction	6
4.		of Planar Systems of planar systems		ations of inver	se and forward	dynamic	6
	Kinematic	s of rigid bodies i	n space				
5.	parameters.	frames for the l Screw motion p between the an	in space. Veloc	ity, acceleratio	on and angular	velocity.	6
		analysis of spatia	l systems	Inisin Cacel	ence		
6.	Basic kiner description	matic constraints. in space of comm Equations of motio	Joint definition non kinematic pa	airs (revolute, p	orismatic, cylindr		6
	Total	Equations of motif		spana systems	•		36
							••
Text B 1. 2. 3. 4. 5. 6.	Wittenburg Kane, T.R. Nikravesh 1988. Roberson, Haug, E.J. Bacon, 198 Huston, R.	L., Multibody Dyn	Dynamics: Theor Aided Analysis o k, R., Dynamics o Kinematics and I pamics, Butterwoo	y and Application f Mechanical S of Multibody Sy Dynamics of Me rth-Heinemann,	ons, McGraw-Hil Systems, Prentice stems, Springer-V chanical Systems 1990.	ll Book Co., 19 -Hall Inc., Eng Verlag, Berlin, s-Basic Method	lewood Cliffs, N 1988.
7. 8. 9.	de Jalo n, .	W. ed., Multibody J.C., Bayo, E., Kin A.A., Computation	ematic and Dyna	mic Simulation	of Multibody Sys		Verlag, 1994.

Reference Books:

- "Why Do Multi-Body System Simulation?" by Rajiv Rampalli, Gabriele Ferrarotti & Michael Hoffmann, Published NAFEMS Publications, January 12 "Principles of Dynamics" by Donald T. Greenwood, 2nd ed., Prentice Hall 1.
- 2.

Program	n: M.Tech. Mecha	nical (Design En	gineering)	Sen	nester : II	
Course :	Professional Ele	ective Lab II		Cor	le : MMD2506	
Course.	Lab Name : Ele	ctive III & Elect	ive IV			•
	Teaching Schem	e		Evalua	tion Scheme	
Practic	al Hours	Credit	TW	PR	OR	Total
2	2	1	50		50	100
Pre-requ				1 1	I	
	es: This course is to provide and the principles.	de students the too	ols required for S	imulate, correlate	and validate th	eoretical concepts and
Outcome After lear	 Solve open end Simulate the prime Understand the 	lents should be at led Design proble roblem and correl impact of assum nalyse, interpret a	em and report the ate with theoretic aptions on the sim	al concepts sulated results		
Guidelin		laryse, interpret a	nd report the resu	Its.		
	Any one subject from	Part A and Part	B as per students	elective choices		
	Total experiments to be		-		n Part B	
	Total : 6 experiments				10	
0.	rotur to experiments					
	Detailed Sylleburg					
	Detailed Syllabus:	A: Elective 1- Fa	tique and Fract	uro Analysis (Al	W Three)	
Expt.	Description	A. LIECUVE I- Fa	ligue and Flact	are Analysis (Al	vi imee)	Duration
<u> </u>	Case Studies based o	n		-	1 = 1	Durution
	Rain Flow Counting	Technique 🦯			61	2
2.	Stress / Strain Based					2
3.	FEA Simulation of f	0				2
4.	Crack tip stresses usi			and the second second		2
5.	Stress Analysis using	Image Processin	geage Brin	gs Freedoi	D	2
	Total	. Fl. 4 1 D.l	- 1 114	Destant (06
Event	Description	: Elective 1- Rel	lability in Engin	eering Design (A	(NY Inree)	Duration
Expt.	Characteristics of Bi	nomial and Poiss	on distributions			
<u>1.</u> 2.	Characteristics of No			2		2 2
<u> </u>	Determination of MT			,		2
<u> </u>	Evaluation of basic p			rallel systems		2
5.	Markov Analysis of		151 Series and pa	and systems		2
<u> </u>	Reliability allocation					2
	Failure mode effects		/ amiti a ality			2
7.		analysis, severity				4
7.	Total	analysis, severity				06
7.	Total Part A:		2	ontrol Systems (ANY Three)	
	Part A:	Elective 1- Mecl	2	ontrol Systems (ANY Three)	06
Expt.	Part A: Description	Elective 1- Mecl	hatronics and Co	ontrol Systems (ANY Three)	
	Part A: Description Interfacing of any set Modelling and Analy	Elective 1- Mecl nsor / actuator wit vsis in Time Doma	hatronics and Co h Arduino ain: State Space N			06 Duration
Expt. 1.	Part A: Description Interfacing of any ser Modelling and Analy System using MATL Modelling and Analy	Elective 1- Mecl nsor / actuator wit ysis in Time Doma AB and Simulink ysis in Frequency	hatronics and Co h Arduino ain: State Space M Domain: Transfe	Aodelling of MIM	IO/SISO	06 Duration 2
Expt. 1. 2. 3.	Part A: Description Interfacing of any ser Modelling and Analy System using MATL Modelling and Analy MIMO/SISO System	Elective 1- Mecl nsor / actuator wit ysis in Time Doma AB and Simulink ysis in Frequency using MATLAB	hatronics and Co h Arduino ain: State Space M Domain: Transfe and Simulink	Nodelling of MIM	IO/SISO	06 Duration 2 2 2 2
Expt. 1. 2.	Part A: Description Interfacing of any ser Modelling and Analy System using MATL Modelling and Analy	Elective 1- Mecl nsor / actuator wit vsis in Time Doma AB and Simulink vsis in Frequency using MATLAB ro and analysis of	hatronics and Co h Arduino ain: State Space M Domain: Transfe and Simulink system stability	Aodelling of MIM r Function Model of mechanical sys	IO/SISO	06 Duration 2 2

Expt.	Description	Duration
1.	Case Studies Based on	
	Use and importance of different material handling equipment's.	2
2.	Safety in Material handling system.	2
3.	Design aspects and failures in the material handling system	2
4.	Design of any one material handling system based on Manufacturing assembly and cost consideration.	2
	Total	06
	Part B: Elective 2- Computer Aided Design (ANY Three)	
Expt.	Description	Duration
1.	Curves: Line DDA, Line Bresenham, Circle Bresenham	2
2.	Curves & Clipping: Mid-point ellipse, Window Clipping	2
3.	Transformations: Translation, Rotation, Scaling, Shear, Mirror	2
4.	Transformations: Combination of above	2
5.	Curves: Bezier curve, B-spline Curve, Hermite Curve,	2
6.	Surfaces: Lofted Surfaces, Bezier surface, B-spline Surface	2
	Total	06
	Part B: Elective 2- Multi-body Dynamics (ANY Three)	
Expt.	Description	Duration
1.	Velocity and acceleration analysis of planar systems	2
2.	Constraint analysis for planar kinematic analysis for revolute, prismatic, gear and cam pairs	2
3.	Dynamic analysis of planar systems	2
4.	Inverse and forward dynamic analysis	2
5.	Kinematic analysis of rigid bodies	2
6.	Kinematic analysis of spatial systems	2
7.	Reaction forces from actuator-spring-damper system	2
	Total	06

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Department of Mechanical Engineering

Program:	M. Tech Mecha	nical (Design Eng	gineering)	Semeste	Semester : II				
Course :	-	ent Lab - II (Soft	Skills and Englis	h Code: 1	M 2101				
0000000	Aptitude)				on Scheme				
	Teaching Schem	le		Evaluati	on Scheme				
Practica	l Hours	Credit	TW	PR	OR	Total			
2	2	2	50		-	50			
Objective									
	o facilitate holistic gro		· · · · · · · · · · · · · · · · · · ·		1 4 1				
	o make the students av	•		-	-				
	o develop the ability o		•		• •				
4. T	o expose students to ri	ight attitude and be	ehavioural aspects	and build the	same through variou	s activities			
Outcomes	5:								
	ning the course the stud	dents should be abl	le to:						
1. E	express effectively through	ough verbal/oral co	mmunication skill	s					
2. P	repare for group discu	ssions/meetings/in	terviews and prese	entations					
3. C	Deprate effectively in	multi-disciplinary	and heterogeneou	s teams throu	gh the knowledge o	f team work,			
ir	nter personal relationsh	nips, conflict mana	gemen <mark>t an</mark> d leader	ship activities					
		achw.		- VII Pa					
Guideline									
	otal experiments to be		out of eight						
	otal : 6 experiments	12 hours	<u> </u>		81				
Detailed S	Syllabus:	Skill Dovo	lopmen <mark>t L</mark> ab (Al	IV Sir)	2.				
Expt.	100	Skiii Deve	iopinent Lab (Al	NI SIX)		Duration			
Елри	Description					h			
1.	Group Discussion:	Make students aw	vare of proper and	globally acce	epted ethical way to				
	handle work, colleag					2			
	one's opinion in a f			enting solution	on-driven analytical	-			
2.	arguments making th	iem contributors in	any team.						
4.	Public Speaking:	· · · · · · · · · · · · · · · · · · ·	1						
	Any one of the follo 1. Prepared speech	• • • • • • • • • • • • • • • • • • •	11/10/15/11/1/15	nts get 10 mi	nutes to prepare the	2			
	speech and 5 minu					-			
	spontaneously for 5 i				s conver specenes				
3.		0.0	imism Excelle	10:6	. 1	_			
	Writing An Article knowledge about how			skins, improv	e language and gain	2			
4.	Reading and Liste			ded into pairs	. Each pair will be				
	given a article by the								
	article one by one. A					2			
	and needful correcti	ons in the article.	The facilitator car	evaluate the	students for reading				
	and listening skills.			evaluate the	e				
5.	Debate On Current		elevance Topics:	Cultivate the h	abit to present				
5.	Debate On Current forceful arguments w		elevance Topics:	Cultivate the h	abit to present	2			
5.	forceful arguments w	while respecting the	elevance Topics: e opponents perspe	Cultivate the lective and enha	nabit to present ance verbal skills.	2			
		tes: To teach stude	elevance Topics: e opponents perspe	Cultivate the here the fective and enha	habit to present ance verbal skills.	2			
	forceful arguments w Telephonic etiquet phone. Students will such as phone call	tes: To teach stude l be divided into j to enquire about	elevance Topics: e opponents perspe ents the skills to c pairs. Each pair w t job vacancy, so	Cultivate the h ective and enha ommunicate e vill be given d cheduling a n	abit to present ance verbal skills. ffectively over the lifferent situations, neeting with team				
	forceful arguments w Telephonic etiquet phone. Students wil such as phone call members, phone cal	tes: To teach stude tes: To teach stude l be divided into j to enquire about l for requesting of	elevance Topics: e opponents perspe ents the skills to c pairs. Each pair w t job vacancy, so urgent leave from	Cultivate the h ective and enha ommunicate e vill be given d cheduling a n higher author	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will	2			
	Telephonic etiquett phone. Students wil such as phone call members, phone call be given 10 min to p	tes: To teach stude tes: To teach stude l be divided into j to enquire about l for requesting of	elevance Topics: e opponents perspe ents the skills to c pairs. Each pair w t job vacancy, so urgent leave from	Cultivate the h ective and enha ommunicate e vill be given d cheduling a n higher author	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will				
6.	Telephonic etiquett phone. Students wil such as phone call members, phone call be given 10 min to p the telephone call.	tes: To teach stude tes: To teach stude l be divided into p to enquire about l for requesting of prepare. Assessment	elevance Topics: e opponents perspe- ents the skills to c pairs. Each pair w t job vacancy, so urgent leave from nt will be done on	Cultivate the h ective and enha- communicate e will be given d cheduling a n higher author the basis of p	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will erformance during				
	forceful arguments w Telephonic etiquett phone. Students wil such as phone call members, phone call be given 10 min to p the telephone call. Email etiquettes: T	tes: To teach stude tes: To teach stude l be divided into p to enquire about l for requesting of prepare. Assessment	elevance Topics: e opponents perspe- ents the skills to c pairs. Each pair w t job vacancy, so urgent leave from nt will be done on	Cultivate the h ective and enha- communicate e will be given d cheduling a n higher author the basis of p	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will erformance during				
6. 7.	forceful arguments w Telephonic etiquet phone. Students wil such as phone call members, phone call be given 10 min to p the telephone call. Email etiquettes: T emails.	tes: To teach stude tes: To teach stude l be divided into p to enquire about l for requesting of prepare. Assessmen o provide students	elevance Topics: e opponents perspe- ents the skills to c pairs. Each pair w t job vacancy, sc urgent leave from nt will be done on s with an in-depth	Cultivate the h ective and enha- communicate e will be given d cheduling a n higher author the basis of p understanding	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will erformance during	2			
6.	forceful arguments w Telephonic etiquett phone. Students wil such as phone call members, phone call be given 10 min to p the telephone call. Email etiquettes: T	tes: To teach stude tes: To teach stude l be divided into p to enquire about l for requesting of prepare. Assessmen o provide students	elevance Topics: e opponents perspe- ents the skills to c pairs. Each pair w t job vacancy, sc urgent leave from nt will be done on s with an in-depth	Cultivate the h ective and enha- communicate e will be given d cheduling a n higher author the basis of p understanding	habit to present ance verbal skills. ffectively over the lifferent situations, neeting with team ities. Students will erformance during	2			

Text Books:

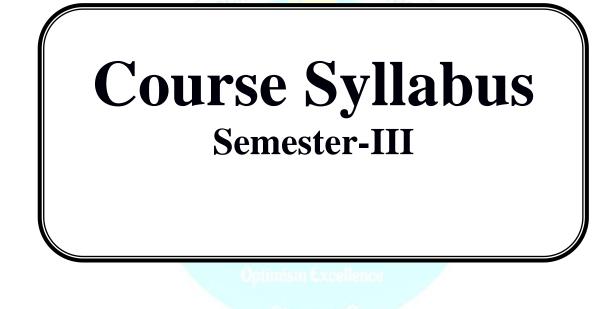
- 1. B. Mitra, Personality Development and Soft Skills
- 2. S. Lucas, The Art of Public Speaking

Reference Books:

- 1. M. Weaver, Empowering Employees Through Basic Skills
- 2. G. Ratigan, Aced: Superior Interview Skills to Gain an Unfair Advantage to Land Your DREAM JOB!



Program:	M. Tech. Mecha		Semester : II			
Course :	Integrated Mini		<u> </u>		Code : MMD2	2701
	Teaching Schem			Evalu	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
6	6	3	50		50	100
	e: cs of Design, Finite cs of MATLAB and			Acoustics, Com	posites	
2. To p 3. To 1	inderstand the 'Proc lan for various acti- build, design and 'orms.	vities of the proje	ect planning and ex	ecution.		ect. omain using available
 Und Desi Prep Deli Und 	g the course the stud erstand, plan and ex gn real time applica are a technical repo ver technical semin erstand publication Total : 36 hours	ecute a Mini Prontion. The based on the Mar based	ject. Iini project. Iini Proj <mark>ect work</mark> (carried out.	~	
2. Stud impl	ementation in Majo	area of project	in field of Mu	-		cated guide. nsidering their futur
	hardware implement	ntation on the boa	nd year and software si	mulation is con	pulsory.	
-	i-Project Report sho er publication assoc	ould be submitted iated with mini-p	rd and software si as a compliance o roject as research	of term work as outcome is app	sociated with su	bject.
6. Min	i-Project Report sho er publication assoc i-project work prefe	ould be submitted iated with mini-p	rd and software si as a compliance o roject as research	of term work as outcome is app	sociated with su	bject.
-	i-Project Report sho er publication assoc i-project work prefe	ould be submitted iated with mini-p erably should be c	and software si as a compliance or roject as research completed in labor	of term work as outcome is app atory.	sociated with su	bject.
6. Min Detailed Syll	i-Project Report sho er publication assoc i-project work prefe	ould be submitted iated with mini-p prably should be c	and software si as a compliance or roject as research completed in labor ntegrated Mini-P	f term work as: outcome is app atory. roject	sociated with su reciable.	
6. Min	i-Project Report sho er publication associ i-project work prefe abus: Activity	buld be submitted iated with mini-p prably should be c In Mini-project guide	and software si as a compliance or roject as research completed in labor	f term work as: outcome is app atory. roject	sociated with su reciable.	bject. Duration, h
6. Min Detailed Syll Sr. No.	i-Project Report sho er publication associ i-project work prefe abus: Activity Week 1 & 2 : M Planning of the w Week 3 & 4: Lit	and be submitted iated with mini-p erably should be c In fini-project guide vork erature review an	and software si as a compliance or roject as research completed in labor ntegrated Mini-P	of term work assoutcome is appratory.	sociated with sur- reciable. and platform,	Duration, h
6. Min Detailed Syll Sr. No. 1. 2. 3.	i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lit Review 1 for fin Week 5 & 6 : S of hardware plat	ould be submitted iated with mini-p prably should be c In Mini-project guide vork erature review an alization of topic imulation of Idea form	and software si as a compliance of roject as research completed in labor ntegrated Mini-P completed in labor and specification and and specification. a on appropriate so	of term work assoutcome is appratory. roject zation of topic ad Methodology oftware tools an	and platform, Finalization, d finalization	Duration, h
6. Min Detailed Syll Sr. No. 1. 2.	i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lit Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : ur	auld be submitted iated with mini-p erably should be c In Mini-project guide vork erature review an alization of topic imulation of Idea form aderstanding plat	ard and software si as a compliance or roject as research completed in labor ntegrated Mini-P allotment, finali and specification an and specification.	of term work assoutcome is appratory. atory. roject ator of topic and Methodology oftware tools and on and related	and platform, y Finalization, ad finalization	Duration, h 6 6
6. Min Detailed Syll Sr. No. 1. 2. 3.	i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lift Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : ur and execute blo project Week 9 & 10: M and execution.	ould be submitted iated with mini-p erably should be c In Mini-project guide vork erature review an alization of topic imulation of Idea form iderstanding platt ck level design	and software si as a compliance of roject as research completed in labor integrated Mini-P and specification and and specification and and specification and form implementat , Review 2 to un rt writing and pub	of term work as outcome is appratory. roject zation of topic ad Methodology oftware tools an on and related derstand the pr ication or copy	and platform, y Finalization, and finalization software flow rogress of the right planning	Duration, h 6 6 6
6. Min Detailed Syll Sr. No. 1. 2. 3. 4.	i-Project Report sho er publication assoc i-project work prefe abus: Activity Week 1 & 2 : M Planning of the v Week 3 & 4: Lift Review 1 for fin Week 5 & 6 : S of hardware plat Week 7 & 8 : ur and execute blo project Week 9 & 10: M and execution.	ould be submitted iated with mini-p prably should be c In Mini-project guide vork rerature review an alization of topic imulation of Idea form inderstanding plattick level design (ini Project Report Demonstration of	and software si as a compliance of roject as research completed in labor ntegrated Mini-P and specification and and specification and and specification and on appropriate so form implementat , Review 2 to un	of term work as outcome is appratory. roject zation of topic ad Methodology oftware tools an on and related derstand the pr ication or copy	and platform, y Finalization, and finalization software flow rogress of the right planning	Duration, h 6 6 6 6 6



Program:	M. Tech. (Mech	anical) – Design 🛛	Engineering	S	emester: III	
Course :	Dissertation Pha	ase – I [Company	/ In-house projec	ct] C	ode: MMD3702	
Te	aching Scheme/we	ek		Evalua	tion Scheme	
Practical	Hours	Credit	IE2	PR	OR	Total
20	20	10	100		100	200
Pre-requisite:						
Basic knowledge	e of Mechanism and	Machine Design,	Mechanical syste	m design, Bas	ics of Analysis sof	tware, MATLA
programming						
Objectives:						
	erstand the product/p					
	n for various activ	vities of the ma	jor project and	channelize the	e work towards	product /proce
develop						
	le students to apply				s to develop their	project.
4. To incul Outcomes:	lcate research cultur	te in students for t	neir technical grov	vtn.		
	e course the student	e should be able to	0.			
	and, plan and execu			reciable resear	rch outcomes	
	grate theory and prace		, 11		ten outcomes.	
	onstrate research sk			t of study.		
	good quality techni					
	good quality paper			work in repute	d conferences.	
Guidelines :		CN I	A 100 -	200		
	al student need to c	lesign and demons	strate project unde	r the guidance	of allocated guide	
2. Sponsor	red Project or Project	ct Internship is acc	ceptable considerin	ng postgraduat	e scope.	
-	vsical / soft model a		-		0.	
	Report-1 should be		-	·	d with subject	
	t 2 paper publication					rance or reput
		-				-
-	and 40% of planne					
	uration: 120 hours) hours are expect	ed to be spend
students	s to satisfy all project	ct requirements an	d implementations	5.		
Plan of Activitie	es			needs.		
Sr. No.	Activity					Duration, H
1.			lotment, applying c and platform, Pla			30
2.			v, objectives and n pic and objectives		inalization,	20
3.	Week 6, 7 & of component		g, analytical / num	erical calculat	ions and design	30
	Review 2 to	understand the pr	ogress of the proje	ect		
4.	Week 9 &		of the experiment		d measurement	20
5.	Week 11 & and execution	12: Project Reportion. Demonstration	rt writing and pub on of Project w			20
	submission a	and term work cor	npnances		Total	120
					Total	140

Department of Mechanical Engineering

Program:		chanical) – Design	Engineering		mester : III	
Course :	Seminar			Co	de: M	MD3703
Т	eaching Scheme/v	veek		Evaluati	on Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2		50	50	100
allo 2. Stu imp 3. The exp 4. Ser 5. At 5. At 6. Tot acti 7. Course Outc 1. To ac 2. To pr 3. To de	ocated guide. dents can choose to oortance. e extensive Literatu oected from semina ninar Report should least 1 review pape cal Duration: 24 C ivities and requiren omes cquire the basic skill rovide students bett	d be submitted as a c r publication is expe- ontact Hours and 2 nents. Ils to for performing er communication s topics in the domain	an of mechanica natical Modeling compliance of te ected as research 24 Hours should literature surve kills	I system consider g of particular r rm work associa outcome of ser I be spent by s	ering recent trend nethod and valua ated with subject ninar. students on comp sentation	ds and its societ able conclusion
4. 1006			minar Activitie		2	
Sr. No.	Activity			5	21	Duration, H
1.	Week 1, 2 & 3: Review-1 condu	Guide allotment, fin	alization of topic	<mark>e, Plann</mark> ing of th	ne work.	6
2.	Week 4 & 5: Lit					
			nethodology of	the selected top	ic.	4
3.	Week 6, 7 & 8 : Review-2 condu	Mathematical mode	lava Dishaay	Freedor)"	4
3.	Review-2 condu	Mathematical mode	l and findings a	nd its analysis	2"	-
	Review-2 condu Week 9 & 10 : C	Mathematical mode ction Comparison of findir Seminar Report writ	I and findings a	nd its analysis s in literature)"	6

rrogram:	ogram: M. Tech (Mechanical) – Design Engineering Semester : III					
Course :	Internship [Cor	npany / In-house	project]		Code :	MMD3801
r	Feaching Scheme/v	veek		Evalua	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100
Guidelines :	1	I	•	L	1	I.
1.	Individual student	need to attempt f	for internship with	n the help o	f PCCOE T&	P cell in the field o
	Mechanical Design	under the guidance	ce of allocated gui	de.		
2.	•	•	•		n of mini-proi	ect / entrepreneurshi
	•	•				ends and its societa
	importance.			orgin comprac		
3.	The idea presentation	on is expected from		1		
5.	The fucu presentati		m the student hase	a on the toni	C	
1	-	-		-		th subject
4. 5	Internship report sh	nould be submitted	l as a compliance o	of term work	associated with	·
4. 5.	Internship report sh Total Duration: 24	nould be submitted Contact Hours an	l as a compliance o	of term work	associated with	th subject. completion of related
5.	Internship report sh Total Duration: 24 activities and requi	nould be submitted Contact Hours an	l as a compliance o	of term work	associated with	·
	Internship report sh Total Duration: 24 activities and requi labus:	nould be submitted Contact Hours an rements.	l as a compliance o ad 24 Hours should	of term work d be spent b	associated with a students on the students of	·
5. Detailed Syl	Internship report sh Total Duration: 24 activities and requi labus:	nould be submitted Contact Hours an	l as a compliance o ad 24 Hours should	of term work d be spent b	associated with a students on the students of	completion of related
5. Detailed Syl	Internship report sh Total Duration: 24 activities and requi labus:	nould be submitted Contact Hours an rements.	l as a compliance o ad 24 Hours should	of term work d be spent b	associated with a students on the students of	·
5. Detailed Syl Sr. No. 1.	Internship report sh Total Duration: 24 activities and requi labus: Activity Week 1, 2 and topic, Planning of	nould be submitted Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revie	as a compliance of ad 24 Hours should ouse / Entreprene nt, Application of w-1 conduction	of term work d be spent b curship activ	associated win y students on vity	Duration, H
5. Detailed Syl	Internship report sh Total Duration: 24 activities and requi labus: Activity Week 1, 2 and topic, Planning of Week 4 &	nould be submitted Contact Hours an rements. Internship / In-ho 3: Guide allotmer	as a compliance of ad 24 Hours should ouse / Entreprene at, Application of w-1 conduction Mini-project/	of term work d be spent b curship activ	associated with y students on with vity finalization of	Duration, H f 6
5. Detailed Syl Sr. No. 1.	Internship report sh Total Duration: 24 activities and requi labus: Activity Week 1, 2 and topic, Planning of Week 4 & implementation	nould be submitted Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revier 5: Internship/	as a compliance of ad 24 Hours should ouse / Entreprene at, Application of w-1 conduction Mini-project/ ts	of term work d be spent b eurship activ internships,	associated with y students on with vity finalization of	Duration, H
5. Detailed Syl Sr. No. 1. 2.	Internship report sh Total Duration: 24 activities and requi labus: Activity Week 1, 2 and topic, Planning of Week 4 & implementation Week 6, 7 & 8 :	nould be submitted Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revier 5: Internship/ as per requirement	as a compliance of ad 24 Hours should ouse / Entreprene at, Application of w-1 conduction Mini-project/ ts	of term work d be spent b eurship activ internships, Entrepreneu	associated with y students on with vity finalization of rship activit	Duration, H f 6 y 4
5. Detailed Syl Sr. No. 1. 2. 3.	Internship report sh Total Duration: 24 activities and requi labus: Activity Week 1, 2 and topic, Planning of Week 4 & implementation Week 6, 7 & 8 : Week 9 & 10: Ir	nould be submitted Contact Hours an rements. Internship / In-ho 3: Guide allotmer of the work. Revier 5: Internship/ as per requirement Review-2 of Action theraction of Guide Internship Report	as a compliance of ad 24 Hours should ouse / Entreprene nt, Application of w-1 conduction Mini-project/ ts wities es with Industry, P	of term work d be spent b eurship activ internships, Entrepreneu oster Presen	associated with y students on with vity finalization of rship activit tation	Duration of related Duration, H f 6 4

"Knowledge Brings Freedom"

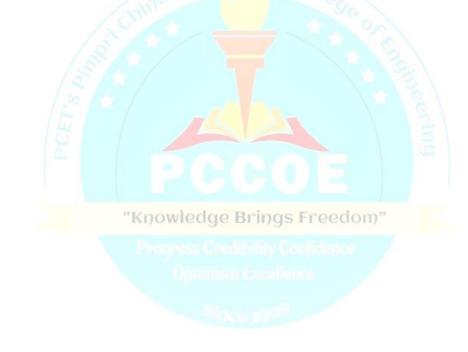
Progress Credibility Confidence

Optimism Excellence

Program:	M. Tech. Mechanical (Design Engineering) Semester : III					III
Course :	MOOCs			Code :	MMD3981	
Т	eaching Scheme/v	veek		Evalu	ation Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50 50 10			

Guidelines :

- 1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related trainings.
- 2. Weekly assignments need to be completed regularly as per requirement of course, which will be considered for internal assessment of course.
- 3. The certification of course or training is mandatory.
- 4. Oral presentation of course/ training will be taken at the end of semester
- 5. Total duration: 24 contact hours and 24 hours should be spent by students on completion of related activities and requirements.



					Semester : III	
Course :	Entrepreneurship				Code: MMD39	81
	Teaching Scheme/w	eek		Evalua	tion Scheme	
Practical	Hours	Credit	IE2	TW	OR	Total
4	4	2	50		50	100
Pre-requisi	te:	•				
	y Engineering Graduat	e with Innovation a	and Design think	ing knowledge		
Objectives:						
	acquaint with Entrepre					
	apply entrepreneurship					
	imbibe Entrepreneuria	l capabilities in eng	gineering student	s.		
Dutcomes:						
After learnin	ng the course, the stude	nts should be able	to:			
1. Mo 2. Reg	otivate students to think gistering students for S	about Entreprener	urship alternative		t.	
1. Mo 2. Re Detailed Sy	otivate students to think gistering students for S llabus:	about Entreprener	urship alternative		t.	Dungtion
1. Mo 2. Reg	otivate students to think gistering students for S	about Entreprener	urship alternative		t.	Duration, H
1. Mo 2. Re Detailed Sy Unit	otivate students to think gistering students for S llabus:	about Entreprenet tartup / Udyam reg	urship alternative gistration of MSM		t.	Duration, H 04
1. Mo 2. Rej Detailed Sy Unit 1.	otivate students to think gistering students for S llabus: Description	about Entreprenet tartup / Udyam reg preneurship and i	urship alternative gistration of MSM its importance	IE.	t.	
1. Mo 2. Re Detailed Sy Unit 1. 2.	otivate students to think gistering students for S llabus: Description Introduction to Entre	about Entrepreneu tartup / Udyam reg preneurship and i	urship alternative gistration of MSM its importance	IE.	t.	04
1. Ma 2. Reg Detailed Sy Unit 1. 2. 3. 4.	otivate students to think gistering students for S llabus: Description Introduction to Entre Achievement Motivat	about Entreprenet tartup / Udyam reg preneurship and i ion. Case Studies	urship alternative gistration of MSM its importance of Indian Entre	IE.	t.	04
1. Mo 2. Reg Detailed Sy Unit 1. 2. 3. 4. 5	otivate students to think gistering students for S llabus: Description Introduction to Entre Achievement Motivat Product Identification	about Entreprenet tartup / Udyam reg preneurship and i ion. Case Studies	urship alternative gistration of MSM its importance of Indian Entre	IE.	t.	04 04 04
1. Mo 2. Reg Detailed Sy Unit 1. 2. 3. 4. 5. 6	otivate students to think gistering students for S <u>llabus:</u> Description Introduction to Entre Achievement Motivat Product Identification Whom to contact for	about Entrepreneu tartup / Udyam reg preneurship and i ion. Case Studies h, Market Survey what? Financial N	urship alternative gistration of MSM its importance of Indian Entre	IE.	t.	04 04 04 04

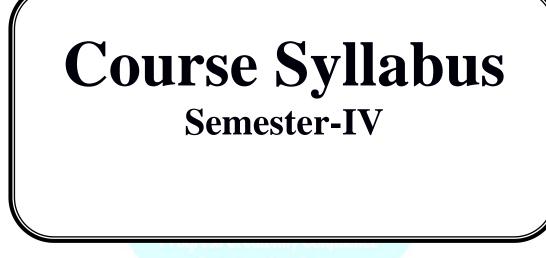
1. Entrepreneurial Development by Vasant Desai, Himalaya publication

2. Entrepreneurship Development and Small Business Enterprise. Poornima M. Charantimath. Pearson Education India, 2005

3. Dynamics of entrepreneurial development and management : Entrepreneurship, project management, finances, programmes, and problems. by Vasant Desai.

4. Course Material by EDII, Ahmedabad

Experiment List: Project Report preparation for an Enterprise and Udyam Registration.



Optimism Excellence

Since 1999

M. Tech. Mechanical (Design Engineering), PCCoE Pune

Program:		anical) – Design l				V
Course :	Dissertation Pha	ase – II [Compan	y/ In-house proje	ct] C	ode: I	MMD4704
	Teaching Scheme/we	ek		Evaluat	ion Scheme	
Practical	Hours	Credit	IE2	PR	OR	Total
24	24	12	200		200	400
Pre-requisit	te:					
- 1.	Basic knowledge of M	Mechanism and M	Machine Design, I	Mechanical sy	stem design, B	asics of Analysi
	software, MATLAB pr	ogramming				
Objectives:	, I	0 0				
1.	To understand the Prod	luct Development	Process including	budgeting.		
2.	To plan for various act				k towards produ	ict development.
3.	To build, design and in					I
4.	To inculcate research c					
Outcomes:				-		
After learnin	ng the course the student	s should be able to	0:			
1.	Understand, plan and e					es.
2.	To integrate theory and			area of study.		
3.	To demonstrate researc					
4.	Prepare good quality te				A	
5.	Publish good quality pa	aper in reputed jou	urnal and present t	heir work in re	eputed conference	ces
Guidelines						
1.	Semester III major pro	· · · · ·		-		
2.	Students need to imple	ment the project u	ising <mark>su</mark> itable com	outational tool	s and /or experin	mental setups.
3.	Final Project Report in	ncluding all proce	ess of project shou	ıld be submitt	ed as a complia	nce of term wor
	associated with subject				5	
4.	Total 2 Paper publicat	-			t Stage-L and I	I (Conference)
	reputed journal) and 1	-			-	
		00% of plained	project work shou	iu de complet	eu foi subillissi	on of Dissertatio
	Phase-II					
5.	Total Duration: 144 h					are expected to b
	spend by students to sa	tisfy all project re	equirements and in	plementations	3.	
Plan of Acti	ivities	Proveess C	nedibility Cont	idence		
Sr. No.	Activity					Duration, H
1.	West 1 8 2	60 0/ Work show	ld he completed h	y fabrication	he setur	24
	week 1 & 2	: 60 % WORK Shou	ld be completed, b	by labrication	ne setup	24
2.	Week 3 &	4: experimentat	ion on the setup,	generate and	compile the	24
	results.	·· · · · ·		8	·····	
	Review 1 co	nduction.				
3.						24
			on should be in p	rocess or com	pleted during	
	this week, 80	0% work should b	e completed.			
4.	Week 7 & 8	: Compliance of 1	100 % work.			24
		1	/ ··· ·· ·· ··			
		vill be conducted				
5.			eviews will be con			24
	of project an	d requirements fu	lfillment to permit	project submi	ission.	
6.	Week 11 &	& 12: Project R	eport writing and	d copyright i	planning and	24
			Project work an			
			ll be conducted for			
	compliances					
	· ·				Total	144

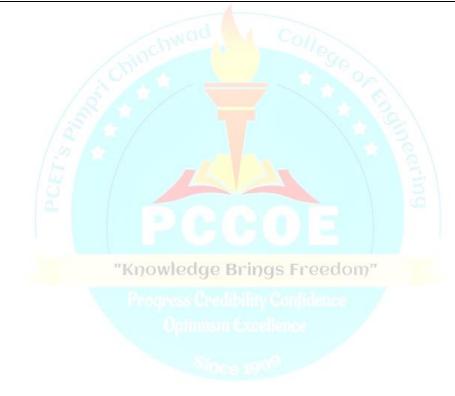
Total

144

Program:	M. Tech. (Design Engineering)				Semester : IV		
Course :	MOOCs		Code : MMD4982				
	Teaching Scheme/w	reek	Evaluation Scheme				
Practical	Hours	Credit	IE2	TW	OR	Total	
4	4	2	50 50 100				

Guidelines :

- 1. Individual student needs to register for MOOC course of their interest or Entrepreneurship related training.
- 2. Week assignment needs to be regularly completed as per requirement of course, which will be considered for internal assessment of course.
- 3. The certification of course or training is mandatory.
- 4. Oral and Presentation of course/ training will be taken at the end of semester
- 5. Total Duration: 24 Contact Hours and 24 Hours should be spent by students on completion of related activities and requirements.



Annexure-I Open Electives Syllabus

Progress Credibility Confidence Optimism Excellence

Since 1989

Program	n: M. Tech. Mechanie	cal (Heat Power Engineering)	Semeste	er:I		
Course :	Electronic Coolin	g (Open Elective)	Code : 1	MMH1601	A	
	Teaching	Scheme		Evalı	ation Scher	ne
Lectu	ire Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requ					ł	
Object 1. 2. 3.	To establish fundamental u To select a suitable cooling To increase the capabilities	nderstanding of heat transfer in e processes for electronic compon in design and analysis of cooling ure for electronic components an	ents and sy g of electro	vstems. nic package	25.	
1. 2. 3. 4.	After learning the course, the Understand Heat transfer p Analyze thermal failure for Assign the best cooling me Design cooling system for a	he students should be able to rocesses involved in electronics c electronic components and defin thod for each individual applicati any electronic device and select E	e the solut		ch for any de	sign.
Detaile Unit	ed Syllabus:			31		Duration
Umt	Description				λ	Duration,
1.	Conduction Heat Transfer	Frends and Thermal Management , Multi-Dimensional Conduction ectronic Devices, Forced Convec	n, Transier	nt Conducti	on,	06
2.	Heat Sinks, Heat Pipes in	hods in Industry ase change materials, passive and Electronics Cooling, Thermoele le and Two-phase), Cooling Tecl	ctric Cooli	ng, Liquid		06
3.	Packaging of Electronic Components of Electronic	Equipments c Systems, Packaging of Electron Circuit Boards, Chip/circuit mater	ic Equipme ial for aug	ent, Conduc menting hea	etion at	06
4.		asurement and simulation requirement, CFD analysis for A etc	irflow & te	emperature		06
	Total					24
		g Techniques for Electronic Equ	ipment ",	Second Ed	lition, John	Wiley & Sor
2. F 3. S	Frank P. Incropera, "Introdu	ction to Heat Transfer ", Fourth E to Lee, "Air cooling Technology				press, Londo
iı	nc, 1999.	Cooling of Electronic Devices b	y Single-F	Phase Conv	ection", John	Wiley& sor
	nce Books:	Dackaging of Flootronic Fauirman	nt" Von N	ostrand Da	nhold Come	any 1095
2. B		Packaging of Electronic Equipment leat Sink Performance for Forced				
3. B S	Biber C., Wakefield Engine inks,", Personal Communic					
	Vram Bar-Cohen, "Encycl	opedia of Thermal Packaging v	olume I to	oo, Febru	ary 2013, W	oria Scientii

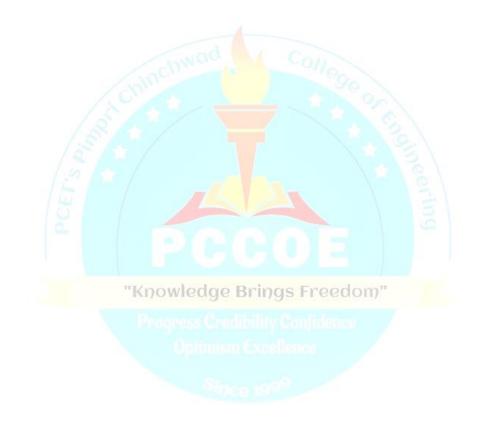
	m: M. Tech. (Mechar	nical)- Heat Powe	r Engineering		Semester: I		
Course		s (Open Elective			Code: MMH16	01B	
	Teaching Schem		-	Evalua	ation Scheme		
Lectu	re Hours	Credit	IE1	IE2	ETE	То	otal
2	2	2	20		30	5	0
	equisite:						
	sics of air conditioning						
	sics of building construct	ion					
Object				1 i		h:1.1:	
2.	To develop a multidisci						onmont i
3.	To develop knowledge buildings in an environ			mons that pro	ovide optimar in	door enviro	omment i
4.	To create awareness of						
			Tatilig tools				
	earning the course, the stu	dents should be al	ole to:				
1				uilding system	ı		
2						rulations ev	zaluate
2	the relationship betwe			indings to peri	onn energy eare	ulutions, ev	uruute
3	-			ng measures ir	existing building	ng on the ba	asis of
	engineering and econo		5 05	e e e e e e e e e e e e e e e e e e e	C C	0	
4			cipl <mark>es of ene</mark> rgy m	anagement to	obtain buildings	that can be	•
	certified			A La Ca	10.)		
Detaile	ed Syllabus:				(3)		
Unit	Description					1	Duration
1	Overview and compar						h
	What is groon building						
	comparison of USGBC Conducting feasibility credit categories, under	LEED, IGBC, GR studies, reference	building practice IHA, EDGE and o standards, key do	s versus inter other green bu efinitions, syn	ilding rating sys ergies between	tems,	6
2.	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in but Water efficiency – indo systems, strategies for r Waste management – so	LEED, IGBC, GR studies, reference standing building f "Knowlect ildings, or water use, rainw educing water con burce reduction, re	building practice IHA, EDGE and o standards, key do forms, site level fe 1ge Brings vater harvesting, in sumption duce – recycle – r	s versus inter other green bu efinitions, syn atures, microc Freedon rrigation water	ilding rating sys ergies between limate features	tems, various	6
2.	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in bu Water efficiency – indo systems, strategies for r Waste management – so management, construction	LEED, IGBC, GR studies, reference standing building f "Knowlect ildings, or water use, rainw educing water con burce reduction, re	building practice IHA, EDGE and o standards, key do forms, site level fe 1ge Brings vater harvesting, in sumption duce – recycle – r	s versus inter other green bu efinitions, syn atures, microc Freedon rrigation water	ilding rating sys ergies between limate features	tems, various	
2.	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in but Water efficiency – indo systems, strategies for r Waste management – so	LEED, IGBC, GR studies, reference standing building f "Knowled" ildings, or water use, rainv educing water con burce reduction, re- on waste managen ir quality, ASHRA parameters affectin ategies to enhance	building practice IHA, EDGE and o standards, key do forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environt daylight availabili	s versus inte- other green bu- efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ maity,	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan	r rate	
3	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in but Water efficiency – indo systems, strategies for r Waste management – so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stat	LEED, IGBC, GR studies, reference standing building f "Knowled" ildings, or water use, rainv educing water con burce reduction, re- on waste managen ir quality, ASHRA parameters affectin ategies to enhance	building practice IHA, EDGE and o standards, key do forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environt daylight availabili	s versus inte- other green bu- efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ maity,	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan	r rate	6
3	comparison of USGBC Conducting feasibility credit categories, unders Resource Efficiency Energy efficiency in bu Water efficiency – indo systems, strategies for r Waste management – so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stat health Site features Erosion and sedimentati microclimate, heat islam	LEED, IGBC, GR studies, reference standing building f "Knowled" ildings, or water use, rainw educing water com purce reduction, re- on waste managen ir quality, ASHRA parameters affectinategies to enhance indard for buildings ion control, water of d effect, exterior lit	building practice IHA, EDGE and o standards, key do forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environt daylight availabilits, impact of VOCs efficient landscapt ighting pollution,	s versus inter other green bu efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan s chemicals on l	r rate	6
3	comparison of USGBC Conducting feasibility credit categories, unders Resource Efficiency Energy efficiency in bu Water efficiency – indo systems, strategies for r Waste management – so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stathealth Site features Erosion and sedimentati	LEED, IGBC, GR studies, reference standing building f "Knowled" ildings, or water use, rainw educing water com ource reduction, re- on waste managen ir quality, ASHRA parameters affectinategies to enhance ndard for buildings ion control, water of d effect, exterior liter tent strategies and	building practice IHA, EDGE and o standards, key do forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environt daylight availabilits, impact of VOCs efficient landscapt ighting pollution,	s versus inter other green bu efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan s chemicals on l	r rate	6
	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in bu Water efficiency - indo systems, strategies for r Waste management - so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stat health Site features Erosion and sedimentati microclimate, heat islan transportation managem Materials and resource Low-embodied energy for material categories of IC	LEED, IGBC, GR studies, reference standing building f ildings, or water use, rainw educing water con burce reduction, re- on waste managen ir quality, ASHRA parameters affectin ategies to enhance ndard for buildings ion control, water of d effect, exterior li- nent strategies and es materials, environr GBC, LEED & GR	building practice IHA, EDGE and o standards, key de forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environn daylight availabilities, impact of VOCs efficient landscapi ighting pollution, planning nental product dec RIHA, life cycle ar	s versus inter other green bu efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou ing and irrigati Location and t	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan s chemicals on l on practices, transportation, Ds), overview of	r rate	6
3 4 5	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in bu Water efficiency – indo systems, strategies for r Waste management – so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stathealth Site features Erosion and sedimentati microclimate, heat islan transportation managem Materials and resource Low-embodied energy material categories of IC	LEED, IGBC, GR studies, reference standing building f ildings, or water use, rainw educing water con burce reduction, re- on waste managen ir quality, ASHRA parameters affectin ategies to enhance ndard for buildings ion control, water of d effect, exterior li- nent strategies and es materials, environr GBC, LEED & GR	building practice IHA, EDGE and o standards, key de forms, site level fe Ige Brings vater harvesting, in sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environn daylight availabilities, impact of VOCs efficient landscapi ighting pollution, planning nental product dec RIHA, life cycle ar	s versus inter other green bu efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ ma ity, s and hazardou ing and irrigati Location and t	Ilding rating sys ergies between limate features use, wastewate s for waste nts, ventilation r nagement plan s chemicals on l on practices, transportation, Ds), overview of	r rate	6 4 2
3	comparison of USGBC Conducting feasibility credit categories, under Resource Efficiency Energy efficiency in bu Water efficiency - indo systems, strategies for r Waste management - so management, constructi Health and Wellness Introduction to indoor a procedure method, key Daylight and views, stra Overview of WELL stat health Site features Erosion and sedimentati microclimate, heat islan transportation managem Materials and resource Low-embodied energy for material categories of IC	LEED, IGBC, GR studies, reference standing building f ildings, or water use, rainw educing water con burce reduction, re- on waste managen ir quality, ASHRA parameters affectin ategies to enhance ndard for buildings ion control, water of d effect, exterior li- nent strategies and es materials, environr GBC, LEED & GR CA, and incentive pro for green building	building practice IHA, EDGE and o standards, key de forms, site level fe Ige Brings vater harvesting, is sumption duce – recycle – r nent plan AE 62.1 overview ng indoor environ daylight availabilits, impact of VOCs efficient landscapi ighting pollution, planning nental product dea RIHA, life cycle ar grams rating programs,	s versus inter other green bu- efinitions, syn atures, microce Freedom rrigation water euse, strategie and requireme ment, IAQ ma- ity, s and hazardou ing and irrigati Location and the clarations (EPI nalysis and its	Ilding rating sys ergies between limate features ruse, wastewate s for waste nts, ventilation r nagement plan s chemicals on l on practices, transportation, Ds), overview of application, over	r various r r ate human r r r r	6 4 2

Text Books:

- 1.
- Shahane, V. S, "Planning and Designing Building", Poona, Allies Book Stall, 2004. Michael Bauer, Peter Mösle and Michael Schwarz "Green Building Guidebook for Sustainable 2. Architecture" Springer, 2010.
- 3. Tom Woolley, Sam Kimmins, Paul Harrison and Rob Harrison "Green Building Handbook" Volume I, Spon Press, 2001.

Reference Books:

- Mili Majumdar, "Energy-efficient buildings in India" Tata Energy Research Institute, 2002. 1.
- 2. TERI "Sustainable Building Design Manual- Volume I & II" Tata Energy Research Institute, 2009
- 3. Reference manuals of green building rating programs (LEED, WELL, IGBC, GRIHA)
- 4. ASHRAE Standard 62.1, Standard 55, Standard 90.1, and other standards referred by green building programs
- 5. EDGE App user manual
- National Building Code of India 2016 6.
- ECBC 2017 7.



Program:	M. Tech. Mechanic	al (Heat Power E	Engineering)	Se	mester : I	
Course :	System Modellin	ng and Simulation	n (Open Elective)	Co	de: MMH1601C	
	Teaching Scheme			Eva	luation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisite:						
Objectives: 1. Stude	nts able to model any p nts able to simulate any					
 Devel Devel Apply 	the course, the students op mathematical model op Bond Graph model v transfer function and S late the system using su	for practical prob for system State space model	olem techniques	ters by opti	mization	
Detailed Sylla	bus:		d			
	escription	- Chwo		110		Duration
Ma	roduction to Modelling athematical modelling, I	Basic building blo	cks Mechanical, E	lectrical, T	hermal systems.	6
mu	nd Graph Modelling of Iltiports Causality, App stem					6
	Dynamic Response and System Transfer Function: Poles, Stability Block diagram/Signal flow diagram/State Space formulation and Frequency response					
	Simulation and Simulation application Parameter Estimation, System Identification and Optimization					
Т	otal					24
Reference Boo Brown, Forbes	oks: T. Engineering System		<mark>ge Brings F</mark> York, NY: CRC, 2			

Optimism Excellence

Program:	M. Tech Mecha	nical (Heat Power Ei	ngineering)		Semester: II		
Course:	Waste Manager	nent for Smart Cities	s (Open Elect	ive)	Course: MM	H2602A	
	Teaching Scho	eme		Ev	aluation Schem	ne	
Lecture	Hours	Credit	IE1	IE2	ETE		Total
2	2	2	20		30		50
Course Obj	ective:						
1. To 2. To 3. To 4. To 5. To Course Out The 1. Iden mu 2. Eva effe 3. Eva	provides an in-depti make aware about r equip with the meth provide an in-depth be able to design the comes: e learners will be ntify and evaluate th nicipal waste treatm duate and analysis t ects.	n understanding of Mu egulations in the area ods of environment ri- understanding of Phy e land-fields for the sn he sources; compositio ent. he risk and methods or mical and biological w or solid and hazardous	municipal was sk assessment siochemical an nart cities. n; generation f handling the waste for its tr	ste managemen of waste. nd biological t rates, methods hazardous and eatment and di	nt. reatment of Mur s of separation at l radioactive was	nicipal w	ction methods o
Detailed Sy	llabus						
Unit D	escription						Duration, h
Fu and hai usa	l transport of wast adling rules for soli- age and batteries	e Management ; composition, genera e, treatment and disp id waste, hazardous w ctive Waste Managem	oosal options. vaste, biomed	Municipal w	aste manageme	nt and	6
Fu Fu	ndamentals Charact	erization of waste, fate , measures and health nuclear power plants;	e and transpor effects; nucle	ar power plan		uction;	6
Ph MS pro	SW (combustion, s presses for hazardo	nent of Solid waste tment of Solid and H tabilization and solid ous wastes (soil vapo nation and remediation	lification of l ur extraction,	nazardous was	stes); physicoch	emical	6
Bid dec me La	blogical Treatment composition of soli- tabolism; oxidative	of Solid waste and land of Solid and Hazar d waste; principles of and reductive process fill design for solid rs; incineration	dous Waste of biodegrada es; slurry pha	tion of toxic se bioreactor.	waste; inhibitio	on; co-	6
То							24
1. Joh 2. LaC Edi	Grega, M.D.Bucking tions, New York, 19		J.C. Hazardou	is Waste Mana	gement, McGra		
4. Bas	ics of Solid and Ha	rdous Wastes - Source zardous Waste Mgmt. Vaste Management 20	Tech. by Kan	ti L.Shah 1999	, Prentice Hall.		1 UIK, 1777.

		hanical (Heat Power			Semester : II		
Course :		gement for Electric V	ehicle (Open		Code : MMH26	02B	
	Teaching Schen	ne		Eval	uation Scheme	[
Lecture	Hours	Credit	IE1	IE2	ETE	Т	otal
2	2	2	20		30		50
	te: Basics of Electrical	Engineering,					
2. To 3. To 4. To 5. To 6. To Outcomes: After learnin 1. the 2. the 3. Th 4. the 5. the	understand the various understand the requirer make the learners conv make the learners conv make the learners conv make the learners awar ng the course, learners will be able to learners will be able to	ments of battery managers ant with Equivaler rersant with SOC estim- rersant with Battery Pare of thermal issues of eselect battery for EV estimate available end o simulate charge disc estimate SOC and SC o understand various m	gement system nt Circuit Cell nation ick Balancing Lithium ion b application ar ergy and powe harge characte DH of battery iethods of batter	Modeling of and Power Es attery and the ad design batter of battery p eristics of a battery pack balan	Battery stimation rmal managemer ery pack ack ack attery using equiv	nt system	cuit model
pac	ck.	estimate neat generat		ery and prope	se coomig strate	gy for the	battery
Detailed Sy	llabus			and the	6.		
Unit	Description						Duration h
	Cells components, pri BMS design requirer Primary functions of D	nd performance paran mary functions and co ments BMS, sensing voltage, C and battery pack SO	omponents of I current and te	BMS emperature of	cell and battery	pack,	6
2.	Equivalent Circuit C Modeling OCV and S Model parameter value	OC, Modeling voltage es: OCV, Columbic E steresis, using the ECI	e polarization, fficiency, tota	Warburg imp l capacity, ter	edance, Estimation nperature depender	lence	5
3.	State-of-Charge (SO Different approaches linear Kalman filter, Reasons of battery pac balance a battery pack	C) Estimation and B to estimating battery c extended Kalman filter ck unbalancing, criter c, Passive balancing m pacitor-based circuits,	ell SOC, Kaln r ia for specifyi ethods for bat	nan-filter met ng a balancin tery packs, A	g set point and v ctive balancing n	when to nethods	7
4.	range, Energy analysi	e battery , Thermal iss	ng of LIB, Coo	oling strategie	es in thermal		6
	management : Air coo arrangement, spacing, Total						24

Gregory L. Plett, Battery Management Systems Volume II, Equivalent-Circuit Methods, Artech House, London
 Gianfranco Pistoia, Boryann Liaw (eds.), Behaviour of Lithium-Ion Batteries in Electric Vehicles_ Battery

Health, Performance, Safety, and Cost, Springer International Publication

4. Reiner_Korthauer, Li-I Batteries Basics and Applications, Springer International Publication

Teaching Scheme Evaluation Scheme Lecture Hours Credit IE1 IE2 ETE Total 2 2 2 20 30 50 Pre-requisite: Thermodynamics: Fluid Mechanics: Heat Transfer; Elements of Electrical Engineering: Economics Dipervives: 0010wing concepts to be taught to the students, 1. Demonstrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization 2 2. Expose them to conceptualize and design renewable energy appliances and equipment 3 5. Enable them to independently analyze, implement and asces the real-life systems 4. 4. Develop a research insight about renewable technologies on as to motivate all concerned for their enhanced deployment 2. Fnable the students to estimate the potential of solar and wind resources 3. 3. To be able to duderstand the fundamental performance of characteristics of solar thermal, photovoltaic and win energy systems 4. To be able to duderstand the fundamental sol energy conversion from biomass, geothermal, tidal and oce thermal energy conversion systems 4. Description Duration_h 1. Description Duration_h	Program:	M. Tech. Mecha			g)	Semester : II	
Lecture Hours Credit IE1 IE2 ETE Total 2 2 20 30 50 Pre-requisite: Thermodynamics; Fluid Mechanics; Heat Transfer; Elements of Electrical Engineering; Economics 50 Dijettres: 50 50 50 Otomistrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization 51 1. Demonstrate significance of analysis solar and Wind Resources Sources and equipment 3. Expose them to conceptualize and design renewable energy appliances and equipment 3. Expose them to conceptualize and design renewable energy appliances and equipment 3. Enable them to independently analyze, implement and asses the real-life systems 4. Develop a rescarch insight about renewable technologies so as to motivate all concerned for their enhanced deployment 20 30 6 2. Enable the students to estimate the potential of solar and wind resources 3. To be able to determine the fundamental of onlar energy conversion from biomass, geothermal, tidal and oce thermal energy conversion systems 4. To be able to determine the conomic feasibility of renewable energy technologies Vertiled Syllabus: Unit Descorpiption 1 <th>Course:</th> <th></th> <th></th> <th>Dpen Elective)</th> <th></th> <th>Code: MMH2602C</th> <th>1</th>	Course:			Dpen Elective)		Code: MMH2602C	1
2 2 20 30 50 Pre-requisite: Thermodynamics; Fluid Mechanics; Heat Transfer; Elements of Electrical Engineering; Economics 50 Optioning concepts to be taught to the students. 1. Demonstrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization 2. Expose them to conceptualize and design renewable energy appliances and equipment 3. 3. Enable them to independently analyze, implement and asses the real-life systems 4. Develop a research insight about renewable technologies so as to motivate all concerned for their enhanced deployment 20urse Outcomes: To be able to determine the fundamental performance of characteristics of solar thermal, photovoltaic and wit energy systems 3. To be able to determine the conomic feasibility of renewable energy technologies Duration Metabout previous systems 4. To be able to determine the economic feasibility of renewable energy technologies Duration find Duration, h Duration of Renewable energy sources (Flow & not stocks), Current scenario of worldwide instruments for measurement. Instruments for measurement. Source collectors – Heat transfer processes – Short term and long-term collector perfor		Teaching Scheme			Eva	aluation Scheme	
The requisite: Thermodynamics; Fluid Mechanics; Heat Transfer; Elements of Electrical Engineering; Economics Dijectives: Ollowing concepts to be taught to the students, 1. Demonstrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization Expose them to conceptualize and design renewable energy appliances and quipment 2. Expose them to conceptualize and design renewable energy appliances and quipment Enable them to independently analyse, implement and asses the real-life systems 4. Develop a research insight about renewable technologies so as to motivate all concerned for their enhanced deployment Solar thermal, photovoltaic and wind resources 3. To be able to determine the fundamental performance of characteristics of solar thermal, photovoltaic and win energy systems Enable the students to estimate the potential of solar and wind resources 3. To be able to determine the economic feasibility of renewable energy technologies Duration, h 4. To be able to determine the economic feasibility of renewable energy technologies Duration, h 1. Solar energy Potential of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity G 9. Solar - Earth Geometry_for assessment of available solar radiationSolar radiation estimation, instruments for massurement Solar Hontovoltaic Systems - Morking, Constructional details & Performance Assessment for Techno-conomic evaluation (estimatid), the approxement of available solar radiation_S, Win	Lecture	Hours	Credit	IE1	IE2	ETE	Total
Dipictives: oflowing concepts to be taught to the students. 1. Demonstrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization 2. Expose them to conceptualize and design renewable energy appliances and equipment 3. Enable them to independently analyze, implement and asses the real-life systems 4. Develop a research insight about renewable technologies so as to motivate all concerned for their enhanced deployment Source Outcomes: 1. To be able to determine the fundamental performance of characteristics of solar thermal, photovoltaic and wi energy systems 2. Enable the students to estimate the potential of solar and wind resources 3. To be able to determine the economic feasibility of renewable energy technologies Vential of Renewable congy sources (Flow & not stocks), Current scenario of worldwide installed equacity Solar energy Potential of Renewable cnergy sources (Flow & not stocks), Current scenario of worldwide installed equacity Solar thermal collectors – General description and characteristics: Flat plate collectors – Heat transfer processe – Short term and long-term collector performance. Solar concentrators – Aspects of Design, and performance Assessment for Technom-economic evaluation / feasibility 2. Wind energy - Principles of wind energy conversion – Site selection considerations, Wind resource / energy wheeling and banking concepts. Types of wind power conv	2	2	2	20		30	50
 bellowing concepts to be taught to the students, Demonstrate significance of analysis solar and Wind Resources Sources and design technologies of their utilization Expose them to conceptualize and design renewable energy appliances and equipment Enable them to independently analyze, implement and asses the real-life systems Develop a research insight about renewable technologies so as to motivate all concerned for their enhanced deployment To be able to determine the fundamental performance of characteristics of solar thermal, photovoltaic and wi energy systems Enable the students to estimate the potential of solar and wind resources To be able to determine the fundamentals of energy conversion from biomass, geothermal, tidal and oce thermal energy conversion systems To be able to determine the conomic feasibility of renewable energy technologies Ventiled Syllabus: Unit Description Duration, h Solar energy Potential of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity Solar fherma collectors – Gneral description and characteristics: Flat plate collectors – Heat transfer processes – Short term and long-term collector performance. Solar concentrators – Aspects of Design, and performance exaluation. Solar Photovoltaic Systems - Working, Constructional dealis & Performance Assessment for Technmo-economic evaluation / feasibility Enable to determine the and anking concepts. Types of wind power conversion systems – Operation, maintenance and economics Biogas /	Pre-requisite:	Thermodynamics;	Fluid Mechanics;	Heat Transfer; I	Elements of E	lectrical Engineering; E	Economics
1. To be able to determine the fundamental performance of characteristics of solar thermal, photovoltaic and will energy systems 2. Enable the students to estimate the potential of solar and wind resources 3. To be able to understand the fundamentals of energy conversion from biomass, geothermal, tidal and oce thermal energy conversion systems 4. To be able to determine the economic feasibility of renewable energy technologies Duration Methods and the fundamental performance systems Outertial of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity Solar energy Potential of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity Solar thermal collectors – General description and characteristics: Flat plate collectors – General description and characteristics: Flat plate collectors – General description and characteristics: Flat plate collectors – Heat transfer processes – Short term and long-term collector performance. Solar concentrators – Aspects of Design, and performance evaluation. Solar energy potential measurement, wind electric generator components, Wind resource / energy potential measurement, wind electric generator components, Wind resource / energy of wind energy concersion – Site selection considerations , Wind resource / energy potential measurement, wind electric generator components, Wind power conversion systems – Operation, maintenance and economics 6 <td>Following con- 1. Demo utiliza 2. Expos 3. Enabl 4. Devel</td> <td>Instrate significance attion se them to conceptu e them to independent op a research insight</td> <td>of analysis solar alize and design r ently analyze, imp</td> <td>enewable energy plement and asse</td> <td>y appliances a s the real-life</td> <td>nd equipment systems</td> <td></td>	Following con- 1. Demo utiliza 2. Expos 3. Enabl 4. Devel	Instrate significance attion se them to conceptu e them to independent op a research insight	of analysis solar alize and design r ently analyze, imp	enewable energy plement and asse	y appliances a s the real-life	nd equipment systems	
Unit Description Duration, h 1. Solar energy Potential of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity Solar - Earth Geometry_for assessment of available solar radiation,_Solar radiation estimation, instruments for measurement 6 Solar thermal collectors - General description and characteristics: Flat plate collectors - Heat transfer processes - Short term and long-term collector performance. Solar concentrators - Aspects of Design, and performance evaluation. Solar Photovoltaic Systems- Working, Constructional details & Performance Assessment for Technmo-economic evaluation / feasibility 6 2. Wind energy - Principles of wind energy conversion - Site selection considerations , Wind resource / energy potential measurement, wind electric generator components, Wind power plant design - Aerodynamics and performance, vertical vs. Horizontal axis design, and energy wheeling and banking concepts. Types of wind power conversion systems - Operation, maintenance and economics 6 3. Energy from biomass <u>_</u> Sources of biomass Biogas plants - Types of plants - Design and operation - Properties and characteristics of biogas. Biogas / Producer Gas Technology, Engines - Constructional, Operational & Performance aspects 5 4 Geothermal , Tidal and Wave Energy Conversion Geothermal energy -bot springs and steam ejection site selection, power plants, and economics. Environmental impacts, Economic and social considerations, Availability, system development and limitations, Wave and tidal energy -Scope and economics, Introduction to integrated energy systems. Other plants: Fuel cell-based power plants, tidal and wave en	 To be energ Enabl To be therm 	e able to determine y systems e the students to est e able to understan al energy conversio	imate the potentiand the fundament	al of solar and w als of energy c	ind resources onversion fro	om biomass, geotherma	
1. Solar energy Potential of Renewable energy sources (Flow & not stocks), Current scenario of worldwide installed capacity Solar- Earth Geometry_for assessment of available solar radiation_Solar radiation estimation, instruments for measurement Solar thermal collectors – General description and characteristics: Flat plate collectors – Heat transfer processes – Short term and long-term collector performance. Solar concentrators – Aspects of Design, and performance evaluation. Solar Photovoltaic Systems- Working, Constructional details & Performance Assessment for Technmo-economic evaluation / feasibility 6 2. Wind energy - Principles of wind energy conversion – Site selection considerations , Wind resource / energy potential measurement, wind electric generator components, Wind power plant design – <i>Aerodynamics and performance</i> , vertical vs. Horizontal axis design, and energy wheeling and banking concepts. Types of wind power conversion systems – Operation, maintenance and economics 6 3. Energy from biomass <u>1</u> Sources of biomass – Different species, Conversion of biomass into fuels – Energy through fermentation – Pyrolysis, gasification and combustion – Aerobic and anaerobic bio- conversion, Properties of biogas. 5 4 Geothermal, Tidal and Wave Energy Conversion Geothermal energy: hot springs and steam ejection site selection, power plants, and economics. Environmental impacts, Economic and social considerations, Availability, system development and limitations, Wave and tidal energy –Scope and economics, Introduction to integrated energy systems. Other plants: Fuel cell-based power plants, tidal and wave energy plant design 7	r -						Duration h
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	4 Geo Geo Ava Wa	othermal, Tidal a othermal energy: ho nomics. Environme ailability, system de ve and tidal energy	t springs and stea ntal impacts, Eco velopment and lin –Scope and econ	m ejection site s nomic and socia mitations, omics, Introduct	l consideratio	ns, ted energy systems.	7
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Text Books

- 1. S.P. Sukhatme, Solar Energy Principles of thermal collection and storage, II edition, Tata McGraw Hill, New Delhi, 1996.
- 2. Garg H.P., Prakash J., Solar energy Fundamentals and Applications, Tata Mc Graw Hill Publishing Company, New-Delhi, Latest Edition
- 3. V.V. N. Kishore, Editor, Renewable Energy Engineering and Technology, A knowledge Compendium, The Energy and Resources Institute, New Delhi, 2008

Reference Books:

- 1. J.A.Duffie and W.A.Beckman, Solar engineering of Thermal processes, II edition,
- 2. John Wiley, New York, 1991.
- 3. D.Y.Goswami, F.Kreith and J.F.Kreider, Principles of Solar Engineering, Taylor and
- 4. Francis, Philadelphia, 2000.
- 5. D.D.Hall and R.P.Grover, Biomass Regenerable Energy, John Wiley, New York, 1987.
- 6. Mukund R Patel, Wind and Solar Power Systems, CRC Press, 1999.
- 7. J F Manwell, J.G.McGowan, A.L.Rogers, Wind Energy Explained: Theory, Design and Application, John Wiley and Sons, May 2002.
- 8. R D Begamudre, Energy Conversion Systems, New Age International (P) Ltd., Publishers, New Delhi ,2000.
- 9. Bureau of Energy Efficiency Volume 1

List of Assignments

- 1. Visit to a biogas / Bio-engine plant and its report (Energy Capacity assessment).
- 2. Visit to photovoltaic plant for agricultural / Village / Stand-alone applications.
- 3. Economic Analysis of a Renewable Energy system.
- 4. Visit to a Hybrid System & it's assessment system.



Program:		FC (VLSI and Em			Semester:	Ι	
Course:		lectronics and its	Applications (O		Code:	MET16	01A
	Teaching Schen	ne		Evaluat	tion Scheme	1	
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	learn and understand				in automotive	electronics	systems.
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Outcomes:	· · · · · · · · · · · · · · · · · · ·		1				
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Detailed Sy				51911			
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2. Cra EG	nsors and Actuator ank angle position s iO, Air mass flow se gine Control Syste	ensors, Fuel meter nsors, Throttle pos	ring/ vehicle spe- ition sensor, Sole	ed sensors, Flow noids, Stepper Mo	sensor, Tempo otors, Relays, e	erature, etc.,	6
3. Ne	ntrol system, Electro ed of maps, Procedu ting	-			-	-	6
4. ent	tive and passive sat ry, Immobilizers et king system, Electro	tc., Electronic ins	trument clusters	and dashboard	electronics, A		6
			Total	a de			24
Bu	lliam B. Ribbens, "U tterworth-Heineman	n Publications.		-	ng Perspective'	', Seventh	edition,
2. Ro	nald K. Jurgen, "Aut	comotive Electronic	es Handbook", M	c-Graw Hill.			
Reference H	Books:						
1. Ro	bert Bosch," Automo	otive Hand Book",	Fifth edition, SA	E Publications			
	encke, Uwe, Nielsen inger Publication.	& Lars, "Automot	ive Control Syste	ems for Engine, D	riveline and V	ehicle", Se	cond editio
	tomotive Electronics	by Tom H. Dento	n				
1 4		nd Electronic Syst		ancharry Jamas D	Haldamaan / I		

4. Automotive Electrical and Electronic Systems by John F. Kershaw, James D. Halderman / Pearson Education

0		TC (VLSI and Embe	dded Systems)	Semester: I						
Course:		ives (Open Elective)				1601B					
	Teaching Schen	ne		Ev	valuation Scheme						
Lecture	Hours	Credit	IE1	IE2	ETE	Total					
2	2	2	20		30	50					
Pre-requi											
	Drives, Dynamics of El	ectrical drives, Contro	ol Systems								
Objective			•								
1. T	o define electric drive,	its parts, advantages a	nd explain cho	ce of electri	c drive.						
	o explain dynamics and										
	o explain selection of n										
	o analyze the performation										
	o explain the control of				motor drives.						
6. T Outcomes	o discuss typical applic	ations electrical drive	s in the industry	/							
	ing the course, the stud	ents should be able to									
	Explain the advantages										
	Explain dynamics and c			ic drives.							
	Suggest a motor for a d				ifiers.						
	Analyze the performance										
5.	Control induction moto	r, synchronous motor	and stepper mo	otor drives.							
	Suggest a suitable elect	rical drive for specific	application in	the industry	0						
Detailed S		8/01/									
	Description	NS di		× 1		Duration					
					ng and Cooling, Classes						
					tor Drives: Controlled						
				Rectifier Fed dc Drives, Single Phase Fully Controlled Rectifier Control of dc Separately Excited Motor, Single Phase Half Controlled Rectifier Control of dc Separately Excited Motor, Three							
	notor, single phase Ha				. Evolted Motor Three						
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C	hase Fully Controlled Controlled Rectifier Co	Rectifier Control of ntrol of dc Separatel	dc Separately y Excited Mot	Excited Moor, Multi qu	otor, Three Phase Half adrant Operation of do	6					
C S	hase Fully Controlled Controlled Rectifier Co eparately Excited Moto	Rectifier Control of ntrol of dc Separatel or Fed Form Fully C	dc Separately y Excited Mot controlled Rect	Excited Mo or, Multi qu ifier, Rectifi	otor, Three Phase Half adrant Operation of dc er Control of dc Series	6					
C S N	hase Fully Controlled Controlled Rectifier Co- eparately Excited Mote Motor, Supply Harmon	Rectifier Control of ntrol of dc Separatel or Fed Form Fully C ics, Power Factor ar	dc Separately y Excited Mot controlled Rect ad Ripple in M	Excited Mo or, Multi qu ifier, Rectifi Iotor Curren	otor, Three Phase Half adrant Operation of do	6					
C S M S	hase Fully Controlled Controlled Rectifier Co- eparately Excited Mote Aotor, Supply Harmon eparately Excited dc M	Rectifier Control of ntrol of dc Separatel or Fed Form Fully C ics, Power Factor ar otor, Chopper Contro	dc Separately y Excited Mot ontrolled Rect ad Ripple in M l of Series Moto	Excited Mo or, Multi qu ifier, Rectifi Iotor Curren or.	otor, Three Phase Half adrant Operation of dc er Control of dc Series	6					
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2. II 2. II 5 7 7 8 8 9 9 1. G	hase Fully Controlled Controlled Rectifier Co- eparately Excited Moto Aotor, Supply Harmon eparately Excited dc M nduction Motor Driv Operation with Unbalar Cotor Impedances, Ana- tarting, Braking, Tran Variable Voltage Freque Voltage Source Inverter Converter Rating for V Control from a Current inverter control, speed co ynchronous Motor I notor. Self-controlled sy tarting Large Synchron MAC Motor Drives, Br tepper Motor Drives; Br tepper Motor Drives; Br totors, Torque Versus S ndustrial Drives: Texti Total cosal K Dubey , Fundar	Rectifier Control of ntrol of dc Separatel or Fed Form Fully C ics, Power Factor ar <u>otor, Chopper Contro</u> ves: Analysis and I need Source Voltage alysis of Induction M nsient Analysis. Spe- ency Control from Vol (VSI) Control, Cyclo- (VSI) Control, Cyclo- (VSI) Control, Cyclo- (VSI) Control, Cyclo- (VSI) Control, Cyclo- (VSI) Control, Cyclo- Source, Current Sour- pontrol of single phase Drives: Operation fro- ynchronous motor dr ious Machines, Perma rushless dc Motor Dri Variable Reluctance, Stepping Rate Charact ile Mills, Steel Rolling mentals of the electrica	dc Separately y Excited Mot ontrolled Rect d Ripple in M l of Series Mot Performance o and Single Pl Aotor Fed fron red Control T tage Sources. 	Excited Ma br, Multi qu ifier, Rectifi fotor Curren or. f Three Ph hasing, Oper n Non-Sinu echniques-S rol, Closed I Motor Driv- ol, current r rs. iency suppl load comm c (PMAC) M agnet, Impor Circuits for S and Hoists, a publication	otor, Three Phase Half adrant Operation of dc er Control of dc Series nt, Chopper Control of ase Induction Motors, ration with Unbalanced soidal Voltage Supply, tator Voltage Control Loop Speed Control and es, Variable Frequency egulated voltage source y-starting, synchronous utated thruster inverter, fotor Drives, Sinusoidal tant Features of Stepper Stepper Motor. Machine Tools.	6 6 6 6 6 6 6 6 6 7 6 7 6 7 6 7 6 7 6 7					
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Reference Books:

- 1. N.K De, P.K. Sen, Electric Drives PHI Learning 1 st Edition, 2009
- 2. Gobal K.Dubey, Fundamentals of Electrical Drives- Alpha Science Int. Ltd.,
- 3. Shepherd Hullay & Liag, Power Electronics & Motor Control -, Cambridge Univ. Press
- 4. Gopal K Dubey, Power Semiconductor controlled Drives, Prentice Hall pub.
- 5. R. Krishnan, Electric Motor Drives–Modelling, Analysis and Control, Pearson Education, 2003
- 6. P.C. Sen , Thyristorised DC Drives -, Krieger pub.
- 7. S.B.Dewan, G.R.Slemon & A.Stranghan; Power Semi conductor controlled Drives John-Willey pub.



Program:		&TC (VLSI and E		s)	Semester : I	
Course :		A and CPLD (Op	en Elective)			ET1601C
	Teaching Scher	ne		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requis	ite: Fundamentals of	f digital electronics	, Knowledge of on	e hardware d	escription language	
Objectives	:					
1. To	o make students fami	liar with programm	nable logic devices	and its archi	tectures.	
2. To	o understand the arch	itecture and feature	es of FPGA and C	PLD.		
3. To	o make the students	familiar with the de	esign process and	how the desig	gn is mapped to the ex	isting hardwar
	FPGA and CPLD.		0 1	·		U
	TT OFT and OF ED.					
Outcomes	•					
	• ing the course the stu	idents should be ab	le to:			
	o understand the dept					
	o design a system usi					
	• •	•	facing of different	avtornal davi	ces with FPGA/CPLD	
		U	C			
	o apply the complete	design flow of FPG	JA and CPLD To	r the specific	application.	
Detailed S		(in)		. 601		
	Description	The second second	D	N. 1	CD 11.1.	Duration
					f Programmable logic CPLD Architecture:	
	verview, specification					-
0.	verview, specification	in and applications,	reatures of AC95	50 series of C	I LD fainity.	6
		A.C./				
	PGA Architecture:	G G 11 I			11 1 2	
					nmable Interconnects,	(
					ology Trends: Device Design Flow, General	6
	esign Guidelines.	ilu Gale Delisity, F	rogramming metho	Jus, General	Design 140w, General	
		A/CPLD: The pu	rpose of interfaci	ng interfacin	g of external devices	
					le, Different types of	6
	splay devices with F		eage Bring	streed	O, D	Ŭ
			ex-6, Spartan-6, Z	-board Advan	ced features in FPGA	
	ased on Case studies.					(
L	ogical Design by F	PGA/CPLD: Com	plete design of a	ny combinati	onal circuit by gates,	6
В	oolean Algebra, Des	ign of sequential ci	rcuits			
	Fotal		Sec	3		24
Text Book						
			0 0		Array, Prentice Hall (P	, · ·
			"Embedded syste	ems design w	vith platform FPGAs:	Principles an
	actices", Morgan Ka		4-1			
3. D	esign manuals of Al	tera, Amnx and Ac	tei.			
Reference	Books.					
		ald Programmable (Gate Array Techno	ology Kluwe	r Academic Publication	ns 1994
					rinciples & Application	
	earson, 2009	, in lamer, Gregor	y 2. 11055, Digit	ii bystems. I i		ib , io Editio
		Field Programmabl	le Gate Arrays, Joł	nn Wiley & S	ons, Newyork, Reprint	2008.
	rown, R. Francis, J.	-	•	•	• •	
	rown and J. Rose, "A					
Test	of Computers, Vol.	13, No. 2, pp. 42-57	7, 1996.		-	
	hen Brown Zvonko V	/ranesic – Fundam	entals of Digital L	ogic with VH	DL design,	
McG	raw Hill – 2000					

	M. Tech. Ed	&TC (VLSI and E	mbedded Syste	ms)	Semester: II	
Course:		ramming for Begi		ective)	Code: MET2602A	
	Teaching Scheme			Evaluat	ion Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisite: 1. 2. 3.	υ	isors and actuators,	Control systems	5		
2. To c 3. To in Outcomes: After learning t	nderstand the physics b reate the mathematical nplement model into Si the course, the students tify & select different ac	model of quadcopte imulink & check it should be able to:	against real life	performance	es & Experimental da	ıta
2. Estal	blish the mathematical i gn Simulink model sim	model & the Physic	es behind Quade	opter drone		
Detailed Sylla	bus:			A Lat	2	
Unit	Description					
	Description			$\sim \sqrt{2}$	3	Duration (H)
1.	Introduction to dror to Drones programmi owning and operatin issues	ing and Developm	ent Tools, Curre	nt rules and reg	ulations governing	
	Introduction to dron to Drones programmi owning and operatin	ing and Development of a UAS, concern and Applications: working on a Fligh	ent Tools, Curre as surrounding Sensors, Motor at, Principal axe	nt rules and reg UAS safety, sec s, Propellers, B es and rotation	ulations governing curity and privacy attery, Concept of of aerial systems,	(H)
1.	Introduction to drom to Drones programming owning and operation issues Drone accessories a propulsion, Forces w Stable, unstable and drones. Drone control sys Quadcopter with acc functionality block, functionality block	ing and Development of a UAS, concern and Applications: working on a Fligh neutral systems, C stem development ctuator & propell controller functio	ent Tools, Curre as surrounding Sensors, Motor at, Principal axe control drone (ro at in Simulini ers functionality pality block, M	nt rules and reg UAS safety, sec s, Propellers, B es and rotation II, pitch and ya k: Control sys y block, Sensi Motor mixing a	ulations governing curity and privacy attery, Concept of of aerial systems, w), Application of stem architecture, ing & estimation algorithm (RPYT)	(H) 6
1. 2.	Introduction to drom to Drones programmi owning and operatin issues Drone accessories a propulsion, Forces w Stable, unstable and drones. Drone control sys Quadcopter with ac functionality block, functionality block Modelling, Simulati flight control design Applicable software f	ing and Development of a UAS, concern and Applications: working on a Fligh neutral systems, C stem development ctuator & propell controller function ion & Flight control	ent Tools, Curre as surrounding Sensors, Motor at, Principal axe ontrol drone (ro at in Simulini ers functionalit onality block, M trol design: Dy , testing & Tun	nt rules and reg UAS safety, sec s, Propellers, B es and rotation oll, pitch and ya k: Control sys y block, Sensi Motor mixing a mamic quadcop ing the model,	ulations governing curity and privacy attery, Concept of of aerial systems, w), Application of stem architecture, ing & estimation algorithm (RPYT) ter system Model,	(H) 6 6 6
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1. 2. 3. 4. Text books: 1. Build 2. Quad 3. Mod 4. Robo Reference Boo 1. Rob 2. Dro	Introduction to drom to Drones programmi owning and operatin issues Drone accessories a propulsion, Forces w Stable, unstable and drones. Drone control sys Quadcopter with ac functionality block, functionality block Modelling, Simulati flight control design Applicable software f Total ding your own drones, a dcopter modelling and c el based design of a qua otics control, sensing, v	ing and Development of a UAS, concern and Applications: working on a Fligh neutral systems, C atem development cutator & propell controller function a beginner's guide to control with Matlab adcopter by Ryan C ision and intelligen Mittal , I.J.Nagrath e), Ben Rupert, Cre	ent Tools, Currens surrounding Sensors, Motor at, Principal axe control drone (reconstruction and in Simulinit ers functionality block, M trol design: Dy trol design: Dy trol design: Dy trol design: Dy trol design: Dy trol design: Dy functionality block, M trol design: Dy functionality block, M functionality block, M function	nt rules and reg UAS safety, sec s, Propellers, B es and rotation II, pitch and ya x: Control sys y block, Sensi Motor mixing a rnamic quadcop ing the model, analysis S, and ROVs- Jo mentation by M C.Gonzalez, C.G	ulations governing curity and privacy attery, Concept of of aerial systems, w), Application of stem architecture, ing & estimation algorithm (RPYT) ter system Model, Flight operations, hn Baichtal uhammad Usman .Lee	(H) 6 6 6 6

Program	n: M. Tech. E&TC (VLSI and Embedded	Systems)	Semes	ster: II	
Course		and Measurements (O			MET2602B	
	Teaching Scher]		ion Scheme	
Lectur	e Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
	uisite: Basics of sensors and	d Actuators, Basic of E	lectronics, Ana	log and Digita	l Systems	
Objectiv						
-	rt knowledge on the followi					
1.	Basic functional elements of					
2. 3.	Fundamentals of electrical Comparison between vario					
	Various storage and display		ques			
	Various transducers and the		ms			
Outcom		c and acquisition syste	1110			
	rning the course, the studer	ts should be able to:				
1.	Analyse different measurin		ectronics/mecha	atronics system	1	
2.	Design and evaluate charac			•		tem
2. 3.	Understand different types	• 1			i electronic sys	
	• 1					
		monante and analyzea	ite data using d	ata acquisition	evetom	
4.	Interface various system co	omponents and analyse	its data using d	lata acquisition	system.	
4.	interface various system co	omponents and analyse	its data using d	lata acquisition	system.	
4.	Interface various system co	omponents and analyse	its data using d	lata acquisition	system.	
	Interface various system co	omponents and analyse	its data using d	lata acquisition	system.	
	Syllabus:	a Chille		0.00		Duration
Detailed	Syllabus: Description Basics of Measurements: A	Accuracy, Precision, re	esolution, reliab	bility, repeatab	ility, validity,	Duration
Detailed	Syllabus: Description Basics of Measurements: Errors and their analysis,	Accuracy, Precision, re Standards of measure	esolution, reliab	bility, repeatab Measurement:	ility, validity, DC bridges-	Duration
Detailed	Syllabus: Description Basics of Measurements: Errors and their analysis, wheatstone bridge, AC b	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay	esolution, reliatement. Bridge	bility, repeatab Measurement: chering and V	ility, validity, DC bridges- Vien bridges,	
Detailed Unit	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru	esolution, reliatement. Bridge 7, Maxwell, So 8, ments for Me	bility, repeatab Measurement: chering and V asuring Basic	ility, validity, DC bridges- Vien bridges, Parameters:	Duration
Detailed Unit	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM	esolution, reliatement. Bridge 7, Maxwell, So 8, ments for Me	bility, repeatab Measurement: chering and V asuring Basic	ility, validity, DC bridges- Vien bridges, Parameters:	
Detailed Unit	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC meter, Digital voltmeter, V	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM: 'ector Voltmeter.	esolution, reliab ement. Bridge 7, Maxwell, So ments for Me S responding V	bility, repeatab Measurement: chering and V asuring Basic Voltmeter, Elec	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi-	
Detailed Unit	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC meter, Digital voltmeter, V Oscilloscopes: Cathode Ra	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM Vector Voltmeter. ay Tube, Vertical and F	esolution, reliab ement. Bridge 7, Maxwell, So ments for Me S responding V Horizontal Defle	bility, repeatab Measurement: chering and V casuring Basic Voltmeter, Election Systems	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines,	
Detailed Unit	Syllabus: Description Basics of Measurements: A Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC meter, Digital voltmeter, V Oscilloscopes: Cathode Ra Probes and Transducers,	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM Vector Voltmeter. by Tube, Vertical and H Specification of an	esolution, reliatement. Bridge , Maxwell, So ments for Me S responding V Horizontal Defle Oscilloscope.	bility, repeatab Measurement: chering and V asuring Basic Voltmeter, Election Coscilloscope	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement	6
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Detailed Unit 1. 2.	I Syllabus: Description Basics of Measurements: Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC meter, Digital voltmeter, V Oscilloscopes: Cathode Ra Probes and Transducers, Techniques, Special Oscill Generators: Sine wave g frequency Generator. Pulse	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM. Vector Voltmeter. ay Tube, Vertical and H Specification of an loscopes – Storage Os generator, Frequency and square wave gene	esolution, reliatement. Bridge 7, Maxwell, So ments for Me S responding V Horizontal Defle Oscilloscope. scilloscope, Sar – Synthesized erators. Functio	bility, repeatab Measurement: chering and V asuring Basic Voltmeter, Elec ection Systems Oscilloscope npling Oscillo Signal Gene n Generators.	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement scope. Signal rator, Sweep	6
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Detailed Unit 1. 2. 3.	Syllabus: Description Basics of Measurements: Errors and their analysis, wheatstone bridge, AC b Wagner ground Connect Amplified DC meter, AC meter, Digital voltmeter, V Oscilloscopes: Cathode Ra Probes and Transducers, Techniques, Special Oscil Generators: Sine wave g frequency Generator. Pulse Signal Analysis: Wave Frequency Counter; Me Transducers: Types, Strain	Accuracy, Precision, re Standards of measure oridges – Kelvin, Hay ion. Electronic Instru Voltmeter, True- RM Vector Voltmeter. by Tube, Vertical and H Specification of an loscopes – Storage Os generator, Frequency e and square wave gene Analyzer, Spectrum easurement errors; ex Gages, Displacement	esolution, reliatement. Bridge 7, Maxwell, Soments for Me S responding V Horizontal Defle Oscilloscope, Sar esilloscope, Sar esilloscope, Sar esilloscope, Sar crators. Function Analyzer. Free xtending frequents	bility, repeatab Measurement: chering and V asuring Basic Voltmeter, Elec ection Systems Oscilloscope npling Oscillo Signal Gene n Generators. equency Cour uency range	ility, validity, DC bridges- Vien bridges, Parameters: ctronic multi- s, Delay lines, measurement scope. Signal rator, Sweep tters: Simple of counters	6
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Text Books:

1. Modern Electronics Instrumentation & Measurement Techniques, by Albert D.Helstrick and William D.Cooper, Pearson Education. Selected portion from Ch.1, 5-13.

2. Elements of Electronics Instrumentation and Measurement-3rd Edition by Joshph J.Carr.Pearson Education. Selected portion from Ch.1,2,4,7,8,9,13,14,18,23 and 25.

Reference Books:

- 1. Electronics Instruments and Instrumentation Technology Anand, PHI
- 2. Doebelin, E.O., Measurement systems, McGraw Hill, Fourth edition, Singapore, 1990.

Progran					Semeste	r : 11	
Course	Microcontrollers and M	Aicroprocessors	Application	5	Code : N	AET2602	С
	(Open Elective)						
	Teaching Scheme				Evaluati	on Schen	le
Lectur	re Hours	Credit	IE1	I	E2	ETE	Total
2	2	2	20		50		
Pre-req	uisite: Digital Electronics		-			30	
Objectiv							
1.	To understand architecture and f	• •					
2.	To understand need of microcon			S.			
3.	To learn interfacing of real-worl						
4.	To study various hardware and s						
5.	To learn the architecture and pro	grammer's mode	l of advance	l process	or and mic	rocontroll	er
6.	To acquaint the learner with app	lication instruction	on set and log	ic to buil	d assembly	y language	e programs.
Outcom							
	arning the course, the students sho			Coli			
1.	Learn importance of microcontro	-				application	1
2.	To apply the programming skills		ife embedde	d applicat	tion.		
3.	Learn use of hardware and softw	are tools.					
4.	Develop interfacing to real work	d devices.					
	Syllabus:	1			120	31	
Unit	l Syllabus: Description		1			Dear	Duration, h
Unit 1.		anguage program					-
Unit 1.	Description Introduction to single chip M architecture, 8051 assembly 1	anguage program munication design: Assemb ment: assembler	nming, addı ly vs High-J r, compiler	essing n Level lan and inte	nodes, Pro guage pro egrated de	ogrammin gramming	- 6
	Description Introduction to single chip M architecture, 8051 assembly 1 interrupts, timers and serial com Microcontrollers and system System Development Environ	anguage program munication design: Assembler mulation, system ign; Advanced C processors; A	nming, addi ly vs High-J , compiler design with Microproces RM microco	essing n Level lan and inte 8051. sor Arch ontrollers	nodes, Pro guage pro grated de dom" itectures- ; Embedd	grammin gramminş velopmer 286, 486 ed syster	g 6 g 6
Unit 1. 2. 3.	Description Introduction to single chip M architecture, 8051 assembly I interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RIS	anguage program munication design: Assembler mulation, system ign; Advanced C processors; A d controller desig s Applications: Case Study on res	nming, addi ly vs High- c, compiler design with Microproces RM microc n for commu Interfacing v al time embe	essing n Level lan and inte 8051. Sor Arch ontrollers inication, vith displ	uodes, Pro guage pro grated de dom" itectures- ; Embedd digital con ay device	grammin gramminş velopmer 286, 486 ed syster ntrol.	g 6 g, 6 5, 6 5, 6
Unit 1. 2. 3. 4.	Description Introduction to single chip M architecture, 8051 assembly I interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RISC design methodologies, embedded Microcontroller & Processors actuators, and memory devices.	anguage program munication design: Assembler mulation, system ign; Advanced C processors; A d controller desig s Applications:	nming, addi ly vs High- c, compiler design with Microproces RM microc n for commu Interfacing v al time embe	essing n Level lan and inte 8051. Sor Arch ontrollers inication, vith displ	uodes, Pro guage pro grated de dom" itectures- ; Embedd digital con ay device	grammin gramminş velopmer 286, 486 ed syster ntrol.	g 6 g, 6 6, 6
Unit 1. 2. 3. 4. Text Bo	Description Introduction to single chip M architecture, 8051 assembly I interrupts, timers and serial com Microcontrollers and system System Development Environ environment, Debugging and Si System level interfacing des Pentium; Introduction to RISC design methodologies, embedded Microcontroller & Processors actuators, and memory devices.	anguage program munication design: Assembler mulation, system ign; Advanced C processors; A d controller desig s Applications: Case Study on rea Total	nming, add ly vs High- c, compiler design with Microproces RM microc n for commu- Interfacing v al time embe	essing n Level lan and inte 8051. sor Arch ontrollers inication, vith displ dded syst	nodes, Pro guage pro grated de dom" itectures- ; Embedd digital con ay device em.	ogrammin gramming evelopmer 286, 480 ed syster htrol. s, Sensor	g 6 g, 6 6 5, 6 6 3, 6 24
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Program:		puter Engineerin		Semester :	I				
Course :	Programming v	with Python (Ope	en Elective)	Code : MC	CE1601A				
	Teaching Schem			Evalu	ation Scheme				
Lecture	Lecture Hours Credit IE1 IE2 ETE								
2	2	2	20		30	50			
Pre-requi	site: . Basics of Progra	mming							
2.To c 3.Acq Dutcomes After learn 1.Describ 2.Interpre 3. Apply	acquire knowledge in F levelop Python progra <u>uire skills to apply dat</u> : ing the course the stud the the Numbers, Math et Object oriented prog a solution clearly and	ms with condition a analysis method lents should be ab functions, Strings, ramming in Pytho	als and loops and s to a problem le to: List, Tuples and on	Dictionaries in					
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Unit 1	Description	1 and		9	0	Duration			
P p if	ntroduction to Pytho ython environment in ython program, Editon else, for, while, r perations, String Meth	Windows and Lin for Python code, range() function,	ux, basics of Pyt syntax, variable	hon interpreter, , Data types. F	Execution of low control if	6			
a	ists: Basic Operations nd dictionaries, dicti functions: Definition, (onaries & lists.	Tuples and F	iles : reading		6			
3. C		Programming 1	features in P	ython: Class		6			
4. N N F P H	Jumpy and Matplotli Jumpy Basic Statistics Jumpy Basic Statistics Jumpy Basic Statistics Jumpy Basic Statistics Contention Statistics Correlation, Histogram	Matplotlib: Intro Selections and In 5, Mapping, Dat	duction, Simple j dexing, Filling a Frames, Read	plots, Line API, Methods, Seri	Legend API, es operation,	6			
	Total	2.5	Since 10	99		24			
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1. Allen B	Downey, —Think PY								
	Roger D and Elizabeth								
	Consulting 200 (2015)				-				
Reference	Books:								

 Reference Books:

 1. Zed A. Shaw,Learn Python the Hard Way

2 2 2 20 30 Pre-requisite:- Objectives: . . . To learn and understand the principles of Software Engineering 2. To be acquainted with methods of capturing, specifying, visualizing and analyzing software requirem 3. To apply Design and Testing principles to S/W project development. 4. To understand project management through life cycle of the project. 5. To understand software quality attributes. Outcomes: After learning the course the students should be able to: 1. Decide on a process model for a developing a software project 2. Classify software applications and Identify unique features of various domains 3. Design test cases of a software system. 4. Understand basics of IT Project management. 5. Plan, schedule and execute a project considering the risk management. 6. Apply quality attributes in software development life cycle. Detailed Syllabus: Dutit Unit Description Dutition 1. Introduction to Software Engineering and Software Process Models: Software Engineering Process, Concurrent. Advanced Process Models & Tools: Agile software Requ	ogram:		uter Engineering		Semester :				
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Risk Mitigation, Risks Monitoring and Management, The RMMM plan for case study									
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project		•	wontoning and w	lanagement, The		for ease study			
							24		
Text Books:			nainaanina. A D	atitionan's A	aab MaCross		227507		
1. Roger Pressman, —Software Engineering: A Practitioner's Approach ^I , McGraw Hill, ISBN 0-07-337597	xoger Pres	ssman, —Sonware E	angineering: A Pra	cutioner's Appro	achi, Nicoraw	пш, ISBN 0-07-3	176160		
2. Ian Sommerville, — Software Engineering , Addison and Wesley, ISBN 0-13-703515-2	an Somme	<u>erville, — So</u> ftware J	Engineering, Add	<u>lison and W</u> esley,	<u>ISBN 0-</u> 13-70)3515-2			
Reference Books:	ference Bo	ooks:		-					
1. Carlo Ghezzi, —Fundamentals of Software Engineering", Prentice Hall India, ISBN-10: 0133056996									
2. Rajib Mall, —Fundamentals of Software Engineeringl, Prentice Hall India, ISBN-13: 978- 8120348981									
Pankaj Jalote, —An Integrated Approach to Software Engineeringl, Springer, ISBN 13: 9788173192715.	Pankaj Jalo	ote, —An Integrated	Approach to Soft	ware Engineering	I, Springer, IS	BN 13: 978817319	2715.		

4. S K Chang, —Handbook of Software Engineering and Knowledge Engineering, World Scientific, Vol I, II, ISBN: 978-981-02-4973-1

5. Tom Halt, —Handbook of Software Engineeringl, Clanye International, ISBN10: 1632402939

6.Christine Bresnahan, Richard Blum -Linux command line and Shell Scripting Bible -Weilly, ISBN-978-0-470-25128-

Program:		iter Engineering)			ester : I	
Course :	Basics of Machi Teaching Scheme	ne Learning (Op	en Elective)		e : MCE1601C ation Scheme	
	Teaching Scheme	e		Evalu	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisi						
	lgebra, Statistics, Prob	bability and Calcul	lus			
2. Basic Pi Objectives:	ogramming Skills					
1. To mc 2. To	master the concepts deling gain practical knowle	edge over principle	es, algorithms, an	d applications	of Machine Learn	ning through a hands
	approach and to valid					
	dels using another set acquire thorough kno					
	theoretical concepts a	0		1	•	g and To comprehen
	To implement models					cision tree classifie
	dom forest classifier,					
Outcomes:		b	Nad	Con		
	ng the course the stude			09		
	derstand machine lear	rning techniques a	ind computing en	vironment that	are suitable for t	he applications unde
	nsideration.	d with botch loop	ming and online l	acoming and th	a hig data shares	tanistics such as his
	lve problems associate nensionality, dynamic					cteristics such as mg
	velop scaling up ma					and technologies for
	rious applications.		·····	r		
4. Im	plement various ways	of selecting suitab	ole mod <mark>el parame</mark>	ters for differen	nt machine learnin	ng techniques.
Detailed Sy	llabus:				1 3	
Unit D	escription				č	Duration, h
Ur		forcement Lea	rning, Validation	Technique	s (Cross-	6
	llidations);Feature alysis (Eigen v <mark>alues</mark> , E	Reduction/Dimens				
2. Cl Hi va	ustering: Distance erarchical); Iterative c lues in K-Means; C nsity-based clustering	measures;Differer listance-based clu onstructing a hie	nt clustering me stering; Dealing rarchical cluster	ethods (Distan with continuou	ce, Density, s, categorical	6
Re			odel Assumption timates;, Feat			
K- de	formation;Classifier Nearest Neighbors: signing K-Nearest Ne gression problems.	-	-	-		6
4. As Ba an mi	sociation Rule mini sket, Recommendation alysis; Large item set ni sup by iterations;	on Engines, etc. s; Association Ru Interestingness of	; A mathemati les; Apriori: Cor of discovered ass	ical model for istructs large if	r association tem sets with	6
Re	amples; Association a search Aspects: A	pplication of N	AL in various			U
	blication in Qualit			nals/ Conferen	nces;Practical	
	plementation of Indus	try Projects/Appli	cations; IPR			24
	otal 					24
Text Books	: , R. Tibshirani, J. Frie	dman The Fleme	nts of Statistical I	earning 20 20	008	
	er Bishop. Pattern Re			-		
Reference 1						
L. Ethem	Alpaydin, Introduction	n to Machine Lear	ning			

-	ram: M.Tech (Computer Engineering) Semester : II						
Course :		ng with MATLAI	3	Code · M	CE2602A		
	(Open Elective)		1				
	Teaching Scheme			Evalua	tion Scheme		
Lectur	re Hours	Credit	IE1	IE2	ЕТЕ	Total	
2	2	2	20		30	50	
Pre-requ	isite: Programming Basic	CS					
Objectiv	es: op an overview of the field	l of image process	ina				
	the basic theory and algor	• •	•	image process	inσ		
	op hands-on experience in			initige process	ing.		
	arize with MATLAB Ima						
Outcome		ge i locessing 100	ibox course				
After lear	ming the course the stude	nts should be able	to:				
	stand the need for image t			ansforms and t	heir properties.		
	different techniques empl						
	stand the need for imag	e compression an	d to learn the sp	atial and frequ	ency domain	echniques of image	
	pression.	1 cm	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	00			
	different feature extraction		nage <mark>analysis an</mark> d i	recognition.			
5: Develo	op any image processing a	pplication.					
Detailed	Gullohua				Ser.		
Unit	Syllabus:				0	Duration	
Cint	Description				10101	h	
	Introduction: What is image processin perception? Image sam	•	fundamental issu	ues? . What is	the role of		
	MATLAB orientations. Image Transformations Discrete Fourier transfo Discrete cosine transform	rm, Properties of	zation, Basic rel	ationship bet	ween pixels,	6	
2.	Image Transformations Discrete Fourier transfo Discrete cosine transform Image Enhancement Te	rm, Properties of , Discrete Wavelet chniques	zation, Basic rel 2D DFT, FFT, transform.	ationship bet	ween pixels, Correlation,	6	
2.	Image Transformations Discrete Fourier transfor Discrete cosine transform Image Enhancement Te Spatial Domain Techniq Image subtraction, Imag filters. Frequency Domain Tec	rm, Properties of , <u>Discrete Wavelet</u> chniques ues: Basic gray l e averaging, Spa hniques: Frequenc	zation, Basic rel 2D DFT, FFT, transform. evel transformatic tial filtering, Smo cy domain filteri	ationship bet Convolution, Ons, Histogram Dothing filters	veen pixels, Correlation, n processing, Sharpening	6	
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Text Books:

- 1. R. C.Gonzalez, R.E.Woods," Digital Image processing", Pearson edition, Inc3/e,2008.
- 2. A.K.Jain," Fundamentals of Digital Image Processing", PHI,1995

Reference Books:

1. J.C. Russ," The Image Processing Handbook", (5/e), CRC, 2006

- 2. R.C.Gonzalez & R.E. Woods; "Digital Image Processing with MATLAB", Prentice Hall, 2003
- 3.W. K. Pratt, *Digital Image Processing*, John Wiley & Sons, 2006.
- 4.S. Ahmed, Image Processing, McGraw -Hill, 1994.
- 5.S. J. Solari, Digital Video and Audio Compression, McGraw-Hill, 1997



Program:		uter Engineering)		Semester :		
Course :		s (Open Elective)		Code : MC		
	Teaching Scheme			Evalua	tion Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-requisite						
Objectives:						
1.To acqu	uire knowledge of bas	ic Linux OS, comm	ands, and term	inologies		
	elop programs using S					
3. To acq	uire skills related to I	Linux file system				
Outcomes:						
	g the course the studer		:			
	e common and simple		C111			
	onstrate programming velop collaboratively			ore using LoTor		
	ly a solution clearly a					
Detailed Syll		nd decuratery in Em		it .		
Unit						Duration
Des	scription					h
3. Intr	oduction to Linux	Linux introduction	n; Understand	ding philosoph	y of Linux;	
	erstanding Software					
Insta	allation of Linux OS	direct and using	virtual mach	ine); Using co	mmon Linux	6
	rams: Linux desktop					-
Und	erstanding and manag	ing hardware: CPU,	, Dis <mark>k issues</mark> , I	Device drivers, I	Display etc.;	
2. Basi	c Commands and S	Shell Scrinting. Int	roduction to I	inux command	s concept of	
	l, shell variables, get					
	ables declaration &					
	nples, for	and whi				6
	l functions, pipe and	edirection, wildcard				
Awk	script: Environment	andworkflow, synta	x, variables, o	perators, regular	r expressions,	
	ys, control flows, loop		redirections			
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	System - Manipulat					
	g absolute and rela					6
	aging; Basic File and					
	vorking - Understan ing a network connec		ures; Configu	ring a network	connection;	
	ential System Admin		Inicial Souce	lience		
	rs and Group Manag		Troup manage	ment: Creation	Undating	
	tion of user and group					
	pmod, groupdeletc; N				, g ,	
	cess and PackageN				ment,package	
	agement commands		pt; Understan	ding Process h	ierarchy and	
	tifying running proces	sses; Log files.				
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	oduction to GIT and		1			
	EX:Basic syntax, con					
	ons and paragraphs; rences, and Bibliograp				apiis; Adding	
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	: Creating a project u					
	ote repo, working wit	h a remote repo; We	orking on a pr	oject in a distrib	outed fashion;	
	ds-on of GIT.					
Tot	al					24
Fext Books:						
	resnahan, Richard Bl					
	Das, Unix Concepts ar	d Applications, Tat	a-McGraw Hil	I, ISBN 0-07-06	03546-3	
Reference Bo						
Christine Ri	resnahan, Richard Blu	im –Linux command	d line and She	II Scripting Bible	e -Weilly , ISBN-	978-0-470-2512

Program	uter Engineering))	Semester :]	Ι		
Course	e: Design with UN	IL (Open Elective	e)	Code : MC	E2602C	
	Teaching Schem	e		Evalu	ation Scheme	
Lectu	re Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
Pre-req	quisite:	•	•		L L	
	understanding of computer	r programming and	d related programi	ning paradigm	s.	
Objecti						
5.	To introduce the concep	t of Object-oriente	ed design			
6.	To understand and different	rentiate Unified Pr	ocess from other a	approaches		
7.	To design static and dyn	amic UML diagram	ms			
Outcon						
	earning the course the stud					
1.	Understand Basic featur		·			
2.	Identify, analyse, and m					
3.	Apply the concepts of a	chitectural design	for deploying the	code for softw	are.	
		-	ior asprojing une	eoue for softm		
			tor deproying the			
Detaile	ed Syllabus:	ch		01		
Detaile Unit	ed Syllabus: Description	inch		Coll - 0		Duration, (H)
			eling, principles of	of modeling, ob	oject-oriented	Duration, (H)
Unit	Description Introduction to UML: In modeling, conceptual r	eling: Classes,	eling, principles o L, Architecture, S Relationships, co d classes, advanc	of modeling, ob Software Deve Dommon Mech	oject-oriented lopment Life anisms, and	
Unit 4.	DescriptionIntroduction to UML: In modeling, conceptual r CycleBasic Structural Mod diagrams. Advanced Structural M	leling: Classes, odeling: Advance ges. Class & Object Behavioral Model ns, Activity Diagra Modeling Events	eling, principles of L, Architecture, S Relationships, co d classes, advanc ct Diagrams ing: Interactions, uns. and signals, stat	of modeling, ob Software Deve common Mech ed relationship	oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use	6
Unit 4. 2.	DescriptionIntroduction to UML: If modeling, conceptual r CycleBasic Structural Mod diagrams.Advanced Structural M Types and Roles, PackaBasic and Advanced I cases, Use case Diagram Advanced Behavioral D	leling: Classes, odeling: Advance ges. Class & Object Behavioral Model as, Activity Diagra Modeling Events s, state chart diagra g: Component,	eling, principles of L, Architecture, S Relationships, co d classes, advanc ct Diagrams ing: Interactions, ums. and signals, stat ums. Deployment, C	of modeling, ob Software Deve common Mech ed relationship Interaction di e machines, p Component di	oject-oriented lopment Life anisms, and s, Interfaces, agrams. Use rocesses and agrams and	6

1. Grady Booch, - The unified modeling language user guide. Pearson Education India, ISBN: 0-201-57168

 James Rumbaugh. Micheal Blaha- Object-Oriented Modeling and Design with UML: Pearson Education India, ISBN-13: 978-0130159205

Reference Books:

- 2. Charles Ritcher Designing Flexible Object-Oriented systems with UML. New Riders Publishing.
- 3. Jackson, Burd Thomson Object Oriented Analysis & Design. Thomson Course Technology.
- 4. Mike O'Docherty Object-Oriented Analysis and Design: using UML. Wiley Publication
- 5. Joseph Schmuilers Teach Yourself UML in 24 Hours. Sams publishing.

Program:	M. Tech. Civil (Semes		1 60 1 1	
Course :		agement and	Finance (Open E		Code :		1601A	
	Teaching Scheme			E	valuatio	on Scheme		
Lecture	Hours	Credit	IE1	IE2		ETE	Т	otal
2	2	2	20			30		50
Pre-requisit								
Basics of Ma	nagement, Basics o	of Finance						
Description Description 1. Out 2. To a 3. To a 4. To a Outcomes 1. 1. Acces	S: After Complete After Complete After Principles for the principles for the principles for the principles for the principle of the principle the principle of the principle of the the principle of the principle of the principle of the the principle of the principle of	ollowed in car edge and under as an individu of finance and course, the st nds and choos	rying out a project. rstanding of engine tal, and as a membe accounts carried ou udents should be ab	ering and n er or leader it in projec	nanagerr in diver	nent principles. se teams.	stand and	solve th
3. Abili	ty to implement the	project effecti			ms and c	conditions.		
4. Abilit Detailed Syl	ty to select projects	which benefit	me society and org	anization.	n v			
	scription	1.50	C.		100		Du	ration, l
	oduction to Manas	vement			- 20	2		11 ation, 1
Wha Diff	at is Management? l erent Schools/ a tingency Approach	It's Need ,Imp						6
	ject Implementation	on, Monitorin	g and Control			131		
Proj preli allo	ect representation: minary manipulat cation, Setting a	Role of proje ions, Basic base line, Pr	ect managers, rele Scheduling conc oject management	epts: Reso informati	ource 1 on syste	evelling, Resou em: Importance	irce	6
	racts in projects: Te anizing	ani work in P.	roject Management	: Formatio	I OI EIIE	cuve terms.		
Orga orga Cha Prop Dec	anizing as a Mana nizations such as racteristics, Feature orietorship, Partners ision Making, Gro fing, Recruitment, S	line, Line es, their Mer ship, Private I up Decision	& Staff, Function its and Limitation .td., Public Ltd., I Making, Staffing:	al, Matrix , Ownersh ntroduction What is S	or pro- nips of to Org Staffing?	oject Organizati Organization: S anizational climatics	on: ole ate,	6
4. Fina Und	incial Statements erstanding of Finar ount, Ratio Analysi	And Their An acial Statemen	alysis ts and Their Analy	sis, Like B	alance S		oss	6
Tot		s, 1 und 1 10 w 1	marysis, Statemen	t of change	25 111 1 111	anciar i osition.		24
	nents / Assignmen	ts :						
1. 4 2. 4 3. 4 4. 4 T	Assignment based of Assignment based of Assignment based of Assignment based of Ratio Analysis, Fun ext Books:	n Need, Impo n Project Imp n Managemer on Financial S d Flow Analys	lementation, Monit tt process, Principle tatements and The sis.	oring and C es of Organ ir Analysis	Control. ization. , Like B			
2 3	Project Managemen (Sixth Edition), Sep James C.Van Horne Khanna, R.B.,Projec	t 2017. , Fundamental	ls of Financial Man	-		-	dge PMB	OK Guio
Reference B 1. 2.	ooks: Kuster J., Huber, I Handbook, 2015. Prasanna Chandra,					hi, U., Wust, R.	Project M	anageme
3. 4.	Carl S. Warren, Jan Paneer Selvam, R.	mes M. Reeve	, Jonathan Duchac.	Financial a	and Man		ng, 2016	

Program:			n Management	t)	Semester : I	
Course :		nnology (Open	Elective)	T	Code : MCI1601B	
	Teaching S	Scheme			Evaluation Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20		30	50
	te: Environmental stu					
Objectives:	After Completing thi	s course, stude	nt will have ade	equate backgroun	d to:-	
	Evaluate Global warr					
	Demonstrate knowled	0	0	0		
	Apply control measur					
	Apply high tech meas					
	After learning the cou			le to:		
	Analyse effects of C					
	Implement the conce					
	Apply remedial action					
4. Detailed Sy	Apply high tech mea	asures for Redu	icing Cardon El	missions.		
	escription					Duration, h
		its offoot. Intr	oduction and n	hygical definition	n of global warming, the	,
					ential, Carbon Emission	
					n and its effect in India,	
					change and its impact.	
					ken to Control Carbon	
					for Reducing Carbon in	
					eveloping Countrywide	
					ve Measures for Global	
Re	duction of Carbon,	India's Nationa	al Action Plan	on Climate Cha	nge (NAPCC) till date,	
Na	tional Mission for a G	Green India, Th	e MRV Debate		10/01	
					on:- Essential Steps for	
					elop own Priorities and	
					accumulation, Needs a	
					l Approach for Carbon	
					ment rates procedure for	6
	ntrolling carbon emis					
					es Available for Energy	
	-		• • •		Generation, Sources of	
	eding some Prior R&		iternative Meth	ious Ready for C	Jse, Green Technologies	
			nd Citywide	nnlication :- M	leasures to be taken for	
					Emission Reduction at	
	cal Authority and Cit					
	•	•		-	n' Buildings, Guidelines,	
					and Hospitals, Green	
					ustries, Carbon, Carbon	
En	nissions from a Few S	Selected Indust	ries in India, T	he Changing Sce	nario in Cities, Need for	
					ment Projects ,'Green'	
				p Indian Village	es, Green Services for	
	ematoria, Spreading I					
					se of Solar Power with	
			n Capture and	Storage (Sequesti	ration), Microorganisms,	
	Quick SWOT Analys		. 1. NT. (* 1. 4			6
					s to a Low-Carbon Path,	
	-	-		udies on Projects	s undertaken by Various	
	numes adaptive Me			onla to Com'1	Climata Change	
	untites, rauptive me	easures Essentia	al for Indian Peo	ople to Cope with	Climate Change	

Assignments :

- 1. Assignment based on Global Warming and its effect and reduction measures.
- 2. Assignment based on Control of Carbon Emissions and Accumulation
- 3. Assignment based on Applications of green technologies.
- 4. Assignment based on High-tech measure for carbon emission reduction/ action plan

Text Books:

1. Green Technologies, Soli J. Arceivala, Mc Graw Hill Education.

Reference Books

- 1. Green Technologies and Environmental Sustainability edited by Ritu Singh, Sanjeev Kumar
- 2. http://cpcbenvis.nic.in/greentechnology.html



Program:		ch. Civil (Construction		Semester :	II		
Course :		nct Tendering and Ark	oitration	Code: M	CI2602A		
	Teaching So	Elective)		Evalı	ation Scheme		
Lecture	Hours	Credit	IE1	IE2	ETE	Total	
2	2	2	20		30	50	
Pre-requis	site:		l	I	I I		
Objectives	:						
		dge of contracts system					
		pecifications for making					
		of Arbitration in the cor	ntext of various	construction asp	bects.		
Outcomes							
	0	e students should be ab			_		
		al knowledge for maki			nders.		
		documents as per cond					
		f Arbitration to resolution	on of disputes in	construction pi	rojects.		
Detailed S		111	UQQ	Con		.	
Unit	Description	100	3	100		Duration	
1.	Construction (6.4	1.4.67			
		Act (1872): Definition				6	
		Objectives of the act.				Ū	
	governing struc	ture & Working of Con	istruction Organ	ization Firms, L	Laws of Tort.		
2.		Contract Documents:			131		
		ontract documents, need					
		ntract documents, types	s of constructior	contracts, roles	s and functions of	6	
	parties to the co				1		
	Contract Forma						
3.	Stages in Cont		A 43.				
	-	ender documents estimation	ating, pre - qual	ification, bid ev	aluation, award of	6	
	contract,						
		g and contract paymen					
4.	Arbitration:		edge Brin			_	
		Actions and Laws - Ag			tions-Appointment	6	
	of Arbitrators-	Conditions of Arbitration	ons-Powers and	duties of			
	Total	- A. A.	And an Greek	Newce		24	
Text Book							
1.		ing Contracts and Estin					
2.		ntract Act (9 of 1872), 1					
3.		and Conciliation Act,	(1996), 1996 (20	6 of 1996)- 2006	5 Edition, Profession	al Book Publishe	
Reference	Books:						
			D : 00051				
		t I and Part II, Dr. R.K	0		<u> </u>		
		ation and Alternative E	1	•	. S.R. Myneni-		
	-	nted in 2005- Asia Law			feeder al Deele Deele	: - 1 +	
		mpensation Act, 1923					
		conditions for Domestic		1 Ministry Of S	tatistics and Program	Implementation	
		ia. FIDIC Document (1		na 20 Edition			
		Board foundation man	ual-www.drbl.o	rg. 30 Edition			
List of Ass							
•	ignments on:	the set of the set of the			Defeate 's is in	· · · · · · · · · · · · · · · · · · ·	
		itions of Contract relate			Defects in construct	ion work.	
		ssion and necessary Ter	nder Documents	i.			
3. Pr	ocedure of Bid O	pennig					

Program:		ch. Civil (Construc		Semest		
Course :		Quality Manageme	nt (Open Elective)		MCI2602B	
	Teaching Scl	heme		Evalua	ation Scheme	
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Total
2	2	2	20		30	50
		S at UG Level, Aw	areness of Quality O	Construction As	pects	
2. To 3. To	understand the apply necessar apply effective	the need of QM in con- ry trainings for the e ely the eight princip ma tool for TQM in	effective utilization les of ISO for qualit	of resources y processes in c		
Outcomes:						
		he engineers should				
	derstand and ap le to use effecti	pply the TQM phylo	sophy in construction	on		
		ples for effective Qu	ality processes in co	Instruction		
		Sigma effectively.	anty processes in et	insu detton		
Detailed Sy						Deres from 1
	Description Concepts of Qu	ality				Duration, h
A co 1. N ir m	A) Definition o ontrol, Quality Management (T nplementation	of quality as given Assurance (QA/C QM), Need for TC of quality, Quality 1 ing for quality- PDC	QC). Total quality QM in construction manual-Contents, da	control (TQ industry. Orga ita required, pre	rence between Quality C) and Total Quality anization necessary for eparation, responsibility phase in the life cycle	6
2. H	uality control of 'est (NDT).	eto diagram, Fish-b	erial used in RCC V		rt-Testing required for ve and Non destructive	
3. th co D	Turpose of ISO for ISO 9001. C nese principles ommitment nec Development of	ertification bodies i for an effective qua cessary for achieving	ce between ISO 900 nvolved. Eight Prin ility process in the o g implementation fo	ciples of ISO-B organization. M r quality system	4. Certification process basic meaning, applying anagement support and a standards. reports, monitoring and	6
4. A D ra B i) (i	 A) Six Sigma Definition of si atings, Six sigma B) Application (1) C) RCC Work in 	x sigma, evolution na training, six sigma of Six Sigma building	a as an effective too	l in TQM.	distribution Six sigma	6
	Total					24
Text Books 1. Qualit 2.Total E 3.Total P	: y Control and 7 Engineering Qua Project Manager	Fotal Quality Manag ality Management – ment – The Indian C	Sunil Sharma – Ma	cmillan India L		
2. N 3. J	International St Mantri Handbo		truction – Mantri Pu	iblications	Acgraw Hill Internationa	al

4. Management Information Systems - Gordon B. Davis, Margrethe H. Olson - Tata McGraw Hill Publ. Co.

List of Experiments/ Assignments:

- 1. One Assignment on Each Unit
- 2. Activity: Posters / Flex / Flow Charts / Presentation etc. Per students on any one Topic of the Syllabus
- 3. Quality Circle Team for Problem Solving.



Program:		. (Civil Engin				Semester : II		
Course :		n Research (Open Elective	e)		Code : MCI2602C		
	Teaching	Scheme			Evalu	uation Scheme		
Lecture	Hours	Credit	IE1	IE2	ЕТЕ	Tota	al	
2	2	2	20		30	50		
Pre-requisite								
		cs Including C bability/Statis		inear Algebra.				
Objectives:								
		oling students						
						nming Problems.		
					l Assignment Pr	ng decision theory.		
						ies involved in the pro	piect	
Outcomes:		in anagrams w						
	g the course,	the students	should be abl	e to:				
	-	near and Nonl			18.			
					nment Problem			
				•	0 0	decision theory.		
		hedule and ex	pected comple	etion time for	the project.			
Detailed Syll Unit	abus: Description						Duration, h	
Umt		n to Operatio	ns Research				Duration, n	
		-		ch to problem	n solving, Mode	ls and Modelling in		
						s research models,		
		y of operation	s research, Ad	vantages.				
1.	Linear Prog		с т .				6	
						tages, Limitations, lelines for Model		
						bhical Method and		
	Simplex Met		program	ing proore	ing using orup			
		tion and Assig						
2.						ortation Algorithm,		
2.						ematical Models of	6	
		Problem, Solu		of Assignmen	it Floblelli.			
		eory and Gar		nes of Decisi	on-Making Fny	vironment, Decision		
	1			L	0	n Zero Sum Games,		
3.	Pure Strateg	ies (Minimax	and Maximi	n Principles):	Games with S	addle Point, Mixed	6	
				, The Rules o	f Dominance, S	Solution Methods of	6	
		out Saddle Poi	nt.					
4	Project Mar				M Dhasas of D			
4.						roject Management, itical Path Analysis.	6	
						completion time.		
	Total			<u>,</u>	1 5	1	24	
Fext Books:								
	Sharma, "Ope	erations Resea	rch: Theory ar	nd Application	ns", Trinity Pres	ss 5th Edition ISBN N	0.	
	9350593363.							
		er, Gerald Lie	berman, "Intro	oduction to Op	erations Resear	ch, McGraw Hill", 6th	n Edition ISBN	
No. Reference Bo	0071139893. poks:							
		n. "Operations	Research An	Introduction'	. PHL 9th Edition	on, ISBN No. 978- 93	32518223	
						Chand, ISBN No.978-		
3. Way	ne L. Winsto	n, "Operations				Cengage Learning, 4th		
No	978-8131501	900.						

4. P Sankara Iyer, "Operations Research", Sigma Series, TMH, 1st Edition, ISBN No.978-0070669024.

ram:		nation Technology			ester : I	
rse :		ics (Open Elective))	Cod		T1601A
	Teaching Scher	ne		Evalua	ation Scheme	
ecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	2	20	-	30	50
requisit	e:					
	Learning					
ata Scier	nce					
Underst Underst Analyti		robability and its us plication of Descri	sage in various bus	iness application		ir uses for Busine
Evaluat	e different data analy	tics tools.				
learnin Gaining Evaluat To perf Analytic	g the course, the stud Knowledge of basic ing basic concepts of form practical appli- cs. e different tools.	concept / fundame f probability and per	ntals of <mark>bus</mark> iness a rform <mark>probabili</mark> ty t	heoretical distr		of Business
iled Syl		S S S			2	
t	labus.	De	escription		121	Duration, h
UN Wh mo	IT – I : Introductio at is business analyti del building, Deploy lytics, current trends	n ics?, Business Ana ment, Different ty _l	lytics process: properties of business an			6
UN Opt Not pre-	IT - II: Analytics T timization technique n –linear programmi dictive analysis, lo roduction to supervis	echniques s: Linear Programi ng, Predictive mod ogistic regression,	ning, Goal Progra eling :- regression linear discrimir	, multiple linea ant analysis,	ar regression for Data Mining:	6
UN Pro Pro Not Cor	IT III : Probability bability: Theory of bability Theoretical rmal distributions. acept of Business A Spread Sheet to analy	Theory & Distrib Probability, Addi Distributions: Cor nalytics- Meaning t	ution tion and Multipli neept and applicat	cation Law, E ion of Binomi on of Business	Baye's Theorem al; Poisson and s Analytics, Use	6
UN	IT IV : Data analy	ics tools		1		6
			Total			24
	ad , Seema Acharya	"Fundamentals of	business analytics'	', Wiley		
UN Dat Books: .N. Pras	IT IV : Data analy a Visualization using ad , Seema Acharya	ics too g Table . "Fund	ls au/Python/R amentals of	ls au/Python/R/SQL. Case study. Total amentals of business analytics"	ls au/Python/R/SQL. Case study. Total amentals of business analytics", Wiley	ls au/Python/R/SQL. Case study. Total amentals of business analytics", Wiley

Program:								
Course :	R Programming		•	Code		IT1601B		
	Teaching Scher	ne		Evalua	tion Scheme			
Lectur	e Hours	Credit	IE1	IE2	ETE	Total		
2	2	2	20	-	30	50		
Pre-requis	ite:							
	lge of Statistics in Ma							
	owledge of any progra	amming						
Objectives								
	and R Studio Enviror							
	rstand different data ty		ctures in R					
	face R with other lange							
	rstand the use of R for	Big Data analytics.						
Outcomes		1	4					
	ing the course, the stud			ol statements	tring functions			
	and the basics in R property R for Big Dat		a constructs, conti	of statements, s	suring functions.			
	e use of R for Big Dat apply R programming							
	apply R programming ppreciate and apply th		om a statistical no	rspective				
+. ADIC 10 2	ippreciate and apply in	e K programming no	oni a statistical pe	ispective.				
Detailed S	yllabus:	5/5/			~			
Unit	1	Desc	cription		2	Duration, h		
U	UNIT – I : Getting Started with R Programming							
1. Ir	troduction to the R-	Studio, user-interfac	ce, Basic comm	ands, Data Str	uctures in R,	6		
R	eading data into R, Su	bsetting						
U	NIT - II: Matrices, A	rrays And Lists						
	reating matrices ,Matr							
	dding and deleting ro					6		
	eduction, Higher Dir	-	-		-			
	ccessing list compone		lying functions to	lists, Recursive	lists			
	NIT III : Data Fram							
	reating Data Frames,							
	inctions to Data frame					_		
	ith factors, Working					6		
	statements: Arithmetic and Boolean operators and values, Default values for arguments, Returning Boolean values, Environment and Scope issues: Writing Upstairs - Recursion							
	U	,	-	0 1				
	Replacement functions	, Tools for composing	g function code, r	Math and Simul	ations in K			
	NIT IV : Interfacing Iterfacing R to other	amousana Domellal F	Dania Statistics	Lincon Mode	1 Comparatized	4		
	inear models, Non-line					6		
	mear models, Non-mit		Tes and Auto-corr [otal	elation – Cluste	anng	24		
Text Book	S•	L	Utal			<i>2</i> 4		
	s: ardener, " Beginning R	The Statistical Pro	oromming Lang	unge" Wiley 20	12			
	Matloff, "The Art of					ress 2011		
Reference		ivi iogramming. A 1	i our or oranistical	Soliware Desig		1000, 2011		
	Lander, "R for Everyc	ne: Advanced Analy	tics and Granhies	" Addison-We	slev Data & An	alvics Series 201		
	Knell, "Introductory R							
	siteri, muoudetory R	Deginner o Oulu	e io paia moualiz	manum prationed	. i i inai yoio anu	r rogramming ill l		
	igital South Asia Serv	U		,				

2. Identifying Outcomes: After learning 1. Prepare fa Detailed Syll Unit Intro- Clien 1. (Mar actin	Cost Managemen Teaching Scher Hours 2 e: Engineering anagement e the parties concern g "best value" proje g the course, the stua avorable financial o	Credit 2 ned with a most fav ect option selection a dents should be ablutcome to the proje utcome to the proje Des	Project (Open Ele IE1 20 orable financial out and developing reat e to: ect. scription ost Management	Event of technology IEX	2 ETE 30 he project.	EIT1601C Total 50 Duration, h
2 Pre-requisite 1. Software E 2. Project Ma Objectives: 1. To provide 2. Identifying Outcomes: After learning 1. Prepare fa Detailed Syll Unit Intro Clien 1. (Man actin	Hours 2 e: Engineering inagement e the parties concern g "best value" proje g the course, the stur avorable financial o labus: roduction and Pun ent, Engineering co	Credit 2 ned with a most fav ect option selection a dents should be ablutcome to the proje utcome to the proje Des	20 Torable financial out and developing real e to: e to: scription ost Management	IE.	2 ETE 30	50
2 Pre-requisite 1. Software E 2. Project Ma Objectives: 1. To provide 2. Identifying Outcomes: After learning 1. Prepare fa Detailed Syll Unit Intro Clien 1. (Man actin	2 e: Engineering unagement e the parties concern g "best value" proje g the course, the stu- avorable financial o labus: roduction and Pun ent, Engineering co	2 ned with a most fav ect option selection a dents should be abl utcome to the proje Des rpose of Project Co	20 Torable financial out and developing real e to: e to: scription ost Management	tcome to t	30 he project.	50
Pre-requisite 1. Software E 2. Project Ma Objectives: 1. To provide 2. Identifying Outcomes: After learning 1. Prepare fa Detailed Syll Unit I. (Mar actin	e: Engineering magement e the parties concern g "best value" proje g the course, the stu- avorable financial o labus: roduction and Pun ent, Engineering co	ned with a most fav ect option selection a dents should be abl utcome to the proje Des rpose of Project Co	orable financial out and developing real e to: ect. scription ost Management	tcome to t	he project.	
1. Software E 2. Project Ma Objectives: 1. To provide 2. Identifying Outcomes: After learning 1. Prepare fa Detailed Syll Unit I. (Man actin	Engineering unagement e the parties concern g "best value" proje g the course, the stu- avorable financial o labus: roduction and Pun ent, Engineering co	tet option selection and dents should be ablutcome to the proje Des rpose of Project Co	and developing real e to: ect. scription ost Management		1 0	Duration, h
Outcomes: After learning 1. Prepare fa Detailed Syll Unit Intr Clien 1. (Mar actin	g the course, the stu- avorable financial o labus: roduction and Pur ent, Engineering co	dents should be ablutcome to the proje Des	e to: cct. scription ost Management	listic bud _i	gets.	Duration, h
After learning 1. Prepare fa Detailed Syll Unit Intro 1. (Mar actin	avorable financial o labus: roduction and Pur ent, Engineering co	utcome to the proje Des rpose of Project Co	scription	olles		Duration, h
Unit Intr Clier 1. (Mar actin	roduction and Pur ent, Engineering co	rpose of Project Co	ost M <mark>anagem</mark> ent	01100		Duration, h
IntrClien1.(Mailactin	ent, Engineering co	rpose of Project Co	ost M <mark>anagem</mark> ent	- 100		Duration, h
1. Clien (Man actin	ent, Engineering co					/
	ng as PMC for C ernal Finance Provid	Client, Material Su der	M role for project	implemen	tation, Consultant	6
2. Proje	e Project Cost Man ect Concept & lementation, Project	Feasibility, Proj			efinition, Project	6
3. Estin Estin fund Loca Proje finar	mating and Project mate Categories, E mate Scope, Study ling, Estimate qua ation factors, Escala fect Financing: Inter ncing, Banks & Ver tomers	Ext Financing Setimate Quality, P / Development Est lity required for ation ,Currency fluc rnal financing, Fina	Project Schedule in stimates, Estimates project authorizati tuations, Continger ancing of project de	fluence of for prov on, Estin ncy, Cash evelopme	ision of advanced nating techniques, flow nt works, External	6
4. Meg exter in e requ	nerable Projects ga-projects (Projec ensions to existing f emerging markets niring significant re- nolition, Fast Track	Cacilities), New Tec (e.g. E Europe, A gulatory validation	chnology projects, S Asia), Projects in	Sub-surfa remote 1	ce works, Projects ocations, Projects	6
	,		Total			24

Reference Books:

Kenneth K. Humphreys, Lloyd M. English, "Project and cost engineer's handbook", third edition, Ace International, Marcel Dekkar Inc., New York Basel.

Program		mation Technology)			ester : II	
Course :	Cryptography (Code		T2602A
	Teaching Sche	me		Evaluati	on Scheme	
Lectu	re Hours	Credit	IE1	IE2	ETE	Total
2	2	1	20	-	30	50
Pre-requ 1. Basic N 2. Basic C 1. To und 2. To stuc 3. To stuc 4. To stuc Outcome After lear 1. Unders 2. Analyz 3. Learn of	isite: Aathematics Computer Network. erstand computer, netw ly operating system sec ly security issues in inte ly network defense tool s: ning the course, the stu stand modern concepts and use methods for details and design philo	ork and information surity and malwares. ernet protocols. s. dents should be able related to cryptograph cryptography and refl sophy of modern sym	to: ny and cryptanalys ect about limits an metric and public	sis nd applicability key systems	· · · · ·	
Detailed	uses and limitations of Syllabus:	SAN		algorithms		Dungtion k
Unit			eription	1.2.6.2		Duration, h
1.	UNIT – I: Introducti Computer Security Co Information Security, services, Modular Arith Fotient Function, Exter	oncepts, Terminolog Security Policy, Typ metic, GCD, Euclide	bes of Security a an Algorithm, Fe	ttacks , Secur ermat's Little T	ity Goals and Theorem, Euler	6
2.	UNIT – II : Classical I Symmetric Cipher M Substitution Ciphers, T Stream Ciphers	E ncryption Techniq Iodel, Encryption I	ues : Methods, Classic	al Encryptior	Techniques,	6
3.	UNIT III : Private-key Encryption: ledge Brings Freedom					
4. ¹	U NIT IV : Public-key Public-Key Cryptograj Diffie Hellman Key E [ECC]	ohy, Key Manageme				6
		Г	otal			24
2. V. K. F	n Stallings, Computer S Pachghare, "Cryptograp an Katz, Yehuda Lindel	hy and Information S	ecurity", PHI Lea	rning 3rd edition	on	35469-0

Oded Goldreich, "Foundations of Cryptography Basic Tools", Cambridge University Press.
 Nina Godbole, "Information Systems Security", Wiley India Pvt. Ltd, ISBN -978-81-265-1692-6

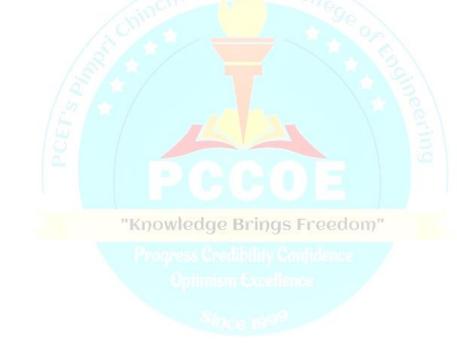
Program:		mation Technology)			ester : II	
Course :		ng and Security (Op	en Elective)	Code		T2602B
	Teaching Sche	me		Evaluatio	on Scheme	
Lecture	Hours	Credit	IE1	IE2	ETE	Total
2	2	1	20	-	30	50
Pre-requisite						
1. Operating	•					
	als of Computer Ne	etworks.				
Objectives:		10				
		d Computing and its of and its importance				
		Cloud Programming				
-		in cloud computing.	, and Services.			
Outcomes:	and security issues	in cloud computing.				
	the course, the stu	dents should be able	to:			
	and the need of Clo					
		anisms and issues in	vari <mark>ous Cl</mark> oud App	olications		
3. To explore	e effective technique	es to program Cloud	Sy <mark>stems.</mark>			
4. To underst	and current challen	ges and trade-offs in	Cloud Computing			
D-4-9-16-1				0,0	1	
Detailed Syll Unit	abus:	Dogo	mintion		8	Duration, I
	T L. Eundomon	tals of cloud compu	cription		6.	Duration, I
1. Cha Tecl Virt	llenges, Roles and loyment Models, mology: Broadban	Basic Concepts and Boundaries, Cloud C Federated Cloud/Int d Networks and Int blogy, Web Techn	Characteristics, Clo cercloud, Types of ernet Architecture	oud Delivery Moof Clouds. C , Data Cente	Models, Cloud Cloud-Enabling r Technology,	6
2. UNI Imp Typ and Stan App and Secu	T – II: Virtualiza lementation Levels es of Hypervisors, Resource Manag dards: The Open lication Developers LAPP),Syndication	tion and common st of Virtualization, Vi Virtualization of CPI ement, Virtualization Cloud Consortium, s: Browsers (Ajax), n (Atom, Atom Pu	rtualization Struct J. Memory, and I on for Data-Cen Open Virtualizat Data (XML, JSOI blishing Protocol,	ures/Tools and /O Devices, V iter Automati tion Format, N), Solution S , and RSS),	irtual Clusters on. Common Standards for Stacks (LAMP	6
3. Feat Prog 3. Env appl Clou App	ures of Cloud and gramming on Am ironments, Unders ication to cloud, I ad Services, Cloud s, Customer Relation	ramming, environm Grid Platforms, Pr azon AWS and M standing Core Ope Microsoft Cloud Ser Applications (Social onship Management).	ogramming Suppo licrosoft Azure, enStack Ecosyste rvices, Google Cl Networking, E-m	ort of Google Emerging Cl em. Applicati loud Applicat	oud Software ions: Moving ions, Amazon	6
Basi Con	siderations, Cloud ic Key Infrastructu	pts, Threat Agents, C Security Mechanist re (PKI), Identity and	ms: Encryption, 1 d Access Manager	Hashing, Digi nent (IAM), S	ital Signature,	6
(SSC Lon	gevity, Business C	ontinuity, Service-Le	evel Agreements,	Agreeing on	the Service of	24

Text Books:

- 1. Jack J. Dongarra, Kai Hwang, Geoffrey C. Fox, Distributed and Cloud Computing: From Parallel Processing to the Internet of Things, Elsevier, ISBN :9789381269237, 9381269238, 1st Edition.
- 2. Thomas Erl, Zaigham Mahmood and Ricardo Puttini, Cloud Computing: Concepts, Technology & Architecture, Pearson, ISBN :978 9332535923, 9332535922, 1 st Edition.

Reference Books:

- 1. Srinivasan, J. Suresh, Cloud Computing: A practical approach for learning and implementation, Pearson, ISBN :9788131776513.
- 2. Brian J.S. Chee and Curtis Franklin, Jr., Cloud Computing: Technologies and Strategies of the Ubiquitous Data Center, CRC Press, ISBN :9781439806128.
- 3. Kris Jamsa, Cloud Computing: Saas, Paas, Iaas, Virtualization, Business Models, Mobile, Security, and More, Jones and Bartlett, ISBN :9789380853772.
- John W. Ritting house, James F. Ransome, Cloud Computing Implementation, Management, and Security, CRC Press, ISBN : 978 1439806807, 1439806802.
- 5. Karl Matthias, Sean P. Kane, Docker: Up and Running, OReilly, ISBN:9781491917572, 1491917571.



Program:							
Course :		mentals of Crypto (Currencies		Code	: MF	CIT2602C
	(Open Elective)						
	Teaching Schen	ne		E	valuati	ion Scheme	
Lecture	Hours	Credit	IE1	IE2		ETE	Total
2	2	1	20	-		30	50
2. Basic of Ir Objectives: 1. To underst 2. To underst 3. To underst 4. To underst Outcomes: After learnin 1. Apply Cr 2. Learn and	and the basic concept and the basic concept and the different Cont and the concepts of 1 and the Mechanics of g the course, the stuc yptography concepts 1 apply different con block chain model co	ots behind Cryptogra nsensus approaches blockchain technolog f bit coin. lents should be able s to Currency (real ti sensus mechanisms	for Bit coin. gy. to: me) problem solv for real time proj	ring.	l on dig	gital currency.	
Detailed Syl Unit Bas	14	Desc	cription		0		Duration, h
1. Fun Trae	damentals of Crypto ling Exchanges ,Ma , Ledger ,Consensus	arket Tradability Cr	ypto T <mark>rad</mark> ing Str				6
2. How Wal	v to Store and Use I v to Store and Use B lets and Exchanges,	Bit coins it coins, Hot and Co	old Storage, Splitt				6
3. Crv	ptography: ptographic Hash Fur ate Keys, A Simple	nctions: Hashing an Crypto currency	d SHA 256, Dig	ital Signa	atures, i	Public Keys ,	6
4. Mea Bit The Dec	chanics of Bit coin coin Transactions, B Bit coin Network, F entralization, Distrib entives, Miners and M	it coin Scripts, Appl Iow Bit coin Achiev outed Consensus : Co	ications of Bit co es Decentralizationsensus without	in Scripts on, Centra Identity,	, Bit co alizatio The Bl	oin Blocks, n vs. ock chain	6
	· · · ·		otal				24
Other Crypto <u>2. Daniel Dre</u> Reference B 1. Bikramad Building Blo	est, "Block chain D currencies", Create escher, "Block chain ooks: itya Singhal, Gautar ck chain Solutions", nen, "Introducing E	Space Independent H Basics", A Non -Tec n Dhameja, Priyans 2018	Publishing Platfor chnical Introducti su Sekhar Panda,	rm, 15-M <u>on in 25</u> "Beginn	ay-201 <u>Steps.</u> iing Bl	8 ock chain A I	Beginner's Guide

Annexure-II Audit Course Syllabus

Program:	M.Tech. (Design Engin	eering)		Semester	Semester : I and II				
Course :	Audit Courses (Semest	er I and II)		Code : M_1961 M_2962					
	Teaching Scheme			Evaluat	tion Scheme				
Lecture	Hours	Credit	IE1	IE2	ETE	Total			
1	1								
Guidelines:			<u>.</u>						
1. The	e audit courses are commo	on to all M.Tech	Courses.						
2. Stu	dents can select any audit	t course from li	st of audit co	urses for semester	r I and II				
3. The	se are non-credit courses	but mandatory	to comply th	e submission of t	he semester.				

LIST OF AUDIT COURSES

(Common to M.Tech and MCA programs)

	SEM-I	A	SEM-II
M_1961A	Constitution of India	M_2962A	Team Building & Leadership
M_1961B	Value Education	M_2962B	English for Research writing
M_1961C	Stress Management	M_2962C	Disaster Management

Program					Semester: I	
Course	Constitution of In		·		Code : M_196	1A
	Teaching Scher	me		Evalua	tion Scheme	
Lectu	ire Hours	Credit	IE 1	IE 2	ETE	Total
1	1	-				
Dbjecti 3. 4. 5.	ves: To understand the constitu To understand the rules an To understand E-governar	nd regulations under wh	nich public and p	private sector w	vork	
Outc	comes:					
1. Ur const 2. Di rights	learning the course, the stunderstand the functions of the itution and assessment of the fferentiate the functioning of s and abide the rules of the ference	ne Indian government a he Parliamentary System of Indian Political system	nd identify and m in India.	-		
Unit	d Syllabus: Description	inchwad	Co	llea		Duration h
1.	Introduction to Constitution Meaning of the constitution and characteristics of the Principles of State Policy, Structure and Function of Cabinet, Parliament, Su distribution of legislative government	on law and constitution e Constitution of Indi Fundamental Duties an of Central Governmen preme Court of Indi	nalism, making o a, Preamble, F nd it's legal stati t, President, Vi ia, Judicial Re	undamental R us, Citizenship ce President, view, Federal	ights, Directive Prime Minister, structure and	6
2.	Judiciary and Constitution Governor, Chief Ministe and other Subordinate Con Constitution Functions: Relations, President's Functionaries, Emergenc India.	r, Cabinet, State Legis urts, Parliamentary For Indian Federal Syst Rule, Constitutional	m of Governme em and it's c Amendments	nt in India. haracteristics, and powers,	Center& State Constitutional	6
		Optimis	an cacellene		Total	12
1. Durga ISBN-1 2. Clare Law", M Referer 1. Dr J 2. <u>https</u> 3. http: 4. Maci ISBN	Books: a Das Basu, "Introduction to 09388548868 ndon Press, Subhash C, Kas JBT, 5th edition, 2014, ISB nee Books: N Pandey : Constitutional s://www.meity.gov.in/divis ://www.meity.gov.in/divis ://www.meity.gov.in/documenty //www.iibf.org.in/documenty ver and Page, "Society: A I-100333916166 Bhakshi, "The constitutior	shyap, "Our Constitution N-9781107034624 I Law of India sions/national-e-gover Y e-book/e-gov policy nts/cyber-laws-chapte n Introduction Analys	on: An Introduct mance-plan y/download/Pol er-in-legal-aspections sis ", Laxmi Pu	tion to India's (icy%20Docur cts-book.pdf blications, 4th	Constitution and c nent.pdf 1 edition, 2007,	onstitutional

Program	M.Tech(All Bi	ranches)/MCA			Semester: I		
Course :	Value Educati	on			Code : M_1961	1B	
	Teaching Schem	ne		Evaluati	ion Scheme		
Lecture	Hours	Credit	IE 1	IE 2	ETE	Total	
1	1	-					
 To ex To en 	ntify and develop At pose students to Fam able student to under able students to unde	ily Relations stand Creative Think	ting and Problem	ı solving			
1 Cha 2 Cha inst	g the course the stude nge in awareness lev nge in attitudes / beh tutional leadership a rovement in social he	els, knowledge and u aviour of students w nd other life skills	understanding of		proved teamwork,		
Detailed Syl	labus:	inch		100	<u> </u>		
Unit D	escription				2	Duration h	
Un and	ay Human Relations a derstanding Behavio I Perception, Attituc aling with Conflict, I	ur, Human Relation les, Self-Concept, N				6	
Ba	tice in Humankind, I sis for Humanistic E mpetence in profession	Education, Humanist		and Humanistic	Universal Order,	6	
		111/011100	age or mys		Total	12	
	dation Course in Hun elhi and Teacher's M ooks:					xcel Books	

2. Atkinson and Hilgard's, "Introduction to psychology" Nolen-Hoeksema, S., Fredrickson, B. L., Loftus, G. R., & Lutz, C., Cengage Learning EME.

Program	n M.Tech(All Branche	s)/MCA			Semester: I	ster: I		
Course	: Stress Management				Code : M_1961C			
	Teaching Schem	e		Ev	aluation Scheme	1		
Lectu	ire Hours	Credit	IE 1	IE 2	ETE	Total		
1	1	-						
3.	ves: To overcome stress To achieve overall health of t To learn to achieve the highes To become a person with stat	st goal happily	onality and d	eterminatio	on			
1. Devel	es: will be able to: op healthy mind in a healthy b we working efficiency	ody thus improving so	cial health al	so				
Detailed	l Syllabus:	bou	1 0					
Unit	Description					Duration hr		
	Definitions of Eight parts of Y Yam and Niyam. Do`s and Don't's in life.	fog. (Ashtanga)			E.	6		
	Pranayam Regularization of breathing teo Types of pranayama Approach to day to day work a		3-23		neering	6		
	<u> </u>		A-7 A	-	Total	12		
Text Bo 1. Yo	oks: ogic Asanas for Group Tarining	g-Part-I" : Janardan Sw						
Referen	ce Books:	Propriet Could	hilling Com	5.1				
Ko 2. We	vami Vivekananda, Rajayoga o olkata endelin Küpers, David J. Paule usiness Practice, 2016	een, A Handbook of Pra	actical Wisdo		ship, Organization a	_		

3. A Foundation Course in Human Values and Professional Ethics Presenting a Universal Approach to Value Education - Through Self-exploration

Program	m	M.Tech(All Brand	ches)/MCA			Semester: II		
Course	:	Team Building &	Leadership			Code: M_296	962A	
		Teaching Scheme			Evaluation	Scheme		
Lec	ture	Hours	Credit	IE 1	IE 2	ETE	Total	
1	1	1	-					
Objecti 1. 2. 3.	Develop Become	o and strengthen inte familiar with and d rize students with the	iscuss different lea					
Outcom After lea		e course, the student Use leadership and To develop the cap	teamwork knowle	edge to develop pr				
	d Syllabu	15:				Γ	Duration	
Unit	nit Description							
4.	using p future What t leader.	rship: Will and me power responsibly a actions and transmit the word "leader" Categories: autocra rial, etc.	and respectfully: that vision to oth means, Types of	th <mark>e leader as a t</mark> ers. Taking the ir leade <mark>rsh</mark> ip, Tradi	eam-builder, Ab attiative and stim attional, legal, an	ility to plan ulate others. d legitimate	6	
2.	Advant Tradition within Strateg vs. per	work s teamwork import tages and disadvanta onal vs. virtuoso tea the organization. Cr gies to develop the t rsonal motivation. pation. Creating tean	ges of teamwork. ms, forming effec eating a friendly a eam's mission, vi Distinguishing pu	How to determine tive and balanced and collaborative e sion, values, and urpose and tasks	e roles in a team. I teams, Strength nvironment. objectives. Share in the team.	ening teams	6	
	Total		Optin	niam Gwellen	88 / T		12	
2. Ro 3. M	tephen Conald A.	ovey, The Seven Ha Heifetz, Leadership Porter, Competitive s:	without Easy Answ	wers, Belknap Pre				
1. Joi 2. Ikt	hn Kottei ujiro Nor	r, Leading Change: V naka, The Knowledg est, The Secrets of S	e-Creating Compa	ny	. 2, "Self-Manag	ement," pgs. 32-	61	

Program		M.Tech(All Branches)/MCA Semester: I					II	
Course :		English For Rese	earch Paper Writing	Code : M	Code : M_2962B			
Teaching Scheme Evaluation						1 Scheme		
Lecture		Hours	Credit	IE1	IE2	ETE	Total	
	1	1	-					
Objecti								
			ve your writing skills a	and level of read	lability			
		t what to write in e						
			when writing a Title					
		good quality of pap	per at very first-time su	ibmission				
Outcon			1 111 11					
After le	arning the	course the students	should be able to:					
	d Syllabus	5:	chuad	1 Co	10		Duration	
Detaile Unit			Descript		lego		Duration h	
	Planning Structuri Redunda Clarifyin Criticizin Writing	and Preparation, W ng Paragraphs and ncy, Avoiding Aml g Who Did What, J ng, Paraphrasing an	Vord Order, Breaking u Sentences, Being Conc biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L	up long sentence cise and Removi , dings, Hedging a of a Paper, Abs	ing and tracts.	Discussion,		
Unit	Planning Structuri Redunda Clarifyin Criticizii Writing Conclusi Key skil Discussio	and Preparation, W ng Paragraphs and ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Che ls needed: Title, A	Vord Order, Breaking u Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I	ing and tracts. hods, Results, Literature, Metho	ods, Results,	h	
Unit 1	Planning Structuri Redunda Clarifyin Criticizii Writing Conclusi Key skil Discussio	and Preparation, W ng Paragraphs and ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Che ls needed: Title, A on, Conclusions, U	Vord Order, Breaking u Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I	ing and tracts. hods, Results, Literature, Metho	ods, Results,	<u>h</u> 6	
Unit 1 2 Text Bo	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussio be the fin Total Doks:	and Preparation, W ng Paragraphs and a ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Che Is needed: Title, A on, Conclusions, U rst- time submission	Vord Order, Breaking u Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to h	up long sentence cise and Removi dings, Hedging a of a Paper, Abs iterature, Meth Review of the I ensure paper is	ing and tracts. hods, Results, Literature, Metho as good as it co	ods, Results, uld possibly	<u>h</u> 6	
Unit 1 2 Text Bo 1.	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussic be the fin Total Dey R (2)	and Preparation, W ng Paragraphs and a ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Chea ls needed: Title, A on, Conclusions, U rst- time submission	Vord Order, Breaking u Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to	up long sentence cise and Removi dings, Hedging a of a Paper, Abs iterature, Meth Review of the I ensure paper is	ing and tracts. hods, Results, Literature, Metho as good as it co	ods, Results, uld possibly	<u>h</u> 6	
Unit 1 2 Text Bo 1.	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussio be the fin Total Doks: Dey R (2 ace Books	and Preparation, W ng Paragraphs and a ncy, Avoiding Aml ng Who Did What, H ng, Paraphrasing am the Introduction, ons, The Final Cher Is needed: Title, A on, Conclusions, U rst- time submission	Vord Order, Breaking u Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to h	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I ensure paper is Brings Fr	ing and tracts. hods, Results, Literature, Metho as good as it co	ods, Results, uld possibly Press	<u>h</u> 6	
Unit 1 2 Text Bo 1.	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussio be the fin Total Doks: Dey R (2 ace Books Goldbort	and Preparation, W ng Paragraphs and S ncy, Avoiding Amb ng Who Did What, H ng, Paraphrasing am the Introduction, ons, The Final Che Is needed: Title, A on, Conclusions, U rst- time submission 006) How to Write R (2006) Writing f	Vord Order, Breaking v Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to n "Knowledge and Publish a Scientif	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I ensure paper is Brings Fi ic Paper, Cambr ersity Press (ava	ing and tracts. hods, Results, Literature, Metho as good as it co eeelom ridge University	ods, Results, uld possibly Press e Books)	h 6 12	
Unit 1 2 Text Bo 1. Referen 1. 2.	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussio be the fin Total Dey R (2 nce Books Goldbort Highmat	and Preparation, W ng Paragraphs and a ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Che Is needed: Title, A on, Conclusions, U rst- time submission (006) How to Write R (2006) Writing f n N (1998), Handbo	Vord Order, Breaking v Sentences, Being Com biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to h www.edge and Publish a Scientif For Science, Yale Univ bok of Writing for the L	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I ensure paper is Brings Fr ic Paper, Cambr ersity Press (ava Mathematical So	ing and tracts. hods, Results, Literature, Metho as good as it co eectom ridge University ailable on Google ciences, SIAM. F	ods, Results, uld possibly Press e Books) Highman's bool	h 6 12	
Unit 1 2 Text Bo 1. Referen 1.	Planning Structuri Redunda Clarifyin Criticizin Writing Conclusi Key skil Discussio be the fin Total Dey R (2 nce Books Goldbort Highmat	and Preparation, W ng Paragraphs and a ncy, Avoiding Amb g Who Did What, H ng, Paraphrasing an the Introduction, ons, The Final Che Is needed: Title, A on, Conclusions, U rst- time submission (006) How to Write R (2006) Writing f n N (1998), Handbo	Vord Order, Breaking v Sentences, Being Con- biguity and Vagueness Highlighting Your Find d Plagiarism, Sections Review of the L ck. bstract, Introduction, seful phrases, how to n "Knowledge and Publish a Scientif	up long sentence cise and Removi dings, Hedging a of a Paper, Abs Literature, Meth Review of the I ensure paper is Brings Fr ic Paper, Cambr ersity Press (ava Mathematical So	ing and tracts. hods, Results, Literature, Metho as good as it co eectom ridge University ailable on Google ciences, SIAM. F	ods, Results, uld possibly Press e Books) Highman's bool	h 6 6 12	

Program M.Tech(All Branches)/MCA			Semester: II					
Course : Disaster Management				Code : M_2962C				
		Feaching Scheme	1	Evaluation Scheme				
Lecture		Hours	Credit	IE-1	IE2	ЕТЕ	Total	
1		1	-					
 To te managem To prov Outcome 	nt enginee each the o ent. vide insigh s:	concept of Disast	atural and manmade er management an ional and regional le should be able to:	d measures to		C	es of disast	
1. Learn	different of institution	disasters and meas	ures to reduce the ri disaster management			level.		
Unit	Description						Duration h	
1.	Introduction – Hazard and Disaster. Concepts of Hazard, Vulnerability, Risks. Different Types of Disaster : A) Natural Disaster: such as Flood, Cyclone, Earthquakes, Landslides etc B) Man-made Disaster: such as Fire, Industrial Pollution, Nuclear Disaster, Biological Disasters, Accidents (Air, Sea, Rail & Road), Structural failures(Building and Bridge), War & Terrorism etc. Slow Disasters (famine, draught, epidemics) and Rapid Onset Disasters(Air Crash, tidal waves, Tsunami) Causes, effects and practical examples for all disasters.							
2.	 Natural disasters- Earthquakes, Tsunami, Floods, Drought, Landslides, Cyclones and Volcanic eruptions. Their case studies. Coastal disasters. Coastal regulation Zone. Disaster Prevention and Mitigation. Refugee operations during disasters, Human Resettlement and Rehabilitation issues during and after disasters, Inter-sectoral coordination during disasters, Models in Disasters. Disaster Management : Role of Government, International and NGO Bodies. Role of IT in Disaster Preparedness Role of Engineers on Disaster Management. 							
	Total							
 2. Tushar 3. Jagbir S 4. J.P. Sin 5. C. K. I Publication 	, M., 2014 Bhattacha Singh, Dis ghal, Disa Rajan, Nav n h Shukla,	rya, Disaster Scier aster, Managemen Ister Management, vale Pandharinath	ment, Wiley India F nce and Managemen t: Future Challenges Laxmi Publications , Earth and Atmosp Biodiversity, Enviro	at, McGraw Hill and Opportuni heric Disaster M	ties, K W Publ Management :	ishers Pvt. Lt Nature and M	Manmade, B	

- Disaster management S.K.Singh, S.C. Kundu, Shobha Singh A 119, William Publications, New
 Disaster Management Vinod K Sharma- IIPA, New Delhi, 1995
 Encyclopedia of Disaster Management- Goel S.L. Deep and Deep Publications, New Delhi, 2006.

VISION AND MISSION OF MECHANICAL DEPARTMENT

Vision

• To recognize for an academic excellence through skill development, innovation fine blend with quality work culture

Mission

• To impart quality education, innovation culture, necessary skill sets and social commitment among the students to build professional carrier by establishing state-of-the-art Mechanical Engineering infrastructure and conducive learning environment

Programme outcomes:

- 1. An ability to independently carry out research /investigation and development work to solve practical problems
- 2. An ability to write and present a substantial technical report/document
- 3. Students should be able to demonstrate a degree of mastery over the area as per the specialization of the program. The mastery should be at a level higher than the requirements in the appropriate bachelor program

Programme Specific Outcomes:

"Knowledge Brings Freedom"

- Students will be able to critically analyze / synthesize, simulate and optimize mechanical systems, components and processes by applying the principles of design engineering.
- 2. Student will be able to investigate and provide solutions to complex interdisciplinary problems using modern tools of design engineering.

Higher Study Scope: Ph.D. Research Centre at PCCOE.





"There are no secrets to success. It is the result of preparation, hard work, learning from failure." - Colin Powell



Pimpri Chinchwad College of Engineering (PCCoE),

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